```
ln[1]:= fn = -3.0 * x_3 * x_1^2 + 7.5 * x_2^2 - 5.0 * x_1^2;
  ln[2]:= g_1 = \sqrt{x_1} - 4. * x_2^2 - 2 * x_3;
          g_2 = 6.0 * x_3^2 - 1.2 * x_1^2 + 3.0 * x_3 * x_2;
  ln[4]:= Minimize[{fn, g_1 \ge 0, g_2 \ge 0, 1.899` - x_1 \ge 0, x_1 \ge 0.001`,
              1.699 -x_2 \ge 0, x_2 \ge 0.001, 0.899 -x_3 \ge 0, x_3 \ge 0.001, \{x_1, x_2, x_3\}
 \texttt{Out[4]=} \ \left\{ -\text{10.9835, } \{ x_1 \rightarrow \text{1.28349, } x_2 \rightarrow \text{0.0550422, } x_3 \rightarrow \text{0.560397} \} \right\}
  In[5]:= SeedRandom[4];
  In[6]:= (* Initialization *)
  ln[7]:= n = 3; m = 2; K = 3; \tilde{N}_1 = 10; \tilde{N}_2 = 10; \tilde{N}_3 = 10; pos = 1;
  In[8]:= Pos = pos;
  ln[9]:= \tau = 0.95; \gamma 1 = 0.98;
 In[10]:= (* Box constraints. *)
 ln[11] := a_1 = 0.001; a_2 = 0.001; a_3 = 0.001;
 ln[12] = \Delta_1 = 1.9; \Delta_2 = 1.4; \Delta_3 = 0.9; q1 = 0.59; qq2 = 1.0; TOL = 1.0 \times 10^{-7};
 In[13]:= b_i := q1 * \Delta_i
 In[14]:= \{b_1, b_2, b_3\}
Out[14]=
           {1.121, 0.826, 0.531}
 In[15]:= \mu_{1,1} = a_1
          \mu_{2,1} = a_2
          \mu_{3,1} = a_3
Out[15]=
          0.001
Out[16]=
          0.001
Out[17]=
          0.001
 In[18]:= \mu_{i_-,k_-} := \mu_{i_+,k-1} + \frac{b_i - a_i}{(K-1)}
 In[19]:=\{\{\mu_{1,1}, \mu_{1,2}, \mu_{1,3}\}, \{\mu_{2,1}, \mu_{2,2}, \mu_{2,3}\}, \{\mu_{3,1}, \mu_{3,2}, \mu_{3,3}\}\}
Out[19]=
           \{\{0.001, 0.561, 1.121\}, \{0.001, 0.4135, 0.826\}, \{0.001, 0.266, 0.531\}\}
 In[20]:= \delta_{i_{-},k_{-}} := \frac{\mu_{i,k+1} - \mu_{i,k}}{\tilde{N}_{i}}
```

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\ln[21]:= \{\{\delta_{1,1}, \delta_{1,2}, \delta_{1,3}\}, \{\delta_{2,1}, \delta_{2,2}, \delta_{2,3}\}, \{\delta_{3,1}, \delta_{3,2}, \delta_{3,3}\}\}
Out[21]=
           \{\{0.056, 0.056, 0.056\}, \{0.04125, 0.04125, 0.04125\}, \{0.0265, 0.0265, 0.0265\}\}
 In[22]:= \mathbf{cx_i} := \mathbf{x_i} \rightarrow (\mathbf{b_i})
 ln[23]:= cl_i := \{b_i - x_i \ge 0, x_i \ge a_i\}
 ln[24]:= xz = Flatten[Table[\{cx_i\}, \{i, 1, 3\}]]
Out[24]=
           \{x_1 \rightarrow 1.121, x_2 \rightarrow 0.826, x_3 \rightarrow 0.531\}
 In[25]:= f = Simplify [(fn /. xz) + \sum_{i=1}^{n} (\partial_{x_{jj}} fn /. xz) * (x_{jj} - (x_{jj} /. xz))]
Out[25]=
          5.16979 - 14.7815 x_1 + 12.39 x_2 - 3.76992 x_3
 ln[26]:= Cons = Flatten[Table[cl<sub>i</sub>, {i, 1, 3}]]
Out[26]=
           \{\textbf{1.121} - x_1 \geq \textbf{0,} \ x_1 \geq \textbf{0.001,} \ \textbf{0.826} - x_2 \geq \textbf{0,} \ x_2 \geq \textbf{0.001,} \ \textbf{0.531} - x_3 \geq \textbf{0,} \ x_3 \geq \textbf{0.001}\}
 In[27]:= X0 = 0;
 In[28]:= Constraints = Cons
Out[28]=
           \{\textbf{1.121} - x_1 \geq \textbf{0,} \ x_1 \geq \textbf{0.001,} \ \textbf{0.826} - x_2 \geq \textbf{0,} \ x_2 \geq \textbf{0.001,} \ \textbf{0.531} - x_3 \geq \textbf{0,} \ x_3 \geq \textbf{0.001}\}
 In[29]:= Xy_{i,k} := \mu_{i,k} \le X_i \le \mu_{i,k+1}
 In[30]:= Z_{i,k} = Table \{xy_{i,k}\}, {i, 1, n}, {k, 1, K - 1}
           \{\{\{0.001 \le x_1 \le 0.561\}, \{0.561 \le x_1 \le 1.121\}\},\
            \{\{0.001 \le x_2 \le 0.4135\}, \{0.4135 \le x_2 \le 0.826\}\}, \{\{0.001 \le x_3 \le 0.266\}, \{0.266 \le x_3 \le 0.531\}\}\}
 In[31]:= Clear[i, k, k1, k2, k3];
          GenD := Table[Table[Table[dat[k1, k2, k3] =
                   Table[\{x_1, x_2, x_3, -g_{pos}, f\}, \{x_1, \mu_{1,k1}, \mu_{1,k1+1}, \delta_{1,k1}\}, \{x_2, \mu_{2,k2}, \mu_{2,k2+1}, \delta_{2,k2}\},
                     \{x_3, \mu_{3,k3}, \mu_{3,k3+1}, \delta_{3,k3}\}, \{k1, 1, K-1\}, \{k2, 1, K-1\}, \{k3, 1, K-1\}];
 In[32]:= Clear[i, k, k1, k2, k3]; GenD;
 in[33]:= Gen2 := Table[Table[Table[data[k1, k2, k3] = Flatten[dat[k1, k2, k3], 2], {k1, 1, K - 1}],
                \{k2, 1, K-1\}], \{k3, 1, K-1\}]
 In[34]:= Clear[i, k, k1, k2, k3]; Gen2;
 In[35]:= scut = {}; cnt = 0;
 In[36]:= Initial Solution = Minimize [fn, Constraints, \{x_1, x_2, x_3\}]
           \{-8.28503, \{x_1 \rightarrow 1.121, x_2 \rightarrow 0.000999991, x_3 \rightarrow 0.531\}\}
```

```
In[37]:= XZ = Part[InitialSolution, 2];
        f = Simplify \left[ (fn /. xz) + \sum_{j=1}^{n} (\partial_{x_{jj}} fn /. xz) * (x_{jj} - (x_{jj} /. xz)) \right]
Out[38]=
        10.2869 - 14.7815 x_1 + 0.0149999 x_2 - 3.76992 x_3
 In[39]:= Walues = {Table[(gii /. Part[InitialSolution, 2]), {jj, 1, m}]};
        xx = -Max[-Values]; x0 = xx;
 In[41]:= gCut = ExpandAll
          xx + \sum_{i=1}^{n} (\partial_{x_{jj}} g_{\varphi_{os}} / . Part[InitialSolution, 2]) * (x_{jj} - (x_{jj} / . Part[InitialSolution, 2]))]
Out[41]=
        0.52939 + 0.472245 x_1 - 0.00799993 x_2 - 2 x_3
 In[42]:= Conz = Cons;
 ln[43] := Cons = Join[Cons, {gCut \ge 0}]
Out[43]=
        \{1.121 - x_1 \ge 0, x_1 \ge 0.001, 0.826 - x_2 \ge 0, x_2 \ge 0.001, 
         0.531 - x_3 \ge 0, x_3 \ge 0.001, 0.52939 + 0.472245 x_1 - 0.00799993 x_2 - 2 x_3 \ge 0
 ln[44]:= (*\psi_i := qq2*Part[Part[xz,i],2]*) \psi_i := q1*\Delta_i; b_i := \psi_i;
 In[45]:= \{\psi_1, \psi_2, \psi_3\}
Out[45]=
        {1.121, 0.826, 0.531}
 In[46]:= ialg = 0;
 In[47]:= Off[Set::write]; Off[Join::heads];
 In[48]:= For \int ip = 0, ip \le 28,
        ialg = ialg + 1;
           Print["Upper bound=", \{b_1, b_2, b_3\}];
           Clear[i, k, k1, k2, k3];
          GenD;
           Clear[i, k, k1, k2, k3]; Gen2;
          Clear[ii, k1, k2, k3];
        g2 := Flatten[
              Table[Part[Part[data[k1, k2, k3], i], n + 2], {i, 1, Length[data[k1, k2, k3]]}], 4];
        fodat := Flatten[Table[
               Table[Table[fo[k1, k2, k3] = g^2, {k1, 1, K-1}], {k2, 1, K-1}], {k3, 1, K-1}], 1];
        evdat := Flatten[Table[Table[Table[ev[k1, k2, k3] =
                   Table [Abs[\tau * Min[fo[k1, k2, k3]] - Part[Part[data[k1, k2, k3], ii], n + 2]], {ii, 1,}
                      Length[data[k1, k2, k3]]}], {k1, 1, K-1}], {k2, 1, K-1}], {k3, 1, K-1}], 2];
        epos := Flatten[Table[Table[Table[
                  eo3[k1, k2, k3] = Part[Flatten[Position[ev[k1, k2, k3], Min[ev[k1, k2, k3]]]], 1],
```

```
\{k1, 1, K-1\}], \{k2, 1, K-1\}], \{k3, 1, K-1\}], 2];
kdata[k1_, k2_, k3_] := Module[{tt}, Part[data[k1, k2, k3], Part[eo3[k1, k2, k3]]]];
kkdat := Flatten[Table[Table[Kdat[k1, k2, k3] = kdata[k1, k2, k3], {k1, 1, K - 1}],
        \{k2, 1, K-1\}], \{k3, 1, K-1\}], 2];
   fodat;
mxqdat;
evdat;
epos;
kkdat;
kx[0, k1_, k2_, k3_] := Part[kdat[k1, k2, k3], n + 1];
   kx[1, k1_, k2_, k3_] := Part[kdat[k1, k2, k3], 1];
kx[2, k1_, k2_, k3_] := Part[kdat[k1, k2, k3], 2];
kx[3, k1_, k2_, k3_] := Part[kdat[k1, k2, k3], 3];
Clear[kkcon];
   kkcon[k1 , k2 , k3 ] := Module[{tt},
     \{kx[0, k1, k2, k3], kx[1, k1, k2, k3], kx[2, k1, k2, k3], kx[3, k1, k2, k3]\}\}
kconst := Flatten[Table[
      Table[Table[kkcon[k1, k2, k3], {k1, 1, K-1}], {k2, 1, K-1}], {k3, 1, K-1}], 2];
kconst;
px_{i_{-},k1_{-},k2_{-},k3_{-}} := x_{i} \rightarrow kx[i, k1, k2, k3];
rr_{k1_{-},k2_{-},k3_{-}} := \{px_{1,k1,k2,k3}, px_{2,k1,k2,k3}, px_{3,k1,k2,k3}\};
\theta_{i_{-},k1_{-},k2_{-},k3_{-}} := (\partial_{x_{i}} g_{pos}) /. rr_{k1,k2,k3};
CuttingHyperplane2[k1_, k2_, k3_] :=
Simplify [\gamma 1 * kx[0, k1, k2, k3] + \sum_{i=1}^{3} (\theta_{ii,k1,k2,k3} * (x_1 - kx[ii, k1, k2, k3]))];
Cut2 := Flatten[Table[Table[Table[{CuttingHyperplane2[k1, k2, k3]}, {k1, 1, K - 1}],
        \{k2, 1, K-1\}], \{k3, 1, K-1\}], 2];
Cut2;
p<sub>i</sub> [a_] := Coefficient[a, x<sub>i</sub>, 1];
p[i_{-}] := If[Part[ans, i] < 0, Rescale[Part[ans, i], \{-90, 100\}, \{0, \Delta_{i}\}], Part[ans, i]];
   (*{0,\Delta_i}*);
   u := RandomReal[{0.5, 0.98}];
pnt[k1_, k2_, k3_] := Module[{tt},
aa1 = CuttingHyperplane2[1, 1, 1];
aa2 = CuttingHyperplane2[k1, k2, k3];
xa1 = \{p_1[aa1], p_2[aa1], p_3[aa1]\};
xa2 = \{p_1[aa2], p_2[aa2], p_3[aa2]\};
xb_1 = Coefficient[Coefficient[Coefficient[aa1, x_1, 0], x_2, 0], x_3, 0];
xb_2 = Coefficient[Coefficient[Coefficient[aa2, x_1, 0], x_2, 0], x_3, 0];
     ax1 = (xa1) / xa1.xa2;
     ax2 = (xa2) / xa1.xa2;
bx1 = (xb_1) / (xb_1 * xb_2);
     bx2 = (xb_2) / (xb_1 * xb_2);
\omega = ArcCos[Mod[ax1.ax2, 1]];
a1 = ax1; a2 = ax2; xb_1 = bx1; xb_2 = bx2;
x_1 = ((xb_1 - xb_2 * Cos[\omega]) / Sin[\omega]^2) * {\{Part[a1, 1]\}, \{Part[a1, 2]\}, \{Part[a1, 3]\}\} +
```

```
(xb_2 - xb_1 * Cos[\omega]) / Sin[\omega]^2) * { \{Part[a2, 1]\}, \{Part[a2, 2]\}, \{Part[a2, 3]\} \};}
A = \{a1, a2\};
P = IdentityMatrix[3];
G = A.P;
     u := RandomReal[{0.6, 0.98}];
Off[RowReduce::luc]; Z = RowReduce[G];
F1 = Transpose[Z]; F = Transpose[Part[F1, 3]];

g = Flatten[Join[-F, IdentityMatrix[1]]];

     \varsigma = 1 * u;
cx = \varsigma * (P.\varsigma);
ans = Flatten[x_1 + cx];
{p[1], p[2], p[3]}|;
Table[Table[pq[k1, k2, k3] = pnt[k1, k2, k3], \{k1, 1, K-1\}], \{k2, 1, K-1\}],
    \{k3, 1, K-1\}\};
px_{i,k1,k2,k3} := x_i \rightarrow Part[pq[k1, k2, k3], i];
rh_{k1,k2,k3} := \{px_{1,k1,k2,k3}, px_{2,k1,k2,k3}, px_{3,k1,k2,k3}\};
Flatten[
    Table[Table[Table[{rh<sub>k1,k2,k3</sub>}, {k1, 1, K-1}], {k2, 1, K-1}], {k3, 1, K-1}], 2];
GenDat2[k1_, k2_, k3_] := Module[{tt},
     x1 = 1.0 * (x_1) /. rh_{k1,k2,k3};
     x2 = 1.0 * (x_2) /. rh_{k1,k2,k3};
     x3 = 1.0 * (x_3) /. rh_{k1,k2,k3};
     rh2 = \{x_1 \rightarrow x1, x_2 \rightarrow x2, x_3 \rightarrow x3\};
     \{x1, x2, x3, g_{pos}\} /. rh2];
Flatten[Table[Table[Table[{pdat[k1, k2, k3] = GenDat2[k1, k2, k3]; }, {k1, 1, K - 1}],
       \{k2, 1, K-1\}], \{k3, 1, K-1\}], 2];
Clear[ca];
  ca = {};
  Flatten[Table[Table[Table[{ca = Join[ca, {pdat[k1, k2, k3]}]}, {k1, 1, K-1}],
       \{k2, 1, K-1\}], \{k3, 1, K-1\}], 2];
\theta_i := (\partial_{x_i} g_{pos}) /. \{x_1 \rightarrow px1, x_2 \rightarrow px2, x_3 \rightarrow px3\};
CutGen[k1_, k2_, k3_] := Module[{tt}, pdat[k1, k2, k3] = GenDat2[k1, k2, k3];
     pxo = Part[pdat[k1, k2, k3], 4];
\alpha = 1.0; \nu = 1.0; \mu 2 = 1.0;
     px1 = \alpha * Part[pdat[k1, k2, k3], 1];
px2 = v * Part[pdat[k1, k2, k3], 2];
px3 = \mu2 * Part[pdat[k1, k2, k3], 3];
     \{a1, a2, a3\} = \{\theta_1, \theta_2, \theta_3\};
     Simplify [y1 * px0 + (a1 * (x_1 - px1) + a2 * (x_2 - px2) + a3 * (x_3 - px3))]];
    Flatten[Table[Table[Table[Cut1[k1, k2, k3] = CutGen[k1, k2, k3] \ge 0, \{k1, 1, K-1\}],
        \{k2, 1, K-1\}], \{k3, 1, K-1\}], 2];
rhs2 = Expand[FindFit[ca, 0.98 * pxo + ((\phi_1 * (x_1 - px1) + \phi_2 * (x_2 - px2) + \phi_3 * (x_3 - px3))),
       \{\phi_1, \phi_2, \phi_3\}, \{X_1, X_2, X_3\}];
aa1 = Simplify[0.98 * pxo + ((\phi_1 * (x_1 - px1) + \phi_2 * (x_2 - px2) + \phi_3 * (x_3 - px3))) /. rhs2];
  a1 = \{p_1[aa1], p_2[aa1], p_3[aa1]\};
```

```
Print[" **vu_3* ", px1, " * ", px2, " * ", px3, " * ", pxo];
            GCH = ExpandAll[ (1.0 * aa1) / (\sqrt{(a1.a1)})];
            Cons = Join[Cons, {GCH ≥ 0}]; Print[" *** GCH = ", GCH];
            temp = Join[Cons, Cuts];
            Constraints = temp; (*Join[Cons,temp];*)
         Initial Solution = Minimize[f, Constraints, \{x_1, x_2, x_3\}];
        Print[InitialSolution];
        xz = Part[InitialSolution, 2];
            f = Simplify \left[ (fn /. xz) + \sum_{j=1}^{n} (\partial_{x_{jj}} fn /. xz) * (x_{jj} - (x_{jj} /. xz)) \right];
        Values = Flatten[Table[(g_{jj} /. xz), {jj, 1, m}]];
        xx = (*-Max[-Values, x0];*) If [ialg \geq 2, -Max[-Values, x0], -Max[-Values]];
            Print[ialg, " ** xx=", xx]; If[ialg \geq 2 && Abs[xx] < TOL && Abs[xx-x0] < TOL, Break[];];
            Print["***
                              ", {Values}, xx]; Print[xx]; If[Abs[xx] < TOL, {Print[xx]; Break[];}];
        Pos = Part[Flatten[Position[Values, x0]], 1];
            Print["Pos=", Pos, " ", xx];
        gCut = \text{ExpandAll}\left[xx + \sum_{j=1}^{n} \left(\partial_{x_{jj}} g_{Pos} /. xz\right) \star (x_{jj} - (x_{jj} /. xz))\right];
            Print["*** gcut=", gCut ≥ 0];
        Cons = Join[Cons, \{gCut \ge 0\}]; \}, ip++
        Upper bound={1.121, 0.826, 0.531}
          **vu_3* 13.4298 * 0. * 0.737488 * 2.18969
          *** GCH = 0.913255 + 0.0686995 x_1 - 0.997637 x_3
         \{-8.27894, \{x_1 \rightarrow 1.121, x_2 \rightarrow 0.001, x_3 \rightarrow 0.529384\}\}
         1 ** xx = -2.22045 \times 10^{-16}
                 \left\{\left.\left\{-2.22045\!\times\!10^{-16}\text{, 0.175106}\right\}\right\}\!-\!2.22045\!\times\!10^{-16}\right.\right.
         -2.22045 \times 10^{-16}
         -2.22045 \times 10^{-16}
 In[49]:= q1
Out[49]=
        0.59
 In[50]:= Minimize[{fn, g_1 \ge 0, g_2 \ge 0, Conz}, {x<sub>1</sub>, x<sub>2</sub>, x<sub>3</sub>}]
Out[50]=
         \{-8.27894, \{x_1 \rightarrow 1.121, x_2 \rightarrow 0.00100001, x_3 \rightarrow 0.529384\}\}
```