



UDACITY

# Technical Safety Concept Lane

## **Assistance**

**Document Version: 1.0** 

Template Version 1.0, Released on 2017-06-21



# Document history

| Date      | Version | Editor       | Description    |  |
|-----------|---------|--------------|----------------|--|
| 5/12/2018 | 1.0     | Sara Mostafa | Intial version |  |
|           |         |              |                |  |
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## Purpose of the Technical Safety Concept

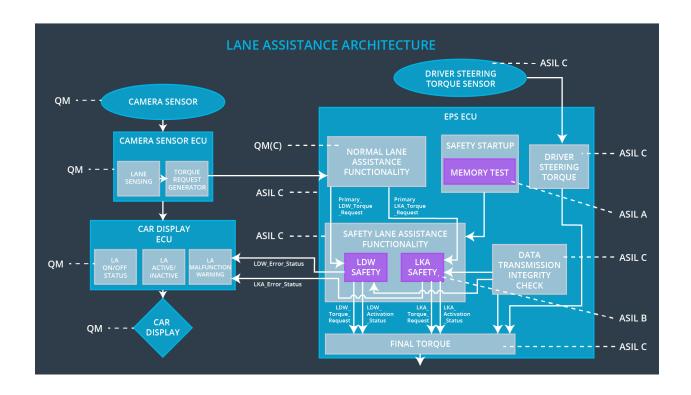
The purpose of the technical safety concept is to refine the functional safety requirements found in the functional safety concept into technical safety requirements.

# Inputs to the Technical Safety Concept

**Functional Safety Requirements** 

| ID   | Functional Safety Requirement   | A<br>S<br>I<br>L | Fault<br>Tolerant<br>Time<br>Interval | Safe State       |
|--|---|------------------|---------------------------------------|------------------|
| Functional<br>Safety<br>Requirement<br>01-01 | The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude   | С                | 50 ms                                 | Turn off system. |
| Functional<br>Safety<br>Requirement<br>01-02 | The lane keeping item shall ensure that the lane departure oscillating torque frequency is below Max_Torque_frequency   | С                | 50 ms                                 | Turn off system. |
| Functional<br>Safety<br>Requirement<br>02-01 | The electronic power steering ECU shall ensure that the lane keeping assistance torque is applied for only Max_Duration | В                | 500                                   | Turn system off. |

### Refined System Architecture from Functional Safety Concept



Functional overview of architecture elements

| Element  | Description   |
|--|---|
| Camera Sensor  | Provide images to camera ECU.   |
| Camera Sensor ECU - Lane Sensing                             | Detect lane lines in the images provided by camera sensor.  |
| Camera Sensor ECU - Torque request generator                 | Generate Torque request to electronic power steering ECU.   |
| Car Display  | Display LKA and LDW warnings to driver.   |
| Car Display ECU - Lane Assistance<br>On/Off Status           | Indicates that Lane assistance feature is Activated or deactivated.   |
| Car Display ECU - Lane Assistant<br>Active/Inactive          | Indicates that Lane assistance system detect lane and is active at the moment.  |
| Car Display ECU - Lane Assistance malfunction warning        | Indicates that Lane assistance system is malfunction and fault is detected.   |
| Driver Steering Torque Sensor                                | Measure steering Torque   |
| Electronic Power Steering (EPS) ECU - Driver Steering Torque | analysis of driver steering torque , recieving torque request generator from camera sensor ecu and output final steering torque to Motor. |
| EPS ECU - Normal Lane Assistance<br>Functionality            | Recieve torque request from camera sensor and output it to safety lane assistance function.   |
| EPS ECU - Lane Departure Warning<br>Safety Functionality     | Checks on malfunction of LDW and output final torque request.   |
| EPS ECU - Lane Keeping Assistant<br>Safety Functionality     | Checks on malfunction of LKA and output final torque request.   |
| EPS ECU - Final Torque                                       | Generate final torque recieved from LKA and LDW safety.   |
| Motor  | Responsible for providing torque to steering wheel  |

# **Technical Safety Concept**

### **Technical Safety Requirements**

#### Lane Departure Warning (LDW) Requirements:

Functional Safety Requirement 01-01 with its associated system elements (derived in the functional safety concept)

| ID   | Functional Safety Requirement   | Electronic<br>Power<br>Steering<br>ECU | Camera<br>ECU | Car Display<br>ECU |
|--|---|--|---------------|--------------------|
| Functional<br>Safety<br>Requirement<br>01-01 | The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below Max_Torque_Amplitude | X                                      |               |                    |

#### Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

| ID   | Technical Safety<br>Requirement   | A<br>S<br>I<br>L | Fault<br>Tolerant<br>Time<br>Interval | Architecture<br>Allocation | Safe State                |
|--|---|------------------|---------------------------------------|----------------------------|---------------------------|
| Technical<br>Safety<br>Requireme<br>nt<br>01 | The LDW safety component shall ensure that the amplitude of the 'LDW_Torque_Request' sent to the 'Final electronic power steering Torque' component is below 'Max_Torque_Amplitude. | С                | 50 ms                                 | LDW safety                 | LDW<br>deactivated        |
| Technical<br>Safety<br>Requireme<br>nt<br>02 | As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light.                     | С                | 50 ms                                 | LDW safety                 | LDW<br>deactivated.       |
| Technical<br>Safety<br>Requireme<br>nt<br>03 | As soon as a failure is detected<br>by the LDW function, it shall<br>deactivate the LDW feature and<br>the 'LDW_Torque_Request'<br>shall be set to zero.                            | С                | 50 ms                                 | LDW safety                 | LDW<br>deactivated.       |
| Technical<br>Safety<br>Requireme<br>nt<br>04 | The validity and integrity of the data transmission for 'LDW_Torque_Request' signal shall be ensured.   | С                | 50 ms                                 | Data integrity             | Keep last<br>valid value. |
| Technical<br>Safety<br>Requireme<br>nt<br>05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory.  | Α                | Ignition<br>cycle                     | Memory Test                | LDW<br>deactivated.       |

# Functional Safety Requirement 01-2 with its associated system elements (derived in the functional safety concept)

| ID   | Functional Safety Requirement   | Electronic<br>Power<br>Steering<br>ECU | Camera<br>ECU | Car Display<br>ECU |
|--|---|--|---------------|--------------------|
| Functional<br>Safety<br>Requirement<br>01-02 | The lane keeping item shall ensure that the lane departure oscillating torque frequency is below Max_Torque_Frequency | X                                      |               |                    |

### Technical Safety Requirements related to Functional Safety Requirement 01-02 are:

| ID                                       | Technical Safety Requirement  | A<br>S<br>I<br>L | Fault<br>Tolerant<br>Time<br>Interval | Architecture<br>Allocation | Safe<br>State                |
|--|---|------------------|---------------------------------------|----------------------------|------------------------------|
| Technical<br>Safety<br>Requirement<br>01 | The LDW safety component shall ensure that the amplitude of the 'LDW_Torque_Request' sent to the 'Final electronic power steering Torque' component is below 'Max_Torque_frequency. | С                | 50 ms                                 | LDW safety                 | LDW<br>deactiva<br>ted       |
| Technical<br>Safety<br>Requirement<br>02 | As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light.                     | С                | 50 ms                                 | LDW safety                 | LDW<br>deactiva<br>ted.      |
| Technical<br>Safety<br>Requirement<br>03 | As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW_Torque_Request' shall be set to zero.  | С                | 50 ms                                 | LDW safety                 | LDW<br>deactiva<br>ted.      |
| Technical<br>Safety<br>Requirement<br>04 | The validity and integrity of the data transmission for 'LDW_Torque_Request' signal shall be ensured.   | С                | 50 ms                                 | Data integrity             | Keep<br>last valid<br>value. |
| Technical<br>Safety<br>Requirement<br>05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory.  | А                | Ignition<br>cycle                     | Memory Test                | LDW<br>deactiva<br>ted.      |

#### Lane Departure Warning (LDW) Verification and Validation Acceptance Criteria:

#### Lane Keeping Assistance (LKA) Requirements:

Functional Safety Requirement 02-1 with its associated system elements (derived in the functional safety concept)

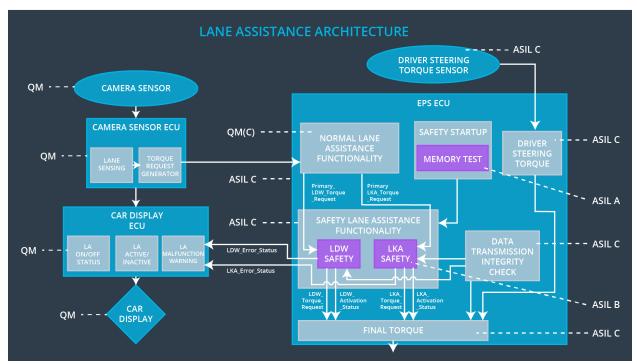
| ID   | Functional Safety Requirement   | Electronic<br>Power<br>Steering<br>ECU | Camera<br>ECU | Car Display<br>ECU |
|--|---|--|---------------|--------------------|
| Functional<br>Safety<br>Requirement<br>02-01 | The lane keeping item shall ensure that the lane keeping assistance torque is applied for only Max_Duration | X                                      |               |                    |

#### Technical Safety Requirements related to Functional Safety Requirement 02-01 are:

| ID   | Technical Safety Requirement  | A<br>S<br>I<br>L | Fault<br>Tolerant<br>Time<br>Interval | Allocation to<br>Architecture | Safe State                |
|--|---|------------------|---------------------------------------|-------------------------------|---------------------------|
| Technical<br>Safety<br>Requireme<br>nt<br>01 | The LKA safety component shall ensure that<br>'LKA_Torque_Request' sent to the<br>'Final electronic power steering<br>Torque' within Max_Duration               | В                | 500 ms                                | LKA safety                    | LKA<br>deactivated        |
| Technical<br>Safety<br>Requireme<br>nt<br>02 | As soon as the LKA function deactivates the LKA feature, the 'LKA Safety' software block shall send a signal to the car display ECU to turn on a warning light. | В                | 500 ms                                | LKA safety                    | LKA<br>deactivated.       |
| Technical<br>Safety<br>Requireme<br>nt<br>03 | As soon as a failure is detected by the LKA function, it shall deactivate the LKA feature and the 'LKA_Torque_Request' shall be set to zero.                    | В                | 500 ms                                | LKA safety                    | LKA<br>deactivated.       |
| Technical<br>Safety<br>Requireme<br>nt<br>04 | The validity and integrity of the data transmission for 'LKA_Torque_Request' signal shall be ensured.   | В                | 500 ms                                | Data integrity                | Keep last<br>valid value. |
| Technical<br>Safety<br>Requireme<br>nt<br>05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory.  | А                | Ignition<br>cycle                     | Memory Test                   | LDW<br>deactivated.       |

#### Lane Keeping Assistance (LKA) Verification and Validation Acceptance Criteria:

### Refinement of the System Architecture



Allocation of Technical Safety Requirements to Architecture Elements

All technical safety requirements are allocated to the Electronic Power Steering ECU.

Warning and Degradation Concept

| ID     | Degradation<br>Mode                         | Trigger for<br>Degradation<br>Mode | Safe State invoked? | Driver Warning  |
|--------|---|------------------------------------|---------------------|---|
| WDC-01 | Turn off lane<br>Assistant<br>functionality | Malfunction_01                     | Yes                 | Lane Assistant<br>Malfunction<br>warning in the<br>car. |
| WDC-02 | Turn off lane<br>Assistant<br>functionality | Malfunction_02                     | Yes                 | Lane Assistant<br>Malfunction<br>warning in the<br>car. |
| WDC-03 | Turn off lane<br>Assistant<br>functionality | Malfunction_03                     | Yes                 | Lane Assistant<br>Malfunction<br>warning in the<br>car. |