# Appendix Data-driven Mutation Testing:

## GomSpace:

### LibGCSP Fault Model

#### Target function

The probes will be inserted in the function *csp\_service\_handler*, contained in the file *libgscsp/lib/libcsp/src/csp\_service\_handler.c* 

This function handles an incoming connection and depending on the destination port, handles the packet to the corresponding service handler. The function takes as a parameter a connection structure of type  $csp\_conn\_t$  and a CSP packet of type  $csp\_packet\_t$ .

#### Target data structure:

In this section, we describe the data structures targeted for the data-driven mutation process.

csp\_conn\_t

Member	Туре
type	csp_conn_type_t
state	csp_conn_state_t
idin	csp_id_t (union)
idout	csp_id_t (union)
rx_event	csp_queue_handle_t
rx_queue	csp_queue_handle_t
socket	csp_queue_handle_t
timestamp	uint32_t
opts	uint32_t
rdp	csp_rdp_t

We are interested in mutating *idin* field, which contain the header of the CSP packet on the incoming connection.

csp\_id\_t

The packet header is represented by the data structure *csp\_id\_t* and contains the following fields.

Member	Туре	Description
ext	uint32_t	
pri	unsigned int	Priority

src	unsigned int	Source
dst	unsigned int	Destination
dport	unsigned int	Destination port
sport	unsigned int	Source port
flags	unsigned int	Flags

#### Identifier Fault Model

The probe will be inserted before the switch statement, before the invocation of the service handlers.

Member	Туре	Fault Classes	
ext	uint32_t	None	
pri	unsigned int	INV(Min=0; Max=3; D=0),	
		VAT(Threshold=3; Delta=1),	
		BF(Min=0; Max=0; State=1),	
		BF(Min=1; Max=1; State=1),	
src	unsigned int INV(Min=0; Max=31; D=0),		
		VAT(Threshold=31;D=1)	
dst	unsigned int	INV(Min=0; Max=31; D=0),	
		VAT(Threshold=31;D=1)	
dport	unsigned int	INV(Min=8; Max=30; D=0),	
		VOR(Min=8; Max=30;D=1),	
		SS(Delta=1), SS(Delta=-1)	
sport	unsigned int	INV(Min=8; Max=30; D=0),	
		VOR(Min=8; Max=30;D=1),	
		SS(Delta=1), SS(Delta=-1)	
flags	unsigned int	BF(Min=0; Max=0; State=1),	
		BF(Min=1; Max=1; State=1),	
		BF(Min=2; Max=2; State=1),	
		BF(Min=3; Max=3; State=1)	

One of the objectives of the fault model is to mutate the *dport* field from the identifier; a different value of this field changes the service required. In the following, a table with the full list of services is presented.

Service	Code	Description
GS_CSP_CMP	0	CSP Management Protocol
GS_CSP_PING	1	CSP Ping
GS_CSP_PS	2	Process status
GS_CSP_MEM_FREE	3	Show memory free
GS_CSP_REBOOT	4	Reboot/reset request
GS_CSP_BUF_FREE	5	Number of free CSP buffers
GS_CSP_UPTIME	6	Show uptime
GS_CSP_PORT_RPARAM	7	Parameter service (libparam)
GS_CSP_PORT_FTP	9	File Transfer Service (libftp)

GS_CSP_PORT_RLOG	11	Remote log service (liblog)
GS_CSP_PORT_RGOSH	12	Remote GOSH service (librgosh)
GS_CSP_PORT_AIS	13	AIS command port (libais)
GS_CSP_PORT_ADSB	14	ADS-B command port (libadsb)
GS_CSP_PORT_GSSB	16	GomSpace Sensor Bus (libgssb)
GS_CSP_PORT_FP	18	Flight Planner (libfp)
GS_CSP_PORT_ADCS	20	ADCS (libadcs)
GS_CSP_PORT_HK	21	House Keeping (libhk)
GS_CSP_PORT_GSCRIPT	22	G(omSpace) script service
		(libgosh)
GS_CSP_PORT_MONITOR	26	Gomspace Monitor application
		command port
GS_CSP_PORT_REMOTE_SHELL	27	Remote shell (libgosh)
GS_CSP_PORT_HK_BEACON	30	Housekeeping beacon port (libhk)