Modeling Relational Event Dynamics with statuet

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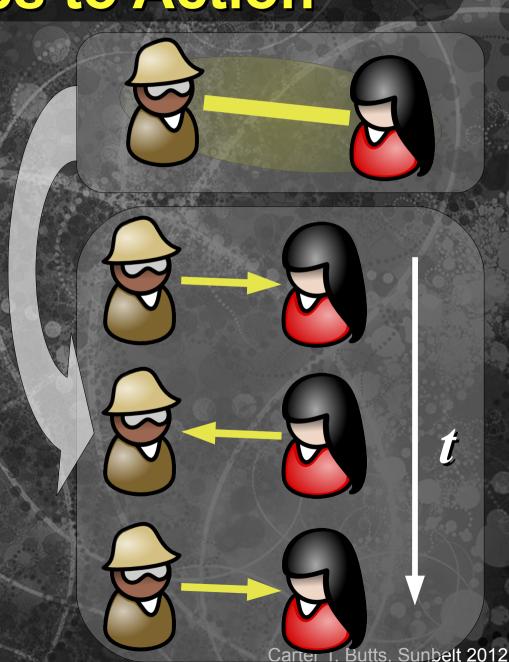
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Overview

- Content in a nutshell
 - Introduction to the use of relational event models (Butts, 2006; 2008) for the modeling interaction dynamics
 - Why this approach?
 - Fairly general
 - Principled basis for inference (estimation, model comparison, etc.) from actually existing data
 - Utilizes well-understood formalisms (event history analysis, multinomial logit)
- This workshop:
 - Introduction to modeling approach
 - Dyadic relational event models
 - Egocentric relational event models
 - Modeling complex event sequences

Unpacking Networks: From Relationships to Action

- Conventional network paradigm: focus on temporally extensive relationships
- Powerful approach, but not always ideal
- Sometimes, we are interested in the social action that lies beneath the relationships....



Actions and Relational Events

- Action: discrete event in which one entity emits a behavior directed at one or more entities in its environment
 - Useful "atomic unit" of human activity
 - Represent formally by relational events
- Relational event: a=(i,j,k,t)
 - $i \in S$: "Sender" of event a; s(a)=i
 - $j \in \mathcal{R}$: "Receiver" of event a; r(a)=j
 - $k \in C$: "Action type" ("category") for event a; c(a)=k
 - $t \in \mathbb{R}$: "Time" of event a; $\tau(a)=t$

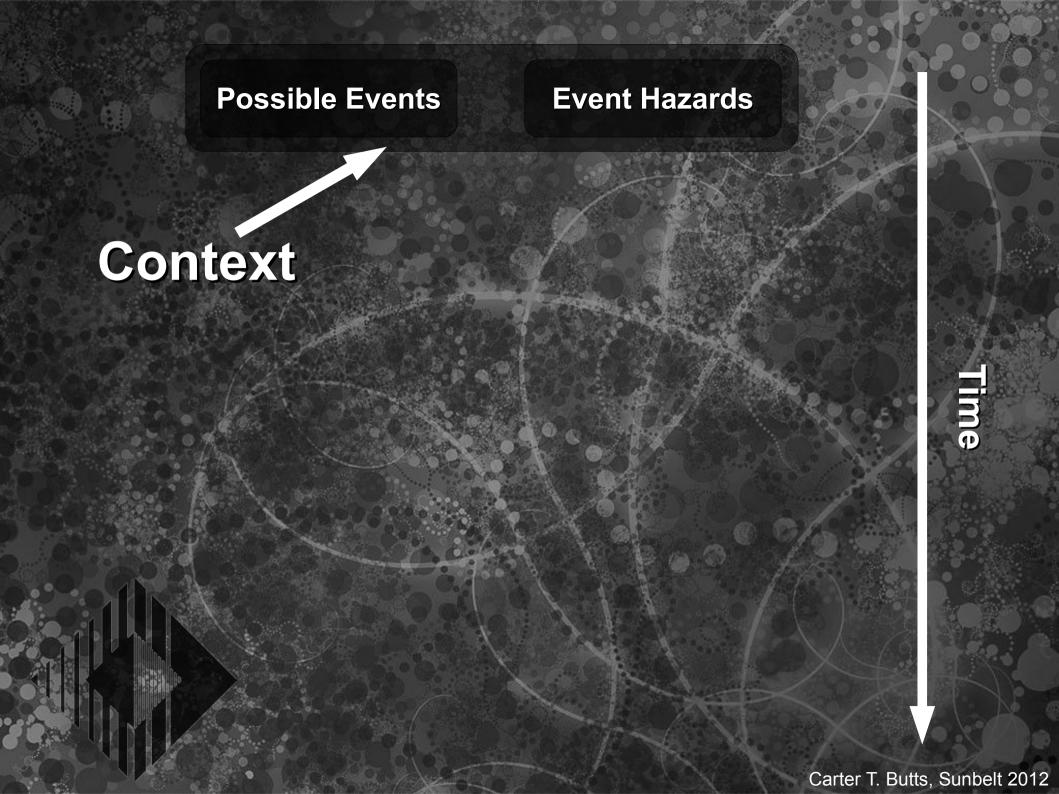
Events in Context

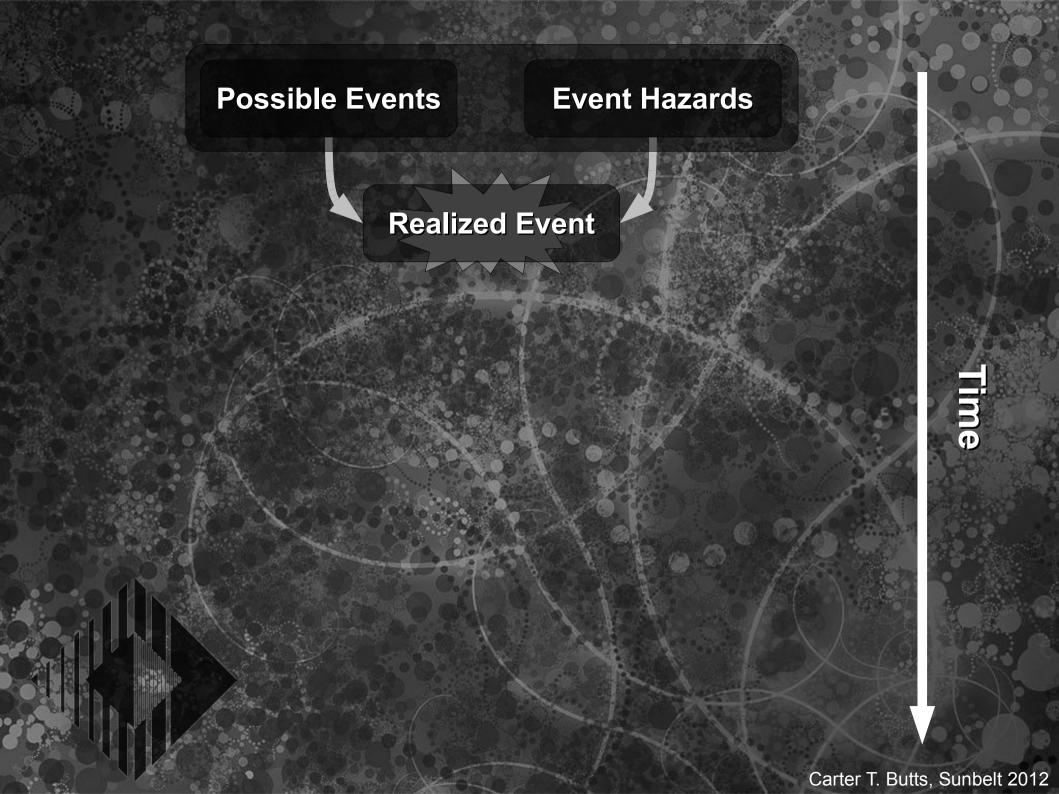
Multiple actions form an event history,

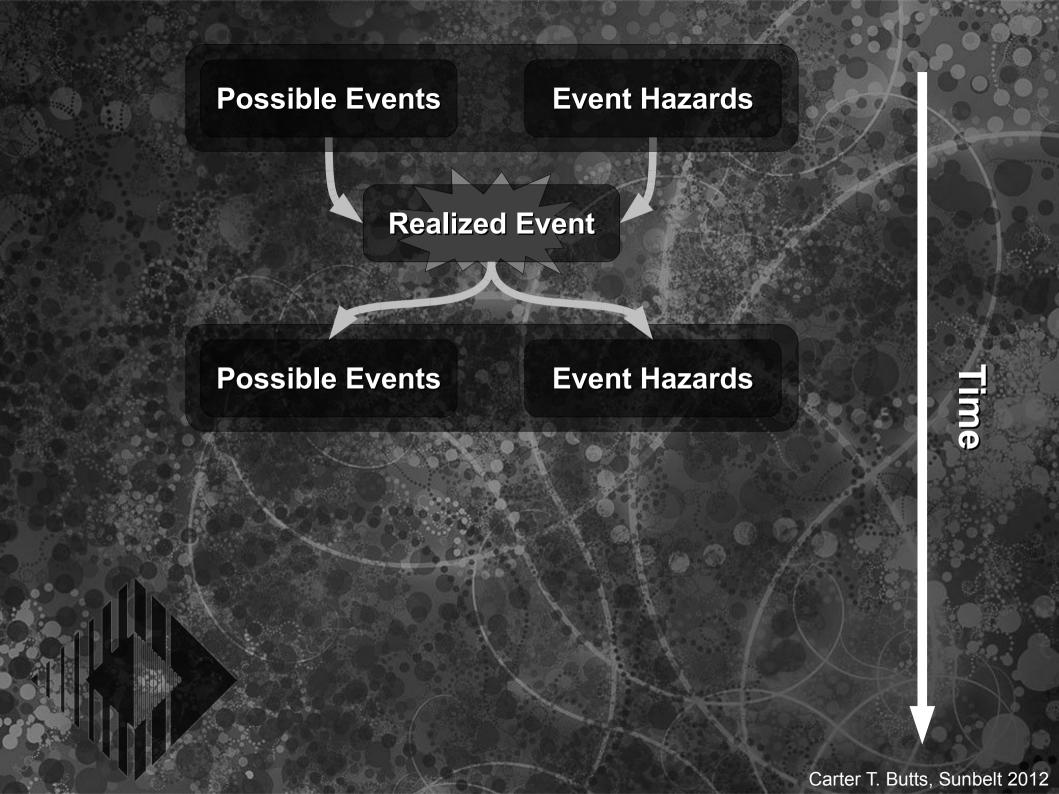
$$A_t = \{a_i : \tau(a_i) \le t\}$$

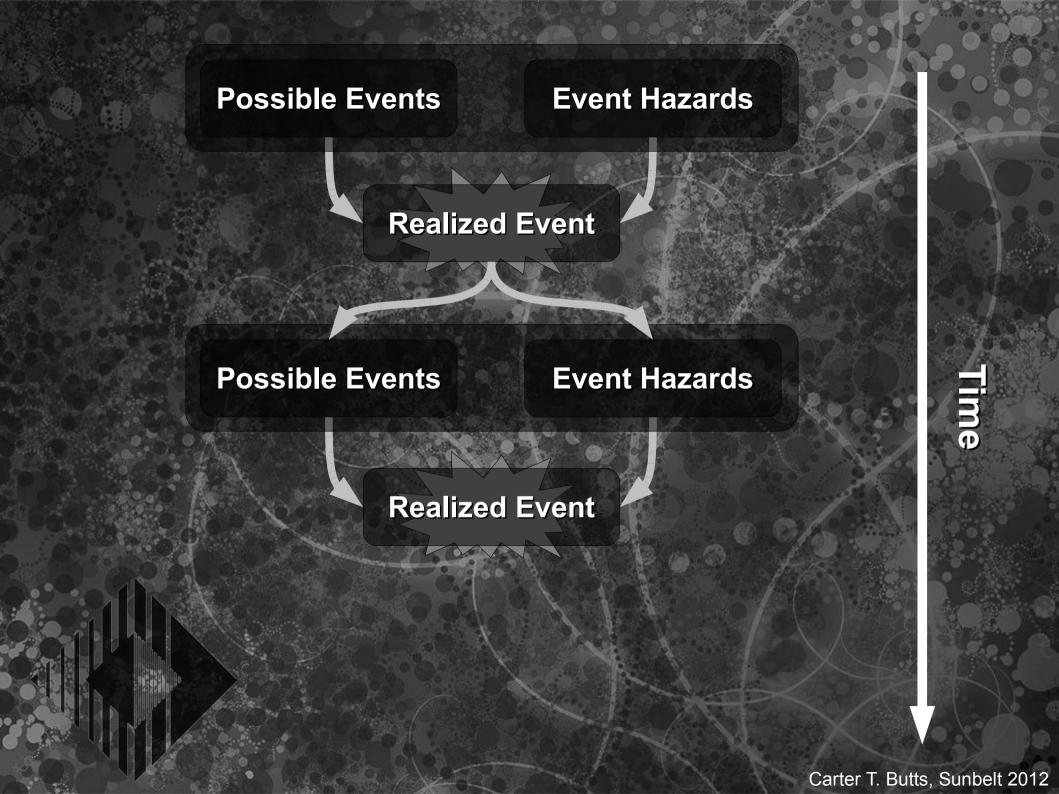
- Take a_0 : $\tau(a_0)=0$ as "null action", $\tau(a_i)\geq 0$
- Possible actions at t given by $\mathbb{A}(A_t) \subseteq S \times \mathcal{R} \times \mathcal{C}$
 - Forms support for next action
 - Assume here that $\mathbb{A}(A_i)$ finite, constant between actions; may be fixed, but need not be
- Goal: model $A_{_t}$
 - Treat actions as events in continuous time
 - Hazards depend upon past history, covariates











Possible Events Event Hazards

Realized Event

Possible Events

Event Hazards

Realized Event

Possible Events

Event Hazards

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Event Model Likelihood: Piecewise Exponential Case

- Natural simplifying assumption: actions arise as conditionally independent, Poisson-like events with piecewise constant rates
 - Intuition: hazard of each possible event is locally constant, given complete event history up to that point
 - Waiting times conditionally exponentially distributed
 - Rates can change when events transpire, but not otherwise
 - · Compare to related assumption in Cox prop. hazards model
 - Possible events likewise change only when something happens
- Can use to derive event likelihood
 - Let $M=|A_i|$, $\tau_i=\tau(a_i)$, w/hazard function $\lambda_{a_iA_k\theta}=\lambda(a_i,A_k,\theta)$; then

$$p(A_{t}|\theta) = \left[\prod_{i=1}^{M} \left(\lambda_{a_{i}A_{\tau_{i-1}}\theta} \prod_{a' \in \mathbb{A}(A_{\tau_{i}})} \exp\left(-\lambda_{a'A_{\tau_{i-1}}\theta} \left[\tau_{i} - \tau_{i-1}\right]\right)\right)\right] \left[\prod_{a' \in \mathbb{A}(A_{t})} \exp\left(-\lambda_{a'A_{t}\theta} \left[t - \tau_{M}\right]\right)\right]$$

The Problem of Uncertain Event Timing

- Likelihood of an event sequence depends on the detailed history
 - Problem: exact timing is generally uncertain for many data sources (e.g., transcripts), though order is known
 - What if we only have (temporally) ordinal data?
- Stochastic process theory to the rescue!
 - Thm: Let $X_1,...,X_n$ be independent exponential r.v. w/rate parameters $\lambda_1,...,\lambda_n$. Then the probability that $x_i=\min\{x_1,...,x_n\}$ is $\lambda_i/(\lambda_i+...+\lambda_n)$.
 - Implication: likelihood of ordinal data is a product of multinomial likelihoods
 - Identifies rate function up to a constant factor

Event Model Likelihood: Ordinal Timing Case

 Using the above, we may write the likelihood of an event sequence A, as follows:

$$p(A_t|\theta) = \prod_{i=1}^{M} \left[\frac{\lambda_{a_i A_{\tau_{i-1}} \theta}}{\sum_{a' \in \mathbb{A}(A_{\tau_i})} \lambda_{a_i A_{\tau_{i-1}} \theta}} \right]$$

Dynamics governed by rate function, λ

$$\lambda_{aA_{t}\theta} = \begin{cases} \exp\left(\lambda_{0} + \theta^{T} u(s(a), r(a), c(a), A_{t}, X_{a})\right) & a \in \mathbb{A}(A_{t}) \\ 0 & a \notin \mathbb{A}(A_{t}) \end{cases}$$

• Where λ_0 is an arbitrary constant, $\theta \in \mathbb{R}^p$ is a parameter vector, and $u: (i,j,A,X) \to \mathbb{R}^p$ is a vector of statistics

Interpreting the Parameters

- In general, each unit change in u_i multiplies the hazard of an associated event by $\exp(\theta_i)$
 - For ordinal time case, unit difference in u_i adds unit of θ_i to log odds of a vs a'
- Connection to multinomial choice models
 - Let $\mathbb{A}_i(A_i)$ be the set of possible actions for sender i at time t. Then, conditional on no other event occurring before i acts, the probability that i's next action is a is given by

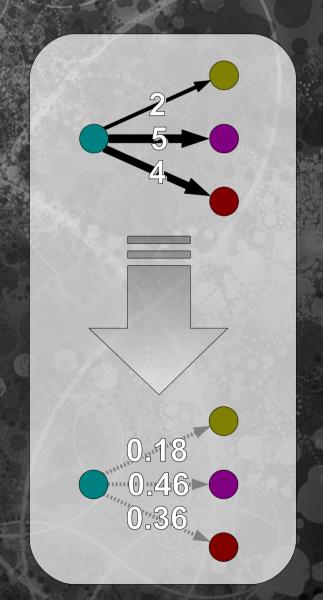
$$p(a|\theta) = \frac{\exp\left[\theta^{T} u[i, r(a), c(a), A_{t}, X_{a}]\right]}{\sum_{a' \in \mathbb{A}_{t}[A_{t}]} \exp\left[\theta^{T} u[i, r(a'), c(a'), A_{t}, X_{a'}]\right]}$$

Fitting Relational Event Models

- Given A_i and u, how do we estimate θ ?
 - Parameters interpretable as logged rate multipliers (in u)
- We have $p(A_i|\theta)$, so can conduct likelihood-based inference
 - Find MLE $\theta^* = \arg \max_{\theta} p(A_t | \theta)$, e.g., using a variant Newton-Rapheson or other method
 - Can also proceed in a Bayesian manner
 - Posit $p(\theta)$, work with $p(\theta|A_t) \propto p(A_t|\theta)p(\theta)$
 - Some computational challenges when |A| is large; tricks like MC quadrature needed to deal with sum of rates across support

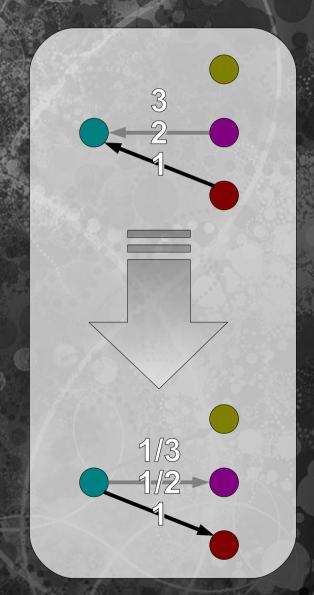
Persistence Effects

- Inertia-like effect: past contacts may tend to become future contacts
 - Unobserved relational heterogeneity
 - Availability to memory
 - (Compare w/autocorrelation terms in an AR process)
- Simple implementation: fraction of previous contacts as predictor
 - Log-rate of (i,j) contact adjusted by $\theta d_{ij}/d_i$



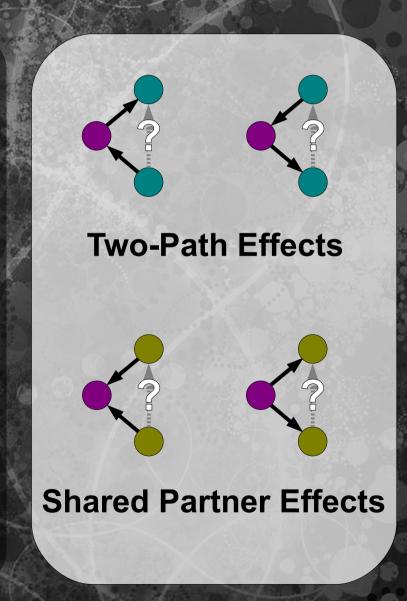
Recency/Ordering Effects

- Ordering of past contact potentially affects future contact
 - Reciprocity norms
 - Recency effects (salience)
- Simple parameterization: dyadic contact ordering effect
 - Previous incoming contacts ranked
 - Non-contacts treated as rank ∞
 - Log-rate of outgoing (i,j) contact adjusted by $\theta(1/\text{rank}_{ii})$



Triadic/Clustering Effects

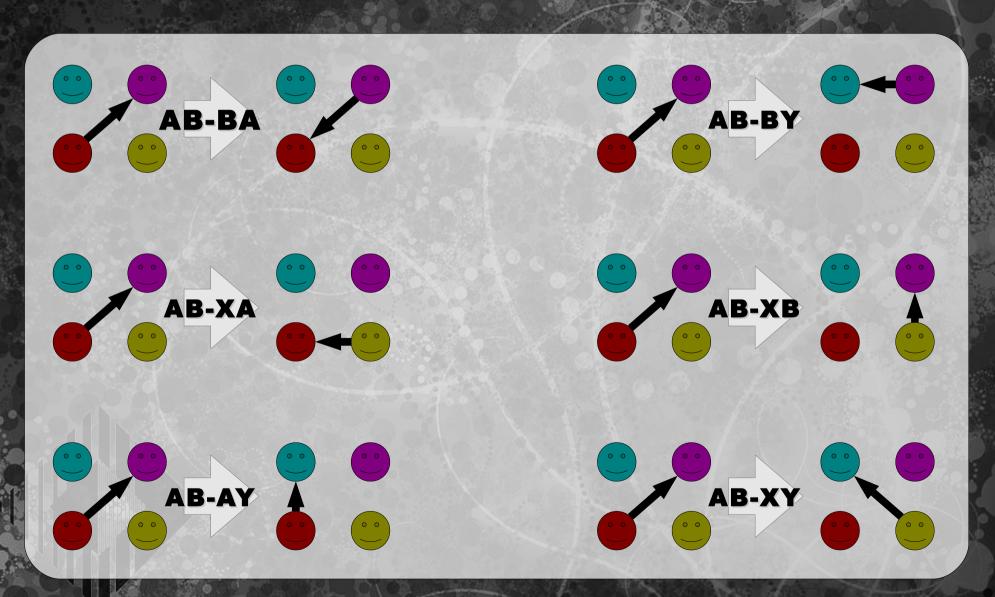
- Can also control for endogenous triadic mechanisms
 - Two-path effects
 - Past outbound two-path flows lead to/inhibit direct contact (transitivity)
 - Past inbound two-path flows lead to/inhibit direct contact (cyclicity)
 - Shared partner effects
 - Past outbound shared partners lead to/inhibit direct contact (common reference)
 - Past inbound shared partners lead to/inhibit direct contact (common contact)



Participation Shifts

- Proposal of Gibson (2003) for studying conversational dynamics
 - Classify actors into senders, receivers, and bystanders
 - When roles change, a participation shift ("P-shift") is said to occur
 - Study conversational dynamics by examining the incidence of P-shifts
- P-shift typology
 - For dyadic communication, 6 possible P-shifts; allowing indefinite targets expands set to 13
 - Can compute observed, potential shifts given an event sequence

Dyadic P-Shifts, Illustrated



Preferential Attachment

- Past interactive activity affects tendency to receive action
 - E.g., emergent coordination roles
 - Exposure-based saliency ("who's out there?")
 - Practice/specialization (efficiency)
- Implement via past total degree effect on hazard of receipt
 - Fraction of all past calls due to i as effect for all j to i events

