

# Toyota HSR-Test Report

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## Evaluation of Navigation

### Navigation Property Tests

### Results

Robot pose is same as simulation pose  
Pose of objects are the same after navigation  
Robot navigation run completed in average time

✓  
✓  
✓

Legality Tests

Evaluation of Pick Action

Data 9	Data 10	Data 11	Data 12	✓
Data 13	Data 7	Data 8	Data 13	x

## Evaluation of Place Action

**Data 188**  
Data 6

**Data 2**  
Data 7

**Data 3**  
Data 8

**Data 4**  
Data 9

✓  
x

Evaluation of Scenario

Data 188	Data 2	Data 3	Data 4	✓
Data 6	Data 7	Data 8	Data 9	x