

```

In[1]:= fn = -3.0 * x3 * x1^2 + 7.5 * x2^2 - 5.0 * x1^2;

In[2]:= g1 =  $\sqrt{x_1} - 4. * x_2^2 - 2 * x_3$ ;
g2 = 6.0 * x3^2 - 1.2 * x1^2 + 3.0 * x3 * x2;

In[4]:= SeedRandom[4];

In[5]:= ndiv = 10; q1 = 0.7;
zz1 = 1.9; zz2 = 0.3; zz3 = 0.9;

In[7]:=  $\Delta_{i1\_} := q1 * zz_{i1}$ 

In[8]:= { $\Delta_1$ ,  $\Delta_2$ ,  $\Delta_3$ }

Out[8]= {1.33, 0.21, 0.63}

In[9]:=  $\delta_1 = \frac{\Delta_1}{ndiv}$ ;  $\delta_2 = \frac{\Delta_2}{ndiv}$ ;  $\delta_3 = \frac{\Delta_3}{ndiv}$ ;

In[10]:= Cons = { $\Delta_1 - x_1 \geq 0$ ,  $\Delta_2 - x_2 \geq 0$ ,  $\Delta_3 - x_3 \geq 0$ ,  $x_1 \geq 0$ ,  $x_2 \geq 0$ ,  $x_3 \geq 0$ }; x0 = 0;

In[11]:= Constraints = Cons

Out[11]= {1.33 - x1 ≥ 0, 0.21 - x2 ≥ 0, 0.63 - x3 ≥ 0, x1 ≥ 0, x2 ≥ 0, x3 ≥ 0}

In[12]:= scut = {};

In[13]:= Clear[linearCut, iter];
linearCut[scut_, iter_] := Module[{tt}, gCut = scut; iter = iter + 1;
InitialSolution = Minimize[f, Constraints, {x1, x2, x3}];
Values = {(g1 /. Part[InitialSolution, 2]), (g2 /. Part[InitialSolution, 2])};
xx = -Max[-Values, x0]; x0 = xx;
Pos = Part[Flatten[Position[Values, xx]], 1];
gCut =
ExpandAll[xx + (∂x1 gPos /. Part[InitialSolution, 2]) * (x1 - (x1 /. Part[InitialSolution, 2])) +
(∂x2 gPos /. Part[InitialSolution, 2]) * (x2 - (x2 /. Part[InitialSolution, 2])) +
(∂x3 gPos /. Part[InitialSolution, 2]) * (x3 - (x3 /. Part[InitialSolution, 2]))];
Constraints = Join[Constraints, {gCut ≥ 0}];
{{gCut}, Pos, InitialSolution}
mxo = 0.7; mfo = 20.0; ialg = 1;
σ = 0.6;
γ = 0.92;
τ = 0.905;
β = 0.98; scut = Constraints; TOL = 1.0 * 10-7;

In[17]:= xz = {x1 → Δ1 - 0., x2 → Δ2 - 0.0, x3 → Δ3 - 0.0}

Out[17]= {x1 → 1.33, x2 → 0.21, x3 → 0.63}

```

```
In[18]:= f = Simplify[(fn /. xz) + (D[fn, x1] /. xz) * (x1 - (x1 /. xz)) +
  (D[fn, x2] /. xz) * (x2 - (x2 /. xz)) + (D[fn, x3] /. xz) * (x3 - (x3 /. xz))]
```

```
Out[18]= 15.2002 - 18.3274 x1 + 3.15 x2 - 5.3067 x3
```

```
In[19]:= aa = LinearCut[scut, 1];
  InitialSolution = Part[aa, 3]
```

```
Out[20]= {-12.5185, {x1 -> 1.33, x2 -> 0., x3 -> 0.63}}
```

```
In[21]:= xz = Part[InitialSolution, 2];
  f = (fn /. xz) + (D[fn, x1] /. xz) * (x1 - (x1 /. xz)) +
  (D[fn, x2] /. xz) * (x2 - (x2 /. xz)) + (D[fn, x3] /. xz) * (x3 - (x3 /. xz));
```

```
In[23]:= For[ii = 0, ii < 29, {
  scut = Constraints; ialg = ialg + 1; pos = Pos;
  If[ialg ≤ 2, data = Flatten[Table[{x1, x2, x3, -gpos, f},
    {x1, 0.0, Δ1, δ1}, {x2, 0.0, Δ2, δ2}, {x3, 0.0, Δ3, δ3}], 2];
  ca = Flatten[
    Table[{x1, x2, x3, -gpos}, {x1, 0.0, Δ1, δ1}, {x2, 0.0, Δ2, δ2}, {x3, 0.0, Δ3, δ3}], 2];
  cc = {}; If[ialg == 1, σ = 0.6, σ = 0.8];
  For[i = 0, i < Length[data], {If[Part[Part[data, i], 4] > 0 && Part[Part[data, i], 4] <
    σ * mxo, cc = Join[cc, {Part[data, i]}];}, i++]; data = Flatten[Table[
    {x1, x2, x3, -gpos, f}, {x1, 0.0, Δ1, δ1}, {x2, 0.0, Δ2, δ2}, {x3, 0.0, Δ3, δ3}], 2];
  If[ialg > 2,
  {data = Flatten[Table[{x1, x2, x3, -gpos, f},
    {x1, 0.0, Δ1, δ1}, {x2, 0.0, Δ2, δ2}, {x3, 0.0, Δ3, δ3}], 2];
  ca = Flatten[
    Table[{x1, x2, x3, -gpos}, {x1, 0.0, Δ1, δ1}, {x2, 0.0, Δ2, δ2}, {x3, 0.0, Δ3, δ3}], 2];
  cc = {}; If[ialg == 1, σ = 0.6, σ = 0.96];
  For[i = 0, i < Length[data],
    {If[Part[Part[data, i], 4] > 0 && Part[Part[data, i], 4] < σ * mxo &&
      Part[Part[data, i], 4] > 0, cc = Join[cc, {Part[data, i]}];}, i++];
  fg = Table[Part[Part[cc, i], 4], {i, 1, Length[cc]}];
  fo = Table[Part[Part[cc, i], 5], {i, 1, Length[cc]}];
  mxo = Max[fg];
  ev = Table[{Abs[τ * Min[fo] - Part[Part[cc, i], 5]], {i, 1, Length[cc]}}];
  eo3 = Part[Flatten[Position[ev, Min[ev]]], 1];
  kdat = Part[cc, eo3];
  kxo = Part[kdat, 4];
  kx1 = Part[kdat, 1];
  kx2 = Part[kdat, 2];
  kx3 = Part[kdat, 3];
  θ1 = (D[x1, gpos] /. {x1 -> kx1, x2 -> kx2, x3 -> kx3});
  θ2 = (D[x2, gpos] /. {x1 -> kx1, x2 -> kx2, x3 -> kx3});
  θ3 = (D[x3, gpos] /. {x1 -> kx1, x2 -> kx2, x3 -> kx3});
  kxo = Part[kdat, 4];
```

```

kx1 = Part[kdat, 1];
kx2 = Part[kdat, 2];
kx3 = Part[kdat, 3];
SharpCut1 = Simplify[γ * kxo + (θ1 * (x1 - kx1) + θ2 * (x2 - kx2) + θ3 * (x3 - kx3))];
rhs2 = Expand[FindFit[ca,
    β * kxo - ((φ1 * (x1 - kx1) + φ2 * (x2 - kx2) + φ3 * (x3 - kx3))), {φ1, φ2, φ3}, {x1, x2, x3}]];
SharpCut2 = Simplify[β * kxo - ((φ1 * (x1 - kx1) + φ2 * (x2 - kx2) + φ3 * (x3 - kx3))) /. rhs2];
coefs = {Coefficient[rhs2, x1], Coefficient[rhs2, x2], Coefficient[rhs2, x3]};
Constraints = Flatten[Join[Constraints, {SharpCut1 ≥ 0, SharpCut2 ≥ 0}]];
InitialSolution = Minimize[f, Constraints, {x1, x2, x3}];
xz = Part[InitialSolution, 2];
f = (fn /. xz) + (∂x1 fn /. xz) * (x1 - (x1 /. xz)) +
    (∂x2 fn /. xz) * (x2 - (x2 /. xz)) + (∂x3 fn /. xz) * (x3 - (x3 /. xz));
Values = {(g1 /. Part[InitialSolution, 2]), (g2 /. Part[InitialSolution, 2])};
xx = -Max[-Values];
x0 = xx; Print[-Values, x0];
If[Abs[xx] < 1.0 × 10-9, {Print[xx];
    Print[{ialg - 1, Length[cc], InitialSolution]}; Break[];]];
Pos = Part[Flatten[Position[Values, xx]], 1];
Print["Pos=", Pos, " ", xx];
If[ialg > 0, {gCut =
    ExpandAll[xx + (∂x1 gPos /. Part[InitialSolution, 2]) * (x1 - (x1 /. Part[InitialSolution, 2])) +
        (∂x2 gPos /. Part[InitialSolution, 2]) * (x2 - (x2 /. Part[InitialSolution, 2])) +
        (∂x3 gPos /. Part[InitialSolution, 2]) * (x3 - (x3 /. Part[InitialSolution, 2]))];
Constraints = Join[Constraints, {gCut ≥ 0}]];
Print[{ialg - 1, Length[cc], InitialSolution]};
Print[ialg, " ** xx=", xx];
x0 = xx; If[Abs[xx] < TOL, {Print[xx]; Break[];]];
}, ii++]

{0.0169732, 0.0149944} - 0.0169732
Pos=1 -0.0169732
{1, 454, {-11.9045, {x1 → 1.33, x2 → 0.0651405, x3 → 0.576628}}}
2 ** xx=-0.0169732
{0.00246369, 0.0782253} - 0.0782253
Pos=2 -0.0782253
{2, 441, {-11.7691, {x1 → 1.33, x2 → 0.0899583, x3 → 0.561675}}}
3 ** xx=-0.0782253
{0.00142092, 0.00198511} - 0.00198511
Pos=2 -0.00198511
{3, 249, {-10.91, {x1 → 1.28383, x2 → 0.0827767, x3 → 0.553538}}}
4 ** xx=-0.00198511
{0.00160409, 2.15616 × 10-6} - 0.00160409

```

```

Pos=1  -0.00160409
{4, 239, {-10.8993, {x1 → 1.28248, x2 → 0.0839602, x3 → 0.552937}}}
5 ** xx=-0.00160409
{1.08315×10-6, 7.85212×10-6}-7.85212×10-6
Pos=2  -7.85212×10-6
{5, 400, {-10.8309, {x1 → 1.27894, x2 → 0.0839654, x3 → 0.551351}}}
6 ** xx=-7.85212×10-6
{1.08774×10-6, 4.47036×10-11}-1.08774×10-6
Pos=1  -1.08774×10-6
{6, 224, {-10.8309, {x1 → 1.27893, x2 → 0.0839701, x3 → 0.551348}}}
7 ** xx=-1.08774×10-6
{5.02043×10-13, 6.0127×10-11}-6.0127×10-11
-6.0127×10-11
{7, 377, {-10.8308, {x1 → 1.27893, x2 → 0.0839701, x3 → 0.551347}}}

```

```
In[24]:= Values
```

```
Out[24]= { -5.02043×10-13, -6.0127×10-11 }
```

```
In[25]:= q1
```

```
Out[25]= 0.7
```

```
In[26]:= Minimize[
```

```
{fn, g1 ≥ 0, g2 ≥ 0, Δ1 - x1 ≥ 0, Δ2 - x2 ≥ 0, Δ3 - x3 ≥ 0, x1 ≥ 0, x2 ≥ 0, x3 ≥ 0}, {x1, x2, x3}]
```

```
Out[26]= {-10.9836, {x1 → 1.28346, x2 → 0.0546964, x3 → 0.560466}}
```