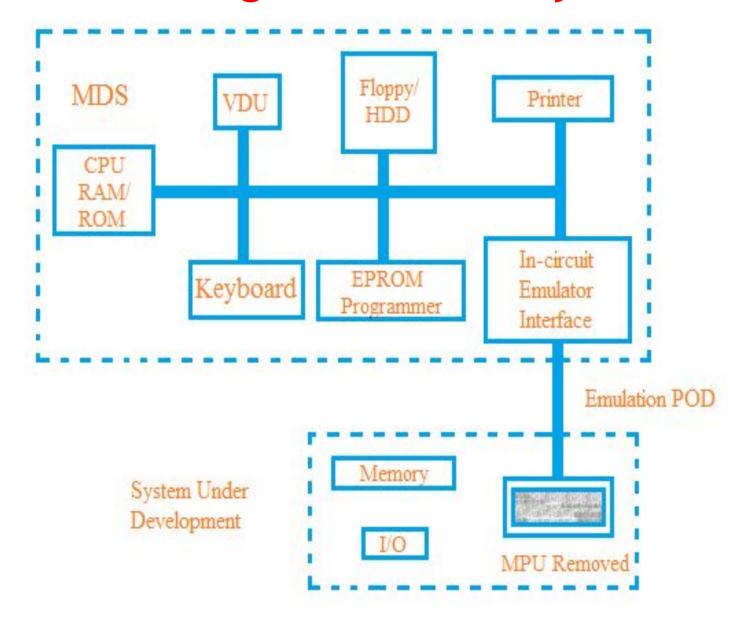
Microprocessor Development System

MDS Hardware SystemMDS Software SystemTypical Development Steps

Microprocessor development system

- ☐ MDS is a microcomputer.
- Combination of special purpose software and hardware, which are provide to aid the design and development of MPU based system.
- ☐ Allow user to develop s/w for any given application based on the particular MPU.
- ☐ Create an environment to test and debug the target H/W.
- ☐ Facilitate integration of the S/W and H/W.
- The System under development is often referred to as target system.

Block Diagram Of MDS System



- MDS H/W system consist of following subsystem -
- i. CPU
- **II.** Console Unit
- ii. Main Memory
- v. Secondary and Backup Memory
- v. Printer
- vi. EPROM Programmer
- II. In- Circuit Emulator

MDS Hardware System(contd.)

CPU:

- . Central Processing Unit.
- Heart of the System.
- Responsible for the overall control of the devices.

MDS Hardware System(contd.)

Console Unit:

- Consisting of a visual display Unit (VDU) and a keyboard.
- II. VDU and keyboard provides an interface between the user and MDS.
- User enters data through the keyboard and it displayed by the VDU.

MDS Hardware System (contd.)

- Main Memory:
- Divided into three functionally different parts.
- II. ROM stores the loader/operating system.
- II. RAM store system s/w and other temporary program loaded.
- Emulation memory consist of fast RAM used for storing the user's program of the target system.
- Size of the three different memories varies from each other.

MDS Hardware System (contd.)

- Secondary and Backup Memory:
- Winchester disk
- II. Floppy disks systems
- II. Solid State disk

Printer:

- Used in MDS to get hardcopy of user programs.
- Allows development and documentation to go hand-in-hand
- Dot matrix printers are currently used because of low cost

- EPROM programmer:
- allows direct loading of the software under development
- made as an optional item with MDS
- made as universal in configuration

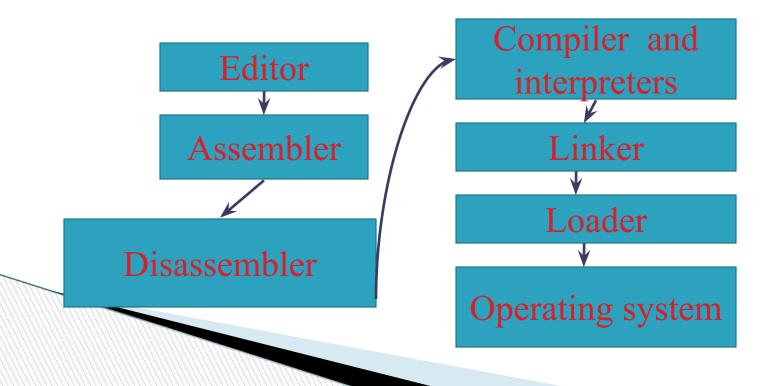
In-circuit emulator:

- Consists of special purpose hardware along with necessary software.
- Enables user to emulate close to target system allowing testing of the target software
- Provides an interface between MDS and target system giving window.

MDS Software Systems.

MDS software system:

Along with hard ware subsystem, a number of system software are provided in MDS. Followings things are found in MDS software:



Editor:

- A program written by the user either assembly language or in a high level language is known as a source program. The source program can be entered into the MDS via the keyboard.
- The response of the MDS is displayed on the VDU.
- The editor allows the user to enter the source code and facilities the modification of the source code whenever necessary.
- A user comes in contact with the editor very frequently.

- Editors with different capabilities and features are available.
- ☐ The simple editor is known as line-oriented editors.
- Another type of editor is recently used known as character-oriented editors.

<u> Assembler:</u>

- The assembler performs the complete translation of a user program in assembly language into the machine language of the microprocessor of the target system.
- The translation process consists of two distinct steps: analysis & synthesis.
- In the analysis phase, the assembler scans through the source program and identifies the various fields; label,opcode and operands of the assembly language instructions.
- In the synthesis phase, machine language code corresponding to each assembly language instruction is generated.

Disassembler:

Another useful software aid is the disassembler, which can generate an assembly language program corresponding to a machine language program.

Compiler and interpreters:

- The translation from a high level language program statements to executable machine codes is performed by a system software known as compiler.
 - ☐ The program development time is considerably shortened.
 - ☐ High level language are not processor dependent, which makes them portable for use with any system.
 - ☐ High level language are also easier to write.

- •There is alternative systems program known as the interpreter, which also translates a high-level language program into a machine language program.
 - Interpreters are usually less sophisticated than compilers.
 - Although interpreters provide much lesser facilities than compilers and execute a source program rather slowly, they are nevertheless very useful software aids.

Linker:

- The object files are generated in relocatable form and the linker converts the object file to executable absolute file, which consists of actual machine code at correct addresses.
- Therefore, linkers provide more flexibility, allow software modules to be developed and translated independently and integrate them by linking at a later stage.

Loaders:

The linked object file is actually loaded into the main memory of the MDS by loaders of execution.

Operating system:

The operating system provides the file and memory management routines and other utility programs to maintain the user's program in secondary and main memory in an orderly manner.

Step 1:

Obtain problem specification.

Step 2a:

Make a block diagram of hardware system satisfying the problem requirements.

Step 2b:

Make a flowchart of the necessary software.

Step 3a:

Obtain detailed circuit implementation based on availability, cost, performance.

Step 3b:

Translate the flowchart into an assembly or higher-level language code.

Step 4a:

Enter the source code module into MDS using the editor.

Step 4b:

fabricate the prototype hardware circuit.

Step 5:

Assemble or compile source code module to produce the corresponding machine language using assembler or compiler.

Step 6:

Link the absolute machine language code modules using the linker and load them into the memory by using the loader.

Step 7:

Test the absolute object codes modules by running them in the emulation mode on the MDS

Step 8:

If necessary Debug the object program module

And-

go back to step 4(a) to edit the source code modules if mistakes.

Step 9:

Connect the prototype target system to MDS

And

Use the emulation mode to test software

Step 10:

Debug the prototype hardware

- using the trace analysis facility And rectify the hardware faults.

Step 11:

Program EPROM in the PROM programming mode.

Step 12:

Disconnect the target system from the MDS

Plug-in the MPU and EPROM to get the complete working model and test its operation.

Various types of MDS

- ☐ Hewlett Packard's HP6400
- ☐ Tektronix
- ☐ Philips PMDS-1 and PMDS-2
- ☐ Intel MDS
- ☐ IBM-PC based MDS

Reference:

Microprocessor: Principles and Applications-By Ajit Pal

Chapter 8