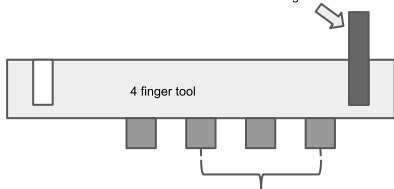
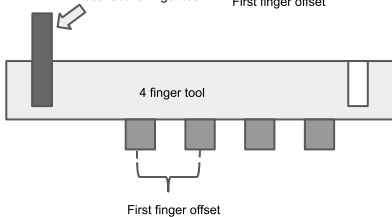


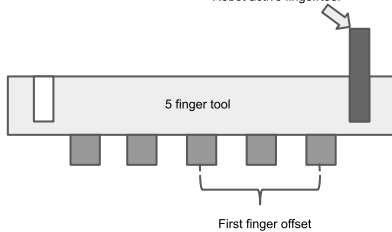
Robot active finger/tool



Robot active finger/tool



Robot active finger/tool



The first finger offset is the distance of the tool middle point to the first finger middle point