Classical statistical inference

Regression and Model fitting

Associated notebook:

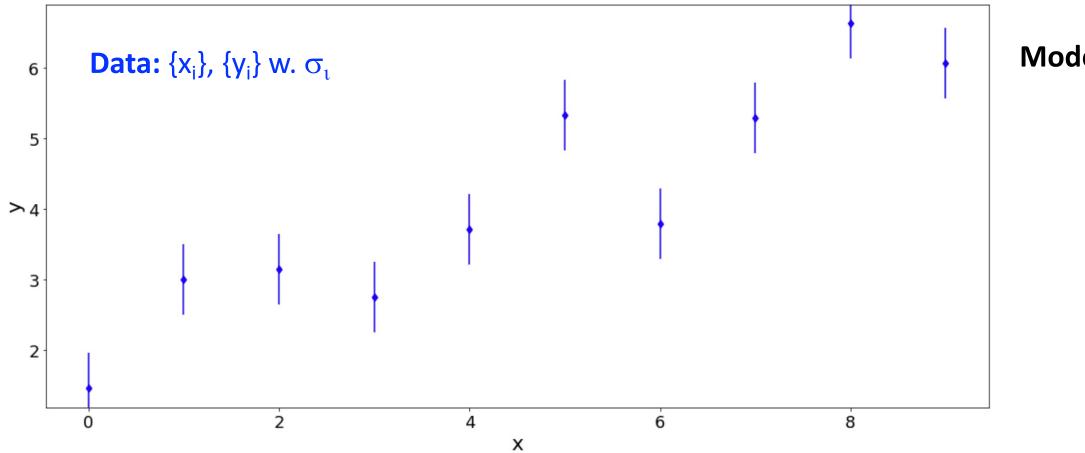
05-MLE and regression/Regression short.ipynb

Problem: the quantities of interest are parameters of a model, not the RV that you measure

Examples

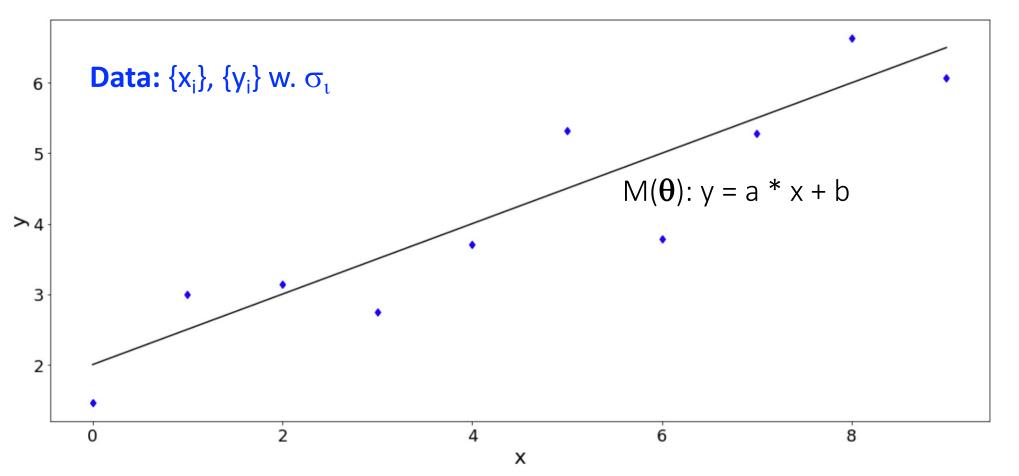
Observation	Quantity of interest	Model
Position of a star: x(t)	Proper motion (velocity) of the star	V = f(x, t,)
Photometry of an asteroid: mag(t)	P (period of rotation)	mag = f(t, P,)
Transit of a planet: mag(t)	P (period), e (eccentricity), D (dist to star)	Δ m = f (t, P, e, D,)
Spectrum of a QSO: F (λ)	M _{BH} (Black hole mass of QSO)	$FWHM = f(M_{BH}, L,)$

Problem: You measure $D \equiv (\{y_i\}, \{x_i\})$



Model: $M(\theta)$

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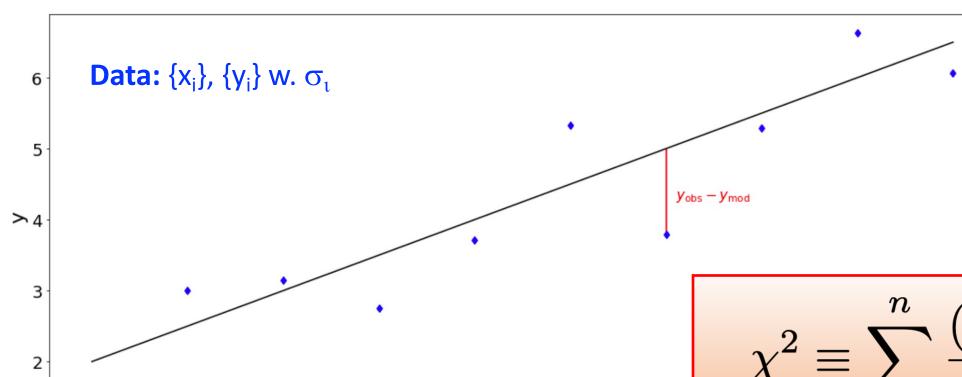
Model: $M(\theta)$

$$y = a * x + b$$

$$\theta$$
 = a, b

How to find a good model?

2



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Model: $M(\theta)$

$$y = a * x + b$$

= $f(x | \theta)$

$$\theta$$
 = a, b

Minimize

$$\chi^2 \equiv \sum_{i=1}^n \frac{(y_i - y_{i,mod})^2}{\sigma_i^2}$$

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If $\sigma_i = 1$: Least square regression

If $\sigma_i \neq 1$: chi-square regression

The χ^2 is called a **merit** function

When uncertainties between variables are correlated, the χ^2 is expressed:

$$\chi^{2} = \sum_{i=1}^{n} \sum_{l=1}^{n} (y_{i} - y_{i,mod}) F_{i,l} (y_{l} - y_{l,mod})$$

Where *F* is the Fisher matrix

$$[F]^{-1} = [C] = \begin{bmatrix} \sigma_k^2 & \sigma_{kl} \\ \sigma_{kl} & \sigma_l^2 \end{bmatrix}$$

$$\chi^2 \equiv \sum_{i=1}^n \frac{(y_i - y_{i,mod})^2}{\sigma_i^2}$$

If $\sigma_i = 1$: Least square regression

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When uncertainties between variables are correlated, the χ^2 is expressed:

$$\chi^2 = (\overrightarrow{d} - \overrightarrow{m})^T C^{-1} (\overrightarrow{d} - \overrightarrow{m})$$

$$[F]^{-1} = [C] = \begin{bmatrix} \sigma_k^2 & \sigma_{kl} \\ \sigma_{kl} & \sigma_l^2 \end{bmatrix}$$

$$[F]^{-1} = [C] = \begin{bmatrix} \sigma_k^2 & \sigma_{kl} \\ \sigma_{kl} & \sigma_l^2 \end{bmatrix} \qquad \overrightarrow{d} \equiv \begin{pmatrix} y_1 \\ y_2 \\ \dots \\ y_N \end{pmatrix} \qquad \overrightarrow{m} \equiv \begin{pmatrix} y_{1,\text{mod}} \\ y_{2,\text{mod}} \\ \dots \\ y_{N,\text{mod}} \end{pmatrix}$$

Link between χ^2 and likelihood $L = p(D \,|\, M(oldsymbol{ heta}))$

$$L = p(D \mid M(\boldsymbol{\theta}))$$

Case of a straight line: $y_i = heta_0 + heta_1 \, x_i + \epsilon_i$ with $\epsilon_i \sim N(0,\sigma_i)$

For each
$$y_k$$
 we have: $p(y_k \mid \mu, \sigma) = \frac{1}{\sigma \sqrt{2 \pi}} \exp \left[-0.5 \left(\frac{y_k - \mu}{\sigma} \right)^2 \right]$

With e.g. $\mu \equiv y_{k,\mathrm{mod}}$ If the model is "correct"

Hence, we have for our data set D:

$$L \equiv p(\{y_i\} | \{x_i\}, \boldsymbol{\theta}) = \prod_{i=1}^{N} \frac{1}{\sigma_i \sqrt{2\pi}} \exp \left[\left(\frac{-(y_i - (\theta_0 + \theta_1 x_i))^2}{2\sigma_i^2} \right) \right]$$

Link between χ^2 and likelihood

Hence, we have for our data set D:

$$L \equiv p(\{y_i\} | \{x_i\}, \boldsymbol{\theta}) = \prod_{i=1}^{N} \frac{1}{\sigma_i \sqrt{2\pi}} \exp \left[\left(\frac{-(y_i - (\theta_0 + \theta_1 x_i))^2}{2\sigma_i^2} \right) \right]$$

$$\ln(L) \propto \sum_{i=1}^{N} \left(\frac{-(y_i - (\theta_0 + \theta_1 x_i))^2}{2 \sigma_i^2} \right) \qquad \chi^2 \equiv \sum_{i=1}^{n} \frac{(y_i - y_{i,mod})^2}{\sigma_i^2}$$

$$\chi^2 \equiv \sum_{i=1}^n \frac{(y_i - y_{i,mod})^2}{\sigma_i^2}$$



Minimizing χ^2 is equivalent to maximizing L

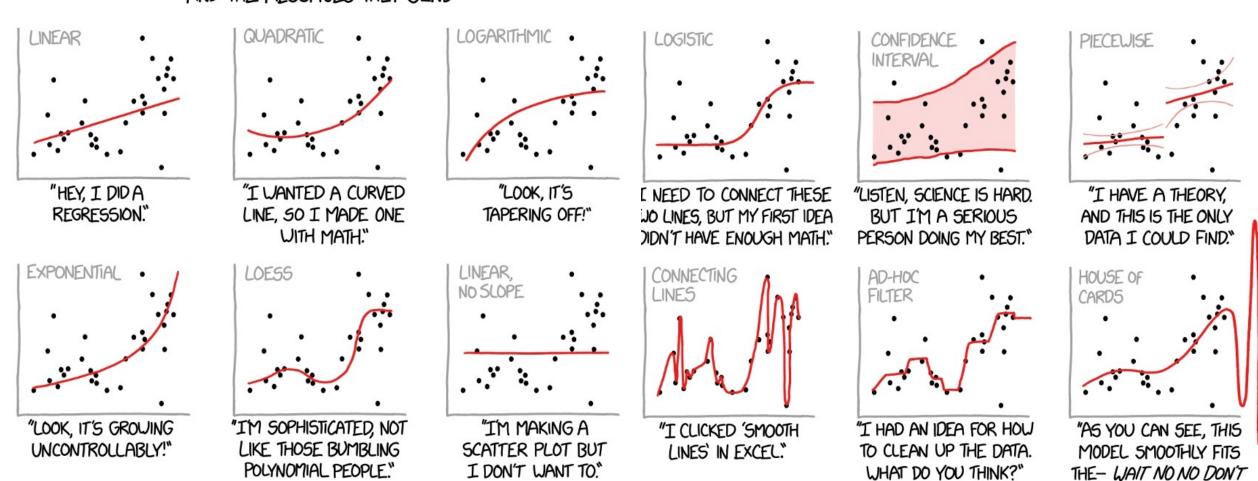
Regression of a straight line in python

Linear model fitting: See Sect. IV.1

Python implementation: numpy.polyfit(x, y, deg=1, w=1/sigma)

Go to Sect. IV.1.1 of the Notebook for practical example

CURVE-FITTING METHODS AND THE MESSAGES THEY SEND



Extend it aaaaaa!!"

How to choose a suitable regression method?

The way you will tackle a regression problem may depend on:

- Linearity: is the model linear in its parameters? $f(x \,|\, m{ heta}) = \sum_{p=1}^\infty \theta_p g_p(x)$
- Complexity: large number of parameters increase complexity and covariance matrix on uncertainties
- Error behaviour: uncertainties on dependent and independent variable and their correlation.

How to choose a suitable regression method?

Frequentist: (this lecture)	Bayes (future lecture):
Optimization with some merit function	Sampling of the likelihood
Search for <i>best</i> (fit) model <i>parameters</i>	PDF on parameters
Often when <i>simple</i> error behaviour	More <i>complex</i> error behaviour

Linear vs non linear regression

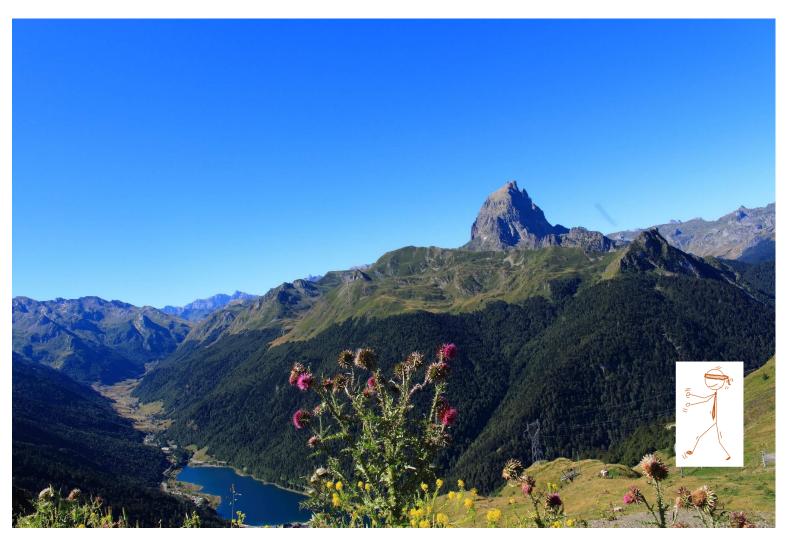
A model is **linear** if:
$$f(x \,|\, \pmb{\theta}) = \sum_{p=1}^k \theta_p g_p(x)$$

 $g_p(x)$ can be a non linear function of x BUT does not depend on any free parameter

In this case, the values of the parameters that yield $\frac{\partial \ln(L)}{\partial \theta_i}=0$ (max. likelihood) can be found via a matrix inversion

When the model is **not linear**, the minimization of the χ^2 has to be performed *numerically*

Non linear regression: gradient descent & LM



You need to reach the lake but you are blind.

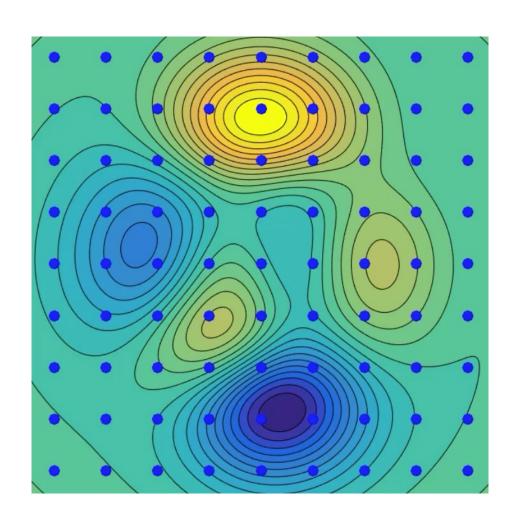
Strategy: Search for steepest descent

$$\theta_{n+1} = \theta_n - h\nabla F(\theta_n)$$

Where h = constant and F the function that you want to minimize. Here, it may be $\chi^2(\theta_n)$

More advanced algorithms, such as Levenberg-Marquardt (LM), exist. LM follows gradient descent first, adapting h depending of $\delta\chi^2$ and assumes quadratic behaviour of χ^2 close to the minimum.

Non linear regression: Illustration



See also here:

https://en.wikipedia.org/wiki/File:Gradient_Descent_in_2D.webm

Linear vs non linear regression

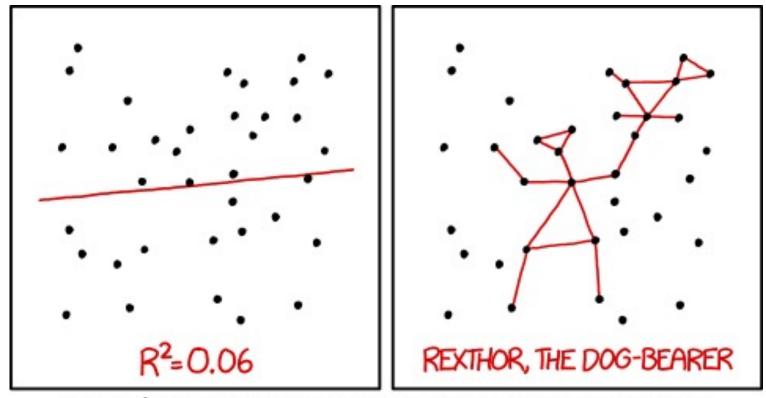
Linear model fitting: See Sect. IV.1

Python implementation: numpy.polyfit(x, y, deg=1, w=1/sigma)

NON Linear model fitting: See Sect. IV.3

Python implementation: scipy.optimize.curvefit()

Go to Sect. IV.3 of the Notebook for practical example

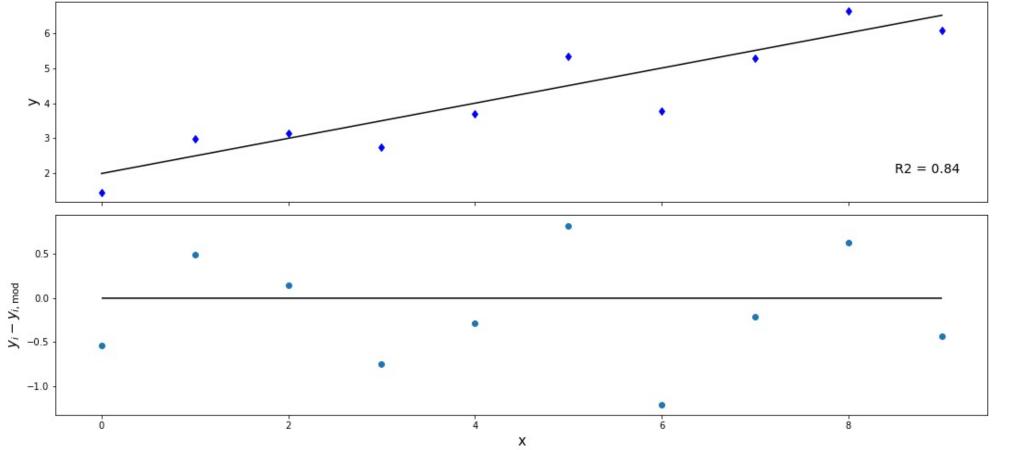


I DON'T TRUST LINEAR REGRESSIONS WHEN IT'S HARDER TO GUESS THE DIRECTION OF THE CORRELATION FROM THE SCATTER PLOT THAN TO FIND NEW CONSTELLATIONS ON IT.

Look at the residuals: $y_i - y_{i, \mathrm{mod}}$

Coefficient of determination of Pearson

$$R^{2} = 1 - \frac{\sum_{i} (y_{i} - y_{i,\text{mod}})^{2}}{\sum_{i}^{n} (y_{i} - \bar{y})^{2}}$$

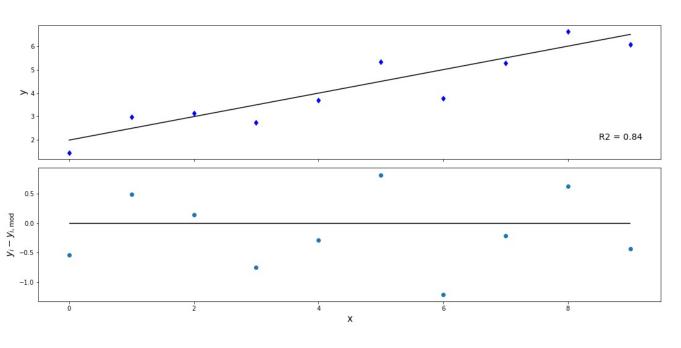


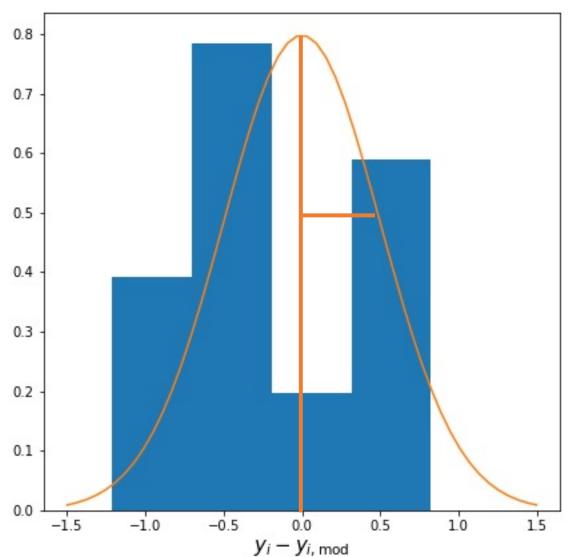
Closer R² is to 1, more the model is good at explaining the data (or at making predictions).

But use with care as it is originally designed for linear models and does not account for uncertainty on data points (cf least-square vs χ^2 regression)

Compare variance of residuals to σ^2 on \textbf{y}_i

Look at the residuals: $y_i - y_{i, \mathrm{mod}}$





Your χ^2 is a random variable!

$$Q = \sum_{i=1}^{k} z_i^2 \to p(Q|k) = \frac{1}{(2\Gamma(k/2))} (Q/2)^{k/2-1} \exp(-Q/2)$$

k = degree of freedom = N points - n parameters

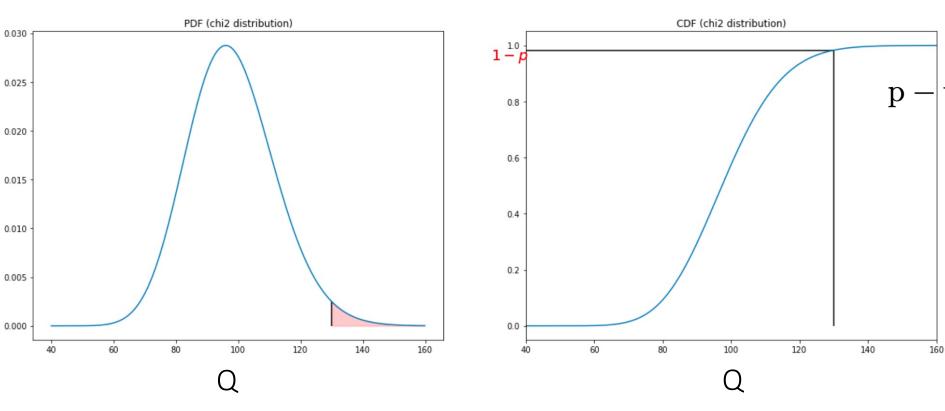
If you fit a model with 2 parameters on a set of 100 points => 98 d.o.f.

Expectation
$$E(\chi^2) = 100 - 2 = 98$$

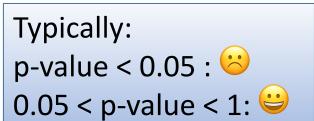
Reduced
$$\chi^2: \chi^2_{\text{red}} = \chi^2_{\text{dof}} / \text{d.o.f.}$$
 \Rightarrow Reduced $\chi^2 \equiv 1$. if good fit

See also the Notebook 03-Basic_statistics_and_proba_concepts/Descriptive_statistics_02.ipynb

$$p(Q|k) = \frac{1}{(2\Gamma(k/2))} (Q/2)^{k/2-1} \exp(-Q/2)$$



$$p-$$
 value = $p(Q \ge \chi^2_{obs})$ = $1-p(Q \le \chi^2_{obs})$



p-value close to 1 : $\stackrel{\smile}{=}$

1-scipy.stats.chi2.cdf(chi2_data, df= len(data)-nparam)

Quality of the regression: Memo

- Calculate the χ² and number of d.o.f. = n_{pts} n_{params}
 BEWARE: Makes sense ONLY if uncertainties on the data points are reliable

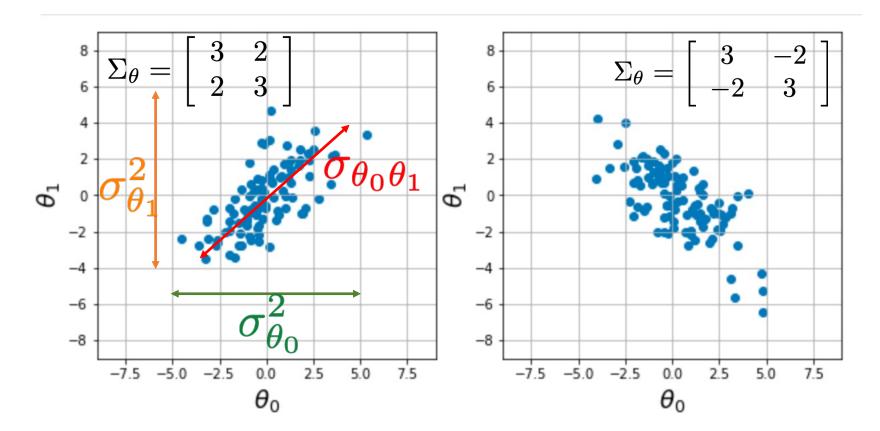
 - p-value can also be calculated if uncertainties are realistic
 - Reduced χ^2 should be close to 1
- Calculate and visualise the (normalised) residuals
 - Is there systematic trends? If yes, the model may not be optimal / is not a good representation of the data
 - A systematic trend can also be caused by groups of points that are outliers
 - Visualise the distribution of normalised residuals: are they distributed as N(0,1)?
- BEWARE: A poor fit does can mean:
 - incorrect uncertainties
 - Poor model
 - Presence of "outliers" among the data points

Uncertainty on the fitted parameters

The python functions return a covariance matrix (Warning: use arg. cov=True)

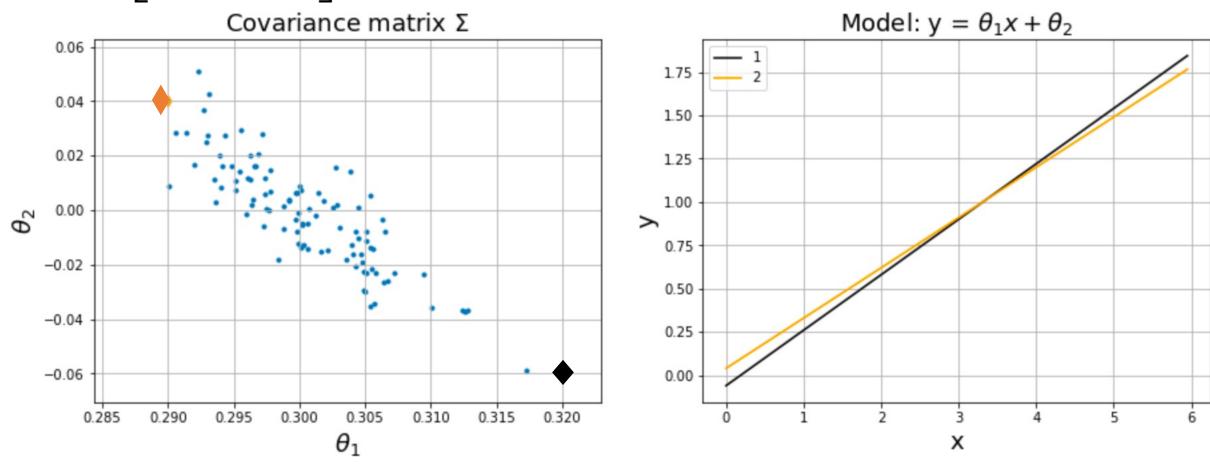
The diagonal elements of the matrix give the variance on the parameters (uncertainty²)

$$\Sigma_{ heta} = \left[egin{array}{ccc} \sigma_{ heta_0}^2 & \sigma_{ heta_0 heta_1} \ \sigma_{ heta_0 heta_1} & \sigma_{ heta_1}^2 \end{array}
ight] egin{array}{ccc} ^{8} \ \Sigma_{ heta} = \ \sigma_{ heta_0}^2 \end{array}$$



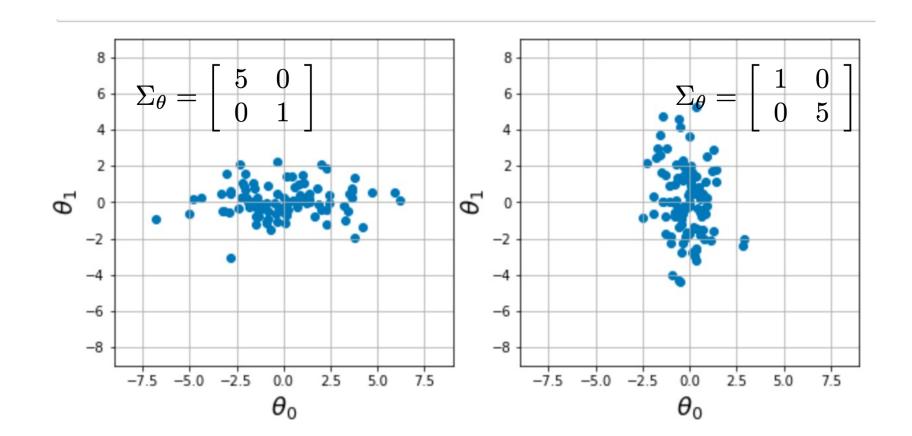
Uncertainty on the fitted parameters

$$\Sigma_{ heta} = \left[egin{array}{ccc} + & - \ - & + \end{array}
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Uncertainty on the fitted parameters

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ight]$$



Non linear models and initial conditions

Non linear regression use numerical methods to find the minimum χ^2 . For this reason the results are highly sensitive to initial conditions!

Tips for choosing good initial conditions

- Visualise the prediction of the model for various sets of parameters
- If too many parameters: Randomly sample the parameter space and calculate the $\chi^2\,$.
- If the optimization is fast, repeat with different sets of initial conditions