ROS Team

Resources Used:

- https://github.com/SPIRE-GMU/MRS Security
- https://arxiv.org/html/2402.10340v4
- https://www.mankier.com/1/v4l2-ctl
- https://emanual.robotis.com/docs/en/platform/turtlebot3/quick-start/
- https://wiki.ros.org/ROS/EnvironmentVariables#:~:text=Node%20Environment%20Variables-,ROS IP/ROS HOSTNAME,talk%20to%20your%20local%20component

VLLM Team

- https://docs.docker.com/engine/daemon/
- https://docs.docker.com/reference/cli/dockerd/#environment-variables
- https://www.jetson-ai-lab.com/tutorial Ilava.html
- https://askubuntu.com/questions/1351780/my-external-drive-used-to-be-auto-mounted-w ith-a-certain-name-and-now-its-auto
- https://askubuntu.com/questions/1451716/name-of-internal-hard-drive-keeps-changing
- https://askubuntu.com/questions/1351855/cheese-will-start-from-terminal-but-not-main-menu-on-20-04
- https://stackoverflow.com/questions/66589238/jpeg-parameter-struct-mismatch-library-th-inks-size-is-584-caller-expects-728-f
- https://askubuntu.com/questions/194510/how-to-edit-label-of-usb-drive