```
\ln[1]:= fn = 4.3 * x_1 + 31.8 * x_2 + 63.3 * x_3 + 15.8 * x_4 + 68.5 * x_5 + 4.7 * x_6;
                                  b_1 = 32.97; b_2 = 25.12; b_3 = -29.08; b_4 = -78.02;
                                  g_1 = 17.1 * x_1 + 38.2 * x_2 + 204.2 * x_3 + 212.3 * x_4 + 623.4 * x_5 + 1495.5 * x_6 - 169.0 * x_1 * x_3 - 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 * 120.0 *
                                                     3580.0 * x_3 * x_5 - 3810.0 * x_4 * x_5 - 18500.0 * x_4 * x_6 - 24300.0 * x_5 * x_6 - b_1;
                                  g_2 = 17.9 * x_1 + 36.8 * x_2 + 113.9 * x_3 + 169.7 * x_4 + 337.8 * x_5 + 1385.2 * x_6 -
                                                     139.0 * X_1 * X_3 - 2450.0 * X_4 * X_5 - 16600.0 * X_4 * X_6 - 17200.0 * X_5 * X_6 - b_2;
                                   g_3 = -273.0 * x_2 - 70.0 * x_4 - 819.0 * x_5 + 26000.0 * x_4 * x_5 - b_3;
                                   g_4 = 159.9 * x_1 - 311.0 * x_2 + 587.0 * x_4 + 391.0 * x_5 + 2198.0 * x_6 - 14000.0 * x_1 * x_6 - b_4;
         \ln[7] = v_1 = 0.02; v_2 = 0.000; v_3 = 0.0000; v_4 = 0.000; v_5 = 0.020; v_6 = 0.01;
                                  \Delta_1 = 0.31; \ \Delta_2 = 0.046;
                                  \Delta_3 = 0.068;
                                  \Delta_4 = 0.042;
                                  \Delta_5 = 0.028; \Delta_6 = 0.0134;
                                  \delta_1 = \Delta_1 / \text{ndiv};
                                  \delta_2 = \Delta_2 / (\text{ndiv});
                                  \delta_3 = \Delta_3 / \text{ndiv};
                                  \delta_4 = \Delta_4 / \text{ndiv};
                                  \delta_5 = \Delta_5 / (\text{ndiv});
                                   \delta_6 = \Delta_6 / \text{ndiv}; SeedRandom[3];
         \ln[9] = Cons = \{x_1 - v_1 \ge 0, x_2 - v_2 \ge 0, x_3 - v_3 \ge 0, x_4 - v_4 \ge 0, x_5 - v_5 \ge 0, x_6 - v_6 \ge 0, x_7 - v_8 \ge 0, x_8 
                                                     \Delta_4 - X_4 \ge 0.0, \Delta_3 - X_3 \ge 0, \Delta_1 - X_1 \ge 0, \Delta_2 - X_2 \ge 0, \Delta_5 - X_5 \ge 0.0, \Delta_6 - X_6 \ge 0.0};
     \ln[10] = \text{NMinimize}[\{fn, g_1 \ge 0, g_2 \ge 0, g_3 \ge 0, g_4 \ge 0, Cons\}, \{x_1, x_2, x_3, x_4, x_5, x_6\}]
                                    \{g_1, g_2\} /. Part [\%, 2]
Out[10]=
                                    \{3.13581, \{x_1 \rightarrow 0.268564, x_2 \rightarrow -9.9991 \times 10^{-9}, \}
                                               x_3 \rightarrow -9.99959 \times 10^{-9}, x_4 \rightarrow -9.99961 \times 10^{-9}, x_5 \rightarrow 0.028, x_6 \rightarrow 0.0134}
Out[11]=
                                    \{-9.96023 \times 10^{-9}, 1.25395\}
    In[12]:= X0 = 0;
                                  Constraints = Cons;
     \ln[14]:=\mathbf{XZ}=\left\{\mathbf{X}_{1}\rightarrow\Delta_{1}-\mathbf{V}_{1},\;\mathbf{X}_{2}\rightarrow\Delta_{2}-\mathbf{V}_{2},\;\mathbf{X}_{3}\rightarrow\Delta_{3}-\mathbf{V}_{3},\;\mathbf{X}_{4}\rightarrow\Delta_{4}-\mathbf{V}_{4},\;\mathbf{X}_{5}\rightarrow\Delta_{5}-\mathbf{V}_{5},\;\mathbf{X}_{6}\rightarrow\Delta_{6}-\mathbf{V}_{6}\right\}
Out[14]=
                                    \{x_1 \to \textbf{0.29,} \ x_2 \to \textbf{0.046,} \ x_3 \to \textbf{0.068,} \ x_4 \to \textbf{0.042,} \ x_5 \to \textbf{0.008,} \ x_6 \to \textbf{0.0034}\}
    \ln[15] = f = (fn / .xz) + (\partial_{x_1}fn / .xz) * (x_1 - (x_1 / .xz)) + (\partial_{x_2}fn / .xz) * (x_2 - (x_2 / .xz)) + (\partial_{x_2}fn / .xz) * (x_2 - (x_2 / .xz)) + (
                                                (\partial_{x_3} fn /. xz) * (x_3 - (x_3 /. xz)) + (\partial_{x_4} fn /. xz) * (x_4 - (x_4 /. xz)) +
                                                (\partial_{x_5} fn /. xz) * (x_5 - (x_5 /. xz)) + (\partial_{x_6} fn /. xz) * (x_6 - (x_6 /. xz))
Out[15]=
                                   8.24178 + 4.3 (-0.29 + x_1) + 31.8 (-0.046 + x_2) + 63.3 (-0.068 + x_3) +
                                        15.8 (-0.042 + x_4) + 68.5 (-0.008 + x_5) + 4.7 (-0.0034 + x_6)
     In[16]:= Off[Join::heads]; Off[Set::write];
                                  1bnd = 0.0001;
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In[18]:= Constraints = Cons
Out[18]=
                                                    \{-0.02+x_1\geq 0,\ 0.+x_2\geq 0,\ 0.+x_3\geq 0,\ 0.+x_4\geq 0,\ -0.02+x_5\geq 0,\ -0.01+x_6\geq 0,\ -0.02+x_5\geq 0,\ -0.01+x_6\geq 0,\ -0.02+x_5\geq 0,\ -0.01+x_6\geq 0,\ -0.02+x_5\geq 0,\ -0.01+x_6\geq 0
                                                          0.042 - x_4 \ge 0., 0.068 - x_3 \ge 0, 0.31 - x_1 \ge 0, 0.046 - x_2 \ge 0, 0.028 - x_5 \ge 0., 0.0134 - x_6 \ge 0.
       In[19]:= (* Cut the first slice. *)
       In[20]:= ndiv = 5;
                                                \eta_1 = \text{ndiv}; \ \eta_2 = \text{ndiv}; \ \eta_3 = \text{ndiv};
                                                 \eta_4 = \text{ndiv};
                                                 \eta_5 = \text{ndiv};
                                                 \eta_6 = \text{ndiv};
                                                 \eta_7 = \text{ndiv};
                                                 \eta_8 = \text{ndiv};
                                                 \eta_9 = ndiv;
                                                 pos = 1; mfo = 20.0;
                                                 ialg = 1;
                                                 \sigma = 0.98; \gamma 1 = 1.0; \gamma 2 = 1.0;
                                                 \tau 1 = 0.905; \beta = 1.0; \mathcal{P}os = pos = 1; ialg = 1;
                                                 \gamma 1 = 1.0; \ \gamma 2 = 1.0;
                                                 \tau = 0.905;
                                                 \beta = 1.0; Pos = 1;
       In[25]:= lbnd<sub>i2</sub> := v_{i2}
       In[26]:= Clear[jval, i7];
                                                 jval[i7_] := Which[i7 == 1, 1, i7 == 2, 1, i7 == 3,
                                                                   1, i7 = 4, 0, i7 = 5, 0, i7 = 6, 0, i7 = 7, 0, i7 = 8, 0, i7 = 9, 0]
       In[27]:= For[i = 0, i \le 5,
                                                           \{For[j=0, j \le jval[i], \{lw[i, j] = lbnd_j + (j-1) * \delta_i; ur[i, j] = lbnd_j + (j) * \delta_i; ur[
                                                                                   Print["i,j="i,j," ", lw[i,j]," @ ", ur[i,j]];}, j++]}, i++]
                                                 i,j=1 0.02 @ 0.082
                                                 i,j=2 0.062 @ 0.124
                                                 2i,j=1 0.02 @ 0.0292
                                                 2i,j=2 0.0092 @ 0.0184
                                                 3i, j=1 0.02 @ 0.0336
                                                 3i,j=2 0.0136 @ 0.0272
                                                 4i,j=1 0.02 @ 0.0284
                                                 5 i, j=1 0.02 @ 0.0256
                                                 6i, j=1 0.02 @ 0.02268
      In[28]:= Constraints = Cons
Out[28]=
                                                   \{-0.02+x_1\geq 0,\ 0.+x_2\geq 0,\ 0.+x_3\geq 0,\ 0.+x_4\geq 0,\ -0.02+x_5\geq 0,\ -0.01+x_6\geq 0,\ -0.02+x_5\geq 0,\ -0.01+x_6\geq 0
                                                          0.042 - x_4 \ge 0., 0.068 - x_3 \ge 0, 0.31 - x_1 \ge 0, 0.046 - x_2 \ge 0, 0.028 - x_5 \ge 0., 0.0134 - x_6 \ge 0.
```

```
In[29]:= scut = {};
  in[30]:= cnt = 0; Off[General::munfl];
                 For [j1 = 0, j1 \le jval[1], \{For [j2 = 0, j2 \le jval[2], \}\}
                              \{For[j3 = 0, j3 \le jval[3], \{For[j4 = 0, j4 \le jval[4], \{For[j5 = 0, j5 \le jval[5], \}\}\}\}
                                                         \{For[j6 = 0, j6 \le jval[6], \{cnt = cnt + 1; data[j1, j2, j3, j4, j5, j6] = \{\}\}
                                                                     -g_{pos}, f}, {x<sub>1</sub>, lw[1, j1], ur[1, j1], (ur[1, j1] - lw[1, j1]) / \eta_1},
                                                                             \{x_2, lw[2, j2], ur[2, j2], (ur[2, j2] - lw[2, j2]) / \eta_2\},
                                                                             \{x_3, lw[3, j3], ur[3, j3], (ur[3, j3] - lw[3, j3]) / \eta_3\},
                                                                             \{x_4, lw[4, j4], ur[4, j4], (ur[4, j4] - lw[4, j4]) / \eta_4\},
                                                                             \{x_5, lw[5, j5], ur[5, j5], (ur[5, j5] - lw[5, j5]) / \eta_5\},
                                                                             \{x_6, 1w[6, j6], ur[6, j6], (ur[6, j6] - 1w[6, j6]) / \eta_6\}\}, 5\}
                                                                 j6++];}, j5++];}, j4++];}, j3++];}, j2++];}, j1++]
  In[31]:= data[j1, j2, j3, j4, j5, j6]
Out[31]=
                       \{0.062, 0.0092, 0.0136, 0.02, 0.02, 0.02, 1.9175, 3.20004\},
                        \{0.062, 0.0092, 0.0136, 0.02, 0.02, 0.020536, 1.57473, 3.20256\},
                        \{0.062, 0.0092, 0.0136, 0.02, 0.02, 0.021072, 1.23196, 3.20508\}, \dots, 46651\dots\}
                        \{0.124, 0.0184, 0.0272, 0.0284, 0.0256, 0.022144, 0.730416, 5.14648\},
                         \{0.124, 0.0184, 0.0272, 0.0284, 0.0256, 0.02268, 0.543878, 5.149\}
                                                                                              €§
                                                                + Show more
  In[32]:= Print[cnt];
  In[33]:= Constraints = Cons
Out[33]=
                   \{ -0.02 + x_1 \geq 0, \ 0. + x_2 \geq 0, \ 0. + x_3 \geq 0, \ 0. + x_4 \geq 0, \ -0.02 + x_5 \geq 0, \ -0.01 + x_6 \geq 0, \ -0.02 + x_5 \geq 0, \ -0.01 + x_6 \geq 0, \ -0.01 + x_6 \geq 0, \ -0.02 + x_5 \geq 0, \ -0.01 + x_6 \geq 0, \ -0.02 + x_5 \geq 0, \ -0.01 + x_6 \geq 0, 
                    0.042 - x_4 \ge 0., \ 0.068 - x_3 \ge 0, \ 0.31 - x_1 \ge 0, \ 0.046 - x_2 \ge 0, \ 0.028 - x_5 \ge 0., \ 0.0134 - x_6 \ge 0.\}
  In[34]:= Initial Solution = Minimize [f, Constraints, {X<sub>1</sub>, X<sub>2</sub>, X<sub>3</sub>, X<sub>4</sub>, X<sub>5</sub>, X<sub>6</sub>}]
Out[34]=
                  \{1.503, \{x_1 \rightarrow 0.02, x_2 \rightarrow 0., x_3 \rightarrow 0., x_4 \rightarrow 0., x_5 \rightarrow 0.02, x_6 \rightarrow 0.01\}\}
  ln[35]:= (*{x_1,s[1],5.54},{x_2,s[2],4.0},{x_3,s[3],4.0},
                  \{x_4, s[4], 12.02\}, \{x_5, s[5], 0.702\}, \{x_6, s[6], 0.852\} *\}
  In[36]:= S[i] := Part[Part[Part[InitialSolution, 2], i], 2]
  ln[37] := \{s[1], s[2], s[3], s[4], s[5], s[6]\}
Out[37]=
                  \{0.02, 0., 0., 0., 0.02, 0.01\}
```

```
In[38]:= XZ = Part[InitialSolution, 2]
                                f = (fn /. xz) + (\partial_{x_1} fn /. xz) * (x_1 - (x_1 /. xz)) + (\partial_{x_2} fn /. xz) * (x_2 - (x_2 /. xz)) +
                                              (\partial_{x_3} fn /. xz) * (x_3 - (x_3 /. xz)) + (\partial_{x_4} fn /. xz) * (x_4 - (x_4 /. xz)) +
                                              (\partial_{x_5} fn /. xz) * (x_5 - (x_5 /. xz)) + (\partial_{x_6} fn /. xz) * (x_6 - (x_6 /. xz))
Out[38]=
                                   \{x_1 \to 0.02, x_2 \to 0., x_3 \to 0., x_4 \to 0., x_5 \to 0.02, x_6 \to 0.01\}
Out[39]=
                                  1.503 + 4.3 (-0.02 + x_1) + 31.8 (0. + x_2) +
                                      63.3 (0. + x_3) + 15.8 (0. + x_4) + 68.5 (-0.02 + x_5) + 4.7 (-0.01 + x_6)
     In[40]:= Values = \{(g_1 /. Part[InitialSolution, 2]), (g_2 /. Part[InitialSolution, 2]), \}
                                                   (g<sub>3</sub> /. Part[InitialSolution, 2]), (g<sub>4</sub> /. Part[InitialSolution, 2])};
                                xx = -Max[-Values, x0]
                                gCut = \frac{1}{1.0 \times 10^4} \times
                                                   (\partial_{x}, g_{pos} / \cdot Part[InitialSolution, 2]) * (x_2 - (x_2 / \cdot Part[InitialSolution, 2])) +
                                                                    (\partial_{x_3} g_{\rho os} /. Part[InitialSolution, 2]) * (x_3 - (x_3 /. Part[InitialSolution, 2])) +
                                                                    (\partial_{x_4} g_{Pos} /. Part[InitialSolution, 2]) * (x_4 - (x_4 /. Part[InitialSolution, 2])) +
                                                                    (\partial_{x_5} g_{pos} /. Part[InitialSolution, 2]) * (x_5 - (x_5 /. Part[InitialSolution, 2])) +
                                                                    (\partial_{x_6} g_{\rho os} /. Part[InitialSolution, 2]) * (x_6 - (x_6 /. Part[InitialSolution, 2]))]);
                                Cons = Join[Cons, \{gCut \ge 0\}]
Out[41]=
                                  -10.065
Out[43]=
                                   \{-0.02+x_1\geq 0,\ 0.+x_2\geq 0,\ 0.+x_3\geq 0,\ 0.+x_4\geq 0,\ -0.02+x_5\geq 0,\ -0.01+x_6\geq 0,\ -0.02+x_5\geq 0,\ -0.01+x_6\geq 0
                                      0.042-x_4 \geq 0., \ 0.068-x_3 \geq 0, \ 0.31-x_1 \geq 0, \ 0.046-x_2 \geq 0, \ 0.028-x_5 \geq 0., \ 0.0134-x_6 \geq 0., \ 0.048-x_6 \geq 0.
                                       0.0001 \; (-28.11 + 17.1 \; x_1 + 38.2 \; x_2 + 129.22 \; x_3 - 48.9 \; x_4 + 380.4 \; x_5 + 1009.5 \; x_6) \; \geq \; 0 \}
     In[44]:= For \begin{bmatrix} ii = 0, ii \le 67, \end{bmatrix}
                                       ialg = ialg + 1; (* If[ialg>4, \{\psi_1=Part[Part[xz,1],2]\};
                                                                        \psi_2=Part[Part[xz,2],2];
                                                                        \psi_3=Part[Part[xz,3],2];
                                                                        \psi_4=Part[Part[xz,4],2];
                                                                        \psi_5=Part[Part[xz,5],2];
                                                                        \psi_6=Part[Part[xz,6],2];
                                                                        ur [1, j1] = \psi_1;
                                                                        ur[2,j2] = \psi_2;
                                                                        ur[3,j3] = \psi_{3}, ur[4,j3] = \psi_{4}, ur[5,j3] = \psi_{5}, ur[6,j3] = \psi_{6}, \}];*)
                                                        pos = Pos;
                                       cnt = 0; Off[General::munfl];
                                                       For [j1 = 0, j1 \le jval[1], {For [j2 = 0, j2 \le jval[2], {For [j3 = 0, j3 \le jval[3], {
                                                                                                   {For[j4 = 0, j4 \le jval[4], \{For[j5 = 0, j5 \le jval[5], \{For[j6 = 0, j6 = 0, j
                                                                                                                                                     j6 ≤ jval[6], {cnt = cnt + 1; data[j1, j2, j3, j4, j5, j6] = {};
```

```
-g<sub>pos</sub>, f}, \{x_1, lw[1, j1], ur[1, j1], \frac{ur[1, j1] - lw[1, j1]}{n_1}\},
                                                                     \{x_2, lw[2, j2], ur[2, j2], \frac{ur[2, j2] - lw[2, j2]}{n_2}\}
                                                                     \{x_3, lw[3, j3], ur[3, j3], \frac{ur[3, j3] - lw[3, j3]}{\eta_3}\}
                                                                     \left\{x_4, 1w[4, j4], ur[4, j4], \frac{ur[4, j4] - 1w[4, j4]}{n}\right\}
                                                                     \left\{x_{5}, lw[5, j5], ur[5, j5], \frac{ur[5, j5] - lw[5, j5]}{n_{c}}\right\}
                                                                    \{x_6, lw[6, j6], ur[6, j6], \frac{ur[6, j6] - lw[6, j6]}{n_6}\}, 5];\},
                                                         j6++];}, j5++];}, j4++];}, j3++];}, j2++];}, j1++] x
Print(cnt);
cnt = 0;
        For[j1 = 0, j1 \leq jval[1], {For[j2 = 0, j2 \leq jval[2], {For[j3 = 0, j3 \leq jval[3], {For[
                                     j4 = 0, j4 \le jval[4], {For[j5 = 0, j5 \le jval[5], {For[j6 = 0, j6 \le jval[6], {
cnt = cnt + 1;
fo[j1, j2, j3, j4, j5, j6] =
                                                             Table[Part[Part[data[j1, j2, j3, j4, j5, j6], i], 8],
                                                                {i, 1, Length[data[j1, j2, j3, j4, j5, j6]]}];
ev[j1, j2, j3, j4, j5, j6] = Table[{Abs[\tau * Min[fo[j1, j2, j3, j4, j5, j6]] -
                                                                        Part[Part[data[j1, j2, j3, j4, j5, j6], i], 8]]},
                                                                 {i, 1, Length[data[j1, j2, j3, j4, j5, j6]]}];
eo3[j1, j2, j3, j4, j5, j6] = Part[Flatten[Position[ev[j1, j2, j3, j4, j5, j6],
                                                                     Min[ev[j1, j2, j3, j4, j5, j6]]]], 1];
kdat[j1, j2, j3, j4, j5, j6] =
                                                             Part[data[j1, j2, j3, j4, j5, j6], eo3[j1, j2, j3, j4, j5, j6]];
                                                           (*Print["kdat=",kdat[j1,j2,j3,j4,j5,j6]];*)
kxo[j1, j2, j3, j4, j5, j6] = Part[kdat[j1, j2, j3, j4, j5, j6], 7];
kx1[j1, j2, j3, j4, j5, j6] = Part[kdat[j1, j2, j3, j4, j5, j6], 1];
kx2[j1, j2, j3, j4, j5, j6] = Part[kdat[j1, j2, j3, j4, j5, j6], 2];
kx3[j1, j2, j3, j4, j5, j6] = Part[kdat[j1, j2, j3, j4, j5, j6], 3];
                                                          kx4[j1, j2, j3, j4, j5, j6] = Part[kdat[j1, j2, j3, j4, j5, j6], 4];
                                                          kx5[j1, j2, j3, j4, j5, j6] = Part[kdat[j1, j2, j3, j4, j5, j6], 5];
                                                          kx6[j1, j2, j3, j4, j5, j6] = Part[kdat[j1, j2, j3, j4, j5, j6], 6];
rr = \{x_1 \rightarrow kx1[j1, j2, j3, j4, j5, j6], x_2 \rightarrow kx2[j1, j2, j3, j4, j5, j6], x_3 \rightarrow kx2[j1, j2, j3, j4, j5, j6], x_3 \rightarrow kx2[j1, j2, j3, j4, j5, j6], x_3 \rightarrow kx2[j1, j2, j3, j4, j5, j6], x_4 \rightarrow kx2[j1, j2, j3, j4, j5, j6], x_5 \rightarrow kx2[j1, j2, j3, j4, j5, j6], x_6 \rightarrow kx2[j1, j2, j3, j4, j5, j6], x_7 \rightarrow kx2[j1, j2, j3, j4, j5, j6], x_8 \rightarrow kx2[j1, j2, j4, j6], x_8 \rightarrow kx2[j1, j2, j4], x_8 \rightarrow kx2[j1, j4, j4], x_8 \rightarrow kx2[j1
                                                                  kx3[j1, j2, j3, j4, j5, j6], x_4 \rightarrow kx4[j1, j2, j3, j4, j5, j6], x_5 \rightarrow
                                                                   kx5[j1, j2, j3, j4, j5, j6], x_6 \rightarrow kx6[j1, j2, j3, j4, j5, j6]\};
\theta_1 = (\partial_{x_1} g_{pos}) / . rr;
\theta_2 = (\partial_{x_2} g_{pos}) / . rr;
\theta_3 = (\partial_{x_3} g_{pos}) / . rr;
                                                         \theta_4 = (\partial_{x_4} g_{pos}) / . rr;
```

```
\theta_5 = (\partial_{x_5} g_{pos}) /. rr;
\theta_6 = (\partial_{x_6} g_{pos}) / . rr;
CuttingHyperplane2[cnt] =
Simplify [\gamma1 * kxo[j1, j2, j3, j4, j5, j6] +
                               (\theta_1 * (x_1 - kx1[j1, j2, j3, j4, j5, j6])) +
(\theta_2 * (x_2 - kx2[j1, j2, j3, j4, j5, j6])) +
\theta_3 * (x_3 - kx3[j1, j2, j3, j4, j5, j6]) +
\theta_4 * (x_4 - kx4[j1, j2, j3, j4, j5, j6]) +
\theta_5 * (x_5 - kx5[j1, j2, j3, j4, j5, j6]) +
\theta_6 * (x_6 - kx6[j1, j2, j3, j4, j5, j6])];
(*Print[cnt, " ", CuttingHyperplane2[cnt]];*)
}, j6++];}, j5++];}, j4++];}, j3++];}, j2++];}, j1++];
p<sub>i</sub> [a_] := Coefficient[a, x<sub>i</sub>, 1];
p[i]:=
     If [Part[ans, i] < 0, Rescale [Part[ans, i], \{-20, 100\}, \{0, \Delta_i\}], Part[ans, i]];
For \lceil cnt = 1, cnt \leq 7, \rceil
aa1 = CuttingHyperplane2[1];
aa2 = CuttingHyperplane2[cnt]; (*Print[cnt,aa1,aa2];*)
a1 = \{p_1[aa1], p_2[aa1], p_3[aa1], p_4[aa1], p_5[aa1], p_6[aa1]\};
a2 = \{p_1[aa2], p_2[aa2], p_3[aa2], p_4[aa1], p_5[aa1], p_6[aa1]\};
b<sub>1</sub> = Coefficient [Coefficient [Coefficient [
             Coefficient [Coefficient [aa1, x_1, 0], x_2, 0], x_3, 0], x_4, 0], x_5, 0], x_6, 0];
b<sub>2</sub> = Coefficient[Coefficient[Coefficient[
             Coefficient [Coefficient [aa2, x_1, 0], x_2, 0], x_3, 0], x_4, 0], x_5, 0], x_6, 0];
      ax1 = (a1) / a1.a2;
      ax2 = (a2) / a1.a2;
bx1 = (b_1) / (b_1 * b_2);
      bx2 = (b_2) / (b_1 * b_2);
\omega = ArcCos[Mod[ax1.ax2, 1]];
a1 = ax1; a2 = ax2; b_1 = bx1; b_2 = bx2;
x_1 = ((b_1 - b_2 * Cos[\omega]) / Sin[\omega]^2) * { \{Part[a1, 1]\}, \{Part[a1, 2]\}, \}}
            {Part[a1, 3]}, {Part[a1, 4]}, {Part[a1, 5]}, {Part[a1, 6]}} +
         ((b_2 - b_1 * Cos[\omega]) / Sin[\omega]^2) * {\{Part[a2, 1]\}, \{Part[a2, 2]\},}
            {Part[a1, 3]}, {Part[a1, 4]}, {Part[a1, 5]}, {Part[a1, 6]}};
A = \{a1, a2\};
P = IdentityMatrix[6];
G = A.P;
      u := RandomReal[{0.6, 0.98}];
Off[RowReduce::luc]; Z = RowReduce[G]; (*Print["Z=",Z]*);
F1 = Transpose[Z]; F = Transpose[Part[F1, {3, 4, 5, 6}]];(*Print["F=",F]*);

g = Join[-F, IdentityMatrix[4]]; (*Print[β]*);
      \varsigma = 1 * \{u, u, u, u\}; (*Print[\varsigma]*);
cx = P.$.5; (*Print["cx=",cx]*);
ans = Flatten[x_1 + cx];
pnt[cnt] = {p[1], p[2], p[3], p[4], p[5], p[6]};
(* Print["*** ",cnt,pnt[cnt]];*)
```

```
}, cnt++];
cnt = 0; ca = {};
For \lceil cnt = 1, cnt \le 7, \rceil
rh = \{x_1 \rightarrow Part[pnt[cnt], 1], x_2 \rightarrow Part[pnt[cnt], 2], x_3 \rightarrow Part[pnt[cnt], 3],
                     x_4 \rightarrow Part[pnt[cnt], 4], x_5 \rightarrow Part[pnt[cnt], 5], x_6 \rightarrow Part[pnt[cnt], 6];
pdat = {x<sub>1</sub>, x<sub>2</sub>, x<sub>3</sub>, x<sub>4</sub>, x<sub>5</sub>, x<sub>6</sub>, g<sub>pos</sub>} /. rh; (*Print[pdat];*)
               x1 = 1.0 * (x_1) /. rh;
               x2 = 1.0 * (x_2) /. rh;
               x3 = 1.0 * (x_3) /. rh;
               x4 = 1.0 * (x_4) /. rh;
               x5 = 1.0 * (x_5) /. rh;
               x6 = 1.0 * (x_6) /. rh;
               rh2 = \{x_1 \rightarrow x1, x_2 \rightarrow x2, x_3 \rightarrow x3, x_4 \rightarrow x4, x_5 \rightarrow x5, x_6 \rightarrow x6\};
               pdat = \{x1, x2, x3, x4, x5, x6, g_{pos}\} /. rh;
ca = Join[ca, {pdat}];
pxo = Part[pdat, 7];
px1 = Part[pdat, 1];
px2 = Part[pdat, 2];
px3 = Part[pdat, 3];
               px4 = Part[pdat, 4];
               px5 = Part[pdat, 5];
               px6 = Part[pdat, 6];
\theta_1 = (\partial_{x_1}, g_{pos}) / \{x_1 \rightarrow px1, x_2 \rightarrow px2, x_3 \rightarrow px3, x_4 \rightarrow px4, x_5 \rightarrow px5, x_6 \rightarrow px6\};
\theta_2 = (\partial_{x_2} g_{pos}) / \{x_1 \rightarrow px1, x_2 \rightarrow px2, x_3 \rightarrow px3, x_4 \rightarrow px4, x_5 \rightarrow px5, x_6 \rightarrow px6\};
               \theta_3 = (\partial_{x_3} g_{pos}) /. \{x_1 \rightarrow px1, x_2 \rightarrow px2, x_3 \rightarrow px3, x_4 \rightarrow px4, x_5 \rightarrow px5, x_6 \rightarrow px6\};
               \theta_4 = (\partial_{x_4} g_{pos}) / \{x_1 \rightarrow px1, x_2 \rightarrow px2, x_3 \rightarrow px3, x_4 \rightarrow px4, x_5 \rightarrow px5, x_6 \rightarrow px6\};
               \theta_5 = (\partial_{x_5} g_{pos}) /. \{x_1 \rightarrow px1, x_2 \rightarrow px2, x_3 \rightarrow px3, x_4 \rightarrow px4, x_5 \rightarrow px5, x_6 \rightarrow px6\};
               \theta_6 = (\partial_{x_6} g_{pos}) /. \{x_1 \rightarrow px1, x_2 \rightarrow px2, x_3 \rightarrow px3, x_4 \rightarrow px4, x_5 \rightarrow px5, x_6 \rightarrow px6\};
Cut1[cnt] = (*\frac{1}{1} e_{-1}e^{4} **) (Simplify[\gamma 1 * pxo + (\theta_{1} * (x_{1} - px1) + \theta_{2} * (x_{2} - px2) + (\theta_{1} * (x_{2} - px1) + \theta_{2} * (x_{2} - px2) + (\theta_{1} * (x_{2} - px1) + (\theta_{2} * (x
                                  \theta_3 * (x_3 - px3) + \theta_4 * (x_4 - px4) + \theta_5 * (x_5 - px5) + \theta_6 * (x_6 - px6))]);
 (*Print[Cut1[cnt]];*)
               Label[Hi]; }, cnt++ ]; (*Print[ca];*)
rhs2 = Expand[FindFit[ca, 0.98 * pxo +
                      ((\phi_1 * (x_1 - px1) + \phi_2 * (x_2 - px2) + \phi_3 * (x_3 - px3) + \phi_4 * (x_4 - px4) + \phi_5 * (x_5 - px5) +
                               \phi_6 * (X_6 - pX_6)), \{\phi_1, \phi_2, \phi_3, \phi_4, \phi_5, \phi_6\}, \{X_1, X_2, X_3, X_4, X_5, X_6\}];
aa1 = Simplify[0.98 * pxo + ((\phi_1 * (x_1 - px1) + \phi_2 * (x_2 - px2) + \phi_3 * (x_3 - px3) +
                               \phi_4 * (x_4 - px4) + \phi_5 * (x_5 - px5) + \phi_6 * (x_6 - px6))) /. rhs2];
         a1 = \{p_1[aa1], p_2[aa1], p_3[aa1], p_4[aa1], p_5[aa1], p_6[aa1]\};
         GCH = Simplify (aa1) / (\sqrt{(a1.a1)});
         Print["GCH=", GCH];
Constr1 = \{\}; For [cnt = 1, cnt \leq 7,
             {Constr1 = Join[Constr1, {CuttingHyperplane2[cnt] ≥ 0}];}, cnt++];
Constr2 = {}; For[cnt = 1, cnt \leq 7, {Constr2 = Join[Constr2, {Cut1[cnt] \geq 0}];}, cnt++];
ConstrT = Join[Constr1, Constr2];
Cons = Join[Cons, \{GCH \ge 0\}];
temp = Join[Cons, Constr2]; Constraints = Join[Constraints, temp];
```

```
(*Print["**1**",xz,f]*);
                    Initial Solution = Minimize [f, Constraints, \{X_1, X_2, X_3, X_4, X_5, X_6\}];
                    Print[InitialSolution];
     xz = Part[InitialSolution, 2]; f =
                         Simplify[(fn /. xz) + (\partial_{x_1} fn /. xz) * (x_1 - (x_1 /. xz)) + (\partial_{x_2} fn /. xz) * (x_2 - (x_2 /. xz)) +
                                     (\partial_{x_3} fn / .xz) * (x_3 - (x_3 / .xz)) + (\partial_{x_4} fn / .xz) * (x_4 - (x_4 / .xz)) + (\partial_{x_5} fn / .xz) *
                                         (x_5 - (x_5 /. xz)) + (\partial_{x_6} fn /. xz) * (x_6 - (x_6 /. xz))]; (*Print["**2**",xz,f]*);
     Values = { (g<sub>1</sub> /. Part[InitialSolution, 2]), (g<sub>2</sub> /. Part[InitialSolution, 2]),
                               (g<sub>3</sub> /. Part[InitialSolution, 2]), (g<sub>4</sub> /. Part[InitialSolution, 2])};
                    xx = -Max[-Values];
                    Print[ialg, " ** xx=", xx];
                   x0 = xx;
                    Print["***
                                                                    ", {Values}, xx]; Print[xx]; If[Abs[xx] < 1.0 x 10<sup>-11</sup>, {Print[xx];
                             Break[];}];
     Pos = Part[Flatten[Position[Values, x0]], 1];
                    Print["Pos=", Pos, " ", XX];
     gCut = \frac{1}{1.0 * 10^4} * ExpandAll[
                                   xx + (\partial_{x_1} g_{pos} / Part[InitialSolution, 2]) * (x_1 - (x_1 / Part[InitialSolution, 2])) +
                                         (\partial_{x}, g_{pos} /. Part[InitialSolution, 2]) * (x_2 - (x_2 /. Part[InitialSolution, 2])) +
                                         (\partial_{x_3} g_{pos} /. Part[InitialSolution, 2]) * (x_3 - (x_3 /. Part[InitialSolution, 2])) +
                                         (\partial_{x_4} g_{pos} /. Part[InitialSolution, 2]) * (x_4 - (x_4 /. Part[InitialSolution, 2])) +
                                         (\partial_{x_5} g_{pos} /. Part[InitialSolution, 2]) * (x_5 - (x_5 /. Part[InitialSolution, 2])) +
                                         (\partial_{x_6} g_{pos} / . Part[InitialSolution, 2]) * (x_6 - (x_6 / . Part[InitialSolution, 2]))];
     Cons = Join[Cons, \{gCut \ge 0\}];
     }, ii++|;
\mathsf{GCH} = \mathbf{0.197152} + \mathbf{0.0027076} \ x_1 + \mathbf{0.923497} \ x_2 + \mathbf{0.0461467} \ x_3 - \mathbf{0.0303208} \ x_4 - \mathbf{0.298863} \ x_5 - \mathbf{0.234047} \ x_6 + \mathbf{0.0303208} \ x_8 - \mathbf{0.0303
 \{2.9696, \{x_1 \rightarrow 0.229912, x_2 \rightarrow 0., x_3 \rightarrow 0., x_4 \rightarrow 0., x_5 \rightarrow 0.028, x_6 \rightarrow 0.0134\}\}
2 ** xx = -0.66096
 *** { {-0.66096, 0.56207, 6.148, 112.053} }-0.66096
 -0.66096
Pos=1 -0.66096
\mathsf{GCH} = \textbf{0.204747} - \textbf{0.000400998} \ x_1 + \textbf{0.965032} \ x_2 - \textbf{0.0389289} \ x_3 - \textbf{0.148285} \ x_4 - \textbf{0.133219} \ x_5 - \textbf{0.165716} \ x_6 + \textbf{0.165716} \ x_6
 \{3.13581, \{x_1 \rightarrow 0.268565, x_2 \rightarrow 0., x_3 \rightarrow 0., x_4 \rightarrow 0., x_5 \rightarrow 0.028, x_6 \rightarrow 0.0134\}\}
3 ** xx = -3.55271 \times 10^{-15}
                  \{\{-3.55271\times10^{-15}, 1.25395, 6.148, 110.982\}\}
 -3.55271 \times 10^{-15}
 -3.55271\times10^{-15}
```