

Ilia Nechaev

CV

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Interest

Robotics, computer vision, system programming, embedded development, ML/DL deployment on edge devices

Education

- 2020 - 2024 **Bachelor**, *SPbU, Saint-Petersburg, Faculty of Mathematics and Computer Science*
Mathematics, algorithms, data science
- 2022 - 2024 **Bachelor**, *UCLan Cyprus, Pyla, School of Science*
Computing

Experience

- May 2024 - present **JetBrains**, *Research and educational assistant*
- Robotics development (autonomous driving, embeded) - redesigned [Duckiebot](#) autonomous driving stack to ROS2
 - Neural networks development for computer vision - developed new lane marking recognition stack for it (with [publication](#))
 - Neural networks deployment on edge devices - created [utility](#) for benchmarking Neural networks across Edge TPU, edge GPU and CPU
 - Teaching university courses - developed from scratch and taught "Programming fundamentals with C and Linux" and "Robotics and CV" courses; taught "Operating systems" course
- September **Ice measuring system**, *Development intern*
- 2022 - May 2024
- Development utility for generation synthetic data for adjusting computer vision algorithms.
 - Development machine learning algorithms for detecting the width of the ice channel left by icebreaker based on camera frames
- February **Veeroute**, *Development intern*
- 2023 - June 2023
- Development of combinatorial optimisation engine
 - Creating tests and benchmarks

Languages

Russian Native
English B2

Skills

Legend



basic knowledge



intermediate knowledge with some
project experience



extensive project experience



deepened expert knowledge



expert / specialist

	Level	Skill	Years	Comments
Programming languages:		Python	3	Used a lot for ML/DL and ice cover generation applications. Worked with Pandas, NumPy, Matplotlib, SciPy, Sklearn, CatBoost, XGBoost, PyTorch libraries
		Kotlin	1	Used in a few pet projects and JetBrains hackathon 2025
		Rust	1	There was a course at the university. Used in a few pet projects, including "Classroom-ToSheetsIntegration"
		C	4	I teach C in my current position. Applying it in just "Programming fundamentals" course as well as "Operating systems" and "Robotics" courses. Used it with OpenCL for GPU computations
		C++	4	I use C++ in my robotics development. The most recent work project was: development of hardware simulator - utility to emulate robotics sensors and actuators
OS and tools:		Linux	5	I use Linux (Ubuntu) as my main OS in addition I teach Linux at university
		Make & CMake	4	Using it on a daily basis as main build systems for both teaching and development
		Docker	3	Using it everyday for educational purposes (autotests) and robotics (almost all robotics deployments are made via docker)
Other:		Machine learning	2	There were 7 modules of ML/DL at the SPbU. I have experience at developing ML/DL algorithms, data preprocessing and models deployment. Field of interests: computer vision
		Computer vision	2	Used at JetBrains and during icebreaker project. Also both of my thesis were connected with computer vision