Introduction to Time Series Analysis OC Data Driven Insights

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Resources

- ► Forecasting: Principles and Practice by Rob J. Hyndman and George Athanasopoulos
- ► Time Series Analysis and Its Applications with R Examples by Robert H. Shumway and David S. Stoffer

Outline

- ▶ What is a time series? Time series model?
 - ► Time Series Examples
- Fundamental building blocks of time series
 - White noise
 - Moving average
 - Random walk
- Second order properties and stationarity
- ► When/why linear regression fails

What is a Time Series?

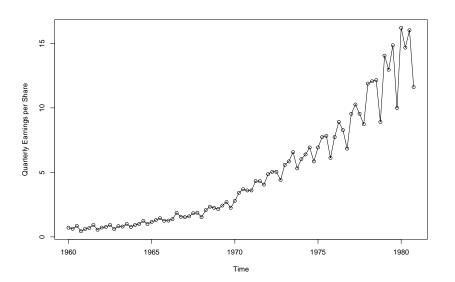
A sequence of values of a variable at **equally spaced** intervals with a **natural temporal ordering**.

```
> require(astsa)
> window(jj, 1960, c(1965,4))
```

```
## Qtr1 Qtr2 Qtr3 Qtr4
## 1960 0.71 0.63 0.85 0.44
## 1961 0.61 0.69 0.92 0.55
## 1962 0.72 0.77 0.92 0.60
## 1963 0.83 0.80 1.00 0.77
## 1964 0.92 1.00 1.24 1.00
## 1965 1.16 1.30 1.45 1.25
```

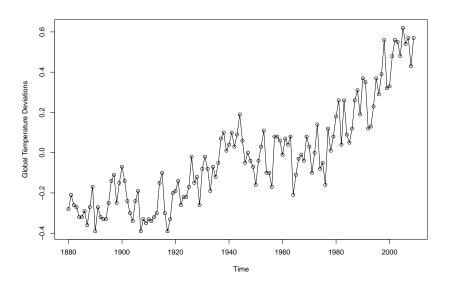
What is a Time Series?

> plot(jj, type="o", ylab="Quarterly Earnings per Share")



What is a Time Series?

plot(gtemp, type="o", ylab="Global Temperature Deviations")



Key Assumption

sample estimates:

Can't assume consecutive observations are independent

```
> jj_v <- unclass(jj)
> lag <- lag(jj_v, 1)
> lm <- lm(jj_v ~ lag)
> cor.test( ~ jj_v + lag,
+ method = "pearson",
+ conf.level = 0.95)
```

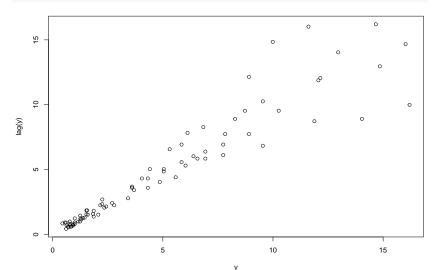
```
##
## Pearson's product-moment correlation
##
## data: jj_v and lag
```

t = 25.987, df = 81, p-value < 2.2e-16
alternative hypothesis: true correlation is not equal to
95 percent confidence interval:
0.9159239 0.9641248</pre>

Key Assumption

Can't assume consecutive observations are independent

> plot(jj_v, lag, ylab="lag(y)", xlab="y")



Why Care about Time Series?

- ► They are everywhere!
- ► Economics (stock market, unemployment, etc)
- Social sciences (population series like birth rates or school enrollments)
- ► Epidemiology (influenza outbreaks)
- Medicine (blood pressure measurements)

Working with Time Series

- ► Time series analysis
 - Analyzing observed data
 - Focus on characteristics of the data
 - Explanatory focus
- ► Time series forecasting
 - Generating a model
 - Predictive focus

Some Additional Terminology

- Stochastic process
 - ► A sequence of random variables
 - Example: flipping a coin
- Sample path
 - Sample path of a stochastic process
 - One sample from a stochastic process
 - For example: HTHHTT (six coin flips)
- A stochastic process can generate MANY sample paths (infinitely many)

Fundamental Stochastic Processes

- ▶ White noise
- Moving average
- ► Random walks

White Noise

- ► Fundamental building block of other stochastic processes
- ► Key: no correlation between observations
- Y_t is called white noise (process looks like white light of spectrometers)

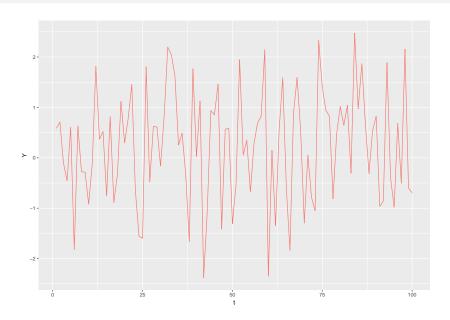
White Noise: Definition

- Assume $e_t \sim N(0,1)$ is a collection of IID random variables all following a normal distribution
- ▶ Normal distribution? Anyone? Anyone at all?
- ▶ Define $Y_t = e_t$ for all t
- A white noise process satisfies:
 - ightharpoonup Mean(Y_t) = constant
 - $ightharpoonup Var(Y_t) = constant$
 - Auto-covariance = 0

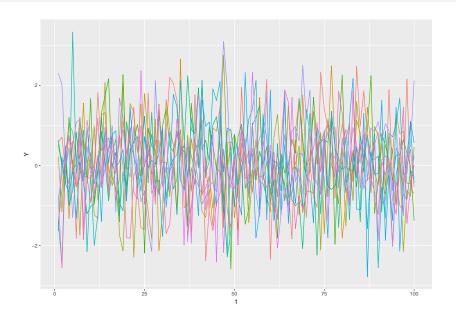
White Noise: Implications

Since the data is random (no pattern) there is no point in modeling

White Noise: 1 Sample Path



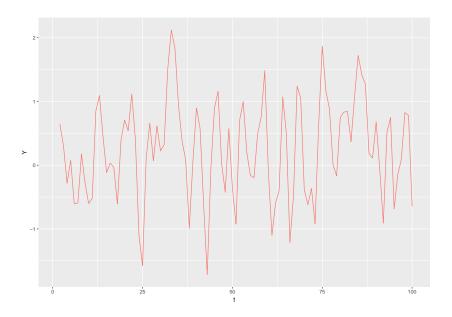
White Noise: Many Sample Paths



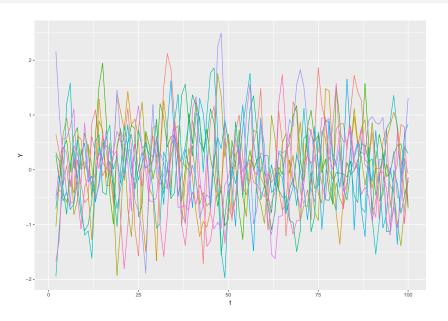
Moving Average

- Big difference: there IS correlation between observations
- Assume $e_t \sim N(0,1)$ is a collection of IID random variables all following a normal distribution
- ▶ Define $Y_t = \frac{e_t + e_{t+1}}{2}$ for all t
- \triangleright Y_t is a type of moving average stochastic process

Moving Average: 1 Sample Path



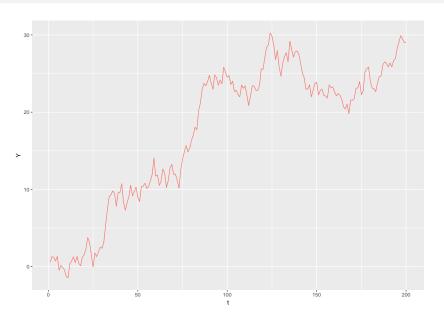
Moving Average: Many Sample Paths



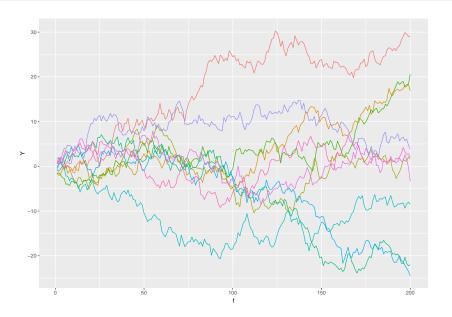
Random Walk

- Assume $e_t \sim N(0,1)$ is a collection of IID random variables all following a normal distribution
- ▶ Define $Y_t = e_1 + e_2 + ... + e_t$ for all t
- \triangleright Y_t is a random walk

Random Walk: 1 Sample Path



Random Walk: Many Sample Paths



Why Care about Stochastic Processes?

- We have ONE sample path of observations
- ► From this sample path we intend to infer the stochastic process that generated it
- We are NOT fitting lines to the data
- ▶ We are understanding the sample paths the process could take

Typical Process

- ▶ We observe a process to a specific point
- We determine what sample paths are likely as we look later in time

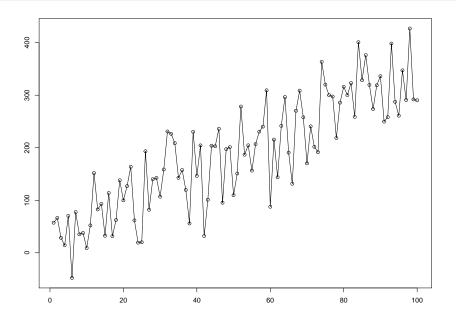
Stationarity

- Heavily mathematical definition
- Essence of it:
 - ▶ The mean (or expected value of the stochastic process) is constant
 - Covariance (or corelation between points only depends on distance between points and not on the value of t)
- Stationarity is an extremely common assumption in time series modeling!

Time Series: Linear Trend

- Assume stochastic process is $Y_t = \beta_0 + \beta_1 t + X_t$
- Assume $E[X_t] = 0$ and X_t is stationary
- ► This is just like linear regression so let's use OLS

Time Series: Linear Trend



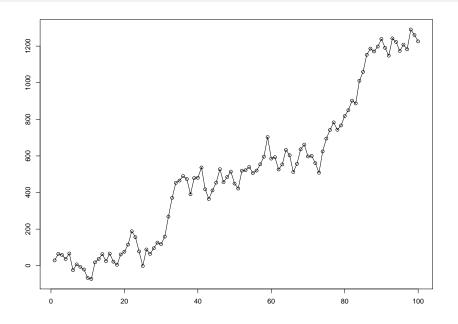
Time Series

► Linear regression recovers the true parameters (close)

Time Series: Linear Model for Random Walk

- ▶ What if we fit a random walk Y_t with a linear model?
- ▶ Put another way: what if we regress a random walk on time with a linear model?
- Good choice, bad choice?

Linear Model for a Random Walk



Linear Model for a Random Walk

- Linear regression fails. Hard
- ► Significant trend when there is NOT one
- Reminder: there is not a trend because the expected value of Y_t is 0

What Happened?

- Spurious regression
- DO NOT regress non-stationary time series
- Our mistake
 - Coefficient is okay
 - Standard error is underestimated
- ► A random walk does not follow required linear regression assumptions!
 - ▶ Which key assumption does it not follow?