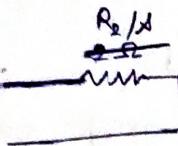


Sol. 1]

440V, 3φ, 50Hz, 945 rpm
6 pole, Y-connected

$$r_1 = 0 \Omega \quad r_2' = 2 \Omega$$

$$x_1 = 0 \Omega \quad x_2' = 0 \Omega$$

$$X_M, \text{rot. losses} = 0$$

Rated Torque of motor :

$$T_{\text{rated}} = \frac{P_{\text{gap}}}{\omega_{\text{synch}}} = \frac{3 I_2'^2 (R)}{\omega_s}$$

$$f = 50 \text{ Hz} \therefore N_s = \frac{120 \times 50}{6} = 1000 \text{ rpm}$$

$$\therefore \delta = \frac{1000 - 945}{1000} = 0.055$$

Now, given T_L is INDEPENDENT of speed

$$\therefore T_L = \frac{3}{\omega_s} \left[\frac{V_t}{(r_2'/s)} \right]^2 (r_2'/s) = \text{CONST}$$

$$\Rightarrow \delta V_t^2 = \text{CONST} \quad \Rightarrow \frac{V_t^2}{\text{rated}} = \delta V_t^2$$

$$\delta = \frac{1000 - 800}{1000} \leftarrow$$

$$= 0.2$$

$$(0.055) \left(\frac{440}{\sqrt{3}} \right)^2 = 0.2 V_t^2$$

$$\Rightarrow V_t = 133.2166 \text{ V}$$

$$\therefore (V_t)_{LL} = 230.73 \text{ V}$$

ii) Given that freq = 50Hz \rightarrow Kept ~~const~~ const
and that now required ~~Ns~~ = 800 rpm

$$\therefore \text{slip has to be } \frac{1000 - 800}{1000} = 0.2$$

and we just calculated that V_t required to acquire a slip of 0.2 at rated conditions to be $V_t = 133.21 \text{ V}$

$$\left(\text{from } \frac{3}{\omega_s} \times \frac{1}{s} \times \left(\frac{V_t}{r_2/s} \right)^2 = \text{rated Torque} = \frac{3}{\omega_s} \frac{(440/\sqrt{3})^2}{(R_2/s + 0.055)} \right)$$

\therefore the current drawn in this case = $\frac{133.21}{\epsilon} \times 0.2 = 13.32 A$

But ... at rated condition,

$$I_2' = \frac{V_t}{(r_2'/s)} = \frac{440/\sqrt{3}}{(2/0.055)} = 6.99 A$$

\therefore current drawn > rated current, overheating occurs.

Load torque that can be born while drawing rated current ($6.99A$)

$$T_L = \frac{3}{\left(\frac{2\pi}{60}(1000)\right)} \times (6.99)^2 \times \frac{2\pi}{0.2} = 13.97 Nm$$

$$\therefore \% \text{ reduction in } T_L \text{ reqd} = \frac{50.831 - 13.97}{50.831} \times 100\% = \boxed{72.51\%}$$

Now, let the per-phase stator voltage = V .

$$\frac{V}{(r_2'/s)} = \cancel{6.99} \Rightarrow \frac{V}{(2/0.2)} = 6.99 \Rightarrow V = 69.9 V$$

$$\therefore V_{(L-L)} = \sqrt{3} \times 69.9 \approx \boxed{121 V}$$

Sol. 2]

440V, 3φ, 50Hz, 4 pole, 1420 rpm Δ -load IM

with $r_1 = 0.5\Omega$, $r_2' = 0.4\Omega$, $x_1 = 0.5\Omega$, $x_2' = 0.8\Omega$

$$\frac{120 \times 50}{4} = 1500$$

~~$\therefore s = \frac{1500 - 1420}{1500}$~~

$$\boxed{s = 4/75}$$

Let applied voltage $\rightarrow k \cdot 440 V$ and applied freq $\rightarrow k \cdot 50 Hz$

\because the motor is fed from VSI at rated values to negotiate const $T_L = 485 Nm$,

$$\therefore \frac{3}{\left[\frac{2\pi}{60}(1000)\right]} \times \frac{(440)^2}{(0.8)^2 + \left(\frac{0.4}{sk}\right)^2} \times \frac{0.4}{(4/75) \times k} = 485$$

$$\Rightarrow \frac{3}{157.08} \times \frac{440^2}{(0.8)^2 + \left(\frac{0.4}{sk}\right)^2} \times \frac{0.4}{sk} = 485$$

$$\Rightarrow 0.21 (sk)^2 - sk + 0.05 = 0$$

~~$\Rightarrow sk = 0.05, 4.71$~~

$$\text{Now, } sk = \frac{k(1500 - 700)}{k(1500)}$$

$$\Rightarrow sk = \left(\frac{k(1500 - 700)}{1500}\right) = 0.05$$

$$K \cdot 7500 = 700 + 75 \Rightarrow K = 0.516$$

$$\therefore V_t \text{ applied} = K \cdot 440 = \boxed{227.04V}$$

$$f_{\text{rated}} = 0.516 \times 50 \text{ Hz}$$

$$\therefore \boxed{25.8 \text{ Hz}}$$

Sol. 3] Rated slip = $\frac{1500 - 1420}{1500} = 0.05$ rated

Rated current = 440

$$= \frac{440}{\sqrt{\left(\frac{0.4}{0.05}\right)^2 + 0.82^2}} = \frac{440}{0.4} \times 0.05 = \boxed{55A}$$

$$\therefore \text{Rated Torque} = \frac{3}{\left[\frac{2\pi}{60} (1500)\right]} \times 55^2 \times \frac{0.4}{0.05} = 462.2 \text{ Nm}$$

$$\therefore \frac{1}{2} \text{ rated Torque} = 231.1 \text{ Nm}$$

\because given the m/c is operating in 4th Quadrant $\Rightarrow T_2$ +ve, speed -ve.

$$\therefore \frac{3}{157.07} \cdot \frac{440^2}{0.4} \times k = 231.10 \Rightarrow 2k = 0.024$$

$$\text{Now, } s = \frac{K \cdot 1500 - (-1500)}{K \cdot 1500} \Rightarrow sK = \frac{K \cdot 1500 + 1500}{1500} = 0.024$$

$$\Rightarrow K + 1 = 0.024 \Rightarrow K = -0.976$$

meant phase sequence of voltage has been reversed.

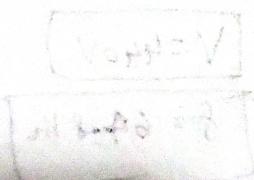
$$\therefore \text{applied voltage} = 440 \times 0.976 = \boxed{429.44V}$$

$$\therefore \text{freq} = 50 \times 0.976 = \boxed{48.8 \text{ Hz}}$$

\hookrightarrow implied that its current synchronous speed
 $= \frac{120 \times 488}{4} = 1464 \text{ rpm}$

\therefore m/c in braking mode \hookrightarrow $< 1500 \text{ rpm}$
(machine speed)

imperial = 1000 ft/min. Then no. of h.p. ratings will be ..



$$\frac{1000 \times 1000}{2021} = 49.4 \text{ ..}$$

Ques-4] EV: 3 ϕ inverter-fed 440V, 50Hz, 3 ϕ , 4pole, 1420 rpm, Δ-IM
with $r_1 = 0$, $r_2' = 0.4 \Omega$, $x_1 = 0 \Omega$, $x_2' = 0 \Omega$ → controlled by
V-f method.

$$\therefore \text{rated Torque} = \frac{3}{\left[\frac{2\pi}{60} (1500) \right]} \times \frac{440^2}{0.4} \times \frac{(1500 - 1420)}{1500}$$

$$= \frac{3}{157.07} \times 55^2 \times \frac{0.4}{0.05} = 462.2 \text{ Nm}$$

$$\therefore \frac{1}{4}^{\text{th}} \text{ rated torque} \approx 115.6 \text{ Nm}, \quad \frac{1}{2} \text{ rated Torque} = 231.1 \text{ Nm}$$

a) $\omega_s = 2000 \text{ rpm} \rightarrow \text{above base speed!}$

$$\therefore \text{for speeds above base speed, } \omega_s = N_s \times \frac{2\pi}{60}$$

$$V = V_{\text{rated}} \quad f = f_{\text{rated}}$$

$$\therefore 115.6 = \frac{3}{\left[\frac{2\pi}{60} (2000) \right] (1-s)} \times \left[\frac{440^2}{(0.4)} \right] = \frac{3 \times 30 \times 440^2}{2000\pi \times 0.4} s(1-s)$$

$$\Rightarrow 0.015 = s - s^2 \Rightarrow s = 0.015, \quad \cancel{s = 0.99}$$

$$\delta' = 0.015 \Rightarrow N_s' = 2030 \text{ rpm}$$

$$f' = \frac{N_s' - N_r}{N_s'} = 50.8 \text{ Hz}$$

$$\text{b) breaking Torque} = \frac{1}{2} T_{\text{rated}}$$

$$\Rightarrow \frac{3}{\frac{\omega_s}{(1-s')}} \times \frac{V_t^2}{(N_s'/s')} = 231.1 \text{ Nm} \Rightarrow \delta' - \delta + 0.0265 = 0$$

$$\delta' = 0.027$$

$$\therefore \omega_s = \frac{2000}{(1-s)} \approx 2055 \text{ rpm}$$

\therefore current synchr. speed for -ve T with $\omega_{s2} = 2000 \text{ rpm}$

$$= 2000 - 55 = 1945 \text{ rpm}$$

$$\therefore k = \frac{1945}{1500} = 1.296$$

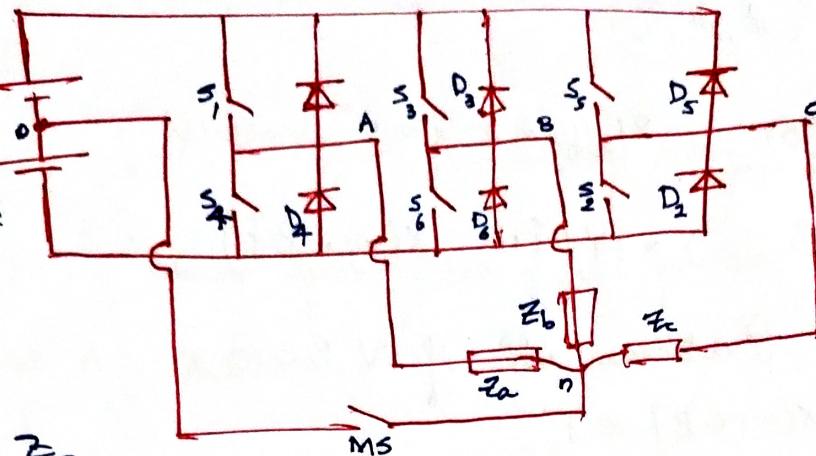
$$V = 440V$$

$$f = 64.8 \text{ Hz}$$

Sol. 5]

$$200V = \frac{V_d}{2}$$

$$200V = \frac{V_d}{2}$$



$$Z_a = Z_b = Z_c$$

[BALANCED]

$$V_{ctr} = 0.5V$$

$$f_{ctr} = 25Hz$$

$$V_{tri} = 1V$$

$$f_{tri} = 2625Hz$$

SPWM

$$\therefore m_a = \frac{0.5}{1} = 0.5 \quad \text{and} \quad m_f = \frac{2625}{25} = 105.$$

$$\Rightarrow (\hat{V}_{AO})_1 = m_a \cdot \frac{V_d}{2} = 0.5 \times \frac{400}{2} = 100V$$

$$\therefore (\hat{V}_{AB})_1 = (\hat{V}_{AO})_1 \cdot \sqrt{3} = 173.2V$$

Now, SPWM \Rightarrow harmonic spectrum: $f_h = (jm_f \pm k) f_i$

$$h = j(m_f) \pm k$$

* If j is odd, $k \rightarrow$ even.

