```
#define XTAL FREQ 20000000 // Define the crystal oscillator frequency as 20MHz (for delay functions)
                                // Function prototype for LCD initialization
24
     void Lcdinit(void);
     void LcdCommand(uint8_t i); // Function prototype for sending commands to the LCD
26
     27
     void LcdOutput(uint16_t i);
     void BatStatus(void);
28
29
     uint8_t Array[15] = {"BAT VOLT= v"};
30
31
     uint8_t BatLowArray[15] = {"BAT LOW
32
     uint8 t BatMediumArray[15] = {"BAT MEDIUM"};
33
     uint8_t BatHighArray[15] = {"BAT HIGH"};
34
     char buffer[10];
35
36
     uint8_t x, m, n, value;
37
     float k = 15.5;
38
     float j = 17.5;
39
40 □ void main(void) {
        Lcdinit(); // Initialize the LCD
41
42
43
        while(1)
44
        {
45
            BatStatus();
             __delay_ms(100);
46
47
48
49
50
     // Function to initialize the LCD
     void Lcdinit(void)
51
52 □ {
         TRISC = 0x00; // Set PORTC as output (for control signals)
53
         TRISD = 0x00; // Set PORTD as output (for data signals)
TRISB = 0xF0; // Set R4 to R7 as Input
54
55
56
         OPTION_REG &= ~(0x1U << 7); // Enable Pull Up
57
         __delay_ms(100); // Wait for LCD to stabilize
58
59
         // LCD initialization sequence as per HD44780 LCD datasheet
60
61
         LcdCommand(0x30); // Send function set command (8-bit mode)
62
           __delay_ms(100);
63
         LcdCommand(0x30); // Repeat function set command
64
           delay ms(100);
65
         LcdCommand(0x30); // Repeat function set command again
66
           _delay_ms(100);
         LcdCommand(0x38); // Set LCD for 8-bit mode, 2-line display, 5x8 font
67
68
           delay ms(100);
69
         LcdCommand(0x0C); // Turn on display, cursor off
70
          __delay_ms(100);
         LcdCommand(0x01); // Clear the display
71
72
          delay ms(100);
73
          LcdCommand(0x06);
74
          __delay_ms(100);
75
76
```

```
// Function to monitor and display battery status on the LCD
 78
      void BatStatus(void)
 value = PORTB & 0xF0; // Mask lower 4 bits and read only the upper 4 bits of PORTB
 80
 81
 82
          switch(value)
 83
              case 0xE0: // PORTB = 1110 0000 -> Initial battery status display
 84
                  LcdCommand(0x80); // Move cursor to the first row, first column
 85
                  for (int i = 0; i < 15; i++)
 86
 87
                      LcdData(Array[i]); // Display battery-related text from Array
 88
 89
 90
                  LcdCommand(0x89); // Move cursor to column 9
                  sprintf(buffer, "%.1f", j); // Convert floating-point battery value to a string
 91
 92
                  for(int i = 0; buffer[i] != '\0'; i++)
 93
 94
                      LcdData(buffer[i]); // Display battery voltage on the LCD
 95
 96
                  LcdCommand(0xC0); // Move cursor to the second row, first column
 97
                  for (int i = 0; i < 7; i++)
                      LcdData(BatLowArray[i]); // Display "Low Battery" warning
 99
100
101
                  break;
102
103
              case 0xD0: // PORTB = 1101 0000 -> Battery voltage increasing
                  j += 0.1; // Increment battery voltage
104
105
                  if(j > 22.5){
                     j = 22.5; // Limit maximum voltage to 22.5V
106
107
108
                  LcdCommand(0x89); // Move cursor to column 9
                  sprintf(buffer, "%.1f", j); // Convert updated voltage to string
109
                  for(int i = 0; buffer[i] != '\0'; i++){
110
                     LcdData(buffer[i]); // Display updated voltage
111
112
113
114
                  if(j >= 15.5 && j <= 17.5){ // Display battery status message based on voltage level
115
                      LcdCommand(0xC0); // Move cursor to the second row
116
                      for(int i = 0; i < 10; i++){
                         LcdData(BatLowArray[i]); // Display "Low Battery"
117
118
119
120
                  else if(j >= 17.6 && j <= 20.5){
121
                     LcdCommand(0xC0);
122
                     for (int i = 0; i < 10; i++) {
123
                          LcdData(BatMediumArray[i]); // Display "Medium Battery"
124
125
                  else if(j >= 20.6 && j <= 22.5){
126
127
                     LcdCommand(0xC0);
128
                     for (int i = 0; i < 10; i++) {
129
                         LcdData(BatHighArray[i]); // Display "High Battery"
130
131
132
                  break:
```

```
133
               case 0xB0: // PORTB = 1011 0000 -> Battery voltage decreasing
 134
                   j -= 0.1; // Decrease battery voltage
 135
                   if(j < 15.5){
 136
                       j = 15.5; // Limit minimum voltage to 15.5V
 137
 138
                   LcdCommand(0x89); // Move cursor to column 9
                   sprintf(buffer, "%.1f", j); // Convert updated voltage to string
 139
 140
                   for(int i = 0; buffer[i] != '\0'; i++){
                       LcdData(buffer[i]); // Display updated voltage
 141
 142
 143
 144
                   if(j >= 15.5 && j <= 17.5){ // Display battery status message based on voltage level
 145
                       LcdCommand(0xC0);
                       for (int i = 0; i < 10; i++) {
 146
                           LcdData(BatLowArray[i]); // Display "Low Battery"
 147
 148
 149
                   else if(j >= 17.6 \&\& j \le 20.5){
 150
 151
                       LcdCommand(0xC0);
                       for (int i = 0; i < 10; i++) {
 152
 153
                           LcdData(BatMediumArray[i]); // Display "Medium Battery"
 154
 155
                   else if(j >= 20.6 && j <= 22.5){
 156
 157
                       LcdCommand(0xC0);
                       for (int i = 0; i < 10; i++) {
 158
                           LcdData(BatHighArray[i]); // Display "High Battery"
 159
 160
 161
162
                   break:
163
164
               case 0x70: // PORTB = 0111 0000 -> Reset battery voltage to 17.6V
                   j = 17.6; // Set voltage to predefined value
165
166
                   LcdCommand(0x89); // Move cursor to column 9
167
                   sprintf(buffer, "%.1f", j); // Convert updated voltage to string
168
                   for(int i = 0; buffer[i] != '\0'; i++)
169
170
                       LcdData(buffer[i]); // Display updated voltage
171
                   LcdCommand(0xC0); // Move cursor to second row
172
173
                   for (int i = 0; i < 10; i++)
174
175
                       LcdData(BatMediumArray[i]); // Display "Medium Battery"
176
177
                   break;
178
179
               default:
180
                   // Handle unexpected values if necessary
181
                  break;
182
183
```

```
186 proid LcdOutput(uint16_t i) {
187
          uint8 t d1, d2, d3, d4;
                                              // Creating local var to reduce memory consumption
188
           d4 = (uint8_t)(i / 1000);
                                             // Extract thousands place
          d3 = (uint8_t)((i % 1000) / 100); // Extract hundreds place
189
190
          d2 = (uint8_t)((i % 100) / 10); // Extract tens place
191
          d1 = (uint8_t)(i % 10);
                                             // Extract ones place
192
          LcdCommand(0x88);
193
          LcdData(0x30 + d4);
194
          LcdData(0x30 + d3);
195
          LcdData(0x30 + d2);
196
           LcdData(0x30 + d1);
197
198
199
      // Function to send data (characters) to the LCD
200 proid LcdData(char i) {
          PORTC |= (0x1 << 3); // Set RS (RC3) = 1 (indicates data mode)
201
202
           PORTD = i;
                                 // Place data on PORTD
203
          PORTC |= (0x1 << 0); // Set EN (RC0) = 1 (enable pulse start)
           __delay_ms(100); // Small delay for command execution
204
           PORTC &= \sim (0x1 << 0); // Set EN (RC0) = 0 (enable pulse end)
205
206
207
208
       // Function to send commands to the LCD
209 void LcdCommand(uint8_t i) {
210
          PORTC &= \sim (0x1 << 3); // Set RS (RC3) = 0 (indicates command mode)
                                 // Place command on PORTD
// Set EN (RCO) = 1 (enable pulse start)
// Small delay for command execution
211
           PORTD = i;
212
           PORTC |= (0x1 << 0);
213
           delay ms(100);
           PORTC &= \sim (0x1 << 0); // Set EN (RCO) = 0 (enable pulse end)
214
215
```