

Bayesian statistical inference

Regression

Associated notebooks:

[06-Bayesian inference MCMC/Bayes basics short.ipynb](#)

[06-Bayesian inference MCMC/Bayes simple modeling.ipynb](#)

Bayesian problem setting

P(science)

Science:

- Mass of a planet
- Rotation P of asteroid
- Super massive BH mass
- ...

Bayesian problem setting

$$\mathbf{P}(\text{science} \mid \text{data})$$

data:

- Observations
- Results of a simulation
- ...

Bayesian problem setting

$$\mathbf{P}(\text{science} \mid \text{data}, \text{background info})$$

background information:

≡ What you know before getting any data

- Physical range (e.g. $M > 0$)
- Previous measurement
- ...

Bayesian problem setting

$\mathbf{P}(\text{science, nuisance parameters} \mid \text{data, background info})$

Nuisance parameters:

\equiv parameters you are not interested in

- Secular motion of a star during a transit
- Dust extinction in SN distance measurement
- ...

Bayesian problem setting

P(science, nuisance parameters | data, background info)

$$\mathbf{P}(\theta_S, \theta_N | D, I)$$


≡ Posterior probability

Bayes theorem

$$P(\boldsymbol{\theta} \mid D, I) = \frac{P(D \mid \boldsymbol{\theta})P(\boldsymbol{\theta})}{P(D)}$$

Bayes theorem

Likelihood


$$P(\boldsymbol{\theta} \mid D, I) = \frac{P(D \mid \boldsymbol{\theta})P(\boldsymbol{\theta})}{P(D)}$$

Bayes theorem

$$P(\boldsymbol{\theta} \mid D, I) = \frac{P(D \mid \boldsymbol{\theta}) \overset{\text{Prior}}{\underset{\downarrow}{P(\boldsymbol{\theta})}}}{P(D)}$$

Bayes theorem

$$P(\boldsymbol{\theta} \mid D, I) = \frac{P(D \mid \boldsymbol{\theta}) P(\boldsymbol{\theta})}{P(D)}$$

$$P(D) = \int P(D \mid \boldsymbol{\theta}) P(\boldsymbol{\theta}) d\boldsymbol{\theta}$$

Evidence

/

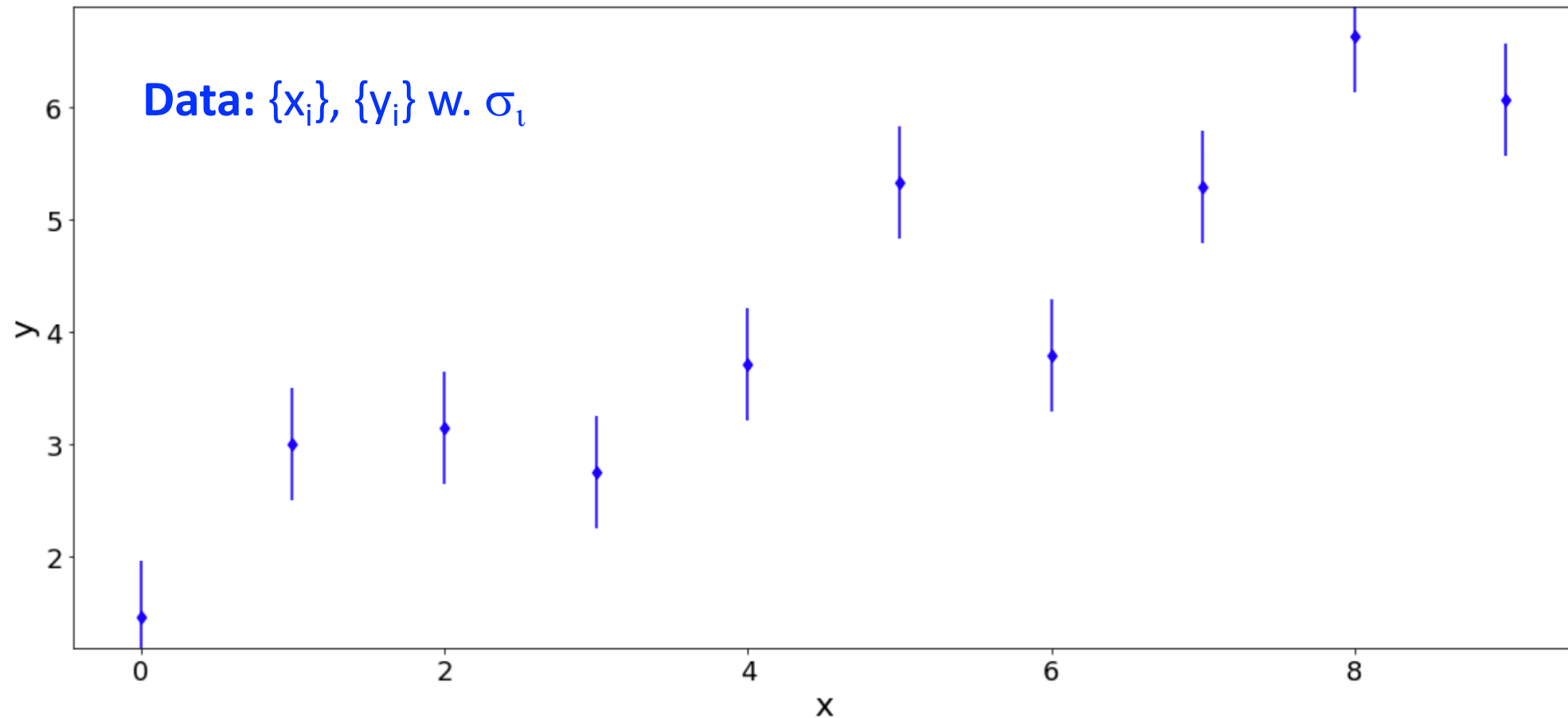
Fully Marginalized likelihood

Bayes theorem

$$\text{Posterior} = \frac{\text{Likelihood} \times \text{Prior}}{\text{Evidence}}$$

Regression in the Bayesian framework

Let's assume that: $y_i \sim N(y_M(x_i; \boldsymbol{\theta}), \sigma)$



“Bayesian” Regression

$$P(\boldsymbol{\theta} \mid D, I) = \frac{P(D \mid \boldsymbol{\theta})P(\boldsymbol{\theta})}{P(D)}$$

1. Model choice: $M(\boldsymbol{\theta}) : y_M(x) = \theta_0 + \theta_1 x$

“Bayesian” Regression

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2. Likelihood: $\ln(P(D \mid \boldsymbol{\theta})) = -\frac{1}{2} \sum_{i=1}^N \left(\ln(2\pi\sigma_i^2) + \frac{(y_i - (\theta_0 + \theta_1 x_i))^2}{\sigma_i^2} \right)$

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3. Prior:

- Conjugate (allows one to get analytic form of $P(\boldsymbol{\theta} \mid D)$)
- Empirical: based on previous measurement
- Flat: constant between 2 bounds (but can be informative)
- Non informative

“Bayesian” vs “Frequentist” regression

<i>Frequentist:</i>	<i>Bayes:</i>
<i>Optimization</i> with some merit function	<i>Sampling</i> of the likelihood
Search for <i>best (fit)</i> model <i>parameters</i>	PDF on parameters
“Ignore” the priors	<i>Accounts</i> explicitly for the priors