Flexible Runtime Security Enforcement with Tagged C

ANONYMOUS AUTHOR(S)

Today's computing infrastructure is built atop layers of legacy C code, often insecure, poorly understood, and/or difficult to maintain. These foundations may be shored up with retroactive security enforcement, but such mechanisms vary widely in their security goals and carry nuanced trade-offs which are often not desirable to legacy code owners. We introduce Tagged C, a C variant with a built-in *tag-based reference monitor* that supports a range of user-defined security policies. Demonstrated in this paper: two varieties of *memory safety* exploring the trade-off between security and support for low-level idioms, *secure information flow* (SIF), and *compartmentalization*.

Adjectives to sell: - flexible - accessible (more than assembly) - comprehensive

1 INTRODUCTION

Many essential technologies of modern life rely on new and old C code. The C language rose to prominence 40 years ago by powering the UNIX, Windows, and OSX operating systems, as well as major applications like the Oracle database [?] . and the Apache web server [Foundation 1997]. Now our cars, smartphones, home appliances (embedded systems like your garage door or tv remote), smart homes and hospitals (Internet of Things, embedded devices), and most of the internet runs the C language family (though it may not be the only language) [?]. [The C language family remains a force in active development, in a 2022 more than 35% of professionals report using it [so dev survey]. Legacy codebases, especially C codebases, pose a security conundrum. They are difficult or impossible to modify, the original programmers are unavailable, and no specification of behavior (however informal), is available.

This means that it may not be feasible to fix the bugs turned up by a conservative static analysis; a more permissive but unsound one, on the other hand, may miss bugs entirely. Worse, most static analyses aim to detect undefined behavior (UB), but UBs may be used intentionally in the form of low-level idioms. Where static analysis is unsatisfactory we turn to dynamic enforcement.

A tag-based reference monitor is a mechanism for dynamic security enforcement. It associates a metadata tag with the data in the underlying system, and throughout execution it updates these tags according to a set a predefined rules. If the program would violate a rule, the system halts instead, replacing a security violation with failstop behavior. By attaching such a monitor to the C language, we enable dynamic enforcement of arbitrary kinds of security, tuned so that non-standard but benign code can still run, while actually dangerous activity is failstopped.

This is the underlying concept of PIPE, an ISA extension that implements a reference monitor in hardware, as well as similar systems such as ARM MTE and [that thing from Binghamton]. Being implemented at the ISA level, these systems currently require their policies to be defined in terms of assembly code, usually with the help of a compiler. Instead, we attach tags to the C language itself, and aim to use PIPE as a compilation target, translating the high-level tags into PIPE's ISA primitives.

We offer the following contributions:

- A full formal semantics for Tagged C, formalized in Coq
- A complete set of control points at which the language interfaces with the policy
- A Tagged C interpreter, implemented in Coq and extracted to Ocaml

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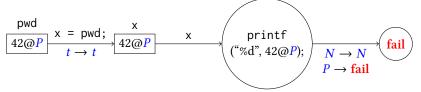
• Policies implementing (1) compartmentalization, (2) realistic, permissive memory models from the literature (PVI and PNVI), and (3) Secure Information Flow (SIF)

In the next section, we give a full account of the formal semantics of Tagged C, including its control points. Then in section 3.1, we describe how we attach a memory safety policy to it, in the process giving some justification of how we chose to attach the control points. In section 3.4, we give a similar description of a secure information flow policy. We round out our policies in section 3.2 with a compartmentalization policy. In ?? we discuss the degree to which the design meets our goals of flexibility and applicability to realistic security concerns.

[TODO: update outdated map]

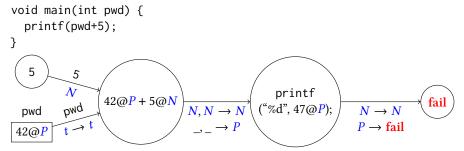
What is Metadata Tagging? Consider a very simple security requirement: "do not printf the password." For simplicity, we will suppose that pwd is an integer in this case. It is not possible to enforce this statically in general, though it may be over-approximated.

We need a way to dynamically track the value of pwd as it moves through the variable x and is then passed to printf. We can do so by associating metadata with the value; namely, that it originates in pwd. We will write this "tagged" value 42@P, with the @ symbol denoting a value tagged with metadata. All other values will be tagged N, for "not pwd." Then when we copy pwd into x, it will bring its tag with it unchanged, as represented by the pattern $t \to t$ under the arrow. When we call printf, we must check that the tag is N, and if it is P, we would like to failstop rather than permit the call.



The points at which the tags are checked and either propagated or updated are termed *control points*, and the particular set of rules that are applied to tags at each control point is a *tag rule*. Collectively, the tag rules form a *policy*.

If our goal is to prevent pwd from being leaked, our policy should also prevent values derived from pwd from leaking. This means that if we add pwd to a constant, we still keep the result tagged *P*—otherwise, someone watching our output could deduce *P* by subtraction.



Function calls aren't the only means of leaking data, however. We might additionally want to prevent pwd from leaking by being written mmapped memory. Supposing the mm is such a location, we would separately tag the location itself (not just the value in the location) to designate it as such. We'll call that tag M. [TODO: the diagrams for this are pretty rough.]

Finally, we may be concerned with less leaks of pwd, such as this one:

```
void main(int pwd) {
  for (int i; i<pwd; i++) {
    printf(i);
  }
}</pre>
```

This will give away the exact value of pwd! In order to prevent this, we must keep track of when we are inside of a loop or conditional that depends on pwd. To this end, we carry an additional tag associated with the global state. [TODO: diagram here, too, except I'm not sure how to effectively represent the added complexity.]

General Purpose Security Enforcement. [TODO: Emphasize breadth]

CompCert C. Tagged C is built on top of CompCert C, the C semantics formalized along with the CompCert verified compiler. Our interpeter is likewise built on top of the CompCert C reference interpreter [Leroy 2009]. We chose CompCert C as a base because it is a widely used and well-supported C semantics, with a working interpreter and a full formalization. Being written in Coq, it is ideal for future proof work.

PIPE Backend Implementation. In ??, Chhak et al. introduce a verified compiler from a toy high-level language with tags to a control-flow-graph-based intermediate representation with a PIPE-based ISA. This establishes a proof-of-concept for compiling a source language's tag policy to realistic hardware. They take advantage of the fact that, like everything else in a PIPE system, instructions in memory carry tags. Instruction tags are statically determined at compile-time. They "piggyback" information about source-level control points onto the tags of the instructions that implement those source constructs.

Tagged C is designed to be implemented in the same way. But, before we can soundly transmit tag rules from the source language to the assembly level, we also need to protect the basic control-flow properties of the source language. So, a compiled Tagged C requires a backend that can at the very least protect its control flow. In the case of a PIPE-based backend, we would run a basic stack-and-function-pointer-safety policy in parallel with whatever Tagged C policy the user has provided.

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⊙ ::= !	⊕ ::= +	«	$e := Eval \ v @ vt$	Value
~	-	>>	Evar x	Variable
-	×	&	Efield e id	Field
abs	÷		EvalOf e	Load from Object
	%	^	Ederef e	Dereference Pointer
s::=Sskip			EaddrOf e	Address of Object
Sdo e			Eunop ⊙ e	Unary Operator
$ Sseq\ s_1 $	s_2		$ Ebinop \oplus e_1 e_2 $	Binary Operator
Sif(e)	then s_1 el	se s_2 j	oin L Ecast e ty	Cast
Swhile	(e) do s jo	oin L	$ Econd e_1 e_2 e_3 $	Conditional
$ Sdo\; s\; w $	hile (e) j	oin L	Esize ty	Size of Type
$ Sfor(s_1) $	$;e;s_2)$ do	s_3 join	Ealign ty	Alignment of Type
Sbreak			$ Eassign e_1 e_2 $	Assignment
Sconti	nue		$ EassignOp \oplus e_1 e_2 $	Operator Assignment
Sretur	n		$ EpostInc \oplus e $	Post-Increment/Decrement
Sswitc	$h e \{ \overline{(L,s)} $	· } joi:	$ Ecomma e_1 e_2 $	Expression Sequence
Slabel		, 3	$ Ecall\ e_f(\overline{e}_{args}) $	Function Call
Sgoto I			$ Eloc\ l@lt$	Memory Location
, 0			Eparen e ty t	Parenthetical with Optional Cast

Fig. 1. Tagged C Abstract Syntax

2 THE LANGUAGE

 Tagged C uses the full syntax of CompCert C [Leroy 2009] with minimal modification (fig. 1). There are two notable syntactical differences in the language, relative to CompCert C: conditionals and loops take an optional *join point* label, and parenthetical expressions an optional "context tag."

Our semantics are a small-step reduction semantics which differ from CompCert C's in two key respects. These are given in full in the appendix. First, Tagged C's semantics contain *control points*: hooks within the operational semantics at which the tag policy is consulted and either tags are updated, or the system failstops. (Control points resemble "advice points" in aspect-oriented programming, but narrowly focused on the manipulation of tags.) A control point consists of the name of a *tag rule* and the bindings of its inputs and outputs; a tag rule is a partial function. The names and signatures of the tag rules, and their corresponding control points, are listed in Section 3.

Second, there is no memory-undefined behavior: the source semantics reflect a concrete target-level view of memory as a flat address space. Without memory safety, programs that exhibit memory-undefined behavior will act as their compiled equivalents would, potentially corrupting memory; we expect that a memory safety policy will be a standard default, but that the strictness of the policy may need to be tuned for programs that use low-level idioms.

The choice of control points and their associations with tag rules, as well as the tag rules' signatures, are a crucial design element. Our proposed design is sufficient for the three classes of policy that we explore in this paper, but it may not be complete.

 Notations. Values are ranged over by v, variable identifiers by x, and function identifiers by f. Tags use a number of metavariables: t ranges over all tags, while we will use vt to refer to the tags associated with values, pt for tags on pointer values and memory-location expressions, lt for tags associated with memory locations themselves, nt for "name tags" automatically derived from identifiers, \mathcal{P} for the global "program counter tag" or PC Tag. An atom is a pair of a value and a tag, $Eval\ v@vt$; the @ symbol should be read as a pair in general, and is used when the second object in the pair is a tag. Expressions are ranged over by e (Figure 1), statements by e, and continuations by e. The continuations are defined in appendix e, and step rules in appendix e.

Global environments, ranged over by ge, map identifiers to either function or global variable definitions, including the variable's location in memory. Local environments, ranged over by le, map identifiers to atoms. Memories m map integers to triples: a value, a "value tag" vt, and a list of "location tags" \overline{lt} .

A memory is an array of bytes, where each byte is part of an atom. Each byte is also associated with a "location tag" lt. When a contiguous region of s bytes starting at location l comprise an atom v@vt, and their locations tags comprise the list \overline{lt} , we write $m[l]_s = v@vt@\overline{lt}$. Likewise, $m[l\dots l+s\mapsto v@vt@\overline{lt}]_s$ denotes storing that many bytes. Visually, we will represent whole atoms in memory as condensed boxes, with their location tags separate. For example, a four-byte aligned address:

States can be of several kinds, denoted by their script prefix: a general state S(...), an expression state S(...), a call state S(...), or a return state S(...). Finally, the special state failstop S(...) represents a tag failure, and carries the state that produced the failure. [Allison: to whatever degree you've figured out what is useful here by publication-time, we can tune this to be more specific.]

```
S ::= S (m \mid s \gg k@\mathcal{P})
|\mathcal{E} (m \mid e \gg k@\mathcal{P})
|C (\mathcal{P} \mid m(le) \gg f'@f) \overline{Eval v@vtk}
|\mathcal{R} (m \mid ge \gg le@\mathcal{P}) Eval v@vtk
|\mathcal{F} (S)
```

3 TAGS AND POLICIES

Tagged C can enforce a wide range of policies, as follows. A policy consists of a tag type τ , a default tag inhabiting that type, and an instantiation of each tag rule identified in section 3.

For each policy under discussion, we will give a code example of the sort of security situation in which it might be useful. We will introduce a formal characterization drawn from the literature of a security property that a correct policy should satisfy. [TODO: talk about properties somewhere before this?] Then we will walk through the important tag rules, and the control points that call them, introducing step rules as needed. Finally, if there are any implementation details that are necessary to realize a policy, we discuss those.

Control Points with Side-effects and Optional Arguments. Chhak et al. [Chhak et al. 2021] give a general strategy for mapping Tagged C's tag rules onto instructions in a PIPE target. But as they note, translating tag rules in full generality requires adding extra instructions that may be unnecessary for some policies. The most problematic situation is when a Tagged-C control point

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246	Name	Inputs	Outputs	Control Points
247	GlobalT	$id \in ident, s \in \mathbb{N}$	pt , vt , \overline{lt}	Program initialization
248	FieldT	pt, id	pt'	Field Access
249	LoadT	\mathcal{P} , pt , vt , \overline{lt}	vt'	ValOf, AssignOp, PostIncr
250	StoreT	\mathcal{P} , pt , vt_1 , vt_2 , \overline{lt}	\mathcal{P}' , vt' , \overline{lt}'	Assign
251	ConstT	_	vt	Const, PostIncr
252	UnopT	\odot , \mathcal{P} , vt	vt	Unary Operation
253	BinopT	\oplus , \mathcal{P} , vt_1 , vt_2	vt'	Binary Operation
254 255	MallocT	\mathcal{P} , vt	$\mathcal{P}', pt, vt, \overline{lt}$	Call to malloc
256	FreeT	P, vt	$\mathcal{P}', pt, vt, \overline{lt}$	Call to free
257 258	PICastT	\mathcal{P} , pt , vt , \overline{lt}	vt	Cast from pointer to scalar
259	IPCastT	\mathcal{P} , vt_1 , vt_2 , \overline{lt}	pt	Cast from scalar to pointer
260 261	PPCastT	$ \mathcal{P}, pt, vt, \overline{lt} $	pt'	Cast between pointers
262	IICastT	\mathcal{P} , vt_1	pt	Cast between scalars
263	ExprSplitT	\mathcal{P} , vt	\mathcal{P}'	Control-flow split points in expressions
264	ExprJoinT	$\mathcal{P}, \mathcal{P}', vt$	$\mathcal{P}^{\prime\prime}$, vt^{\prime}	Parenthetical expressions
265	SplitT	\mathcal{P} , vt , L	\mathcal{P}'	Split points (??)
266	LabelT	\mathcal{P}, L	\mathcal{P}'	Label
267	CallT	\mathcal{P}, f, f'	<i>P'</i>	Call
268	ExtCallT	$\mathcal{P}, f, f', \overline{vt}$	\mathcal{P}'	External Call
269	LocalT	$\mathcal{P}, x \in ident, s \in \mathbb{N}$	pt , vt , \overline{lt}	Call
270	ArgT	\mathcal{P} , vt , f , x , s	\mathcal{P}' , pt , vt' , \overline{lt}	Call
271	RetT	$\mathcal{P}_{CLE}, \mathcal{P}_{CLR}, vt, f$	\mathcal{P}' , vt'	Return
272	DeallocT	\mathcal{P} , $id \in ident$, $s \in \mathbb{N}$	vt, \overline{lt}	Return
273		I		1
274				

requires a tag from a location that is not read under a normal compilation scheme or must update tags in locations that would otherwise not be written.

To mitigate this, control points whose compilation would add potentially extraneous instructions take optional parameters or return optional results. We will explain how the rule should be implemented in the target if the options are used. If a policy does not make use of the options, it will be sound to compile without the extra instructions. Optional inputs and outputs are marked with boxes

Name Tags. When we want to define a per-program policy, we need to be able to attach tags to the program's functions, globals, and so on. We do this by automatically embedding their identifiers in tags, which are available to all policies. These are called name tags and are ranged over by nt. We give name tags to:

- Function identifiers
- Function arguments, written f.x
- Local and global variables
- Labels

3.1 Basic Memory Safety

 Let's begin by walking through a common type of policy: memory safety. Variations of memory safety have been enforced in PIPE at the assembly level already, but what does it look like to enforce it at the source level? Consider some example code:

```
void main() {
   int* x = malloc(1);
   int* y = malloc(1);
   *x = 0;
   *(x+1) = 0;
}
```

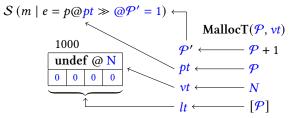
The above code is undefined behavior in C, because it writes to the address one past the end of the array pointed to by x. In Tagged C, it is defined in correspondence to the allocation strategy. x and y are given concrete addresses, and the program writes to the address of x+1. It's possible that this address is free, in which case there is no harm; but if y is allocated there, then it will write to the first address of y.

For our example, we'll assume a straightforward first-fit allocator, with the heap growing upward from address 1000, and the stack growing downward from address 2000. Our set of tags consists of N, for non-pointers, and pointer "colors" $c \in \mathbb{N}$. The PC Tag (\mathcal{P}) tracks the next color to allocate, so it's initialized to 0, and everything else is N. N is the default for constants.

$$S(m \mid e = malloc(1@t) \gg @\mathcal{P} = 0)$$

100	1000 1004 1008							109	92			109	96							
u	undef @ N			u	ndei	f @	N	undef @ N]	u	ndei	f @	N	u	ndef	f @	N
N	N	N	N	N	N	N	N	N	N	N	N		N	N	N	N	N	N	N	N

The call to malloc allocates the region from 1000 to 1039, and returns a pointer to the base address, 1000. We consult the policy to determine (1) the tag on the resulting value, (2) the updated tags on the allocated memory region, and (3) the updated PC Tag. Specifically, we invoke the MallocT tag rule, which takes the PC Tag and the tag on the size argument and returns these three updated tags.



In this case, we tag the pointer and the memory region with the current count, and then increment the count. Once the pointer is stored in x, our memory is:

We do the same for allocating y, to get the memory:

10	1000 1004					100	8(1092				1096					
uı	nde	f @	N	ur	ıde	f @	N	u	ndef	@.	N]	1004 @ 1				1000 @ <mark>0</mark>			
0	0	0	0	1	1	1	1	N	N	N	N]	N	N	N	N	N	N	N	N

Next, the program stores a 0 to address 1000. The constant 0 takes on the default tag, *I*. The policy needs to check that this store is valid, in addition to determining the tags on the value that is stored. This check is performed by comparing the tag on the pointer to the tags on memory—each

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byte being written, in case the pointer is misaligned. Then the tag on the value being stored is propagated with it into memory, unchanged.

StoreT(
$$\mathcal{P}$$
, pt , vt_1 , vt_2 , \overline{lt})

assert $\forall lt \in \overline{lt}$. $pt = lt$
 $\mathcal{P}' \longleftarrow \mathcal{P}$
 $vt' \longleftarrow vt_2$
 $\overline{lt'} \longleftarrow \overline{lt}$

P :	2																			
10	00			10	04			100	8(109	92 (y)		109	96 (x)	
undef@N undef@N			undef@N]		1004	4@1			1000	0@0						
0	0	0	0	1	1	1	1	N	N	N	N]	N	N	N	N	N	N	N	N

Finally, on the last line, we add 2 to x, which invokes the BinopT tag rule to combine the tags on the arguments. BinopT takes as argument the operation \oplus . In memory safety terms, we can add a pointer to a non-pointer in either order, and we can subtract a non-pointer from a pointer (but not the reverse), to yield a pointer to the same object. We can subtract two pointers to the same object from one another to yield a non-pointer, the offset between them. All other binary operations are only permitted between non-pointers.

$$\mathbf{BinopT}(\oplus, \mathcal{P}, vt_1, vt_2)$$

$$\mathcal{P'} \longleftarrow \mathcal{P}$$

$$\mathbf{vt'} \longleftarrow \operatorname{case}(\oplus, vt_1, vt_2) \text{ of}$$

$$+, c, N \mid +, N, c \mid -, c, N \Rightarrow c$$

$$-, c, c \mid _, N, N \Rightarrow N$$

$$, c_1, c_2 \Rightarrow \operatorname{fail}$$

So, when we try to write through the pointer 1004@0, the bytes at addresses 1004-1007 are tagged 1, and the policy issues a failstop.

Realizing Memory Safety. A brief description is in order of how this policy would be implemented by a compiler to a PIPE target. This will serve to outline the basic structure of the compilation scheme described in [Chhak et al. 2021].

3.2 Compartmentalization

 In a perfect world, all C programs would be memory safe. But it is unfortunately common for a codebase to contain undefined behavior that will not be fixed, including memory undefined behavior. This may occur because developers intentionally use low-level idioms that are UB [?]. Or the cost and potential risk of regressions may make it undesirable to fix bugs in older code, as opposed to code under active development that is held to a higher standard [Bessey et al. 2010].

A compartmentalization policy isolates potentially risky code, such as code with known UB, from safety-critical code, minimizing the damage that can be done if a vulnerability is exploited. This is a very common form of protection that can be implemented at many levels. It is often built into a system's fundamental design, like a web browser sandbox untrusted javascript. But for our use-case, we consider a compartmentalization scheme being added to the system after the fact.

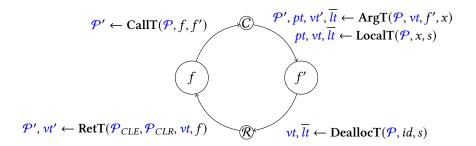


Fig. 2. Structure of a function call

Let's assume that we have a set of compartment identifiers, ranged over by C, and a mapping from function identifiers to compartments, comp(f). This mapping must be provided by a security engineer.

Coarse-grained Protection. The core of a compartmentalization scheme is once again memory protection. For the simplest version, we will enforce that memory allocated by a function is only accessible by functions that share its compartment. To do that, we need to keep track of which compartment we're in, using the PC Tag.

Calls and returns each take two steps: first to an intermediate call or return state, and then to the normal execution state, as shown in fig. 2 with some function f calling f'. Three of these steps feature control points. In the initial call step, CallT uses the name-tags of the caller and callee to update the PC Tag. Then, in the step from the call state, we place the function arguments in memory, tagging their values and locations with the results of ArgT. And on return, RetT updates both the PC Tag and the tag on the returned value.

In our compartmentalization policy, we define a tag to be a compartment identifier or the default N tag.

$$\tau ::= C|N$$

At any given time, the PC Tag carries the compartment of the active function. This is kept up to date by the CallT and RetT rules. Note that Tagged C automatically keeps track of the PC Tag at the time of a call, so that it can be used as a parameter in the return.

Now that we know which compartment we're in, we can make sure that its memory is protected. This will essentially work just like the basic memory safety policy, except that coarse-grained protection means that the "color" we assign to an allocation is the active compartment. And during a load or store, we compare the memory tags to the PC Tag, not the pointer.

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Sharing Memory. The above policy works if our compartments only ever communicate by passing non-pointer values. In practice, this is far too restrictive! Many libraries take pointers and operate on the associated memory, starting with the most basic ones, like the standard library's string functions. And yet, if we are forced to include large external libraries in the same compartment as critical code, we have lost much of the value of compartmentalization.

So, we need to modify our policy to account for intentional sharing of memory. In our example, the function setup in compartment A will allocate several buffers, call a function that fills the buffer msg, and then pass msg to the strlen function in compartment B.

```
// In compartment A
void setup() {
   int* key = malloc(100);
   char* msg = malloc(100);
   char* log = malloc(100);

  fetch_msg(&msg); // Function also in A
   ...
   int msg_size = strlen(msg); // StdLib function in B
   ...
}
```

 Naturally, we want strlen to be able to read msg, but we would rather that it not read key, if it should happen to be malicious. Even if log isn't as sensitive, we have no reason to share it, so it should be protected.

The literature contains two main approaches to this problem: *mandatory access control* and *capabilities*. The former explicitly enumerates the access rights of each compartment, while the latter turns passed pointers into unforgeable tokens of privilege, so that the act of passing one implicitly grants the recipient access.

In either case, our first step is to distinguish which allocation we want to pass. We do this by labeling the statement that contains the relevant call to malloc The annotation could be performed manually, or perhaps automatically using some form of escape analysis. The name of the label doesn't matter, it will just be referenced via its name tag in the policies.

```
// In compartment A
void setup() {
   int* key = malloc(100);
   SHARE: char* msg = malloc(100);
   NOSHARE: char* log = malloc(100);
   fetch_msg(&msg); // Function also in A
   ...
   int msg_size = strlen(msg); // StdLib function in B
   ...
}
```

Executing a labeled statement invokes the **LabelT**(\mathcal{P} , L) tag rule to update the PC Tag. Since we don't want to share log, we will need to label it as well.

Mandatory Access Control. Mandatory access control works by associating objects in memory with the compartments that are allowed to access them.

Memory Shared by Capability. Mandatory access control requires the policy designer to identity every pair of object and compartment that it will be shared with. This may require too much analysis if objects are shared widely throughout the system. Conversely, it does not distinguish between accesses via a valid pointer and those that are the result of UB. [TODO: example]

3.3 PVI Memory Safety

The simple memory safety policy described above is too restrictive to run many real-world C programs, because they contain undefined behavior that is nevertheless part of the "de facto standard" [?]. These low-level idioms are one reason that we might settle for isolating risky code in a compartment instead of enforcing full memory safety.

Memarian et al. [?] propose two memory models that aim to capture this de facto standard, support the common low-level idioms, yet still place sufficient restrictions on programs that it remains sound to use alias analysis in optimizations. The first of these is *PVI* (provenanace via integer), in which pointers remain valid when they are cast to integers, subjected to the full range of arithmetic operations, and cast back.

Memarian et al. do not propose to enforce PVI, merely to use it as an alternative to the C standard. But its relative permissiveness makes it a great target for enforcement in Tagged C!

[TODO: example of what we do want (I-P cast, maybe using low bits as flags?), and what we don't (memory violations that use similar idioms)]

PVI Definitions. Since PVI is a more realistic policy than the basic memory safety described above, we will go into some details elided there. First of all, the distinction between heap-allocated memory, stack objects, and global variables. The latter are tagged based on their identifiers, while heap- and stack-objects are tagged dynamically using unique colors.

$$au ::= \operatorname{glob} \operatorname{id} \qquad \qquad \operatorname{id} \in \operatorname{ident}$$

$$\operatorname{dyn} C \qquad \qquad C \in \mathbb{N}$$

When initializing program memory, before any execution, each global *id* has its memory locations and its pointer in the global environment tagged with *glob id*, using the **GlobalT** tag rule.

[TODO: diagram]

```
\begin{array}{ccc} & \textbf{GlobalT}(id, s) \\ \textbf{\textit{pt}} \longleftarrow & glob \ id \\ \textbf{\textit{vt}} \longleftarrow & N \\ & \overline{\textbf{\textit{lt}}} \longleftarrow & [glob \ id \mid 0 \le i < s] \end{array}
```

Stack-allocated locals are allocated at the start of a function call. Like a global environment, a local environment maps indentifiers to base, bound, type, and tag. The rule is almost identical to allocation of globals, except that the stack allocator, $stack_alloc$ will be more complex in order to support deallocation (in practice, it uses a normal stack structure and allocates and deallocates by increasing and decreasing a "stack pointer".)

The tag rules for allocating memory in the heap and in the stack should look familiar.

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Color Checking. As in the basic policy, when we perform a memory load or store, we check that the pointer tag on the left hand of the assignment matches the location tag on all of the bytes being loaded or stored.

```
\mathbf{StoreT}(\mathcal{P}, pt, vt_1, vt_2, lt)
\mathbf{LoadT}(\mathcal{P}, pt, vt, \overline{lt})
\mathbf{assert} \ \forall lt \in \overline{lt}.pt = lt
\mathbf{t'} \longleftarrow vt
\mathbf{t'} \longleftarrow vt_2
\overline{lt'} \longleftarrow \overline{lt}
```

Color Propagation. In our example memory safety policy, we placed significant restrictions on the ways that pointer-tagged values could be subject to integer operations. In PVI, this is not the case: all unary operations maintain the tag on their input, and all binary operations where exactly one argument is tagged as a pointer propagate that tag to their result. Performing an operation with two pointer-tagged values sets the tag on the result to N. It can still be used as an integer, but if cast back to a pointer it will be invalid.

```
\begin{array}{cccc}
\mathbf{UnopT}(\odot, \mathcal{P}, vt) & \mathbf{BinopT}(\oplus, \mathcal{P}, vt_1, vt_2) \\
\mathcal{P}' \longleftarrow & \mathcal{P} & \mathcal{P}' \longleftarrow & \mathcal{P} \\
\mathbf{vt}' \longleftarrow & vt & \mathbf{vt}' \longleftarrow & \mathrm{case} \ (vt_1, \ vt_2) \ \mathrm{of} \\
& dyn \ n, N \Rightarrow dyn \ n \\
& glob \ id, N \Rightarrow glob \ id \\
& N. \ t \Rightarrow t
\end{array}
```

3.4 Secure Information Flow

Memory safety and compartmentalization are both aimed at preventing or mitigating memory errors. But programs can be memory safe and still do insecure things! Consider the following code, in which we have some error-handling code that writes to a log.

```
int checked_div(int a, int b) {
  if (a % b == 0) {
    return a / b;
  } else {
    fprintf(log, "%d should divide %d but doesn't\n", b, a);
    return 0;
  }
}

void main(int factor) {
    ...
```

```
int key = read_and_parse(keyfile);
int dividend = checked_div(key, factor);
if (!dividend) {
    ...
} else {
    ...
}
```

 The checked_div function sometimes writes its arguments to a log, which is reasonable enough, except when it's called with a key as an argument! Suddenly we have keys being written to an unexpected and probably unprotected file.

This is an instance of problematic information-flow. The solution is to implement a *secure information flow* (SIF) policy in Tagged C. SIF is a variant of *information flow control* (IFC) described in the venerable Denning and Denning [Denning and Denning 1977]. At its simplest, if we classify inputs and outputs to the program into secure ("high") and public ("low") classifications, then the high inputs do not influence the low outputs. This generalizes to an arbitrary set of security classes, but out first example is concerned with just two: the value returned from read_and_parse and the output to the log. In our treatment of this example, we will describe a policy tailored to this particular set of security classes.

SIF Example Policy 1. Let's assume that read_and_parse is an external function—that is, we will not model its internal behavior, so we know nothing about the value it returns. We can therefore treat that value as an input, and track its influence through the system.

For this initial, simplified policy, we will assume that it is the only input that we care about, so we have four classes of tags. The default tag N represents values that are not tainted by the sensitive input, the tag vaint represents values that have been influenced by read_and_parse, and the tag vaint represents values that the current control-flow of the program is tainted (we will discuss this in detail below.) Lastly, the tag vaint marks the memory locations of vaint global variables. Volatile variables represent mmapped regions or memory that for other reasons is accessible outside the process.

Initially, the PC Tag is $pc f \emptyset$, and all values and memory locations are tagged N. The taint tags are introduced at the external call to read_and_parse. At the same time, all external calls must check that they aren't leaking a tainted value!

```
\tau ::= N
vtaint
pc f \overline{L}
vol
vtaint
pc f \overline{L}
vol
vt' \leftarrow case f of
read_and_parse \Rightarrow vtaint
\Rightarrow vt
```

When two values are combined with a binary operation, the resulting value is tainted if either of them was. We define this as the *join* or *least-upper-bound* operator, \Box . We will then compare tags according to a partial order, the *no-higher-than* operator, \Box . In this case, $a \Box b$ means that a does not have higher privilege than b, and so information is allowed to flow from a to b.

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 $t_1 \sqcup t_2 \triangleq \begin{cases} \textit{vtaint} & \text{if } t_1 = \textit{vtaint} \\ \textit{vtaint} & \text{if } t_2 = \textit{vtaint} \\ \textit{N} & \text{otherwise} \end{cases} \qquad t_1 \sqsubseteq t_2 \triangleq \begin{cases} \textit{false} & \text{if } t_1 = \textit{vtaint} \text{ and } t_2 = \textit{vol} \\ \textit{true} & \text{otherwise} \end{cases}$

The policy needs to failstop if a tainted value becomes visible to the outside world. That can happen when the value is passed as an argument to an external function, as we saw above, or when it is stored to volatile memory (typically representing a file or external device that might be read or might transfer.

$$\begin{array}{ccc} \mathbf{StoreT}(\mathcal{P},\mathit{pt},\mathit{vt}_1,\mathit{vt}_2,\overline{lt}) \\ & \mathbf{assert}\,\mathcal{P}\sqcup\mathit{pt}\sqcup\mathit{vt}_2\sqsubseteq\\ \mathbf{t'}\longleftarrow&\mathit{vt}_1\sqcup\mathit{vt}_2 \\ & \mathbf{t'}\longleftarrow&\mathcal{P}\sqcup\mathit{pt}\sqcup\mathit{vt}_2\\ & \overline{\mathit{lt'}}\longleftarrow&\overline{lt} \end{array}$$

Now things become trickier, because the program's control-flow itself can be tainted. This can occur in any of our semantics' steps that can produce different statements and continuations depending on the tained value. At that point, any change to the machine state constitutes an information flow. This is termed an *implicit flow*.

Take, for example, the expression x = y? (z=0): (z=1); where y is tainted and z is volatile. If y is non-zero, then z will be assigned 0, thus leaking one bit of information about the contents of y. So, we need to remember while inside of whichever branch we take that the state depends on y and restrict external writes accordingly.

?? discusses the building of expression contexts. For our purposes here, it is crucial to understand that when we construct a parenthetical expression, we can set the PC Tag locally within that context, so that our rules have different behavior. In this case, when we step from the condition expression to a parenthetical, we will mark it with a PC Tag that reflects the heightened security of its contents.

```
Econd (Eval 1@vtaint ) (Eassign (Evar x) (Eval 0@N)) (s<sub>2</sub>)
\longrightarrow Eparen (Eassign (Evar x) Eval 0@N) ty t
\longrightarrow Eparen (Eassign (Eloc 4000@N) (Eval 0@N)) ty t
\longrightarrow Eparen (Eval 0@N) ty t
\longrightarrow Eparen (Eval 0@N) ty t
Eparen (Eval 0@N) ty t
0 @ fail \leftarrow StoreT(t, N, N, [vol])
vol vol vol vol vol vol
```

On the other hand, if z is not volatile, then we end up with a value in our parentheses, and we will remove the parentheses and carry on with execution. We need to transfer the taint information from the context onto the value, and in some cases we might want to merge it with the global PC Tag. We do this with the ExprJoinT tag rule.

ExprJoinT(
$$\mathcal{P}, \mathcal{P}', vt$$
)
$$\mathcal{P}' \longleftarrow \mathcal{P}$$

$$vt' \longleftarrow t$$

This principle applies to other expressions with control flow, namely *and* and *or* expressions that shortcut.

Implicit flows become much more complex outside of expressions, when we have more complex control flow. This time the taint is carried on the PC Tag itself. When the PC Tag is tainted, all stores to memory and all updates to environments must also be tainted until all branches eventually

```
687
688
689
690
692
694
696
700
701
702
706
707
708
710
711
712
713
714
715
716
717
718
719
720
721
722
723
724
725
726
727
728
729
730
731
732
733
```

```
int f(bool secret) {
    int public1, public2;

S: if (secret) {
    b1:    public1 = 1;
    } else {
    b2:    public1 = 0;
    }

J: public2 = 42;
    return public2;
}
```

Fig. 3. Leaking via if statements

rejoin, which might be at any point. We term the point at which it is safe to remove taint a *join point*. In terms of the program's control-flow graph, the join point of a branch is its immediate post-dominator []. [TODO: this is the Denning cited in Bay and Askarov]

In many simple programs, the join point of a conditional or loop is obvious: the point at which the chosen branch is complete, or the loop has ended. Such a simple example can be seen in fig. 3; public1 must be tagged with the taint tag of secret, while it is safe to tag public2 N, because that is after the join point, J. The same goes for fig. 4, if we are in a *termination-insensitive* setting [Askarov et al. 2008]. In termination-insensitive noninterference, we allow for the possibility that an observer could glean information by the termination or non-termination of the program. So, it is safe to assume that the post-dominator J of the while loop is reached.

But in the presence of unrestricted go-to statements, a join point may not be local (and sometimes may not exist within the function, assuming that we have not consolidated return points.) Consider fig. 5, which uses go-to statements to create an approximation of an if-statement whose join-point is far removed from the for-loop. The label J now has nothing to do with the semantics of any particular statement.

Luckily this can still be determined statically from a function's full control-flow graph. So, to implement the policy, we must first transform our program by adding labels at the join point of each conditional. Every statement that branches carries an optional label indicating its corresponding join point, if it has one—a function with multiple returns might not, in which case once the PC Tag is tainted, it must remain so until a return.

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```
int f(bool secret) {
736
                                   int public1=1;
737
                                   int public2;
738
739
                              S:
                                  while (secret) {
740
                              b1:
                                        public1 = 1;
741
                                        secret = false;
                                   }
743
                                   public2 = 42;
745
746
                                   return public2;
747
                              }
749
                                                      b_1
751
753
755
```

Fig. 4. Leaking via while statements

```
int f(bool secret) {
   int public1, public2;

while (secret) {
     goto b1;
   }

b2: public1 = 1;
   goto J;

b1: public1 = 1;

J: public2 = 42;
   return public2;
}
```

Fig. 5. Cheating with go-tos

Intransitive SIF. Our second example involves information from outside of the system ending up somewhere it isn't supposed to.

```
void sanitize(src, dst);
char* sql_query(char* query);

void get_data(char* name, char* buf, int field) {
   // field: 1=address, 2=phone, 3(default)=astrological sign char[10] name_san;
```

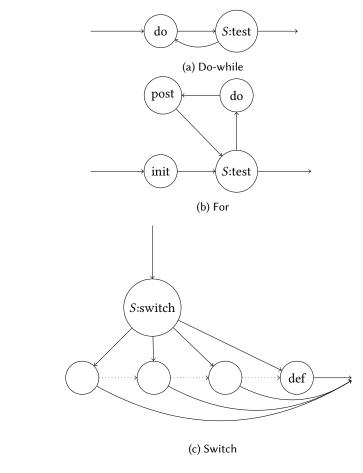


Fig. 6. Remaining Branch Statements

```
char[100] query;
sanitize(name, name_san);

switch(field) {
  case 1:
    sprintf(query, "select address where name =");
    strncat(query, name_san, strlen(name_san));
    break;
  case 2:
    sprintf(query, "select phone where name =");
    strncat(query, name_san, strlen(name_san));
    break;
  default:
    sprintf(query, "select sign where name =");
    strncat(query, name, strlen(name)); // Oops!
    break;
```

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```
834  }
835
836    sprintf(buf, sql_query(query);
837    return;
838  }
```

 This function sanitizes its input name, then appends the result to an appropriate SQL query, storing the result in buf. But, in the default case, the programmer has accidentally used the unsanitized string! This creates the opportunity for an SQL injection attack: a caller to this function could (presumably at the behest of an outside user) call it with field of 3 and name of "Bobby; drop table;".

In this example, we want to implement an *intransitive integrity* SIF policy: we wish to allow name to influence the result of sanitize, naturally, and the result of sanitize to influence the value passed to sql_query, but we do not wish for name to influence sql_query directly.

We are now forced to consider multiple sources of information, name and the output of sanitize, as well as multiple information "sinks," the input to sanitize and sql_query. Let Σ be the set of these three identifiers, ranged over by σ . A value may be tainted any subset of Σ , written *vtaint* $\overline{\sigma}$. The PC Tag tracks the current function identifier and an association list of labels and sources. Each pair (L, σ) in the association list indicates that until reaching label L, the state itself has been influenced by σ .

$$\tau ::= vtaint \overline{id}$$

$$pc f \overline{(L, id)}$$

$$N$$

We define the join operation in this new setting, as well as the *minus* operation $(t_1 - t_2)$.

$$t_1 \sqcup t_2 \triangleq \begin{cases} vtaint \ (\overline{\sigma}_1 \cup \overline{\sigma}_2) & \text{if } t_1 = vtaint \ \overline{\sigma}_1 \text{ and } t_2 = vtaint \ \overline{\sigma}_2 \\ vtaint \ (\overline{\sigma}_2 \cup \{\sigma \mid (L,\sigma) \in \overline{(L,\sigma)}_1\}) & \text{if } t_1 = pc \ f \ \overline{(L,\sigma)}_1 \text{ and } t_2 = vtaint \ \overline{\sigma}_2 \\ vtaint \ (\overline{\sigma}_1 \cup \{\sigma \mid (L,\sigma) \in \overline{(L,\sigma)}_2\}) & \text{if } t_2 = pc \ f \ \overline{(L,\sigma)}_2 \text{ and } t_1 = vtaint \ \overline{\sigma}_1 \\ \bot & \text{otherwise} \end{cases}$$

$$t - \sigma \triangleq \begin{cases} vtaint \ \overline{\sigma} - \sigma & \text{if } t = vtaint \ \overline{\sigma} \\ \bot & \text{otherwise} \end{cases}$$

And once again we wish to define the "no-higher-than" relation. In this case, recall that we want to avoid the name argument flowing to sql_query. So we will define that sql_query(query), as a sink, is strictly higher security than sql_query(name), and every other combination is fine.

$$t_1 \sqsubseteq (t_2, t_3) \triangleq \begin{cases} \mathbf{f} & \text{if } t_1 = vtaint \ \overline{\sigma}, t_2 = \text{sql_query}, t_3 = \text{query}, \text{ and name} \in \overline{\sigma} \\ \mathbf{t} & \text{otherwise} \end{cases}$$

Tainting and Checking Arguments and Returns. A function argument or return value can be either a source or a sink. So, when they are processed by the argument and return rules, we must both check that the value being passed or returned is not tainted by a forbidden source, and then add the new source to its taint. Recall that we want the first argument to the sanitize function to "forget" the influence of name.

Dynamic Sinks and Globals. One scenario that does not really match the others is when the sink is dynamically allocated memory. In this case, we need to tag the memory at allocation-time with the forbidden sources. Global variables are also possible sources or sinks, so we initialize their tags to carry this information.

Ma	$\mathbf{llocT}(\mathcal{P}, vt)$	GlobalT(id, s)						
$pt \leftarrow$	$\mathcal{P} \sqcup vtaint \emptyset$	$pt \leftarrow$	vtaint Ø					
<i>vt</i> ←	vtaint Ø	<i>vt</i> ←	vtaint {id}					
\overline{lt} \leftarrow	[sink f.m]	$\overline{lt} \leftarrow$	[sink id]					
$P' \leftarrow$	\boldsymbol{arphi}							

PC Tag Taint. It now becomes slightly more complicated to keep track of the join-point labels associated with various sources. [TODO: fix the alignment here.]

```
SplitT(\mathcal{P}, vt, \boxed{L})
let \ pc \ f \ \overline{(L, \sigma)} := \mathcal{P} \ in
let \ vtaint \ \sigma := vt \ in
\mathcal{P'} \longleftarrow pc \ f \ \overline{(L, \sigma)} \cup (L, \sigma)
LabelT(\mathcal{P}, L)
let \ pc \ f \ \overline{(L, \sigma)} := \mathcal{P} \ in
\mathcal{P'} \longleftarrow pc \ f \ \{(L', \sigma) \mid (L', \sigma) \in \overline{(L, \sigma)} \land L \neq L'\}
```

The branching constructs are rather complicated, involving multiple steps and manipulations of the continuation that are not that relevant to their control points. Rather than give their semantics in full, it suffices to identify which transitions contain **SplitT** control points. In fig. 6, these are the transitions from the state marked *S*. Their semantics are given in full in the appendix.

Realizing IFC. In order to implement an IFC policy, we need to specify the rules that it needs to enforce. The positive here is that the rules are not dependent on one another (with the exception of declassification rules), and default to permissiveness when no rule is given. We assume that the user would supply a separate file consisting of a list of triples: the source, the sink, and the type of rule. This is then translated into the policy.

The other implementation detail to consider are the label tags. These resemble instruction tags, and that is exactly how they would be implemented: as a special instruction tag on the appropriate instruction, which might be an existing instruction or a specially added no-op, that the processor handles by introducing a tag corresponding to that label.

It remains to generate those labels. For purposes of an IFC policy, we first generate the program's control flow graph. Then, for each if, while, do-while, for, and switch statement, we identify the immediate post-dominator in the graph, and wrap it in a label statement with a fresh identifier.

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That identifier is also added as a field in the original conditional statement. The tags associated with the labels are initialized at program state—in the case of IFC, these defaults declare that there are no secrets to lower when it is reached.

4 IMPLEMENTING TAGGED C WITH PIPE

[TODO: more detailed description of Chris' work and why the optional arguments are optional]

5 EVALUATION

Tagged C aims to combine the flexibility of tag-based architectures with the abstraction of a high-level language. How well have we achieved this aim?

[Here we list criteria and evaluate how we fulfilled them]

- Flexibility: we demonstrate three policies that can be used alone or in conjunction
- Applicability: we support the full complement of C language features and give definition to many undefined C programs
- Practical security: our example security policies are based on important security concepts from the literature

5.1 Limitations of the Tag Mechanism

By committing to a tag-based mechanism, we do restrict the space of policies that Tagged C can enforce. In general, a reference monitor can enforce any policy that constitutes a *safety property—* any policy whose violation can be demonstrated by a single finite trace. This class includes such policies as "no integer overflow" and "pointers are always in-bounds," which depend on the values of variables. Tag-based monitors cannot enforce any policy that depends on the value of a variable rather than its tags.

6 RELATED WORK

Reference Monitors. The concept of a reference monitor was first introduced fifty years ago in ??: a tamper-proof and verifiable subsystem that checks every security-relevant operation in a system to ensure that it conforms to a security *policy* (a general specification of acceptable behavior; see ??.)

A reference monitor can be implemented at any level of a system. An *inline reference monitor* is a purely compiler-based system that inserts checks at appropriate places in the code. Alternatively, a reference monitor might be embedded in the operating system, or in an interpreted language's runtime. A *hardware reference monitor* instead provides primitives at the ISA-level that accelerate security and make it harder to subvert.

Programmable Interlocks for Policy Enforcement (PIPE) [Dhawan et al. 2014] is a hardware extension that uses *metadata tagging*. Each register and each word of memory is associated with an additional array of bits called a tag. The policy is decomposed into a set of *tag rules* that act in parallel with each executing instruction, using the tags on its operands to decide whether the instruction is legal and, if so, determine which tags to place on its results. PIPE tags are large relative to other tag-based hardware, giving it the flexibility to implement complex policies with structured tags, and even run multiple policies at once.

Other hardware monitors include Arm MTE, [Binghamton], and CHERI. Arm MTE aims to enforce a narrow form of memory safety using 4-bit tags, which distinguish adjacent objects in memory from one another, preventing buffer overflows, but not necessarily other memory violations. [TODO: read the Binghamton paper, figure out where they sit here.]

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 CHERI is capability machine [TODO: cite OG CHERI]. In CHERI, capabilities are "fat pointers" carrying extra bounds and permission information, and capability-protected memory can only be accessed via a capability with the appropriate privilege. This is a natural way to enforce spatial memory safety, and techniques have been demonstrated for enforcing temporal safety [Wesley Filardo et al. 2020], stack safety [Skorstengaard et al. 2019], and compartmentalization [TODO: figure out what to cite], with varying degrees of ease and efficiency. But CHERI cannot easily enforce notions of security based on dataflow, such as Secure Information Flow.

In this paper, we describe a programming language with an abstract reference monitor. We realize it as an interpreter with the reference monitor built in, and envision eventually compiling to PIPE-equipped hardware. An inlining compiler would also be plausible. As a result of this choice, our abstract reference monitor uses a PIPE-esque notion of tags.

Aspect Oriented Programming. [TODO: do forward search from original AOP paper]

7 FUTURE WORK

We have presented the language and a reference interpreter, built on top of the CompCert interpreter [Leroy 2009], and three example policies. There are several significant next-steps.

Compilation. An interpreter is all well and good, but a compiler would be preferable for many reasons. A compiled Tagged C could use the hardware acceleration of a PIPE target, and could more easily support linked libraries, including linking against code written in other languages. The ultimate goal would be a fully verified compiler, but that is a very long way off.

Language Proofs. There are a couple of properties of the language semantics itself that we would like to prove. Namely (1) that its behavior (prior to adding a policy) matches that of CompCert C and (2) that the behavior of a given program is invariant under all policies up to truncation due to failstop.

Policy Correctness Proofs. For each example policy discussed in this paper, we sketched a formal specification for the security property it ought to enforce. A natural continuation would be to prove the correctness of each policy against these specifications.

Policy DSL. Currently, policies are written in Gallina, the language embedded in Coq. This is fine for a proof-of-concept, but not satisfactory for real use. We plan to develop a domain-specific policy language to make it easier to write Tagged C policies.

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A CONTINUATIONS

```
k ::= Kemp
|Kdo; k
|Kseq s; k
|Kif s_1 s_2 L; k
|Kwhile Test e s L; k
|Kwhile Test e s L; k
|KdoWhile Test e s L; k
|KdoWhile Test e s L; k
|Kfor (e, s_2) s_3 L; k
|Kfor Post (e, s_2) s_3 L; k
```

B INITIAL STATE

Given a list xs of variable identifiers id and types ty, a program's initial memory is defined by iteratively allocating each one in memory and updating the global environment with its base address, bound, type, and a static identity tag. Let |ty| be a function from types to their sizes in bytes. The memory is initialized $\mathbf{undef} @vt@\overline{tt}$ for some vt and \overline{tt} , unless given an initializer. Let m_0 and ge_0 be the initial (empty) memory and environment. The parameter b marks the start of the global region.

```
globals \ xs \ b = \begin{cases} (m_0, ge_0) & \text{if } xs = \varepsilon \\ (m[p \dots p + |ty| \mapsto \mathbf{undef}@vt@\overline{lt}]_{|ty|}, & \text{if } xs = (id, ty) :: xs' \\ ge[id \mapsto (p, p + |ty|, ty, pt)]) & \text{and } pt, vt, \overline{lt} \leftarrow \mathbf{GlobalT}(id, s) \\ & \text{where } (m, ge) = globals \ xs' \ (b + |ty|) \end{cases}
```

C STEP RULES

C.1 Sequencing rules

```
\overline{S(m \mid \mathsf{Sdo} \ e \gg k@\mathcal{P}) \longrightarrow \mathcal{E}(m \mid e \gg Kdo; \ k@\mathcal{P})}
\overline{\mathcal{E}(m \mid \mathsf{Eval} \ v@\ vt \gg Kdo; \ k@\mathcal{P}) \longrightarrow \mathcal{S}(m \mid \mathsf{Sskip} \gg k@\mathcal{P})}
```

1125

1126 1127

```
1079
                                            S(m \mid \text{Sseg } s_1 \mid s_2 \gg k@\mathcal{P}) \longrightarrow S(m \mid s_1 \gg Kseg \mid s_2; k@\mathcal{P})
1080
1081
1082
                                                 S(m \mid Sskip \gg Kseq s: k@P) \longrightarrow S(m \mid s \gg k@P)
1083
1084
                                   S(m \mid Scontinue \gg Kseq s; k@P) \longrightarrow S(m \mid Scontinue \gg k@P)
1085
1086
                                          S(m \mid Sbreak \gg Kseg s; k@P) \longrightarrow S(m \mid Sbreak \gg k@P)
1088
                                                 \frac{\mathcal{P}' \leftarrow \mathbf{LabelT}(\mathcal{P}, L)}{\mathcal{S}(m \mid \mathsf{Slabel}\ L: \ s \gg k@\mathcal{P}) \longrightarrow \mathcal{S}(m \mid s \gg k@\mathcal{P}')}
1090
1091
           C.2 Conditional rules
1092
1093
                                                                   s = Sif(e) then s_1 else s_2 join L
                                                 S(m \mid s \gg k@P) \longrightarrow \mathcal{E}(m \mid e \gg Kif s_1 s_2 L; k@P)
1094
                                       s' = \begin{cases} s_1 & \text{if } boolof(v) = \mathbf{t} \\ s_2 & \text{if } boolof(v) = \mathbf{f} \end{cases}
\mathcal{E}(m \mid Eval \ v@vt \gg Kif \ s_1 \ s_2 \ L; \ k@\mathcal{P}) \longrightarrow \mathcal{S}(m \mid s' \gg k@\mathcal{P}')
1097
1098
1099
1101
                    S(m \mid Sswitch \ e \mid \overline{(v,s)}) \text{ join } L \gg k@P) \longrightarrow \mathcal{E}(m \mid e \gg Kswitch 1 \mid \overline{(v,s)} \mid L; k@P)
1102
1103
                         \begin{array}{ll} select \ v \ \overline{(v,s)} = s & \mathcal{P}' \leftarrow \text{SplitT}(\mathcal{P}, vt, \boxed{L}) \\ \mathcal{E}\left(m \mid Eval \ v@vt \gg Kswitch1 \ \overline{(v,s)} \ L; \ k@\mathcal{P}\right) \longrightarrow \mathcal{S}\left(m \mid s \gg Kswitch2; \ k@\mathcal{P}'\right) \end{array}
1105
1106
                                                                          s = \mathsf{Sbreak} \lor s = \mathsf{Sskip}
1107
                                              S(m \mid s \gg Kswitch2; k@P) \longrightarrow S(m \mid Sskip \gg k@P)
1108
1109
                                 S(m \mid Scontinue \gg Kswitch2; k@P) \longrightarrow S(m \mid Scontinue \gg k@P)
1110
1111
           \mathbf{C}.3
                      Loop rules
1112
1113
                                                                          s = Swhile(e) do s' join L
1114
                                            S(m \mid s \gg k@P) \longrightarrow \mathcal{E}(m \mid e \gg KwhileTest \ e \ s' \ L; \ k@P)
1115
                                                             boolof(v) = \mathbf{t} k_1 = KwhileTest \ e \ s \ L; \ k
1116
                                                  k_2 = KwhileLoop \ e \ s \ L; \ k \qquad \mathcal{P}' \leftarrow \mathbf{SplitT}(\mathcal{P}, vt, \boxed{L})
\mathcal{E}(m \mid Eval \ v@vt \gg k_1@\mathcal{P}) \longrightarrow \mathcal{S}(m \mid s \gg k_2@\mathcal{P}')
1117
1118
1119
                                       boolof(v) = \mathbf{f} k = KwhileTest\ e\ s\ L;\ k' \mathcal{P}' \leftarrow \mathbf{SplitT}(\mathcal{P}, vt, \boxed{L})
1120
                                               \mathcal{E}(m \mid Eval\ v@vt \gg k@\mathcal{P}) \longrightarrow \mathcal{S}(m \mid Sskip \gg k'@\mathcal{P}')
1121
1122
                                        s = Sskip \lor s = Scontinue k = KwhileLoop e s L; k'
1123
                                        S(m \mid s \gg k@P) \longrightarrow S(m \mid Swhile(e) do s join <math>L \gg k'@P)
```

k = KwhileLoop e s L; k'

 $S(m \mid \text{Sbreak} \gg k@P) \longrightarrow S(m \mid \text{Sskip} \gg k'@P)$

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```
s = Sdo s' while (e) join L k' = KdoWhileLoop e s' L; <math>k
1128
                                                                                  S(m \mid s \gg k@\mathcal{P}) \longrightarrow S(m \mid s' \gg k'@\mathcal{P})
1129
1130
                                              k_1 = KdoWhileLoop\ e\ s\ L;\ k' k_2 = KdoWhileTest\ e\ s\ L;\ k
                                               \frac{1}{S(m \mid s' = \text{Sskip} \lor s' = \text{Scontinue} \gg k_1@\mathcal{P})} \longrightarrow \mathcal{E}(m \mid e \gg k_2@\mathcal{P})
                                                  boolof(v) = \mathbf{f} \quad k = KdoWhileTest \ e \ s \ L; \ k' \quad \mathcal{P}' \leftarrow \mathbf{SplitT}(\mathcal{P}, vt, \boxed{L})\mathcal{S}(m \mid Eval \ v@vt \gg k@\mathcal{P}) \longrightarrow \mathcal{S}(m \mid \mathsf{Sskip} \gg k'@\mathcal{P}')
1135
1137
1138
                                           boolof (v) = \mathbf{t} k = KdoWhileTest\ e\ s\ L;\ k' \mathcal{P}' \leftarrow \mathbf{SplitT}(\mathcal{P}, vt, \boxed{L}) \mathcal{S}(m \mid Eval\ v@vt \gg k@\mathcal{P}) \longrightarrow \mathcal{S}(m \mid \mathsf{Sdo}\ s\ \mathsf{while}\ (e)\ \mathsf{join}\ L \gg k'@\mathcal{P}')
1139
1141
                                                                                                      k = KdoWhileLoop\ e\ s\ L;\ k'
                                                                    S(m \mid \text{Sbreak} \gg k@P) \longrightarrow S(m \mid \text{Sskip} \gg k'@P)
1143
                                    \frac{s = \mathsf{Sfor}(s_1; e; s_2) \; \mathsf{do} \; s_3 \; \mathsf{join} \; L}{\mathcal{S} \; (m \mid s \gg k@\mathcal{P}) \longrightarrow \mathcal{S} \; (m \mid s_1 \gg \mathit{Kseq} \; \mathsf{Sfor}(\mathsf{Sskip}; e; s_2) \; \mathsf{do} \; s_3 \; \mathsf{join} \; L; \; k@\mathcal{P})}
                                   s = \mathsf{Sfor}(s_1; e; s_2) \ \mathsf{do} \ s_3 \ \mathsf{join} \ L
                                                                                            s = Sfor(Sskip; e; s_2) do s_3 join L
                                                              S(m \mid s \gg k@P) \longrightarrow \mathcal{E}(m \mid e \gg Kfor(e, s_2) s_3 L; k@P)
                                            \begin{array}{c|c} boolof(v) = \mathbf{f} & \mathcal{P}' \leftarrow \mathsf{SplitT}(\mathcal{P}, vt, \boxed{L}) \\ \mathcal{E}(m \mid Eval \ v@vt \gg Kfor \ (e, s_2) \ s_3 \ L; \ k@\mathcal{P}) \longrightarrow \mathcal{S}(m \mid \mathsf{Sskip} \gg k@\mathcal{P}) \end{array}
1155
                                                    \frac{k = K for (e, s_2) s_3 L; k' \quad boolof(v) = \mathbf{t} \quad \mathcal{P}' \leftarrow \mathbf{SplitT}(\mathcal{P}, vt, L)}{\mathcal{E}(m \mid Eval \ v @ vt \gg k @ \mathcal{P}) \longrightarrow \mathcal{S}(m \mid s_3 \gg k @ \mathcal{P})}
1157
1158
1159
1160
                     \begin{array}{ll} \textit{k} = \textit{Kfor}\;(\textit{e}, \textit{s}_{2})\;\textit{s}_{3}\;\textit{L}; & \textit{s} = \mathsf{Sskip}\;\forall\;\textit{s} = \mathsf{Scontinue} \\ \mathcal{S}\;(\textit{m}\;|\;\textit{s} \gg \textit{k@P}) \longrightarrow \mathcal{S}\;(\textit{m}\;|\;\mathsf{Sfor}(\mathsf{Sskip};\textit{e};\textit{s}_{2})\;\mathsf{do}\;\textit{s}_{3}\;\mathsf{join}\;\textit{L} \gg \textit{KforPost}\;(\textit{e},\textit{s}_{2})\;\textit{s}_{3}\;\textit{L};\;\textit{k@P}) \end{array} 
1161
1162
1163
                                                                   \frac{k = Kfor(e, s_1) s_2 L; k'}{S(m \mid \text{Sbreak} \gg k@\mathcal{P}) \longrightarrow S(m \mid \text{Sskip} \gg k'@\mathcal{P})}
1164
1165
1166
1167
                                                                                                      k = K for Post (e, s_2) s_3 L; k'
1168
                                        S(m \mid Sskip \gg k@P) \longrightarrow S(m \mid Sfor(Sskip; e; s_2) do s_3 join L \gg k@P)
1169
```

C.4 Contexts

1170 1171

1172

1173

1174

1175 1176 Our expression semantics are contextual. A context *ctx* is a function from an expression to an expression and a tag. We identify a valid context using the *context* relation over a "kind" (left-hand or right-hand, LH or RH), and an expression.

```
1177
                  context \ k \ C[e] ::=
1178
1179
                          |context k \lambda e.e
1180
                          |context lh \lambda e.Ederef C[e]
                                                                                        where context RH C[e]
                          |context lh \lambda e.Efield C[e] id
                                                                                        where context RH C[e]
1182
                          |context RH \lambda e.EvalOf C[e]
                                                                                        where context LH C[e]
1184
                           |context RH \lambda e.EaddrOf C[e]
                                                                                        where context LH C[e]
                          |context RH \lambda e.Eunop \odot C[e]
                                                                                        where context RH C[e]
1186
                          |context RH \lambda e.Ebinop \oplus C[e_1] e_2
                                                                                       where context RH C[e_1]
1187
                          |context RH \lambda e.Ebinop \oplus e_1 C[e_2]
                                                                                       where context RH C[e_2]
1188
1189
                          |context RH \lambda e.Ecast C[e] ty
                                                                                        where context RH C[e]
1190
                          |context RH \lambda e.EseqAnd C[e_1] e_2
                                                                                       where context RH C[e_1]
1191
                          |context RH \lambda e.EseqOr C[e_1] e_2
                                                                                       where context RH C[e_1]
1192
                          |context RH \lambda e.Econd C[e_1] e_2 e_3
                                                                                       where context RH C[e_1]
                          |context RH \lambda e.Eassign C[e_1] e_2
                                                                                       where context LH C[e_1]
1195
                          |context RH \lambda e.Eassign e_1 C[e_2]
                                                                                       where context RH C[e_2]
1196
                                                                                       where context LH C[e_1]
                          | context RH \lambda e. Eassign Op \oplus C[e_1] e_2
1197
                                                                                       where context RH C[e_2]
                          |context RH \lambda e.EassignOp \oplus e_1 C[e_2]
1199
                          |context| RH \lambda e.EpostInc \oplus C[e]
                                                                                        where context LH C[e]
1200
                          | context RH \lambda e. Ecall C[e_1](\overline{e_2})
                                                                                       where context RH C[e_1]
1201
                          | context RH \lambda e. Ecall e_1(C[\overline{e_2}])
                                                                           where context RH C[e] for e \in \overline{e_2}
1202
1203
                          |context RH \lambda e.Ecomma C[e_1] e_2
                                                                                       where context RH C[e_1]
1204
                          |context RH \lambda e.Eparen C[e] ty
                                                                                        where context RH C[e]
1205
                          |context RH \lambda e.Eparen C[e] ty t
                                                                                        where context RH C[e]
1206
```

Next, we define a notion of expression reduction. A left-hand reduction relates an expression to an expression. A right-hand reduction relates a triple of PC Tag, memory, and expression to another such triple.

$$\begin{array}{ccc} & context \ LH \ C[e] & e \Rightarrow_{LH} e' \\ \hline \mathcal{E} \ (m \mid C[e] \gg k@\mathcal{P}) \longrightarrow \mathcal{E} \ (m \mid C[e] \gg k@\mathcal{P}) \\ \hline context \ RH \ C[e] & (\mathcal{P}, m, e) \Rightarrow_{RH} (\mathcal{P}', m', e') \\ \hline \mathcal{E} \ (m \mid C[e] \gg k@\mathcal{P}) \longrightarrow \mathcal{E} \ (m' \mid C[e] \gg k@\mathcal{P}') \\ \hline \end{array}$$

C.5 Expression Rules

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1221 1222

1223 1224 1225

$$\frac{le[id] = (l, _, pt, ty)}{Evar id \Rightarrow_{LH} Eloc \ l@pt}$$

$$\frac{le[id] = \bot \quad ge[id] = VAR(l, _, pt, ty)}{Evar id \Rightarrow_{LH} Eloc \ l@pt}$$

$$\frac{le[id] = \bot \quad ge[id] = VAR(f, pt)}{Evar id \Rightarrow_{LH} Efloc \ l@pt}$$

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```
1226
                                                   (\mathcal{P}, m, Ederef (Eval v@vt)) \Rightarrow_{RH} (\mathcal{P}, m, Eloc (to ptr v)@vt)
1227
                                    ty = TStruct \ id \lor ty = TUnion \ id \quad offset \ id \ fld = \delta \quad pt' \leftarrow \mathbf{FieldT}(pt, id)
1229
                                                             Efield (Eval p@pt : ty) fld) \Rightarrow_{IH} Eloc (p + \delta)@pt'
                                                        \begin{array}{ll} m[l]_{|ty|} = v@vt@\overline{lt} & vt' \leftarrow \mathbf{LoadT}(\mathcal{P}, pt, vt, \overline{lt}) \\ (\mathcal{P}, m, EvalOf \ (Eloc \ l@pt) : ty) \Rightarrow_{\mathtt{RH}} (\mathcal{P}, m, Eval \ v@vt') \end{array} 
1231
1233
                                                          (\mathcal{P}, m, EaddrOf (Eloc p@pt)) \Rightarrow_{RH} (\mathcal{P}, m, Eval p@pt)
1235
                                                       \langle \odot \rangle v = v'  vt \leftarrow \text{UnopT}(\odot, \mathcal{P}, vt)
                                                       (\mathcal{P}, m, Eunop \odot (Eval v@vt)) \Rightarrow_{RH} (\mathcal{P}, m, Eval v'@vt')
1237
                                                                   v_1 \langle \oplus \rangle v_2 = v' \quad vt' \leftarrow \mathbf{BinopT}(\oplus, \mathcal{P}, vt_1, vt_2)
                                                                 e = Ebinop \oplus (Eval \ v_1@vt_1) (Eval \ v_2@vt_2)
                                                                             (\mathcal{P}, m, e) \Rightarrow_{\text{RH}} (\mathcal{P}, m, \text{Eval } v' @ vt')
1241
                                              1243
                                                       ty_1 = ptr \ ty'_1
1245
                                              m[v]_{|ty_1'|} = \_@vt@\overline{lt} \qquad vt \leftarrow \text{PICastT}(\mathcal{P}, pt, vt, \overline{lt})
(\mathcal{P}, m, Ecast (Eval v@pt : ty_1) ty_2) \Rightarrow_{RH} (\mathcal{P}, m, Eval v@vt' : ty_2)
1247
                                                         \neg isptr(ty_1)
                                                                                                                             ty_2 = ptr \ ty_2'
1249
                                              m[v]_{|ty_2'|} = \underline{\@wt_2@\overline{lt}} \qquad pt \leftarrow \mathbf{IPCastT}(\mathcal{P}, vt_1, vt_2, \overline{lt})
(\mathcal{P}, m, Ecast (Eval v@vt_1 : ty_1) \ ty_2) \Rightarrow_{\mathsf{RH}} (\mathcal{P}, m, Eval v@pt : ty_2)
1250
1251
1252
                                                                  tu_1 = ptr tu'_1
1253
                                             m[v]_{|ty_1'|} = m[v]_{|ty_2'|} = \underline{\ @vt@\overline{lt} \ pt' \leftarrow PPCastT(\mathcal{P}, pt, vt, \overline{lt})}
(\mathcal{P}, m, Ecast (Eval v@pt : ty_1) ty_2) \Rightarrow_{RH} (\mathcal{P}, m, Eval v@pt' : ty_2)
1255
                                                                                                      \mathcal{P}' \leftarrow \text{ExprSplitT}(\mathcal{P}, vt)
                                                boolof(v) = \mathbf{t}
1257
                                                (\mathcal{P}, m, EseqAnd (Eval \ v@vt) \ e) \Rightarrow_{RH} (\mathcal{P}', m, Eparen \ e \ Tbool \ \mathcal{P})
1258
                                                                                                        \mathcal{P}' \leftarrow \text{ExprSplitT}(\mathcal{P}, vt)
1259
                                    boolof(v) = \mathbf{f}
                                    (\mathcal{P}, m, EseqAnd (Eval \ v@vt) \ e) \Rightarrow_{RH} (\mathcal{P}', m, Eparen (Eval \ 0@vt') \ Tbool \ \mathcal{P})
1260
1261
                                                                                                       \mathcal{P}' \leftarrow \text{ExprSplitT}(\mathcal{P}, vt)
                                      boolof(v) = \mathbf{t}
1262
                                     (\mathcal{P}, m, EseqOr (Eval \ v@vt) \ e) \Rightarrow_{RH} (\mathcal{P}', m, Eparen (Eval \ 1@vt') \ Tbool \ \mathcal{P})
1263
1264
                                                                                                        \mathcal{P}' \leftarrow \text{ExprSplitT}(\mathcal{P}, vt)
                                                  boolof(v) = \mathbf{f}
                                                 (\mathcal{P}, m, EseqOr (Eval \ v@vt) \ e) \Rightarrow_{RH} (\mathcal{P}', m, Eparen \ e \ Tbool \ \mathcal{P})
1265
1266
                                                   e' = \begin{cases} e_1 & \text{if } boolof(v) = \mathbf{t} \\ e_2 & \text{if } boolof(v) = \mathbf{f} \end{cases} \quad \mathcal{P}' \leftarrow \text{ExprSplitT}(\mathcal{P}, vt)
(\mathcal{P}, m, Econd \; (Eval \, v@\, vt) \; e_1 \; e_2) \Rightarrow_{\text{RH}} (\mathcal{P}', m, Eparen \, e' \, \mathcal{P})
1267
1268
1269
1270
                                                                                                              m' = m[l \mapsto v_2 \otimes vt' \otimes \overline{lt'}]
                                        m[l]_{|ty|} = v_1@vt_1@\overline{lt}
1271
                                                                          \mathcal{P}', vt', \overline{lt}' \leftarrow \mathbf{StoreT}(\mathcal{P}, pt, vt_1, vt_2, \overline{lt})
1272
                                         (\mathcal{P}, m, Eassign (Eloc \ l@pt) (Eval \ v_2@vt_2)) \Rightarrow_{RH} (\mathcal{P}', m', Eval \ v_2@vt_2)
1273
1274
```

```
m[l]_{|ty|} = v_1@vt@\overline{lt} \quad \oplus \in \{+, -, *, /, %, <<, >>, \&, ^{\wedge}, |\} \quad vt' \leftarrow \mathbf{LoadT}(\mathcal{P}, pt, vt, \overline{lt})
e = Eassign (Eloc l@pt) (Ebinop \oplus (Eval v_1@vt') (Eval v_2@vt_2))
(\mathcal{P}, m, EassignOp \oplus (Eloc l@pt) (Eval v_2@vt_2)) \Rightarrow_{\mathrm{RH}} (\mathcal{P}, m, e)
m[l] = v@vt@\overline{lt} \quad \oplus \in \{+, -\} \quad vt' \leftarrow \mathbf{LoadT}(\mathcal{P}, pt, vt, \overline{lt})
e = Ecomma (Eassign (Eloc l@pt) (Ebinop \oplus Eval v@vt' 1@def)) (Eval v@vt')
(\mathcal{P}, m, EpostInc \oplus Eloc l@pt) \Rightarrow_{\mathrm{RH}} (\mathcal{P}, m, e)
\overline{(\mathcal{P}, m, Ecomma (Eval v@vt) e)} \Rightarrow_{\mathrm{RH}} (\mathcal{P}, m, e)
\overline{(\mathcal{P}, m, Eparen e ty \mathcal{P}')} \Rightarrow_{\mathrm{RH}} (\mathcal{P}'', m, Eval v@vt')
```

C.6 Call and Return Rules

In order to make a call, we need to reduce the function expression to an *Efloc* _@ value, an abstract location corresponding to a particular function. Then we can make the call.

$$\mathcal{P}' \leftarrow \mathbf{CallT}(\mathcal{P}, f, f')$$

$$\mathcal{E}\left(m \mid C\left[\mathit{Ecall Efloc}\ f'@(\overline{v@vt})\right]ty \gg k@\mathcal{P}\right) \longrightarrow C\left(m \mid f'(v@vt) \gg \mathit{Kcall}\ f \in \mathcal{P};\ k@\mathcal{P}'\right)$$

When we make an internal call, we need to allocated space for locals and arguments using the helper function *frame*.

$$\begin{cases} (m''[p\mapsto \mathbf{undef}@vt@\overline{lt}]_{|ty|}, & \text{if } xs=(id,ty)::xs'\\ le'[id\mapsto (p,p+|ty|,ty,pt)]) & \text{where } (m',p) \leftarrow stack_alloc |ty| \ m,\\ pt, vt, \overline{lt} \leftarrow \mathbf{LocalT}(\mathcal{P},x,s),\\ & \text{and } (m'',le') = frame \ xs' \ as \ m' \end{cases}$$

$$\begin{cases} (m''[p\mapsto v@vt'@\overline{lt}]_{|ty|}, & \text{if } as=(id,ty,v@vt):: as' \ and \ xs=\varepsilon\\ le'[id\mapsto (p,p+|ty|,ty,pt)]) & \text{where } (m',p) \leftarrow stack_alloc \ |ty| \ m,\\ \mathcal{P}',pt,vt',\overline{lt} \leftarrow \mathbf{ArgT}(\mathcal{P},vt,f,x,s),\\ & \text{and } (m'',le') = frame \ xs' \ as \ m' \end{cases}$$

$$(m,\lambda x.\bot) & \text{if } xs=\varepsilon \ and \ as=\varepsilon$$

$$\underline{def(f)=INT(xs,as,s) \quad m',le'=frame \ xs \ (zip \ as \ args) \ m \ le}_{C \ (m|f(args)\gg k@\mathcal{P}) \longrightarrow S \ (m'|s\gg k@\mathcal{P})/le'}$$

On the other hand, when we make an external call, we step directly to a return state with some value being returned and an updated memory. [TODO: talk more about how the tag policy applies in external functions, what they can and can't do with tags.]

$$\frac{def(f) = EXT(spec) \quad \mathcal{P}' \leftarrow \text{ExtCallT}(\mathcal{P}, f, f', \overline{vt}) \quad \mathcal{P}'', m', (v@vt) = spec \, \mathcal{P}' \, args \, m}{C \, (m \mid f(args) \gg k@\mathcal{P}) \longrightarrow \mathcal{R} \, (m' \mid v@vt \gg k@\mathcal{P}'')}$$

Special external functions, such as malloc, just get their own rules.

```
 \begin{array}{ccc} \mathcal{P}', pt, & \overline{vt, lt} \end{array} \leftarrow & \mathbf{MallocT}(\mathcal{P}, vt) & m', p \leftarrow heap\_alloc \ size \ m \\ & m'' = m' \ [p+i \mapsto (\mathbf{undef}, vt, lt)]_{size} \\ \hline C(m \mid malloc((size@t)) \gg k@\mathcal{P}) \longrightarrow & \mathcal{R}(m'' \mid Eval \ p@pt \gg k@\mathcal{P}') \end{array}
```

1:28 Anon.

And finally, we have the return rules. $k = Kcall \ le' \ ctx \mathcal{P}_{CLR} \ k'$ 1326 $R(m \mid Fyal \ v@vt \gg k@\mathcal{P}_{CYR})$

$$\frac{k = Kcall \ le' \ ctx \ \mathcal{P}_{CLR} \ k'}{\mathcal{R} \ (m \mid Eval \ v@vt \gg k@\mathcal{P}_{CLE}) \longrightarrow \mathcal{E} \ (m \mid ctx [Eval \ v@vt'] \gg k'@\mathcal{P}') \ /le'}$$

$$dealloc\ m\ {\color{red} P}=({\color{red} P'},m')$$

$$\mathcal{E}(m \mid \text{Eval } v@vt \gg \text{Kreturn}; \ k@\mathcal{P}) \longrightarrow \mathcal{R}(m \mid \text{Eval } v@vt \gg k@\mathcal{P}')$$

dealloc
$$m \mathcal{P} = (\mathcal{P}', m')$$

$$S(m \mid Sreturn \gg k@P) \longrightarrow R(m' \mid Eval \, undef@def \gg k@P')$$

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