VLLM Team

Resources used:

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- https://docs.docker.com/engine/daemon/
- https://docs.docker.com/engine/install/linux-postinstall/
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- https://askubuntu.com/questions/1451716/name-of-internal-hard-drive-keeps-changing
- https://github.com/dusty-nv/jetson-containers/issues/441
- https://github.com/dusty-nv/jetson-containers/issues/687
- https://github.com/dusty-nv/jetson-inference/blob/master/docs/aux-streaming.md
- https://www.jetson-ai-lab.com/agent_studio.html
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- https://pypi.org/project/pygtail/
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- https://github.com/ThuCCSLab/FigStep?tab=readme-ov-file
- https://github.com/NVIDIA-AI-IOT/ros2_nanollm
- https://stackoverflow.com/questions/13564851/how-to-generate-keyboard-events
- https://github.com/asweigart/pyautogui
- https://github.com/boppreh/keyboard
- https://forums.developer.nvidia.com/t/vlm-refresh-rate/315785

ROS Team

Resources Used:

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- https://releases.ubuntu.com/jammy/
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- https://github.com/eProsima/Fast-DDS/security/advisories/GHSA-v5r6-8mvh-cp98
- https://github.com/eProsima/Fast-DDS/security/advisories/GHSA-qcj9-939p-p662
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- https://github.com/ROBOTIS-GIT/turtlebot3/blob/main/turtlebot3_teleop/turtlebot3_teleop/script/teleop_keyboard.py
- https://discourse.ros.org/t/giving-a-turtlebot3-a-namespace-for-multi-robot-experiments/10756
- https://gazebosim.org/docs/latest/ros_installation/

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