## **ASSIGNMENT 3**

**COURSE:** Naan Mudhalvan (Internet of Things)

**Team ID** : NM2023TMID15707

**Team Leader**: SRISABARI S

**Team member:** SHARUKESHAN R

**Team member:** VEDANAYAGAM L

**Team member:** SRUTHIE N

#### **Question:**

Build wowki product, use ultrasonic sensor and detect the distance from the object. Whenever distance is less than 100cms upload the value to the ibm cloud.in recent device events upload the data from wokwi.

Example: distance is 20 cms. Upload the 20 value to the ibm cloud in recent event in the ibm iot platform device.

#### **Requirement:**

- Wokwi Platform
- Ibm cloud

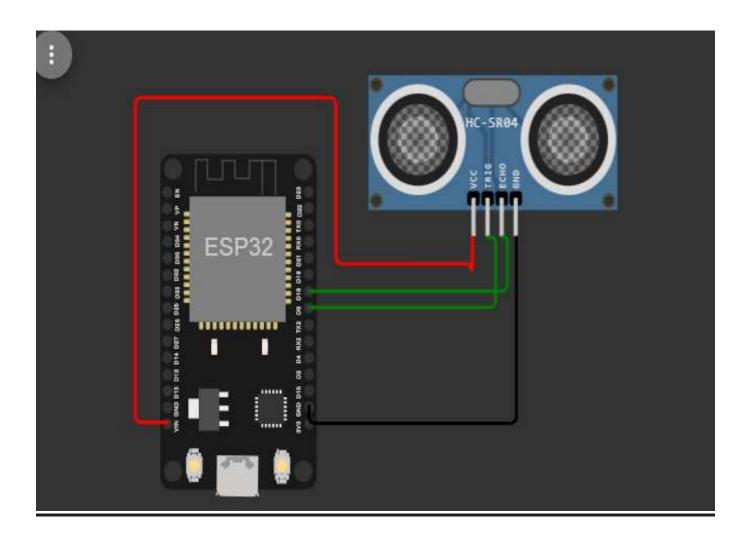
#### **Wokwi Project Link:**

https://wokwi.com/projects/364169802473364481

# **Components Required:**

- ESP 32
- Ultrasonic sensor

# **Connection:**



### **PROGRAM:**

```
#include <WiFi.h>
#include < PubSubClient.h >
void callback(char* subscribetopic, byte* payload, unsigned intpayloadLength);
//----credentials of IBM Accounts- - -
#define ORG "z0daqf"//IBM ORGANITION ID
#define DEVICE TYPE "ESP32"//Device type mentioned in ibm watson
IOTPlatform
#define DEVICE ID "12345"//Device ID mentioned in ibm watson IOTPlatform
#define TOKEN "kUbT7UdS(+g75i(qcB" //Token
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback, wifiClient);
const int trigPin = 5;
const int echoPin = 18;
#define SOUND SPEED 0.034
long duration;
float distance;
void setup()
```

```
Serial.begin(115200);
 pinMode(trigPin, OUTPUT);
 pinMode(echoPin, INPUT);
 wificonnect();
 mqttconnect();
void loop()
{
 digitalWrite(trigPin, LOW);
 delayMicroseconds(2);
 digitalWrite(trigPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 duration = pulseIn(echoPin, HIGH);
 distance = duration * SOUND SPEED/2;
 Serial.print("Distance (cm): ");
 Serial.println(distance);
 if(distance<100){Serial.println("ALERT!!");
 delay(1000);
 PublishData(distance);
 delay(1000);
 if (!client.loop()) {mqttconnect();
 } }
 delay(1000);
```

```
}
void PublishData(float dist)
{
mqttconnect();
String payload = "{\"Distance\":";
payload += dist;
payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str()))
  Serial.println("Publish ok");
  }
  else
   Serial.println("Publish failed");
void mqttconnect()
 if (!client.connected())
  {
   Serial.print("Reconnecting client to ");
   Serial.println(server);
```

```
while (!!!client.connect(clientId, authMethod, token))
   Serial.print(".");
   delay(500);
   initManagedDevice();
   Serial.println();
void wificonnect()
 Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while(WiFi.status() != WL CONNECTED)
  {
   delay(500);
   Serial.print(".");
   Serial.println("");
   Serial.println("WiFi connected");
   Serial.println("IP address: ");
   Serial.println(WiFi.localIP());
 void initManagedDevice()
```

```
if (client.subscribe(subscribetopic))
   {
    Serial.println((subscribetopic));
   Serial.println("subscribe to cmd OK");
    else {
     Serial.println("subscribe to cmd FAILED");
      }
void callback(char* subscribetopic, byte* payload, unsigned intpayloadLength)
{
 Serial.print("callback invoked for topic: ");
 Serial.println(subscribetopic);
 for(int i = 0; i < intpayloadLength; i++)
  Serial.print((char)payload[i]);
  data3 += (char)payload[i];
  Serial.println("data: "+ data3);
  data3="";
```

## Diagram.json:

```
{
 "version": 1,
 "author": "SRISABARI S",
 "editor": "wokwi",
 "parts": [
  { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": 27.31, "left": -103.79,
"attrs": {} },
   "type": "wokwi-hc-sr04",
   "id": "ultrasonic1",
   "top": -17.03,
   "left": 37.63,
   "attrs": { "distance": "116" }
 ],
 "connections": [
  ["esp:TX0", "$serialMonitor:RX", "", []],
  [ "esp:RX0", "$serialMonitor:TX", "", []],
  ["esp:D18", "ultrasonic1:ECHO", "green", ["h135.2", "v-44.63"]],
  ["esp:D5", "ultrasonic1:TRIG", "green", ["h127.2", "v-51.56"]],
  ["ultrasonic1:GND", "esp:GND.1", "black", ["v108.93", "h-145.1"]],
   "ultrasonic1:VCC",
   "esp:VIN",
```

```
"red",

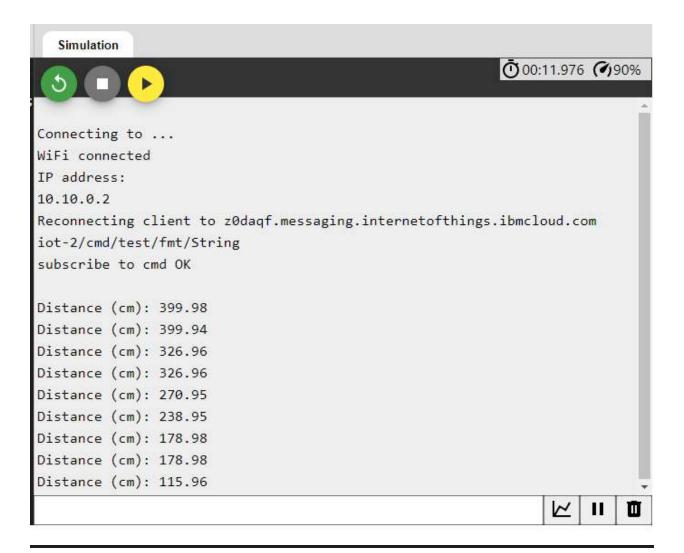
[ "v18.93", "h-1.1", "v-3.33", "h-92", "v-97.33", "h-136.67", "v201.33" ]

]

],

"dependencies": {}
```

## **Simulation output:**



## **Ibm cloud:**

