

EE-229 (Signal Processing-I)

Homework-2

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$$\text{Sol. 1]} \quad x(t) = u(t-3) - u(t-5) = \begin{cases} 1, & 3 \leq t < 5 \\ 0, & \text{elsewhere} \end{cases}$$

$$h(t) = e^{-3t} u(t)$$

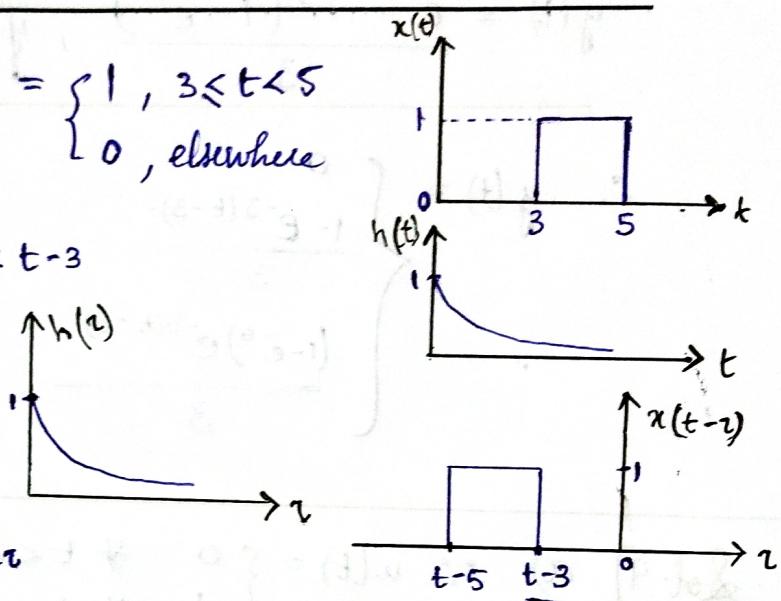
$$x(t-\tau) = \begin{cases} 1, & t-5 \leq \tau < t-3 \\ 0, & \text{elsewhere} \end{cases}$$

$$h(\tau) = e^{-3\tau} u(\tau)$$

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} x(t-\tau) h(\tau) d\tau$$

(we will 'slide' $x(t-\tau)$ to convolve)



Now, for $t-3 < 0 \Rightarrow t < 3$, $\therefore x(t-\tau)$ will have NO overlap with $h(\tau)$,
 $\therefore y(t) = 0 \quad \forall t < 3$.

For $(t-3) \geq 0$ and $(t-5) < 0 \Rightarrow t \in [3, 5]$, there will be overlapping of samples and the limits of integration will be from $\tau=0$ to $\tau=t-3$.

$$\therefore y(t) = \int_0^{t-3} x(t-\tau) h(\tau) d\tau = \int_0^{t-3} (1) e^{-3\tau} d\tau$$

$$y(t) = \left[-\frac{e^{-3\tau}}{3} \right]_0^{t-3} = -\frac{(e^{-3(t-3)} - e^{-3(0)})}{3}$$

$$y(t) = \frac{1 - e^{-3(t-3)}}{3}, \quad \forall t \in [3, 5]$$

\therefore For $(t-3) < \infty$ and $(t-5) \geq 0 \Rightarrow t \in [5, \infty)$,

the overlap of samples can be computed by applying bounds of integration from $\tau = t-5$ to $\tau = t-3$.

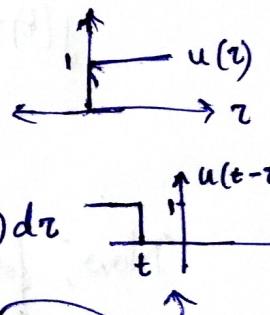
$$\begin{aligned}\therefore y(t) &= \int_{t-5}^{t-3} x(t-\tau) h(\tau) d\tau = \int_{t-5}^{t-3} 1 e^{-3\tau} d\tau \\ &= \left[-\frac{e^{-3\tau}}{3} \right]_{t-5}^{t-3} = \frac{e^{-3(t-5)} - e^{-3(t-3)}}{3}\end{aligned}$$

$$y(t) = \frac{e^{-3(t-5)}(1-e^{-6})}{3}, \text{ if } 5 \leq t < \infty$$

$$\therefore y(t) = \begin{cases} 0 & -\infty < t < 3 \\ \frac{1-e^{-3(t-3)}}{3} & 3 \leq t < 5 \\ \frac{(1-e^{-6})e^{-3(t-5)}}{3} & 5 \leq t < \infty \end{cases}$$

Sol. 9] a) $\therefore u(t) = \begin{cases} 0 & \# t < 0 \\ 1 & \# t \geq 0 \end{cases}$

The convolution integral simplifies to $r(t) = \int_0^t u(\tau) \cdot u(t-\tau) d\tau$ due to the limited range of integration.



$\# t < 0$, $u(r)$ and $u(t-r)$ will be zero (as shown in plots)

\therefore they're defined only for $r \geq 0$. $\therefore r(t) = 0 \# t < 0$.

When $t \geq 0$, both $u(r)$ and $u(t-r)$ will be equal to 1

for $0 \leq r \leq t$. $\therefore r(t) = \int_0^t 1 \cdot 1 dr = t$

$$\therefore r(t) = \begin{cases} 0 & \# t < 0 \\ t & \# t \geq 0 \end{cases}$$

b)

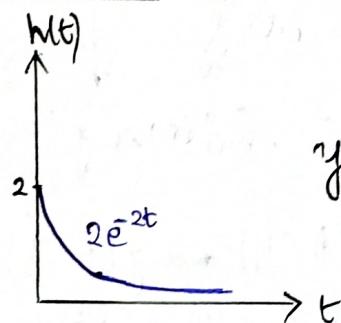
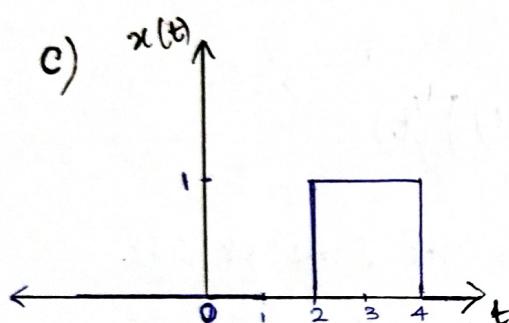
$$x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) \cdot h(t-\tau) d\tau = \int_{-\infty}^{\infty} x(t-\tau) h(\tau) d\tau$$

\because the first are multiplied by $u(\tau)$ and $u(t-\tau)$,
the convolution integral reduces to :

$$(x * h)(t) = \int_0^t (10e^{-3(t-\tau)} u(t-\tau)) \cdot (-e^{-\tau} + 2e^{-2\tau}) u(\tau) d\tau$$

$$= 10e^{-3t} \int_0^t (2e^{-\tau} - e^{2\tau}) d\tau = 10e^{-3t} \left[2e^{-\tau} - \frac{e^{2\tau}}{2} \right]_0^t$$

$$(x * h)(t) = 10e^{-3t} \left(2e^{-t} - \frac{e^{2t}}{2} - \frac{3}{2} \right)$$



$$\begin{aligned} y(t) &= (x * h)(t) \\ &= \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \\ &= \int_{-\infty}^{\infty} x(t-\tau) h(\tau) d\tau \end{aligned}$$

for $t-2 < 0 \Rightarrow t < 2$, $\therefore h(\tau < 0) = 0$, \therefore No overlap.

$$\therefore y(t) = 0, \quad t < 2.$$

for $t-2 \geq 0$ and $t-4 < 0 \Rightarrow t \in [2, 4]$,

$$y(t) = \int_0^{t-2} 1 \times 2e^{-2\tau} d\tau = \left[\frac{2}{(-2)} e^{-2\tau} \right]_0^{t-2} = 1 - e^{4-2t}, \quad 2 \leq t < 4.$$

for $t-4 \geq 0 \Rightarrow t \geq 4$,

$$y(t) = \int_{t-4}^{t-2} 2e^{-2\tau} d\tau = \left[\frac{2}{(-2)} e^{-2\tau} \right]_{t-4}^{t-2} = e^{8-2t} - e^{4-2t}, \quad t \geq 4.$$

$$\therefore y(t) = \begin{cases} 0, & t < 2. \\ 1 - e^{4-2t}, & 2 \leq t < 4. \\ e^{4-2t}(e^4 - 1), & t \geq 4. \end{cases}$$

$$\text{Sol. 10] a) } \because (f * g)(t) = \int_{-\infty}^{\infty} f(\tau) \cdot g(t - \tau) d\tau$$

$$\therefore f(t - T_1) * g(t - T_2)(t) = \int_{-\infty}^{\infty} f(\tau - T_1) \cdot g(t - \tau - T_2) d\tau$$

now, substitute $u = \tau - T_1 \Rightarrow \tau = u + T_1$ and $d\tau = du$:

$$\therefore (f(t - T_1) * g(t - T_2))(t) = \int_{-\infty}^{\infty} f(u) \cdot g(t - T_2 - (u + T_1)) du$$

$$= \int_{-\infty}^{\infty} f(u) \cdot g(t - (T_1 + T_2) - u) du$$

let $T' = T_1 + T_2$, then



$$(f(t - T_1) * g(t - T_2))(t) = (f(t) * g(t - T'))(t)$$

\Rightarrow The convolution of $f(t - T_1)$ and $g(t - T_2)$ is the same as the convolution of $f(t)$ and $g(t)$ shifted by $T' = \underline{T_1 + T_2}$.

$$\therefore [f(t - T_1) * g(t - T_2)] = f(t) * g(t - T_1 - T_2).$$

$$\text{b) } (u(t+1) - u(t-2)) * (u(t-3) - u(t-4))$$

$$= u(t+1) \{u(t-3) - u(t-4)\} - u(t-2) \{u(t-3) - u(t-4)\} \quad [\text{Distributive property}]$$

$$= u(t) * u(t-2) - u(t) * u(t-3) - u(t) * u(t-5) + u(t)u(t-6)$$

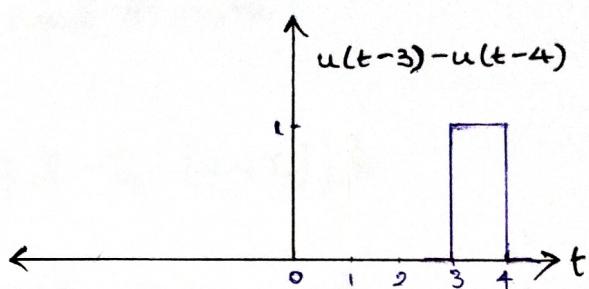
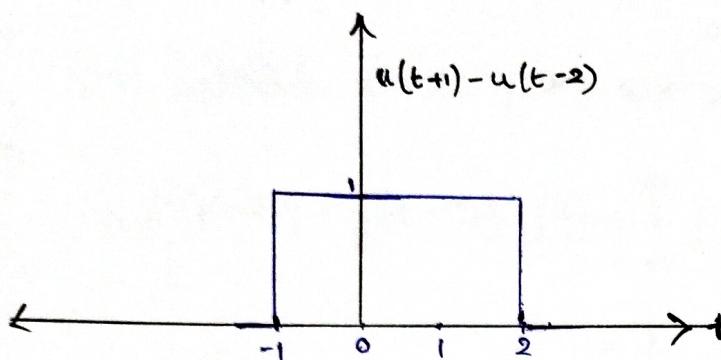
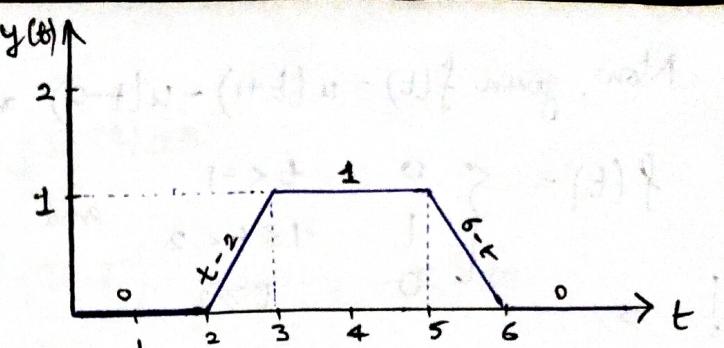
[result proved above]

$$= r(t-2) - r(t-3) - r(t-5) + r(t-6) \quad (\text{using } u(t) * u(t) = r(t))$$

$$= \begin{cases} t-2 & , t \in (2, 3) \\ (t-2) - (t-3) & , t \in [3, 5] \\ (t-2) - (t-3) - (t-5) & , t \in [5, 6) \\ (t-2) - (t-3) - (t-5) + (t-6) & , t \in [6, \infty) \end{cases}$$

↓
ramp fn

$$= \begin{cases} 0 & , t < 2 \\ t-2 & , 2 \leq t < 3 \\ 1 & , 3 \leq t < 5 \\ 6-t & , 5 \leq t < 6 \\ 0 & , t \geq 6 \end{cases}$$



As plotted above, the convolution of two rectangular pulses gives rise to a trapezoidal plot. If we imagine sliding the 1-unit width long bar on (shown on the plot on right side) through the rectangular plot on the left, then it sweeps as much area as in the left plot itself. This is exactly equal to the area under the convolved plot (= 3 sq. units). Hence, the result has been graphically verified.

Sol 11] Given, $y(t) = f(t) * g(t) = \int_{-\infty}^{\infty} f(\tau) g(t-\tau) d\tau$

Now, $(f(ct) * g(ct))(t) = \int_{-\infty}^{\infty} f(c\tau) g(ct - c\tau) d\tau$

(NOTE: $c\tau$ and $ct - c\tau$ are new variables of integration, following the same rule of as t and $t-2$ in the original convolution)

$$\therefore (f(ct) * g(ct))(t) = \int_{-\infty}^{\infty} f(u) g\left(c(t - \frac{u}{c})\right) \frac{du}{c}$$

$$\boxed{ct = u}$$

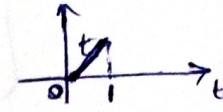
$$\boxed{c du = du}$$

$$\therefore \boxed{(f(ct) * g(ct))(t) = \frac{1}{c} \int_{-\infty}^{\infty} f(u) g\left(c(t - \frac{u}{c})\right) du}$$

→ This gives convolution of scaled f(t) and g(t) at time t, given a general scaling factor 'c'.

Now, given $f(t) = u(t+1) - u(t-2)$ and $g(t) = u(t)(u(t) - u(t-1))$

$$f(t) = \begin{cases} 0 & t < -1 \\ 1 & -1 \leq t < 2 \\ 0 & t \geq 2 \end{cases} \quad \text{and} \quad g(t) = \begin{cases} 0 & t < 0 \\ t & 0 \leq t < 1 \\ 0 & t \geq 1 \end{cases}$$



$$\therefore (f(t) * g(t))(t) = \begin{cases} 0 & , t+1 < 0 \\ \int_0^{t+1} 1 \cdot t dt & , 0 \leq t+1 < 1/2 \\ 0 & , 1+t \geq 1/2 \end{cases} = \begin{cases} 0 & , t < -1 \\ \frac{(t+1)^2}{2} & , -1 \leq t < -1/2 \\ 0 & , -1/2 \leq t \end{cases}$$

Using the derived formula,

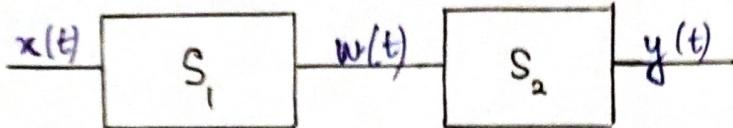
$$\text{we compute } (f(2t) * g(2t))(t) =$$

$$\boxed{\begin{cases} 0 & , t < 0.5 \\ (t + \frac{1}{2})^2 & , 0.5 \leq t < 0 \\ 0 & , t \geq 0 \end{cases}}$$

Ques. 13] Given, $x(t) = e^{-2t}u(t)$, $h(t) = e^{-t}u(t)$.

$S_1 \rightarrow y(t) = x(2t)$ $S_2 \rightarrow$ impulse response $h(t) = e^{-t}u(t)$.

Case 1:



$$\therefore w(t) = x(2t) = e^{-2(2t)}u(2t) = e^{-4t}u(2t)$$

$$y(t) = w(t) * h(t) = \int_{-\infty}^{\infty} w(\tau) h(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} e^{-4\tau} u(2\tau) e^{-(t-\tau)} u(t-\tau) d\tau$$

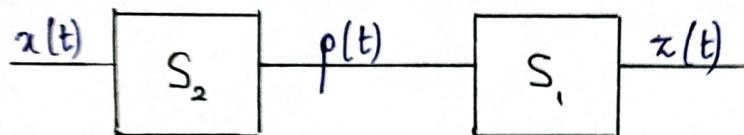
$\downarrow \quad \quad \quad \downarrow$

$= 1 \text{ if } \tau \geq 0 \quad = 1 \text{ when } \tau \leq t$

$$\therefore (w * h)(t) = \int_0^t e^{-4\tau} e^{-(t-\tau)} d\tau = \int_0^t e^{-3\tau-t} d\tau$$

$$\Rightarrow y(t) = \frac{1}{-3} (e^{-3\tau-t}) \Big|_0^t = \boxed{\frac{1}{3} (e^{-t} - e^{-4t})}$$

Case 2:



$$\therefore p(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} e^{-2\tau} u(2\tau) e^{-(t-\tau)} u(t-\tau) d\tau$$

$\downarrow \quad \quad \quad \downarrow$

$= 1 \text{ when } \tau \geq 0 \quad = 1 \text{ when } \tau \leq t$

$$\therefore (x * h)(t) = \int_0^t e^{-2\tau} e^{-(t-\tau)} d\tau = \int_0^t e^{-\tau-t} d\tau$$

$$\Rightarrow p(t) = -e^{-\tau-t} \Big|_{\tau=0}^{t=t} = (e^{-t} - e^{-2t}).$$

$$\text{Now, } z(t) = p(2t) = \boxed{e^{-2t} - e^{-4t}}$$

$$\therefore \boxed{y(t) \neq z(t)}$$

- * The OUTPUTS were expected to be **NOT EQUAL** because of 'S' being a **NON-LTI system** in the cascaded connections. Clearly, the result affirms it.

[REASON: $y(t) = x(2t)$ \rightarrow time being scaled, \therefore NOT time-invariant]

Sol. 14] a) TRUE

If $h(t) \rightarrow$ periodic and non-zero, then $\int_{-\infty}^{\infty} |h(t)| dt \rightarrow \infty \therefore \text{UNSTABLE.}$

b) FALSE

Counterexample: $x[n] = \delta[n-1] \xrightarrow{\text{inverse}} y[n] = \delta[n+1]$
(CAUSAL) (NON-CAUSAL)

c) FALSE

Standard counterexample is the unit fn: $x[n] = u[n] \therefore \sum_{n=-\infty}^{\infty} |x[n]| \rightarrow \infty.$

d) TRUE

Now that $h[n] \rightarrow$ finite duration (say, n_1 to n_2) then $\sum_{k=n_1}^{n_2} |h[k]| < \infty$
(BOUNDED)

e) FALSE

Counterexample: $x[n] = u[n] \rightarrow \text{Causal but NOT stable.}$

f) FALSE

Consider $S_1: h_1[n] = \delta[n-k] \xrightarrow{\text{causal}}$ and $S_2: h_2[n] = \delta[n+k] \xrightarrow{\text{non-causal}}$
 $\Rightarrow y[n] = h_1[n] * h_2[n] = \delta[n]. \xrightarrow{\text{causal}}$

g) TRUE

$\int_{-\infty}^{\infty} |h(t)| dt < \infty \Rightarrow \text{BOUNDED} \therefore \text{Stable.}$

h) FALSE

Causality has \leftarrow nothing to do with past values being enforced to zero. It may be causal even for non-zero values for $n < 0$, provided it does NOT depend on 'future' values.