

# Implement of the MPS-FEM Coupled Method for 3-D FSI Problem

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  - ✓ Shape function based data transmission technique
- Application of MPS-FEM coupled method
- Conclusions

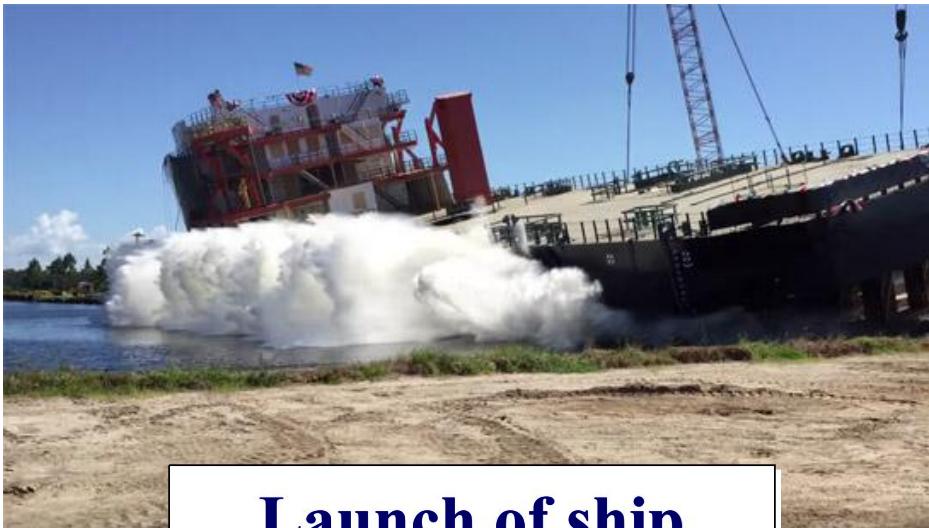
# Background



Ship in wave



Platform in storm



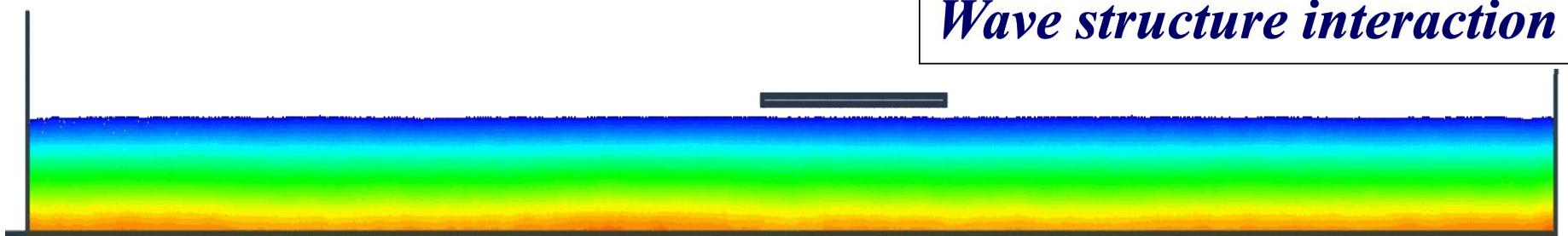
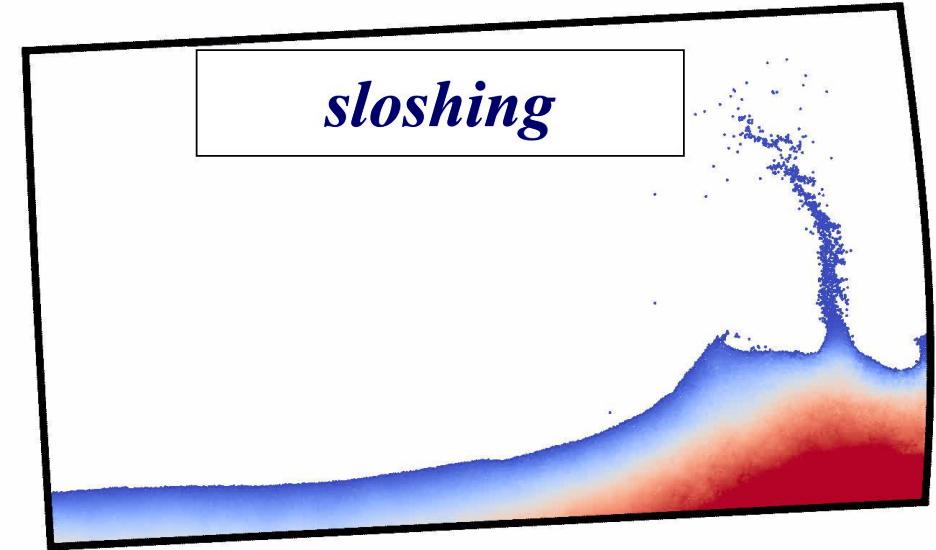
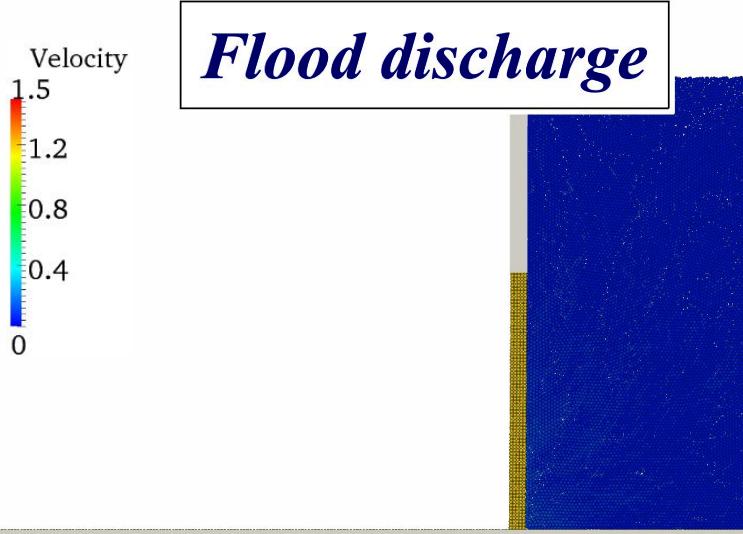
Launch of ship



Trestle bridge in tsunami

# Background

## ● Fully Lagrangian particle approach

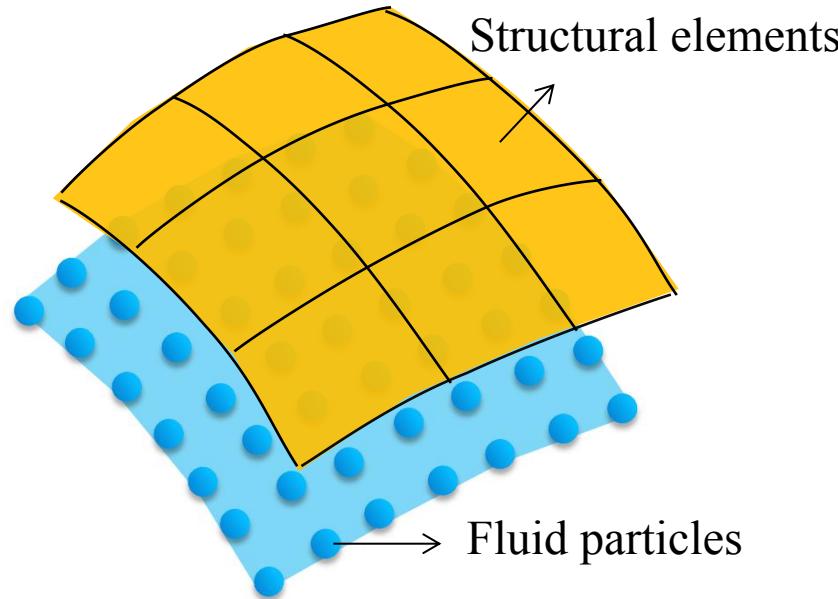


2-D FSI problems simulated by *MPSFEM-SJTU*

MPS-FEM coupled method for 3-D FSI problems

# Background

## Challenge for 3-D FSI simulations



How to implement the data transmission between the two boundaries?

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## Fluid domain

Fluid governing equations

$$\nabla \cdot \mathbf{V} = 0 \quad \frac{D\mathbf{V}}{Dt} = -\frac{1}{\rho} \nabla P + \nu \nabla^2 \mathbf{V} + \mathbf{g}$$

Kernel function

$$W(r) = \begin{cases} \frac{r_e}{0.85r + 0.15r_e} - 1 & 0 \leq r < r_e \\ 0 & r_e \leq r \end{cases}$$

Pressure Gradient

$$\langle \nabla P \rangle_i = \frac{D}{n^0} \sum_{j \neq i} \frac{P_j + P_i}{|\mathbf{r}_j - \mathbf{r}_i|^2} (\mathbf{r}_j - \mathbf{r}_i) \cdot W(|\mathbf{r}_j - \mathbf{r}_i|)$$

Source term

$$\langle \nabla^2 P^{n+1} \rangle_i = (1 - \gamma) \frac{\rho}{\Delta t} \nabla \cdot \mathbf{V}^* - \gamma \frac{\rho}{\Delta t^2} \frac{\langle n^* \rangle_i - n^0}{n^0}$$

Free surface detection

$$\langle \mathbf{F} \rangle_i = \frac{D}{n^0} \sum_{j \neq i} \frac{1}{|\mathbf{r}_i - \mathbf{r}_j|} (\mathbf{r}_i - \mathbf{r}_j) W(\mathbf{r}_{ij})$$

## Structure domain

Structure governing equations

$$\Pi = \frac{1}{2} \int_V \boldsymbol{\epsilon}^T \boldsymbol{\sigma} dv - \int_V \mathbf{u}^T \mathbf{f} dv - \int_{S_\sigma} \mathbf{u}^T \bar{\mathbf{f}} ds$$

$$\delta \Pi = 0$$

Structural dynamic equation

$$\mathbf{M}\ddot{\mathbf{y}} + \mathbf{C}\dot{\mathbf{y}} + \mathbf{K}\mathbf{y} = \mathbf{F}(t)$$

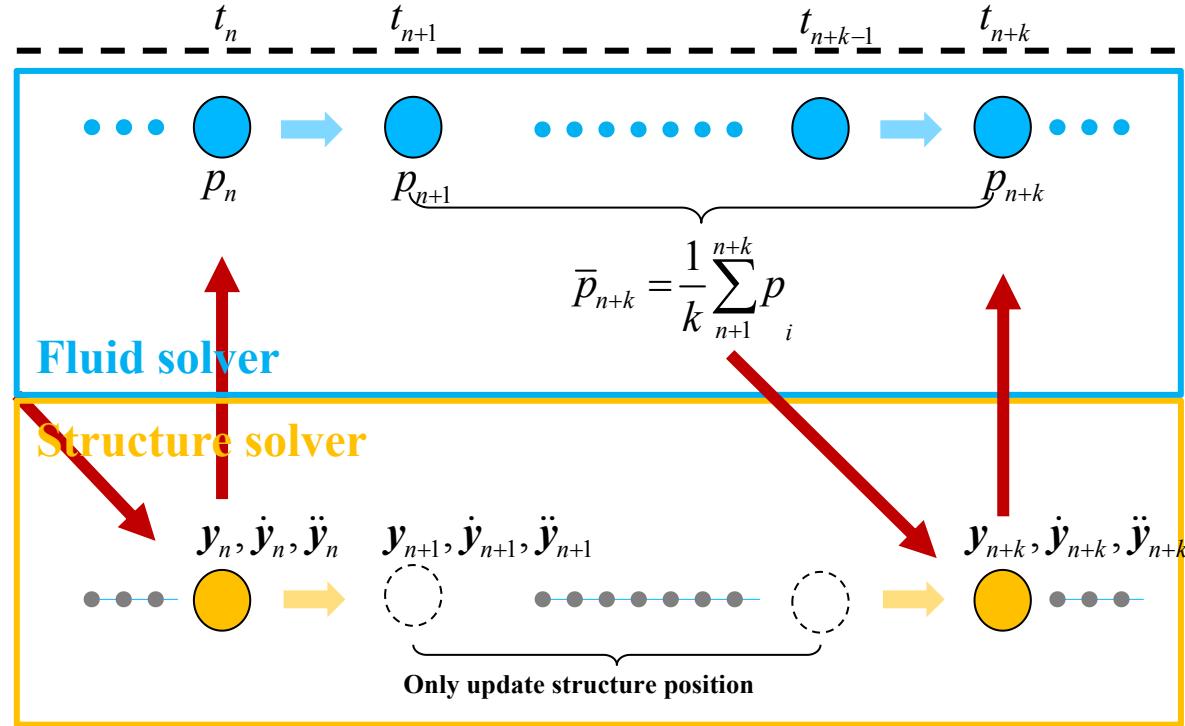
Newmark-beta method

$$\dot{\mathbf{y}}_{t+\Delta t} = \dot{\mathbf{y}}_t + (1 - \gamma)\ddot{\mathbf{y}}_t \Delta t + \gamma \ddot{\mathbf{y}}_{t+\Delta t} \Delta t$$

$$\mathbf{y}_{t+\Delta t} = \mathbf{y}_t + \dot{\mathbf{y}}_t \Delta t + \frac{1 - 2\beta}{2} \ddot{\mathbf{y}}_t \Delta t^2 + \beta \ddot{\mathbf{y}}_{t+\Delta t} \Delta t^2$$

# Coupling strategy

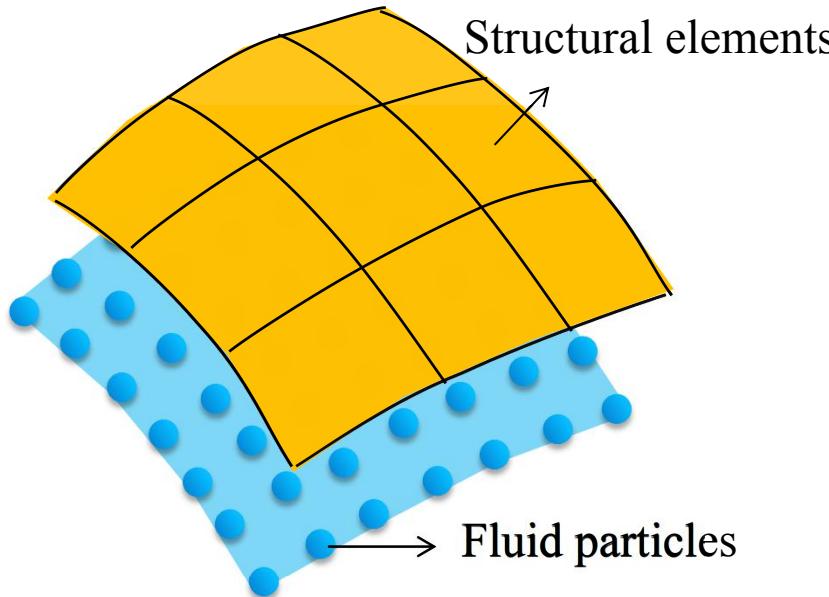
- Implement the coupling between the two domains



- Partitioned coupling strategy:
  - ✓ the fluid and structure fields are self-governed by different equations.
  - ✓ separated fluid and structure codes are used for each computational domain.
  - ✓ different time step sizes can be used for fluid & structure analysis ( $t_s = k \times t_f$ ).

# Data transmission on F-S interface

- Data transmission between the F-S boundaries



Different types and sizes of discretization for fluid and structure boundaries.

Interpolation of quantities is necessary.

*Shape function based interpolation technique*

Boundary conditions on the F-S interface:

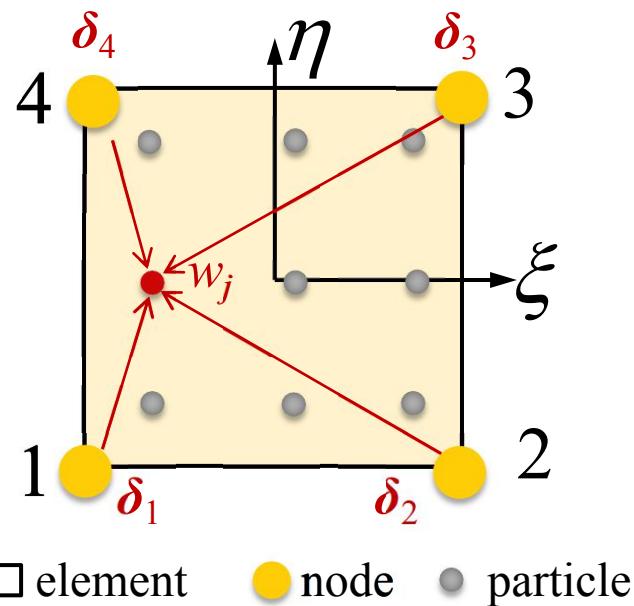
- ✓ displacement compatibility,  $\mathbf{d}_f = \mathbf{d}_s$
- ✓ traction equilibrium,  $\mathbf{f}_f = \mathbf{f}_s$

*Kernel function based interpolation technique*

# Data transmission on F-S interface

- Shape function based interpolation technique

- Displacement interpolation on the F-S interface:



$$w = N^e \delta^e$$

Calc particle displacement

$$\delta^e = [\delta^1 \ \delta^2 \ \delta^3 \ \delta^4]$$

Nodal displacement

$$= [w_1 \ \theta_{x1} \ \theta_{y1} \ w_2 \ \theta_{x2} \ \theta_{y2} \ w_3 \ \theta_{x3} \ \theta_{y3} \ w_4 \ \theta_{x4} \ \theta_{y4}]^T$$

$$N^e = [N_i \ N_j \ N_m \ N_n]$$

Shape function

$$= [N_i \ N_{xi} \ N_{yi} \ N_j \ N_{xj} \ N_{yj} \ N_m \ N_{xm} \ N_{ym} \ N_n \ N_{xn} \ N_{yn}]$$

$$N_i = \frac{1}{8} (1 + \xi_i \xi)(1 + \eta_i \eta)(2 + \xi_i \xi + \eta_i \eta - \xi^2 - \eta^2)$$

$$N_{xi} = -\frac{1}{8} b \eta_i (1 + \xi_i \xi)(1 + \eta_i \eta)(1 - \eta^2)$$

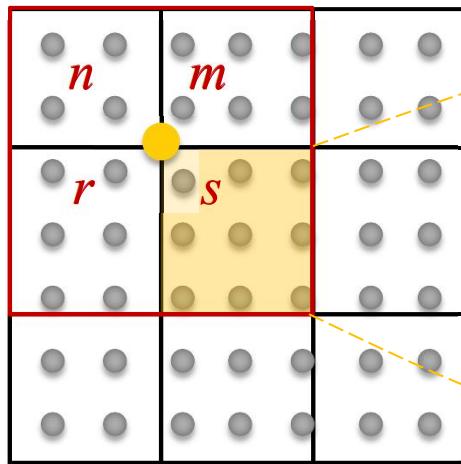
$$N_{yi} = \frac{1}{8} a \xi_i (1 + \xi_i \xi)(1 + \eta_i \eta)(1 - \xi^2)$$

$$\xi = \frac{x}{a}, \xi_i = \frac{x_i}{a}, \eta = \frac{y}{b}, \eta_i = \frac{y_i}{b}$$

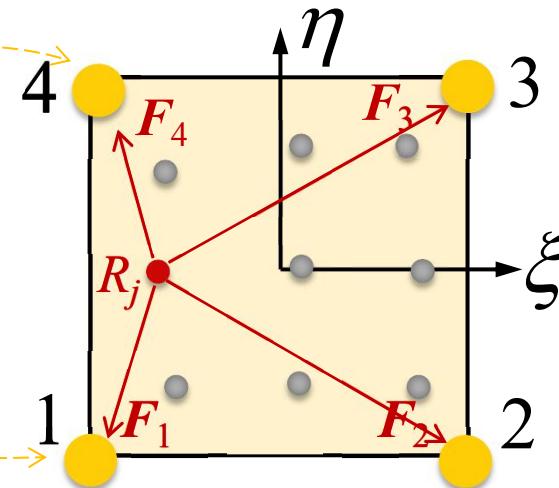
# Data transmission on F-S interface

- Shape function based interpolation technique

- Force interpolation on the F-S interface:



element     contribution region  
 node             particle



Equivalent force within element  $s$

Total nodal force

$$\mathbf{F} = \mathbf{F}_r + \mathbf{F}_s + \mathbf{F}_m + \mathbf{F}_n$$

Force component within element  $s$

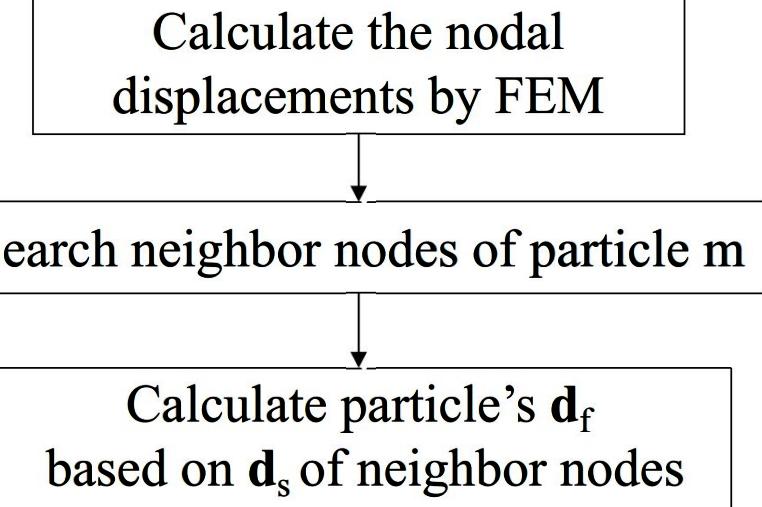
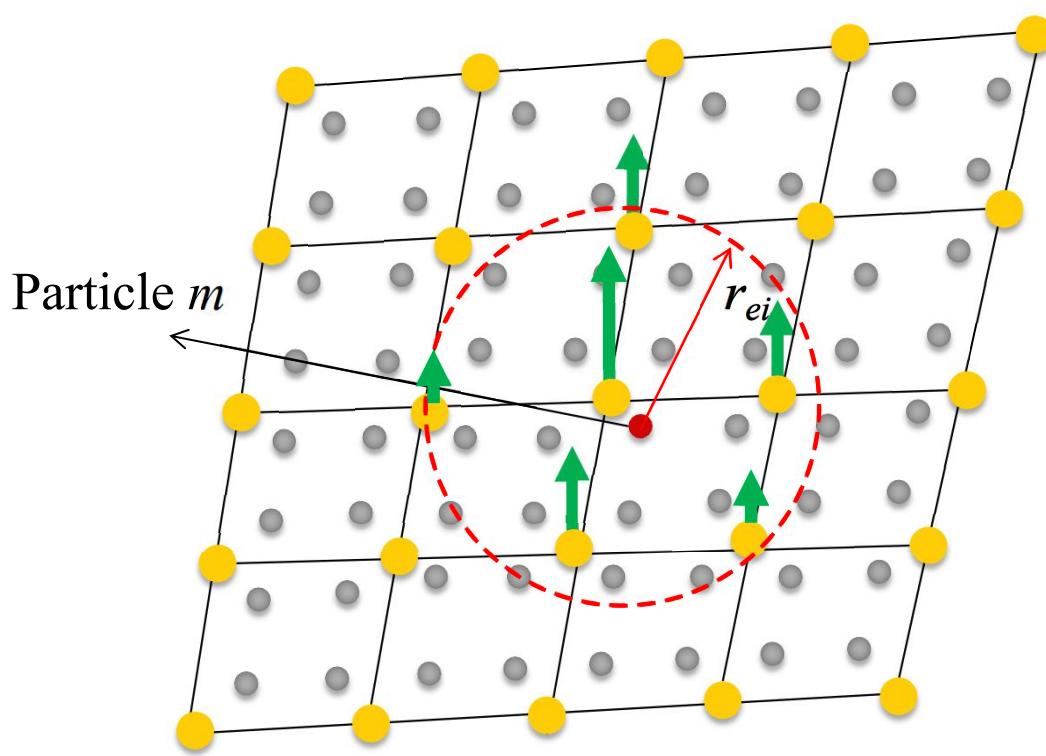
$$\mathbf{F}_s = \mathbf{N}^T \mathbf{R}_j \quad (j = 1, 2 \dots n)$$

Force subcomponent of particle  $j$      $\mathbf{R}_j = \mathbf{P}_j \cdot \mathbf{l}_0^2$

# Data transmission on F-S interface

- Kernel function based interpolation technique

- Displacement interpolation on the F-S interface:



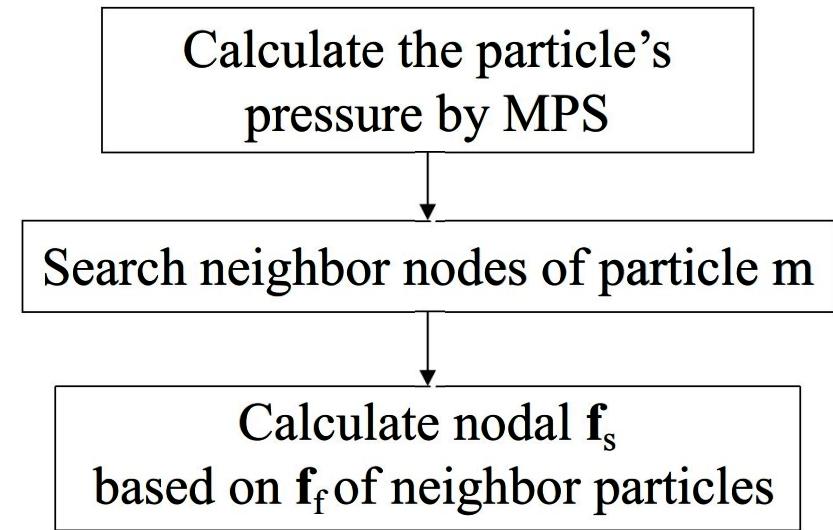
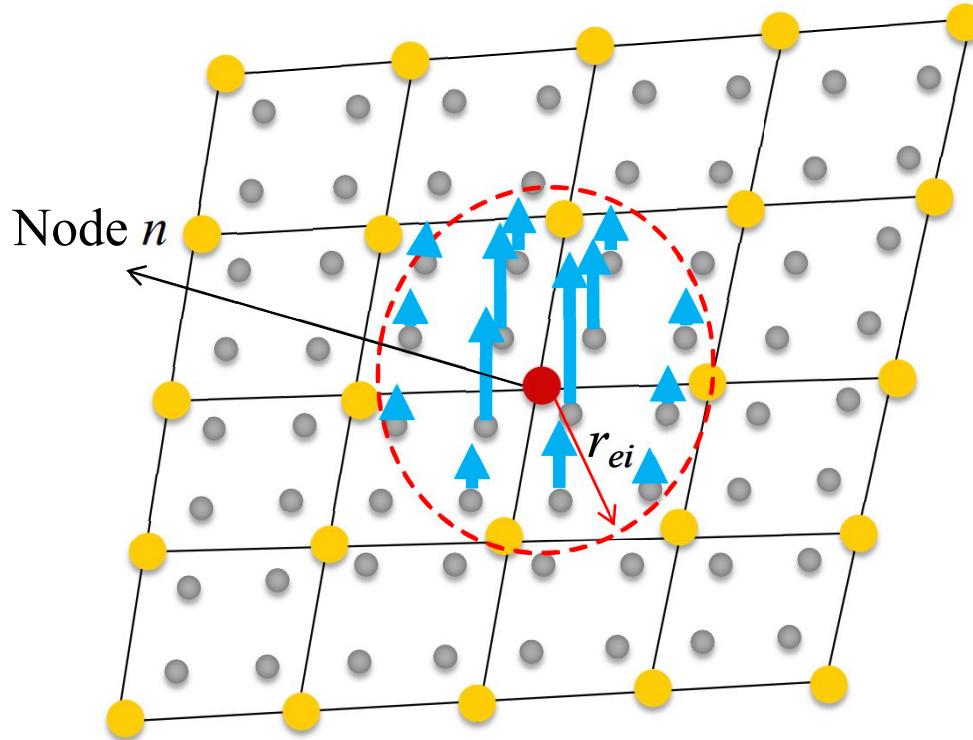
$$w_m = \frac{\sum_i \delta_i \cdot W(|\mathbf{r}_i - \mathbf{r}_m|)}{\sum_i W(|\mathbf{r}_i - \mathbf{r}_m|)}$$

$$W(r) = \begin{cases} \frac{r_e}{0.85r + 0.15r_e} - 1 & 0 \leq r < r_e \\ 0 & r_e \leq r \end{cases}$$

# Data transmission on F-S interface

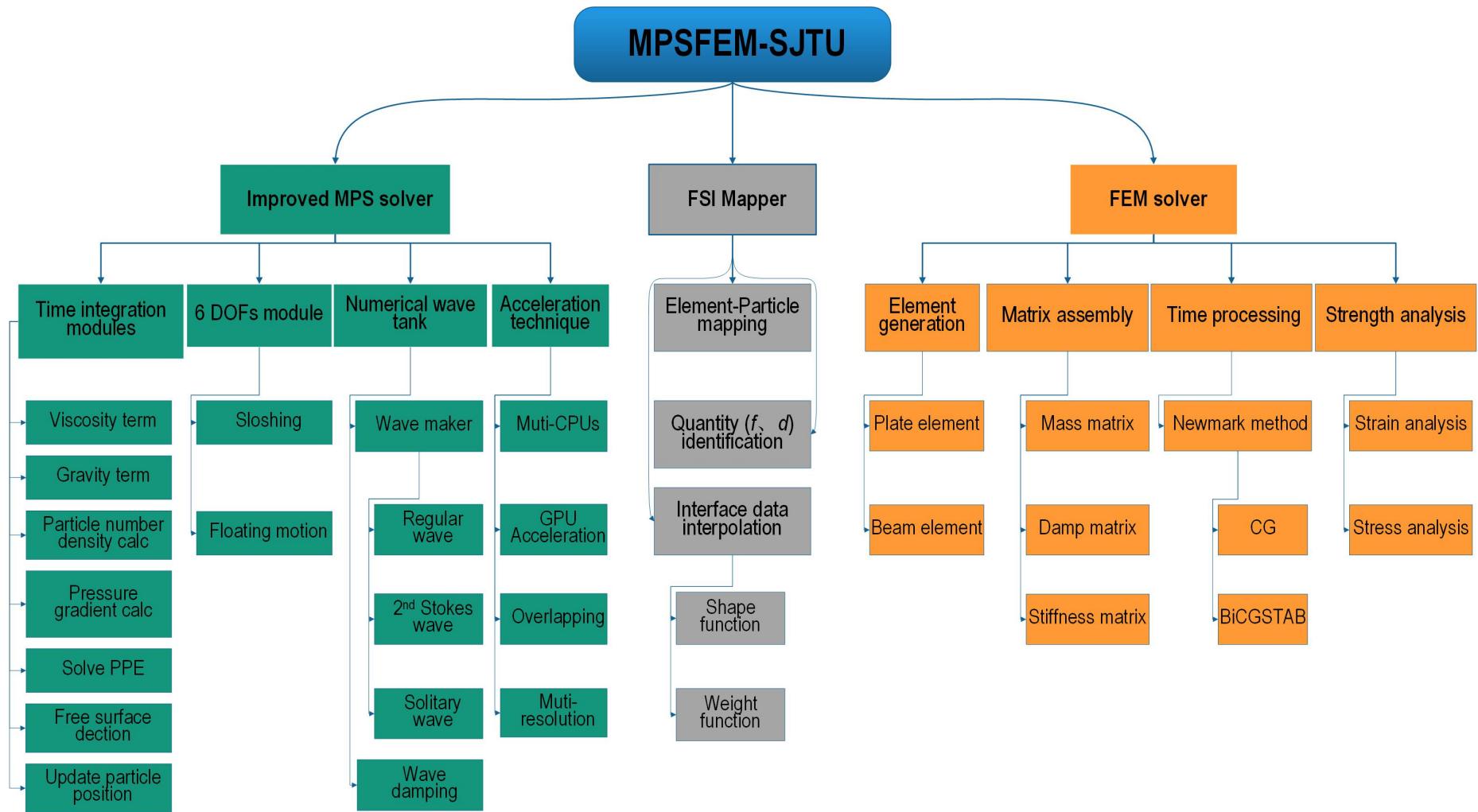
- Kernel function based interpolation technique

- Force interpolation on the F-S interface:



$$F_n = \frac{\sum_i P_i \cdot l_0^2 \cdot W(|\mathbf{r}_i - \mathbf{r}_n|)}{\sum_i W(|\mathbf{r}_i - \mathbf{r}_n|)}$$

# FSI solver- Framework

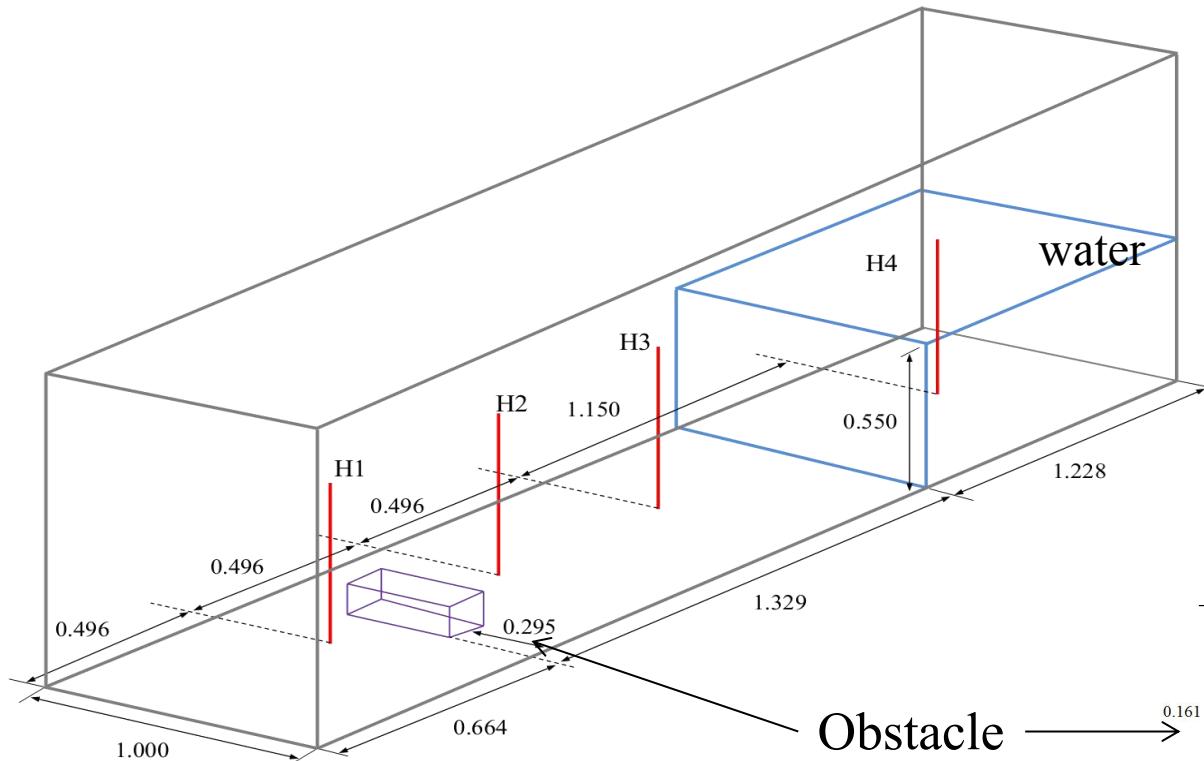


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# Validation of solver-MPS

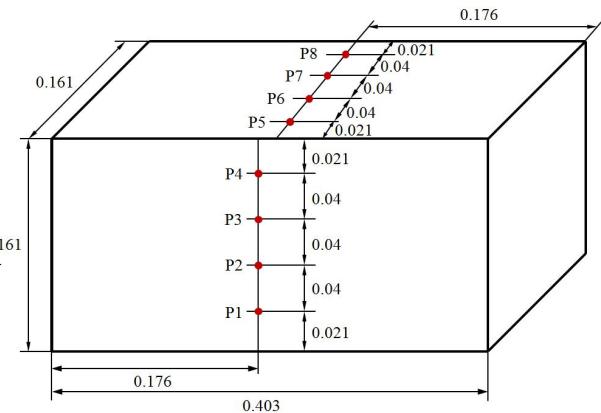
- MPS method for dam-break flow in rigid tank



Schematic diagram of 3D tank

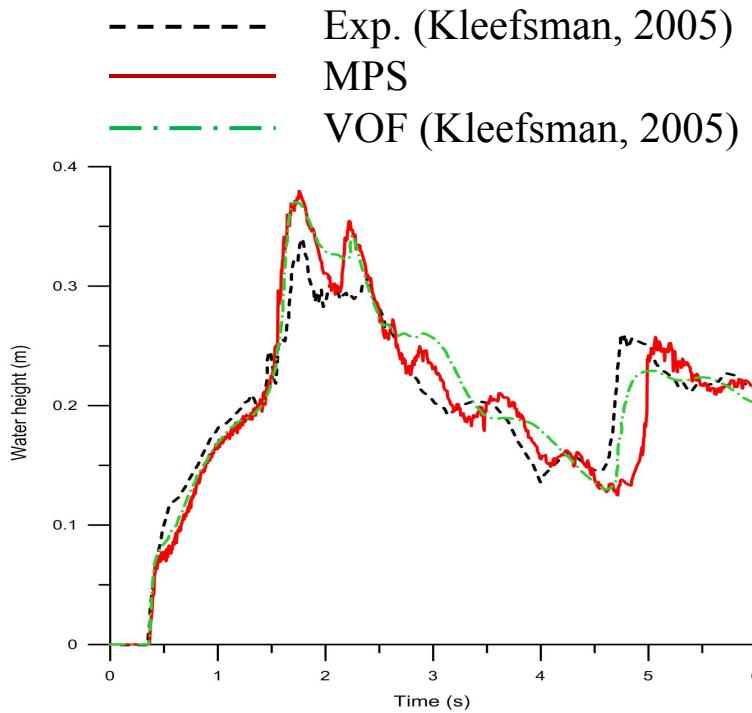
## Particle size

$N_{\text{total}}$	1.01 million
$N_{\text{fluid}}$	0.67 million
$N_{\text{wall}}$	0.33 million
$l_0$	0.01 m

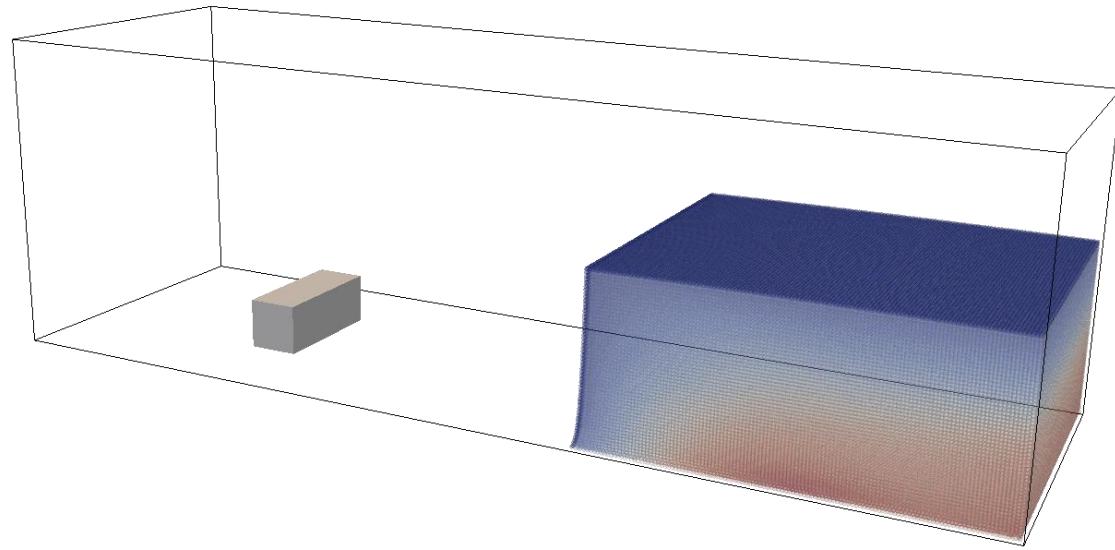


# Validation of solver-MPS

- MPS method for dam-break flow in rigid tank



Comparison of wave height (H2)



Animation of dam break

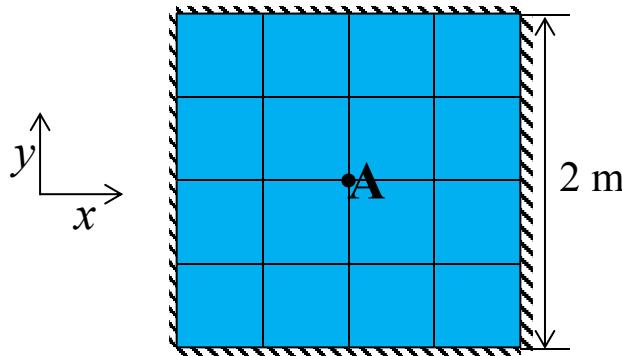
Zhang Yuxin. Improved MPS Method and Its 3D Parallel Computation. Shanghai: Shanghai Jiao Tong University, 2014.

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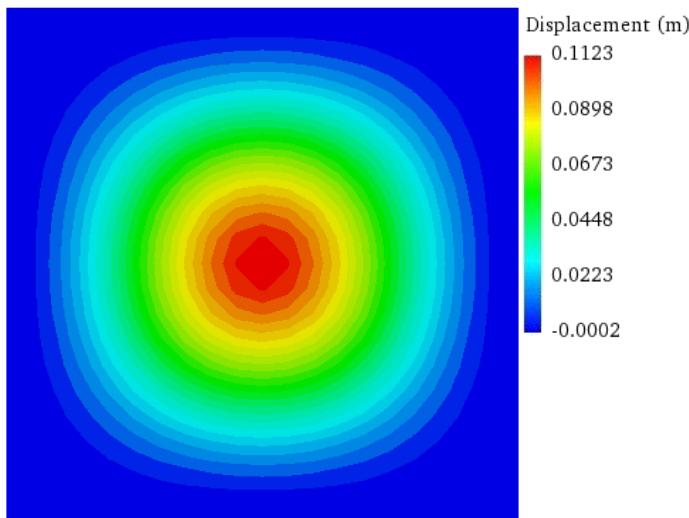
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# Validation of solver-FEM

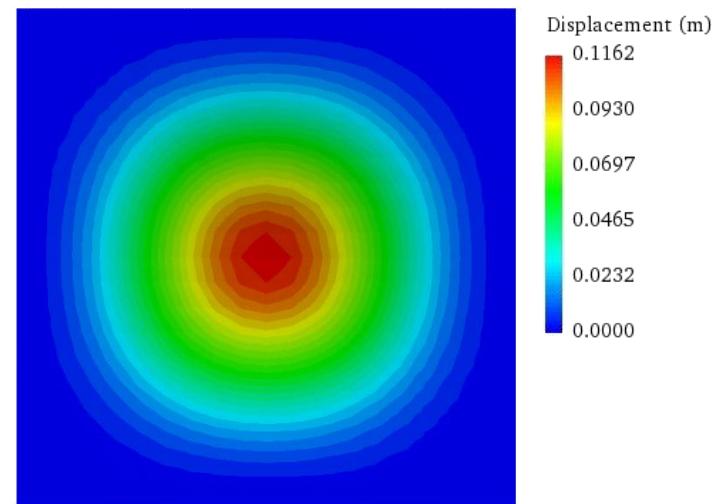
## ● FEM method for structural response



**Elements:**  $20 \times 20$       **Thickness:** 1 mm  
**Density:**  $1800 \text{ kg/m}^3$       **Stiffness:**  $E = 40 \text{ GPa}$   
**Poisson's ratio:** 0.3  
**Constraint:** boundary nodes fixed with six DoFs  
**Load:** force applied at the point A  $f(z, t) = 10 \text{ N}$



(a) Calculated by ANSYS

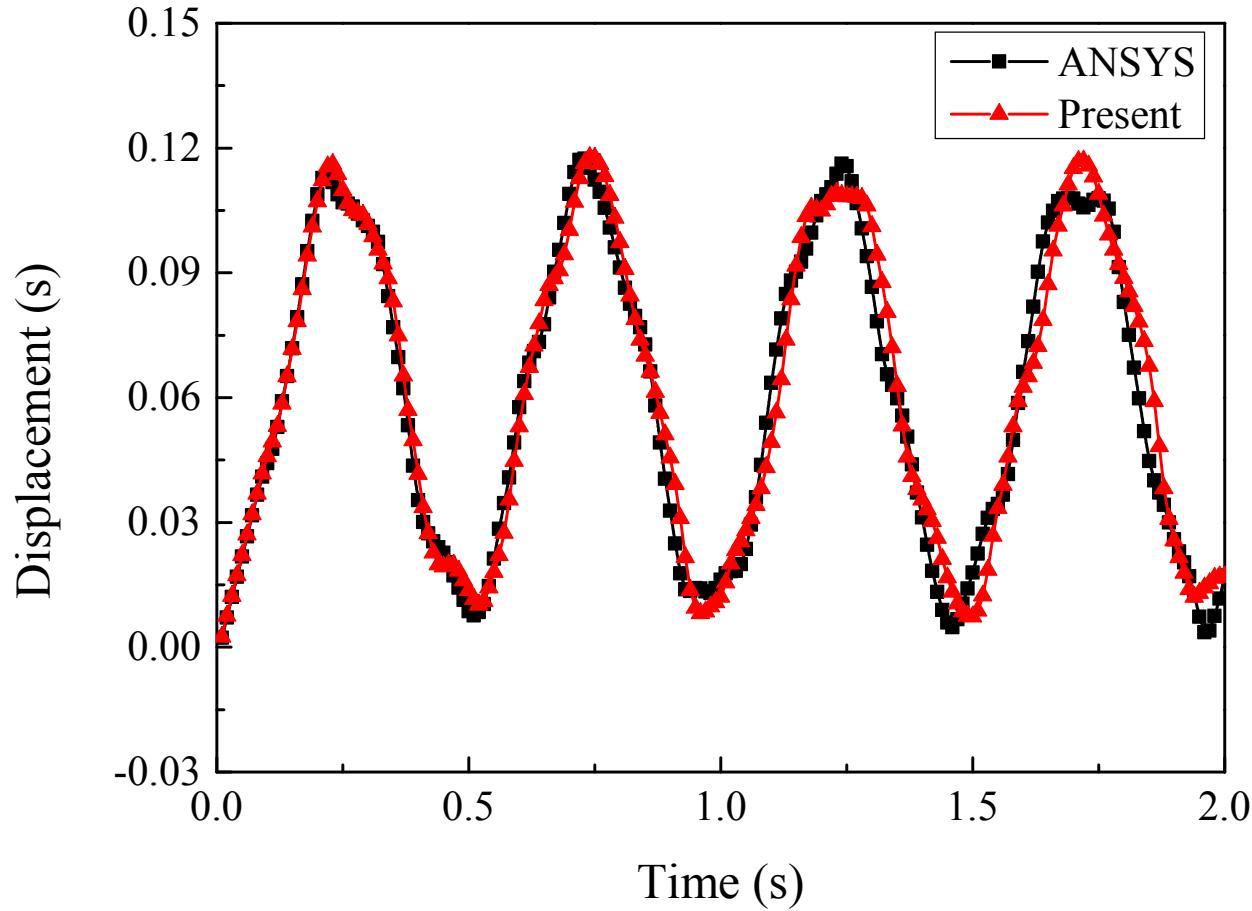


(b) Present solver

Contours of Structural deformation at  $t = 0.75 \text{ s}$

# Validation of solver-FEM

- FEM method for structural response



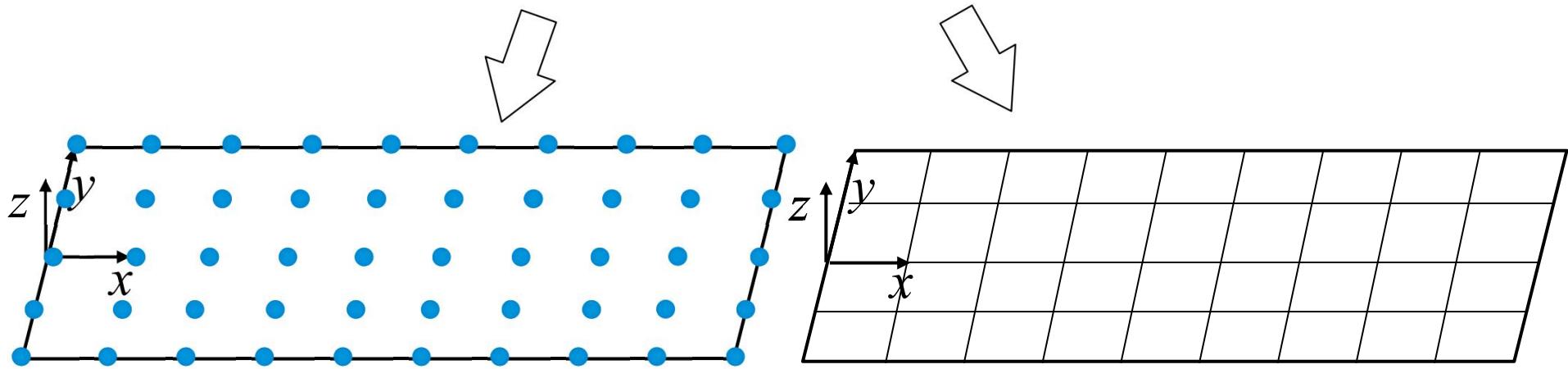
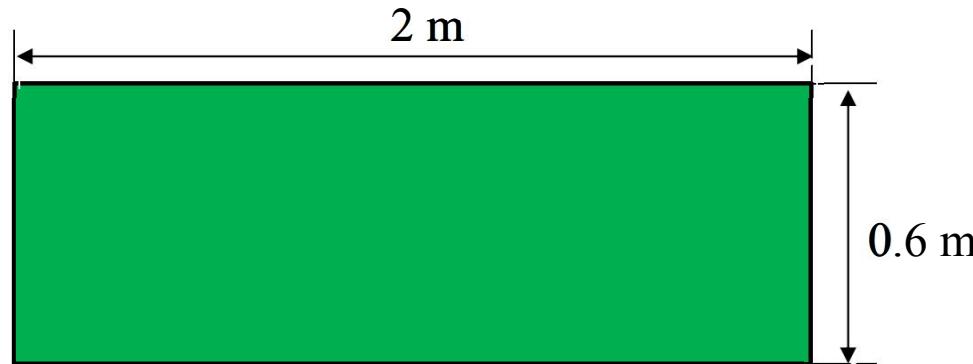
Comparison of time histories of structure vibrations at the measuring point A

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# Validation of solver-Data transmission

## Fluid and structure boundary models



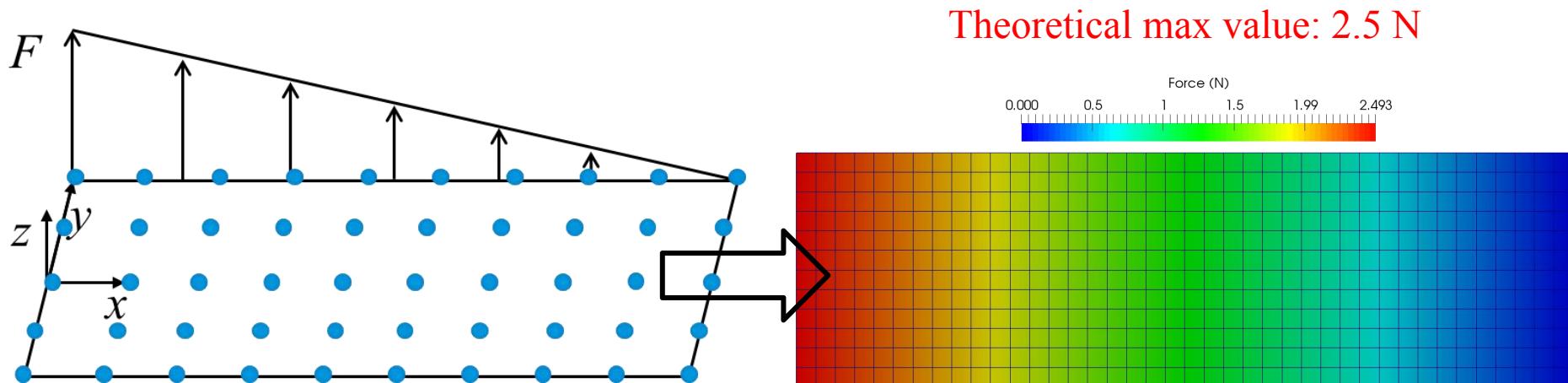
particle model (spacing size  $l_0=0.02$  m)

element model (spacing size  $l_s$  m)

- Data transmission between F-S boundaries

***Test 5: Force transmission from fluid particles to structure nodes***

Force distribution function  $F=1000-500x$



Initial force distribution on particle model

Force distribution on element model after transmission

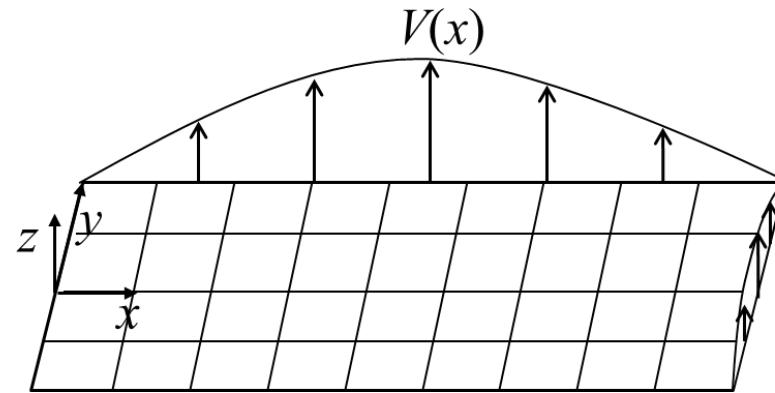
- Data transmission between F-S boundaries

***Test 6: Displacement transmission from structure nodes to fluid particles***

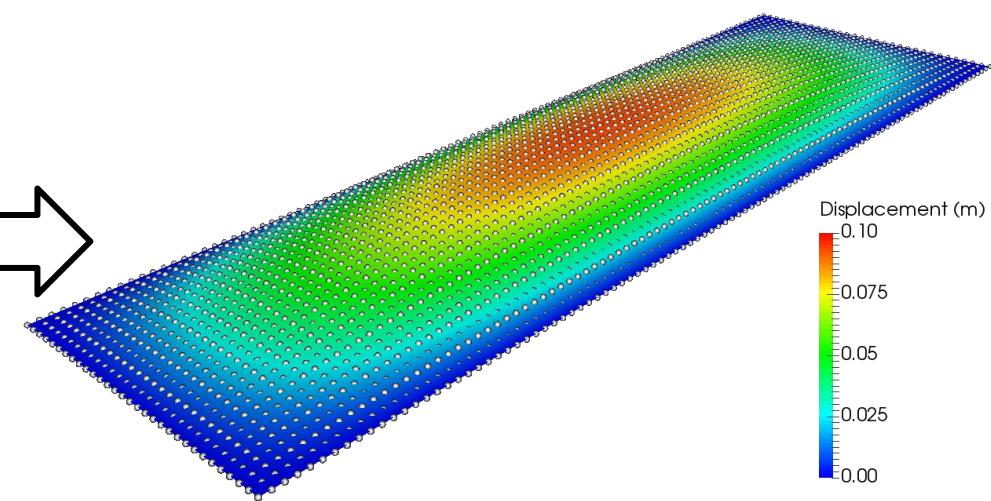
Displacement distribution function

$$V = 2\pi f(x)f(y)\cos(\omega t)$$

$$\text{where } f(x) = 2x - x^2, f(y) = 1 - \frac{100}{9}y^2$$



Initial displacement distribution on element model



Deformation of the particle model and element model after transmission ( $t=0.12s$ )

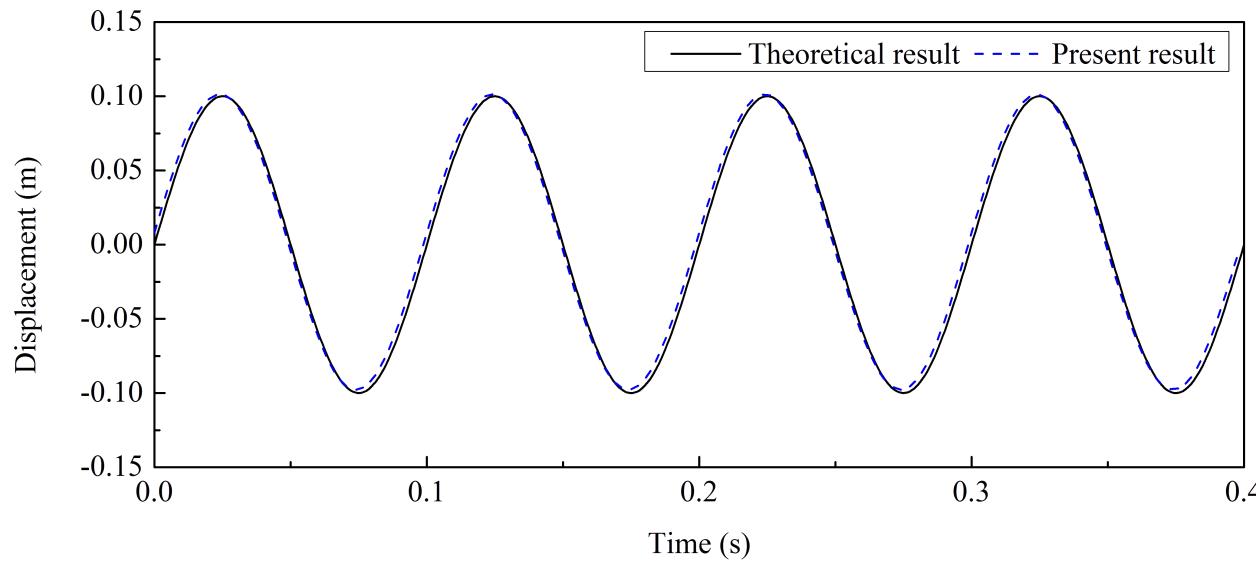
- Data transmission between F-S boundaries

***Test 6: Displacement transmission from structure nodes to fluid particles***

Displacement distribution function

$$V = 2\pi f(x)f(y)\cos(\omega t)$$

$$\text{where } f(x) = 2x - x^2, f(y) = 1 - \frac{100}{9}y^2$$



Displacement of the geometric center point of the **particle** model

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# Validation of solver-Data transmission

***Test 3: Displacement transmission from structure nodes to fluid particles (Shape function based data transmission technique)***

Test conditions:

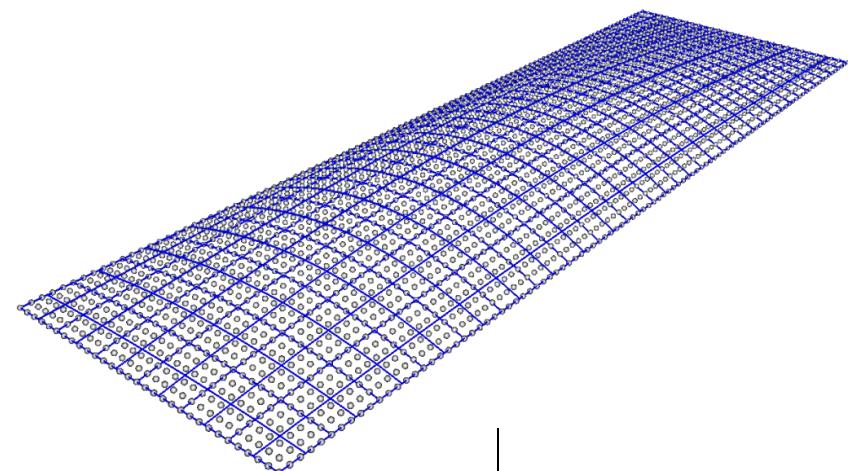
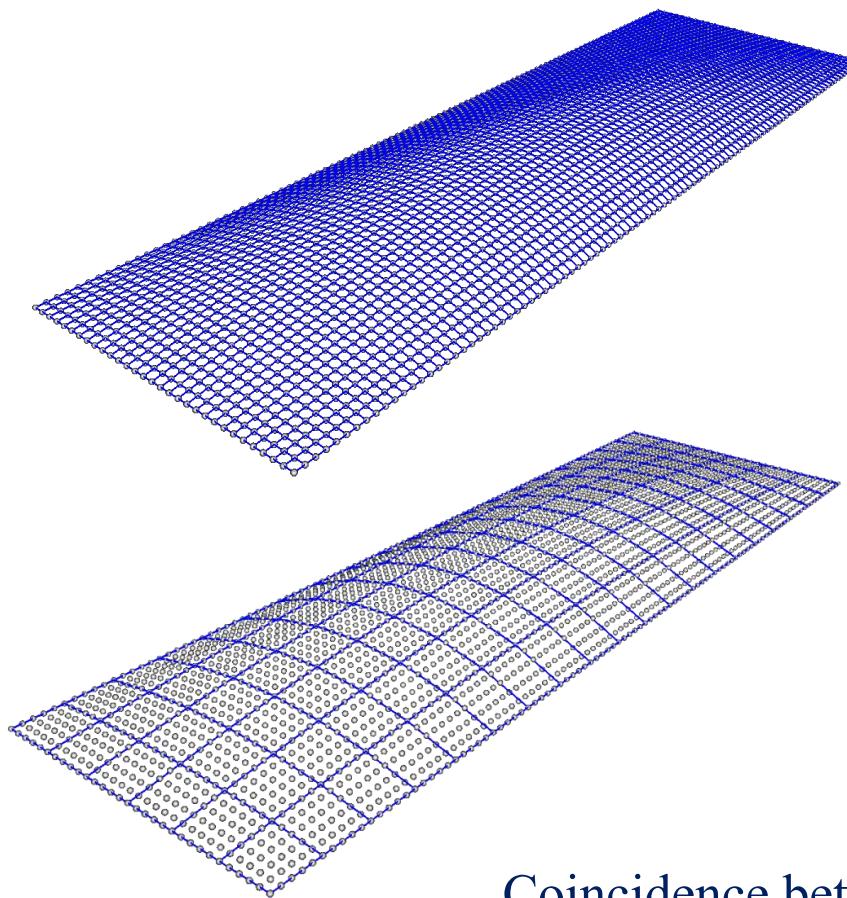
spacing size of particle model  $l_0=0.02$  m

spacing size of element model  $dx \times dy$

Case	1	2	3
$dx \times dy$	$0.02 \times 0.02$	$0.05 \times 0.05$	$0.1 \times 0.1$
$Nx \times Ny$	$1 \times 1$	$2.5 \times 2.5$	$5 \times 5$

# Validation of solver-Data transmission

***Test 3: Displacement transmission from structure nodes to fluid particles (Shape function based data transmission technique)***



Case 1  
 $0.02 \times 0.02$

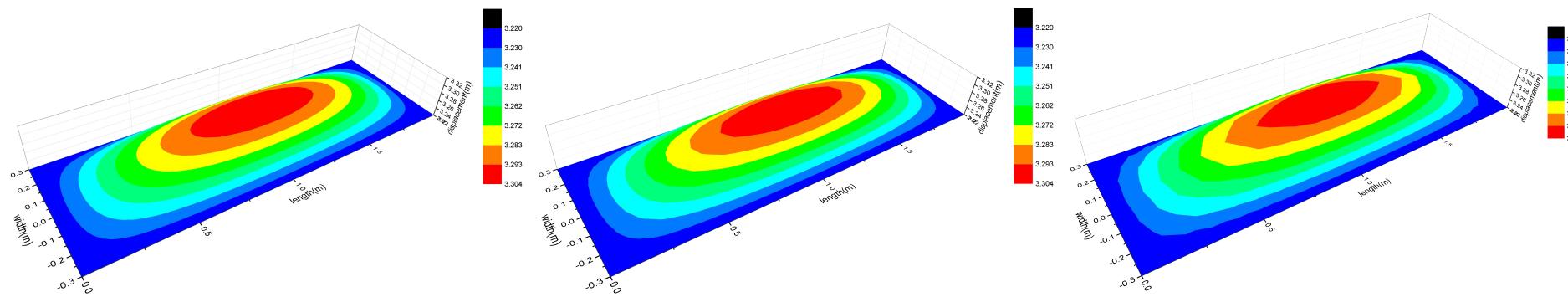
Case 3  
 $0.1 \times 0.1$

Case 2  
 $0.05 \times 0.05$

Coincidence between particle and element boundaries

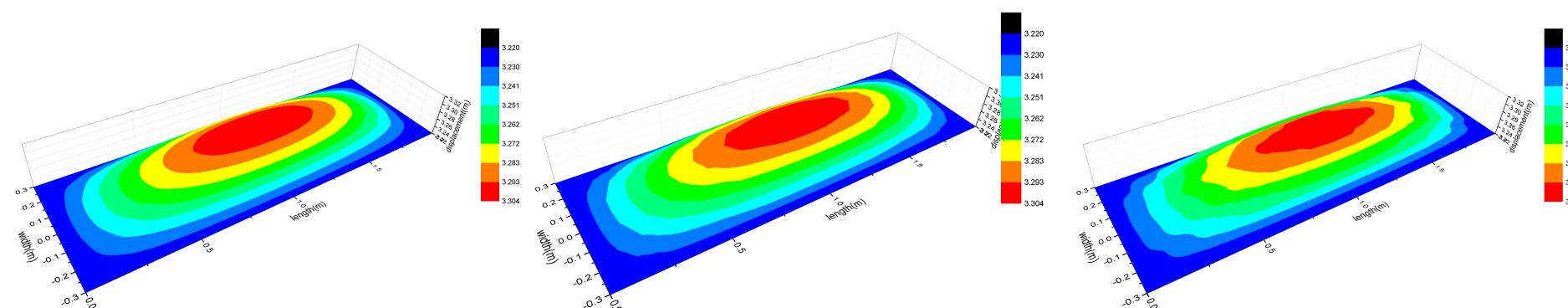
# Validation of solver-Data transmission

- Comparison of displacement distribution



Displacement distribution on element boundary

Displacement distribution on particle boundary



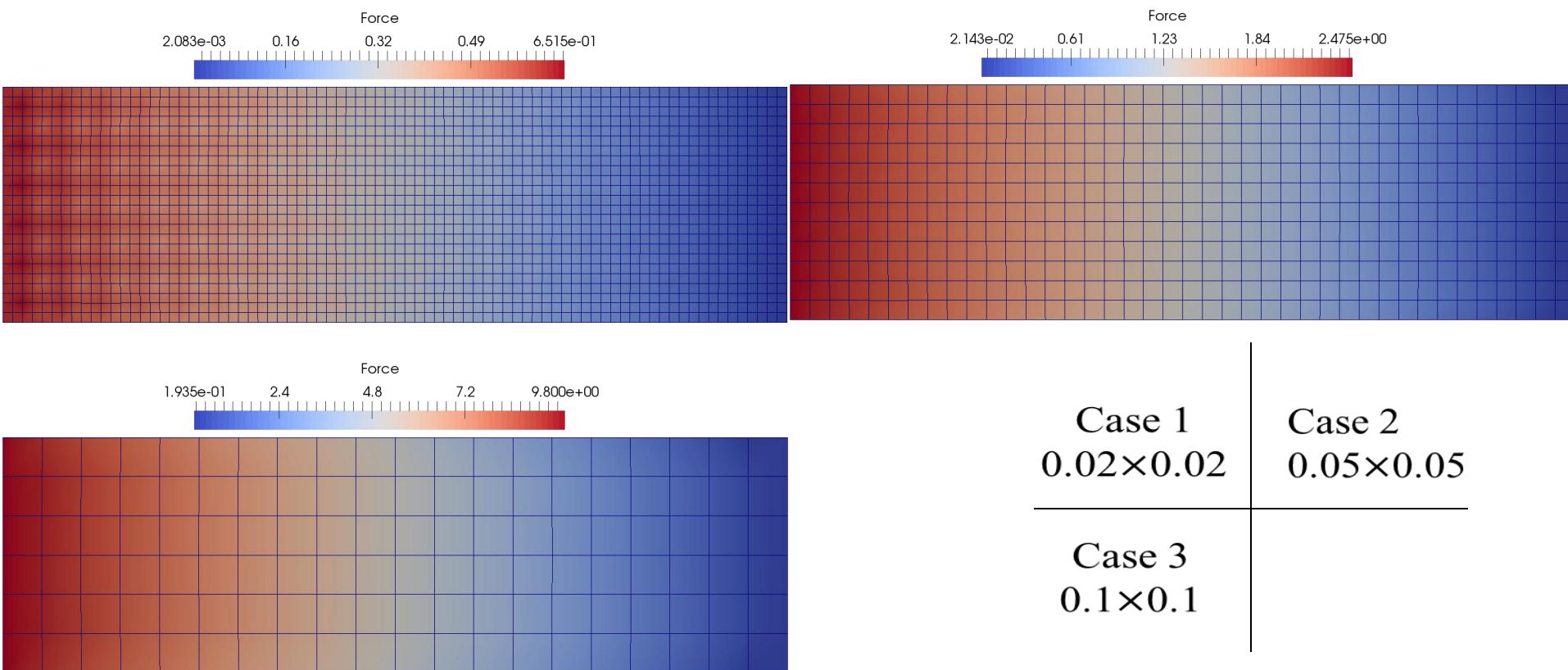
Case 1:  $0.02 \times 0.02$

Case 2:  $0.05 \times 0.05$

Case 3:  $0.1 \times 0.1$

# Validation of solver-Data transmission

***Test 4: force transmission from fluid particles to structure nodes  
(Shape function based data transmission technique)***

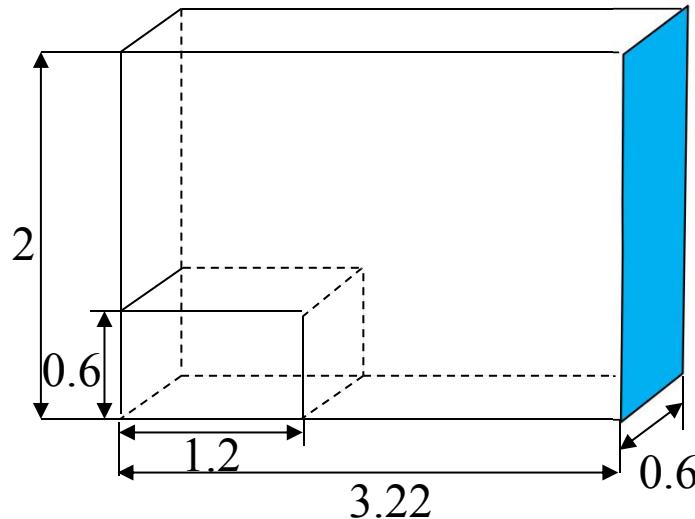


# Contents

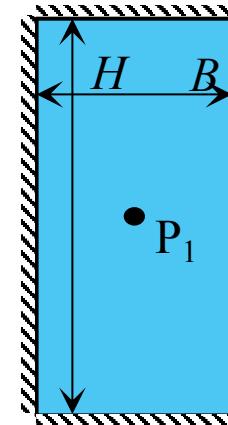
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# Dam-break flow interacting with elastic wall

## ④ Numerical setup



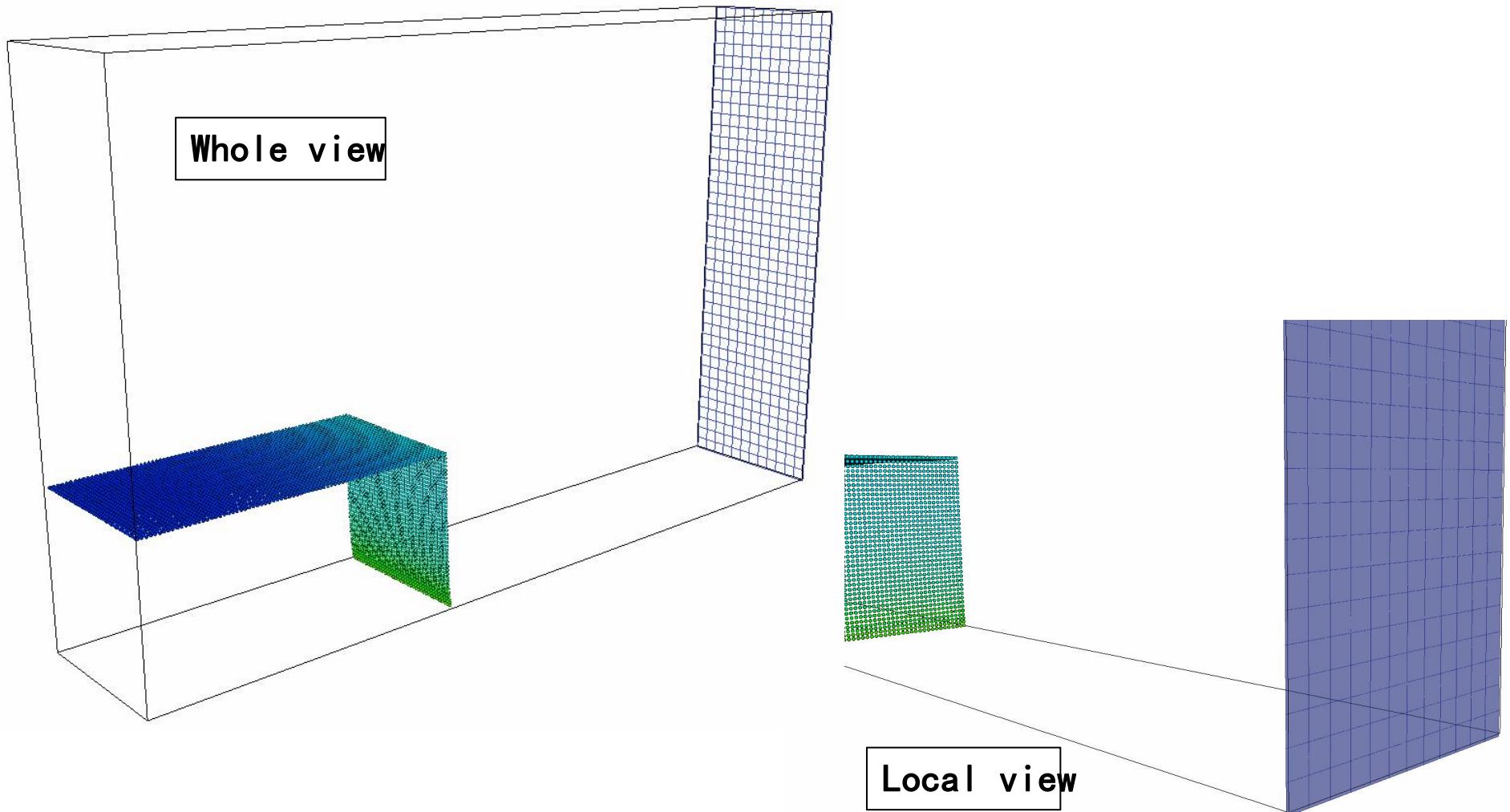
(a) Schematic diagram of tank (Unit: m)



(b) Elastic lateral wall

Fluid parameters	Value	Structural parameters	Value
Fluid density ( $\text{kg}/\text{m}^3$ )	1000	Structure density ( $\text{kg}/\text{m}^3$ )	1800
Kinematic viscosity ( $\text{m}^2/\text{s}$ )	$1 \times 10^{-6}$	Young's modulus (GPa)	40
Gravitational acceleration ( $\text{s}/\text{m}^2$ )	9.81	Poisson's ratio	0.3
Particle spacing (m)	0.03	Element size (m)	0.05
Number of fluid particles	15200	Damping coefficients $\alpha_1$	0.025
Total number of particles	44371	Damping coefficients $\alpha_2$	0.0005
Time step size (s)	$5 \times 10^{-4}$	Time step size (s)	$5 \times 10^{-4}$

# Dam-break flow interacting with elastic wall



Fluid structure interaction process

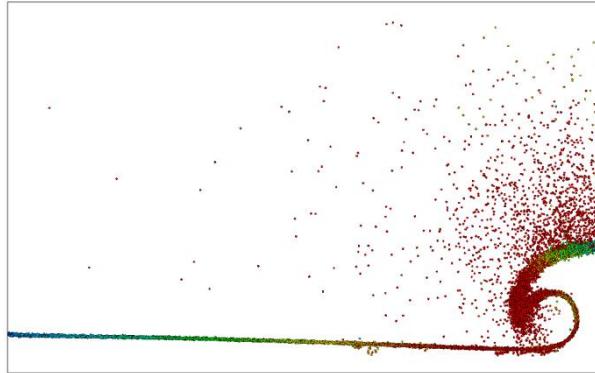
MPS-FEM coupled method for 3-D FSI problems

# Dam-break flow interacting with elastic wall

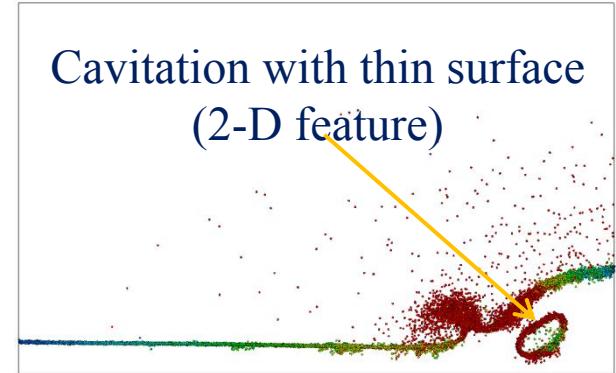
## Evolution of free surface

Rigid wall

$h_r$

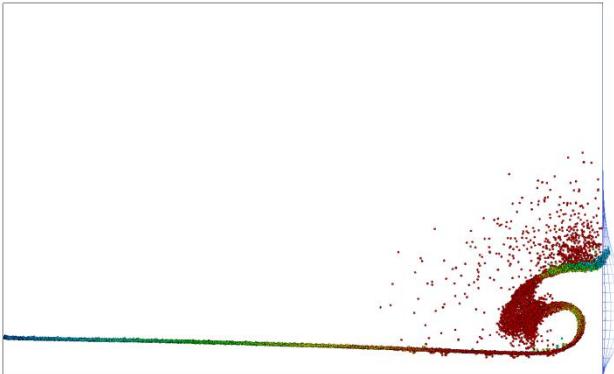


Cavitation with thin surface  
(2-D feature)

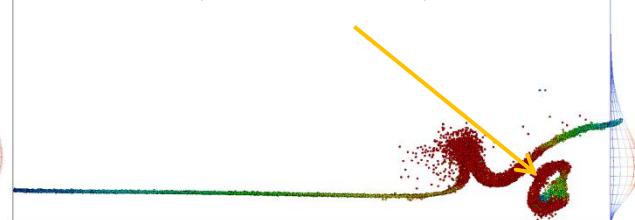


Elastic wall  $h_r > h_e$

$h_e$



Cavitation with thick surface  
(3-D feature)



$t=0.8s$

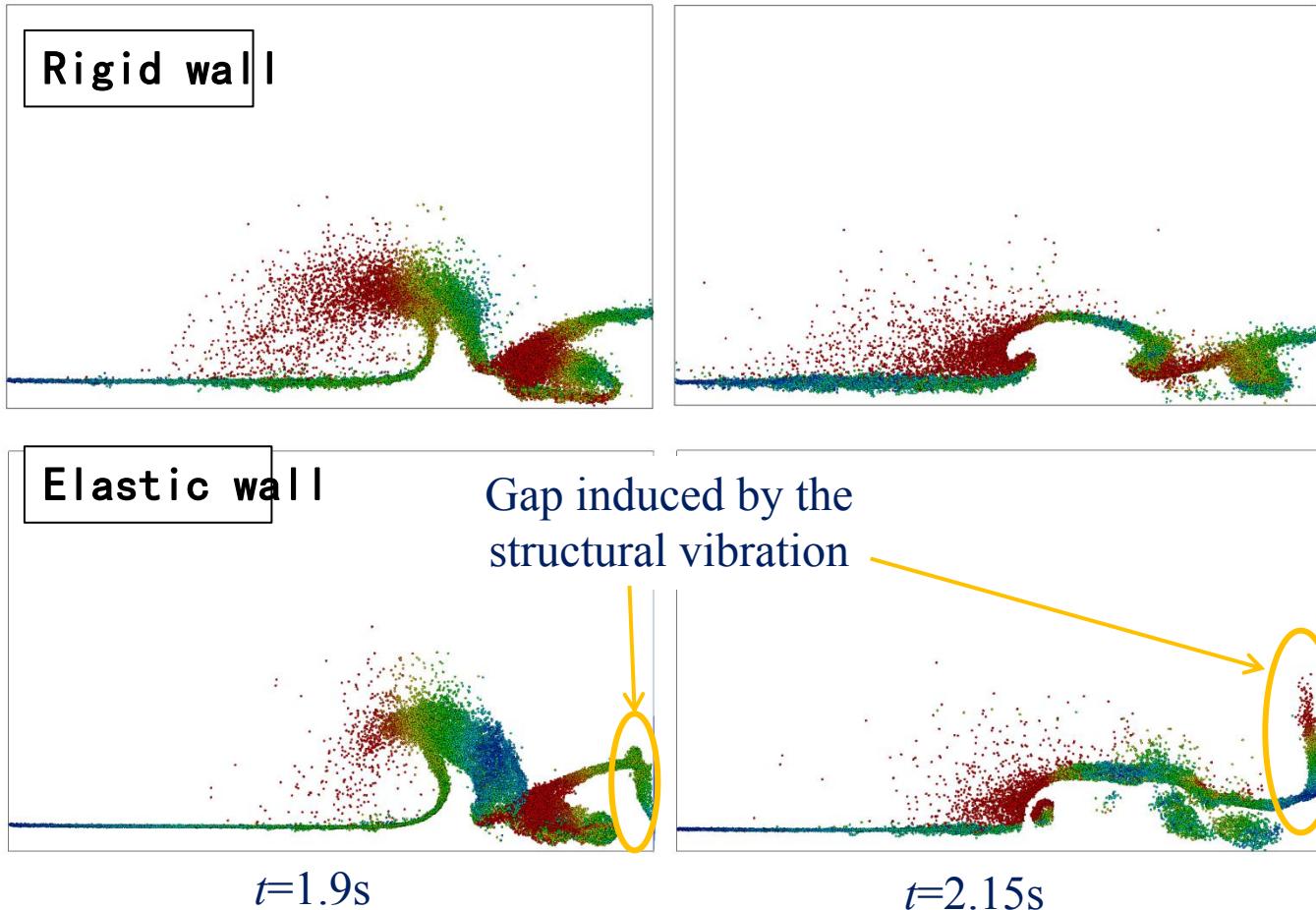
$t=1.4s$

$t=1.6s$

Free surface in side view (top: rigid wall; bottom: elastic wall)

# Dam-break flow interacting with elastic wall

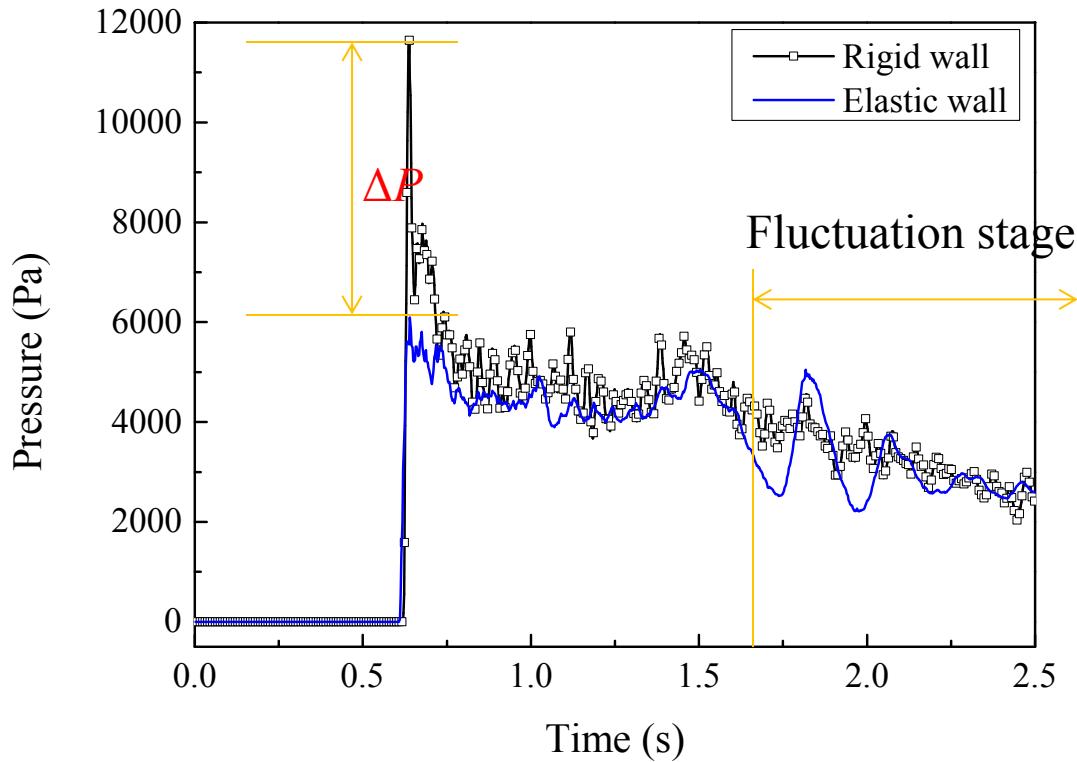
## Evolution of free surface



Free surface in side view (top: rigid wall; bottom: elastic wall)

# Dam-break flow interacting with elastic wall

## Impact loads

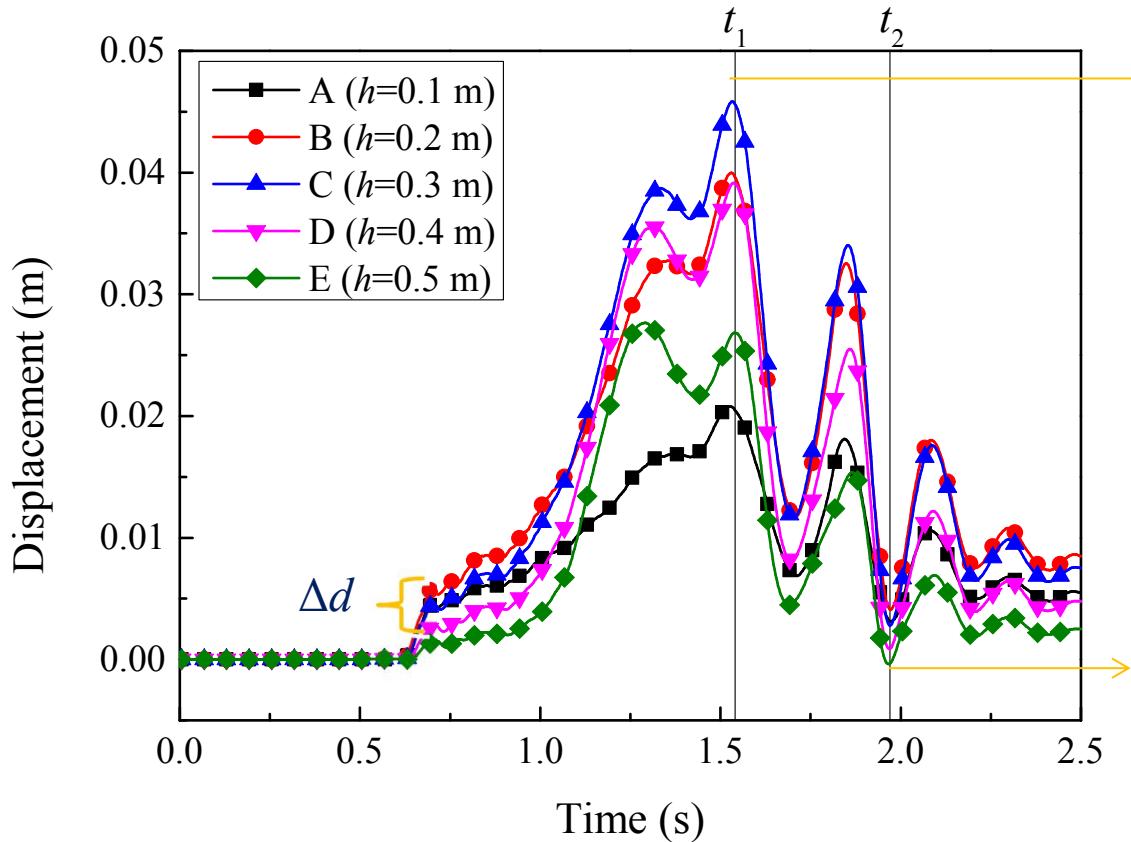


- ✓ The amplitude of slamming pressure ( $6096.89 \text{ Pa}$ ) concerning the elastic tank is 47.77% smaller than that of rigid tank ( $11673 \text{ Pa}$ )

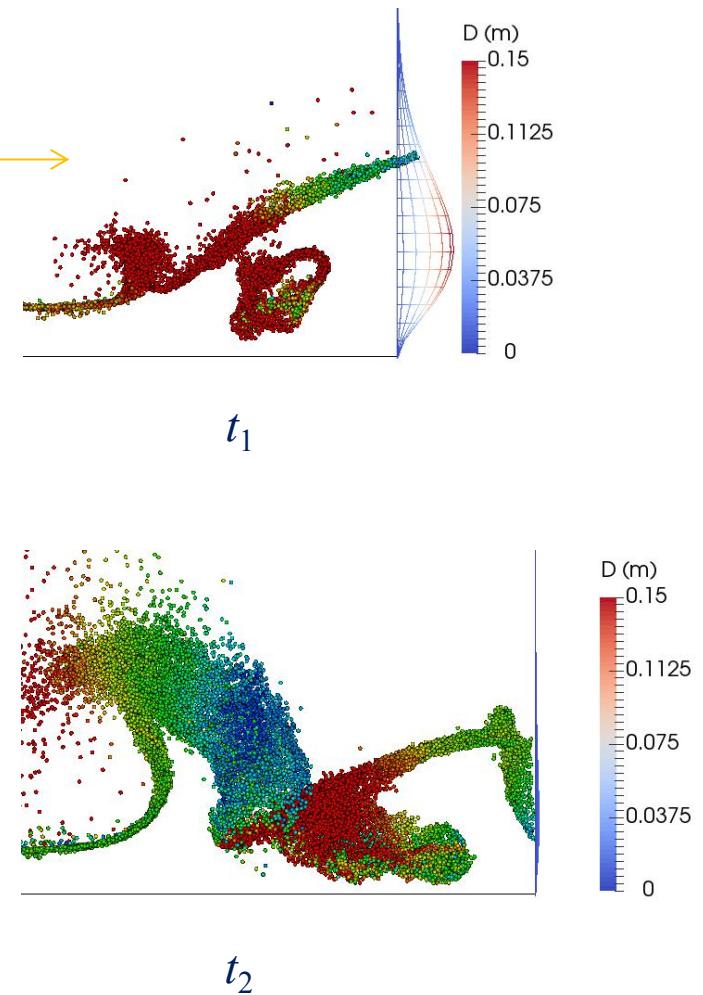
- ✓ The pressure curve fluctuates after the instance 1.5 s.

# Dam-break flow interacting with elastic wall

## Vibrations of elastic wall



Time histories of structural vibrations



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# Conclusions

- An in-house solver based on the fully Lagrangian MPS-FEM coupled method for FSI problems with free surface, is developed.
- Two techniques, the kernel function and the shape function based interpolation techniques, for the data transmission between the fluid and structure boundaries are proposed.
- Accurate fluid force and structure displacement interpolation results can be achieved by the two techniques.
- With the help of the two data transmission techniques, the 3-D dam-break FSI problem can be simulated by the coupled MPS-FEM method.

# Thank You !

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