Pre-modelled expected behaviours	Start-point verification	Target entity movement	
	End-point verification	Target entity final position verification	
	Operation zone verification	Target entity contact with end-of-effector	
	Object proximity verification	Target entity in target position	
	Object movement verification	Target entity between end-of-effector	
Composite Property	TargetPosition	Collision	
Primitive Property	Spatial	Physical	Environment