



Intel(R) Perceptual Computing SDK Demo Application

Glass Balls

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Notice revision #20110804

2 Introduction

The Intel® Perceptual Computing SDK is a library of pattern detection and recognition algorithm implementations exposed through standardized interfaces. The library aims at lowering barriers to using these algorithms and shifting the application developers' focus from coding the algorithm details to innovating on the usage of these algorithms for next generation human computer experience.

This document describes the `GlassBalls` demo application.

Document Convention

The SDK document uses the Calibri typeface for normal prose.

With the exception of section headings, captions and the table of contents, all code-related items appear in the Courier New typeface (`pxcStatus`).

Hyperlinks appear underlined in blue, such as [pxcStatus](#).



This is a note that provides additional information to aid your understanding of the procedure or concept.



This is a tip that provides alternate methods or shortcuts.



This is a result statement which indicates what you can expect to see or happen after performing a step.

3 Glass Balls

`GlassBalls` is a sample application that showcases hand interaction with physical objects (glass balls). The user will be able to use his/her fingertips to interactive with glass balls. The application uses the Unity* game engine for 3D visualization and physics interaction.

The application directory structure is as follows:

Directory/File	Description
<code>Assets</code> <code>ProjectSettings</code>	The Unity assets and project setting directories that contain buildable source code.
<code>doc</code>	The directory that contains this document, and two farm pictures.
<code>GlassBalls_Data</code> <code>GlassBalls.exe</code>	The prebuilt application executable and data files.

3.1 Operation Instructions

Run the prebuilt executable `GlassBalls.exe` to start the application. By default, the application uses the screen resolution 800x600. The user can do one of the following to change the screen resolution, as illustrated in Figure 1:

- Start the application by holding down the SHIFT key.
- Start the application in a DOS command prompt window.

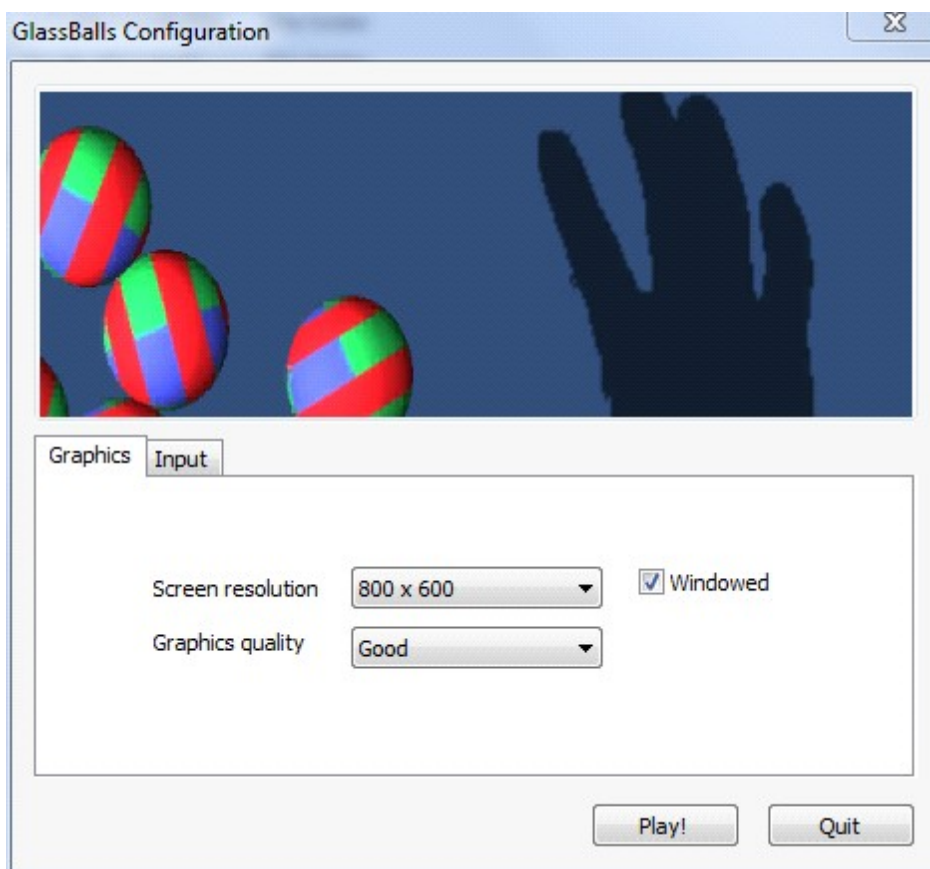


Figure 1: Screen Resolution Configuration

The application shows a few glass balls at the center of the screen, and some instructions and buttons at the left. When the user shows his/her hand(s) in front of the camera, the application will visualize with the hand shadow(s). The user will be able to use the shadow fingertip(s) to interact with the glass balls, as illustrated in Figure 2.

Click the Show Fingertips button will show the actual interaction points as illustrated in Figure 2. It is recommended to hide the points to make the experience more natural.

The application applies a constant force towards the center of the screen to the balls so that the balls do not fly away. Thus the balls always have a tendency to gather around the center of the screen. In rare cases, mostly due to unreliable fingertip detection, the balls may suddenly gain huge velocity and fly off the screen. Click the Restart button to re-start the application.

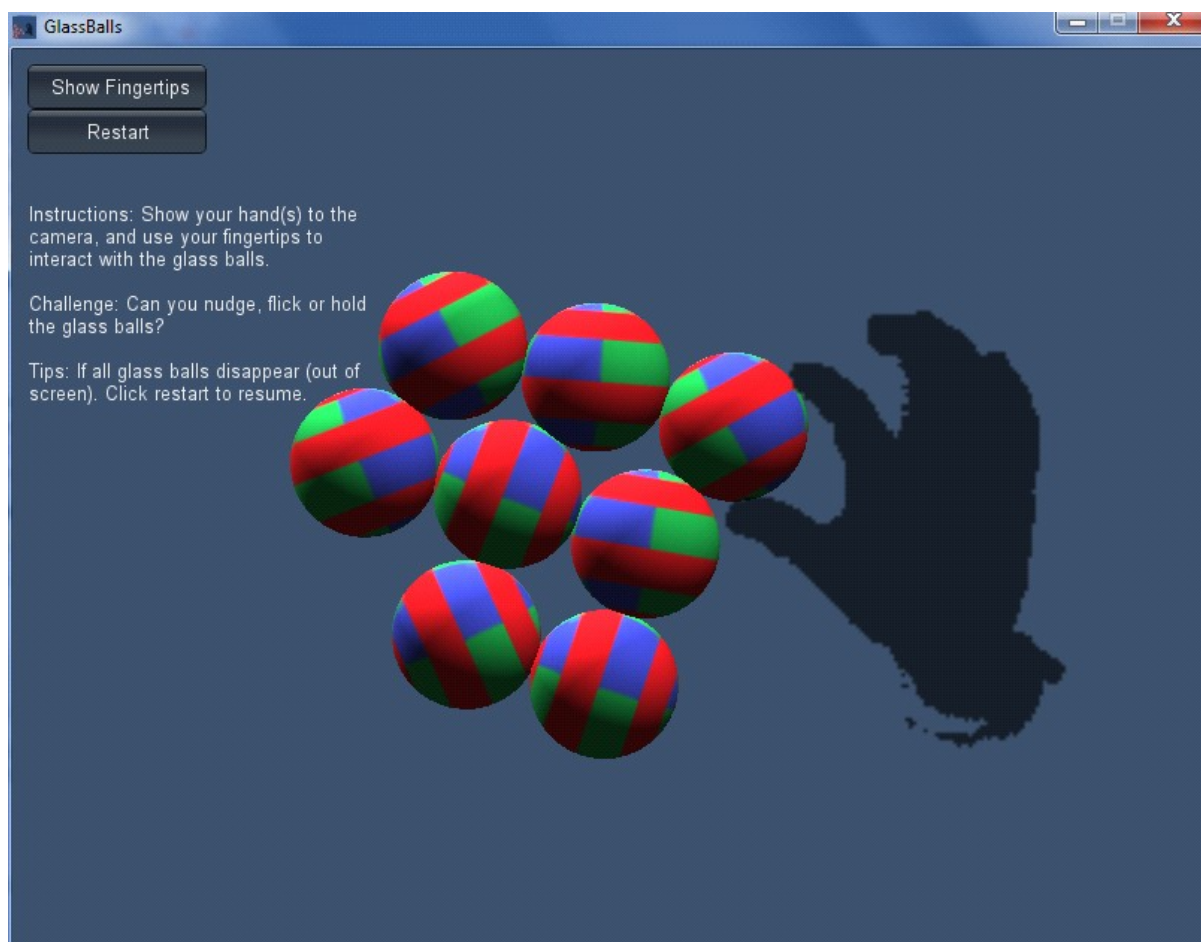


Figure 2: Hand Interaction with GlassBalls

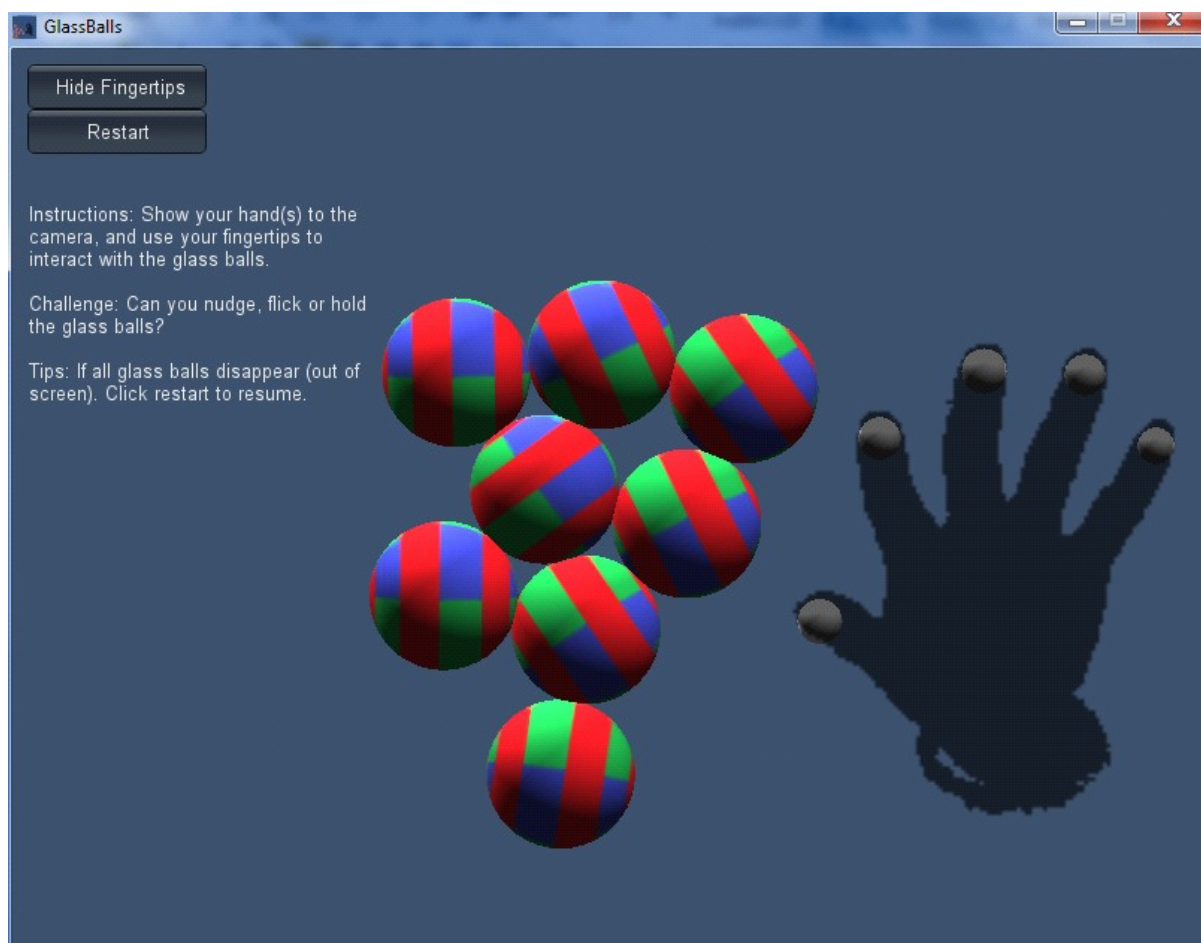


Figure 3: Fingertip Interaction Points

3.2 Build Instructions

The application comes with source code in the `Assets` and `ProjectSettings` directories. The solution file is under `Assets/GlassBalls.unity`. Launch Unity by double clicking on the solution file. Then the developer will be able to make modification or rebuild the application. The application is tested under Unity PRO 3.5.1f2.

3.3 Design Points

This section describes the application design that is related to Intel® Perceptual Computing SDK and is not meant to be a code walkthrough of all application designs.

The application creates 8 glass balls with limited Z-axis movement so that they move only in the

XY 2D space. Each glass ball is a rigidbody sphere, whose movement is governed by physical interaction. The script `BallScript.cs` attached to each glass ball applies constant force to the ball to make it by default move to the center of the screen. The script also checks whether the ball flies out of screen. If so, move it back.

The application also creates 10 fingertips (primary and secondary hands in the view). Each fingertip is a kinematic rigidbody sphere, whose size and position are assigned, at fixed interval, from detected finger parameters. See the script `Fingertip.cs` for details.

As the user interacts with the glass balls, the fingertip sphere objects interact with the glass ball sphere objects and cause the glass ball sphere objects to move in different directions.

The `ShadowHand.cs` script runs the SDK finger tracking pipeline and displays the shadow hand(s) onto the screen. At each frame, the script retrieves the detected labelmap, removes any background and displays the shadow hand image. The script also retrieves detected fingertip parameters, to be used by the `Fingertip.cs` script.

The script `Options.cs` handles on-screen instructions and button clicks.