

# Dijkstra Goes Random

Weakest-Precondition-Reasoning on Probabilistic Programs

Joost-Pieter Katoen



The 20th KeY Symposium, July 2024



# Probabilistic programs

Programs with random assignments and conditioning

```
{ w := 0 } [5/7] { w := 1 };
if (w = 0) { c := poisson(6) }
else { c := poisson(2) };
observe (c = 5)
```

probabilistic branching

$$\Pr \{ \omega=0 \} = \frac{5}{7} \quad \Pr \{ \omega=1 \} = \frac{2}{7}$$

---

<sup>1</sup>[Gordon, Henzinger, Nori and Rajamani, FOSE 2014]

# Probabilistic programs

Programs with **random assignments** and **conditioning**

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They encode:

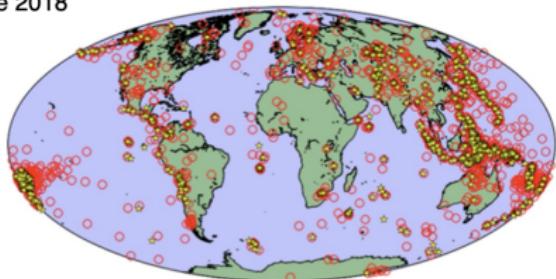
- ▶ randomised algorithms
- ▶ probabilistic graphical models beyond Bayes' networks
- ▶ controllers for autonomous systems
- ▶ security mechanisms
- ▶ .....

"Probabilistic programming aims to make  
probabilistic modeling and machine learning accessible to the programmer."<sup>1</sup>

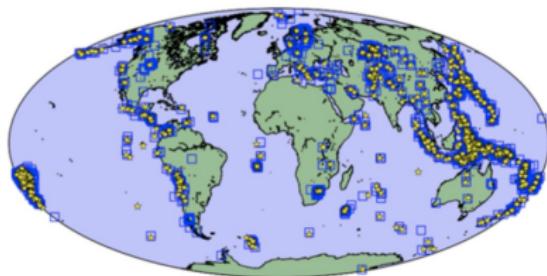
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# "Real" Examples

before 2018



since 2018

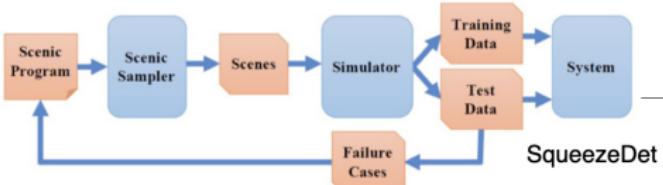
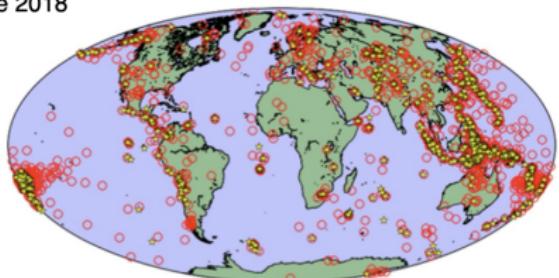


the UN diagnoses seismic events  
using probabilistic programs

[Arora et al, Bull. Seism. 2017]

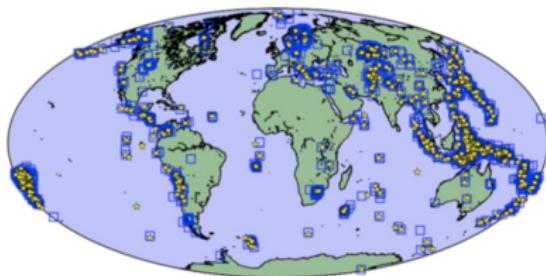
## "Real" Examples

before 2018



SCENIC generates more effective training sets  
[Fremont *et al.*, Mach. Learn. 2023]

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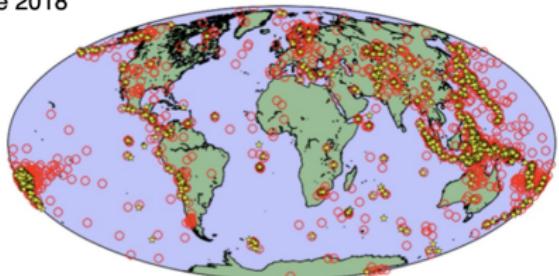


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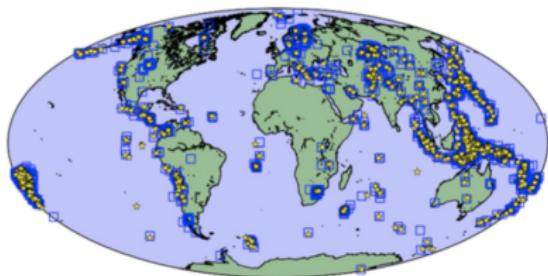
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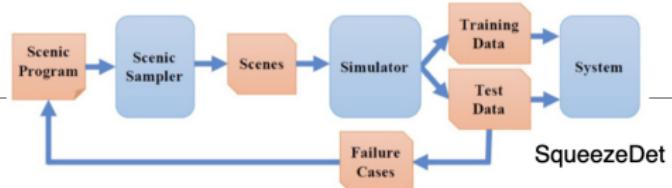


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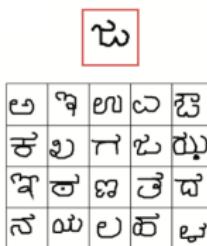


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**SCENIC generates more effective training sets**  
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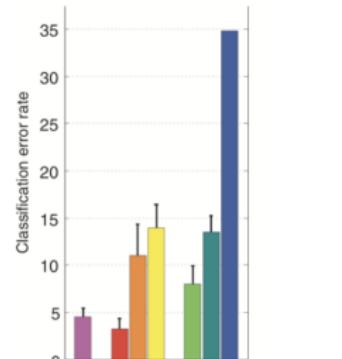


STAN, PyMC,  
Edward, Pyro,  
ProbLog, WebPPL

humans

programs

neural networks

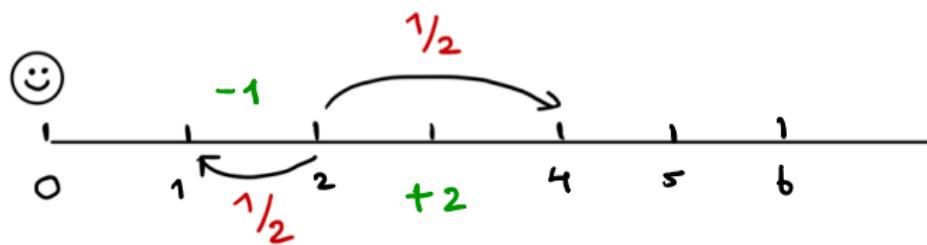


[Lake et al, Science 2015]

# Probabilistic programs are hard to grasp

Does this program almost surely terminate? That is, is it AST?

```
x := 1;
while (x > 0) {
    x := x+2 [1/2] x := x-1
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```

If not, what is its probability to diverge?

# Even if all loops are bounded

[Flajolet *et al*, 2009]

```
x := geometric(1/4);
y := geometric(1/4);
t := x+y+1 [5/9] t := x+y;
r := 1;
for i in 1..3 {
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    }
    r := (s == t)
}
```

What is the probability that  $r$  equals one on termination?

# Positive AST

```
int x := 1;
bool c := true;
while (c) {
    c := false [0.5] c := true;
    x := 2*x
}
```

Finite expected termination time?  
aka: is this program positive AST?

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Finite termination time!  
PAST.

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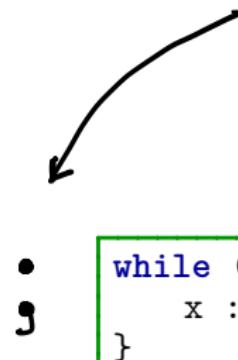
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Expected runtime of these programs in sequence?

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Finite termination time!  
PAST.

Expected runtime of these programs in sequence?

$\infty$

$$\text{PAST}(P) \wedge \text{PAST}(Q) \quad \cancel{\Rightarrow} \quad \text{PAST}(P ; Q)$$

# Our objective

A powerful, simple proof calculus for probabilistic programs.

At the source code level.

No “descend” into the underlying probabilistic model.

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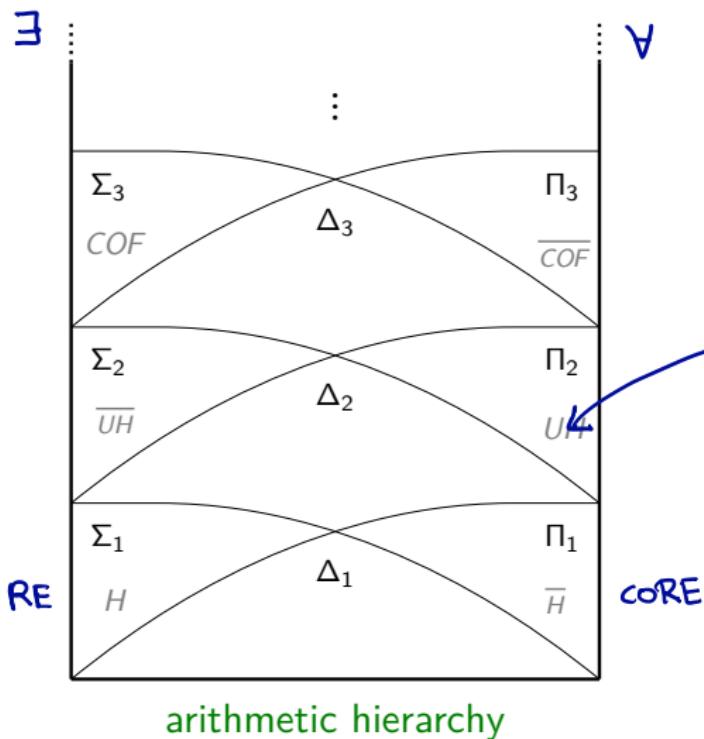
No “descend” into the underlying probabilistic model.

Push **automation** as much as we can.

This is a true challenge: undecidability!

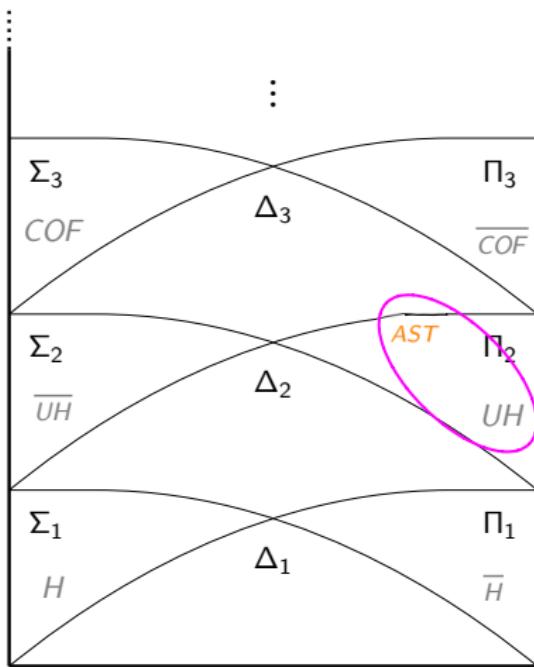
Typically “more undecidable” than deterministic programs

# Probabilistic programs are “more undecidable”



Turing's universal  
halting problem

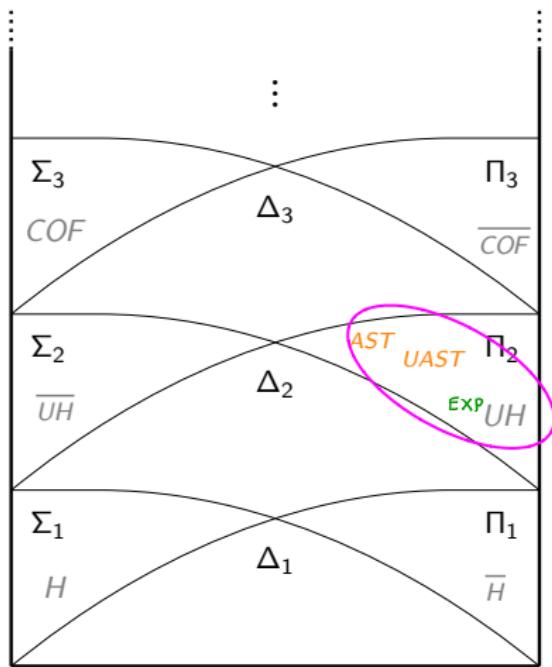
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arithmetic hierarchy

AST for **one** input  
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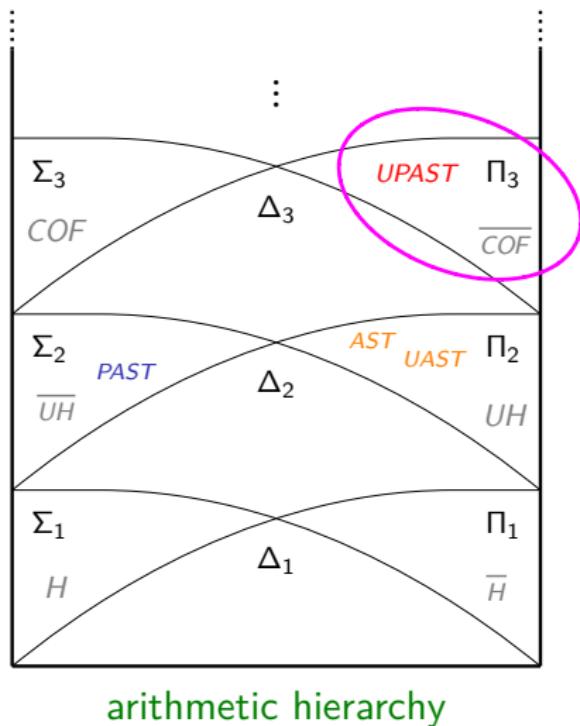
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# Probabilistic programs are “more undecidable”



AST for **one** input  
is as hard as  
the halting problem for **all** inputs  
is as hard as  
computing expected outcomes  
but  
deciding finite expected runtime?  
is “**even more undecidable**”

[Kaminski, K., MFCS 2015]

# Roadmap of this talk

## Part 1

- ▶ Probabilistic weakest preconditions

## Part 2

- ▶ Proof rules for probabilistic loops

## Part 3

- ▶ Relative completeness and automation

“Dijkstra’s weakest preconditions go random”

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## WEAKEST PRE-EXPECTATIONS

---



Dexter Kozen, Annabelle McIver, and Carroll Morgan

# From predicates to quantities

- ▶ Let program  $P$  be:

$x := x+5 \quad [4/5] \quad x := 10$

initial value  
of  $x$

The expected value of  $x$  on  $P$ 's termination is:

$$\frac{4}{5} \cdot (x + 5) + \frac{1}{5} \cdot 10 = \frac{4x}{5} + 6$$

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$$\frac{4}{5} \cdot (x + 5) + \frac{1}{5} \cdot 10 = \frac{4x}{5} + 6$$

- ▶ The probability that  $x = 10$  on  $P$ 's termination is:

$$\frac{4}{5} \cdot \underbrace{[x+5 = 10]}_{\text{Iverson brackets}} + \frac{1}{5} \cdot 1 = \frac{4 \cdot [x = 5] + 1}{5}$$

# Expectations

The set of expectations<sup>2</sup> (read: random variables):

$$\mathbb{E} = \left\{ f \mid f : \underbrace{\mathbb{S}}_{\text{states}} \rightarrow \mathbb{R}_{\geq 0} \cup \{ \infty \} \right\}$$

---

<sup>2</sup> ≠ expectations in probability theory.

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Examples:  $[x = 5]$     $\frac{4x}{5} + 6$     $\frac{4 \cdot [x=5] + 1}{5}$     $\mathbf{1}$     $x^2 + \sqrt{y+1} \dots$

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Examples:  $[x = 5] \quad \frac{4x}{5} + 6 \quad \frac{4 \cdot [x=5] + 1}{5} \quad \mathbf{1} \quad x^2 + \sqrt{y+1} \dots$

$(\mathbb{E}, \sqsubseteq)$  is a complete lattice where  $f \sqsubseteq g$  if and only if  $\forall s \in \mathbb{S}. f(s) \leq g(s)$

expectations are the quantitative analogue of predicates

---

<sup>2</sup># expectations in probability theory.

# Weakest pre-expectations

For program  $P$ , let  $wp[\![P]\!]: \mathbb{E} \rightarrow \mathbb{E}$  an expectation transformer

$g = wp[\![P]\!](f)$  is  $P$ 's weakest pre-expectation w.r.t. post-expectation  $f$  iff

the expected value of  $f$  after executing  $P$  on input  $s$  equals  $g(s)$

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Examples:

For  $P:: x := x+5 [4/5] x := 10$ , we have:

$$wp[\![P]\!](x) = \frac{4x}{5} + 6 \quad \text{and} \quad wp[\![P]\!](\llbracket x = 10 \rrbracket) = \frac{4 \cdot \llbracket x = 5 \rrbracket + 1}{5}$$

$wp[\![P]\!](\varphi)$  is the probability of predicate  $\varphi$  on  $P$ 's termination

$wp[\![P]\!](1)$  is  $P$ 's termination probability

# Kozen's duality theorem

$wp[\![P]\!](f)(s)$  is the expected value of  $f$  after running  $P$  on input  $s$

Let  $\mu_P^s$  be the distribution over  $P$ 's final states when  $P$  starts in  $s$ .

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$$\text{Then for post-expectation } f: \underbrace{\text{wp}[\![P]\!](f)(s)}_{\text{"backward"}} = \underbrace{\sum_{t \in S} \mu_P^s(t) \cdot f(t)}_{\text{"forward"}}$$

# Kozen's duality theorem

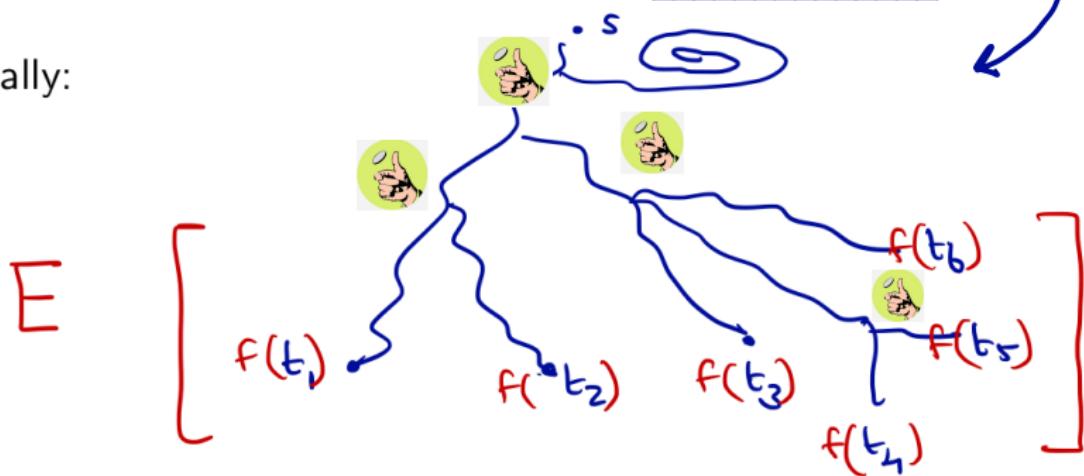
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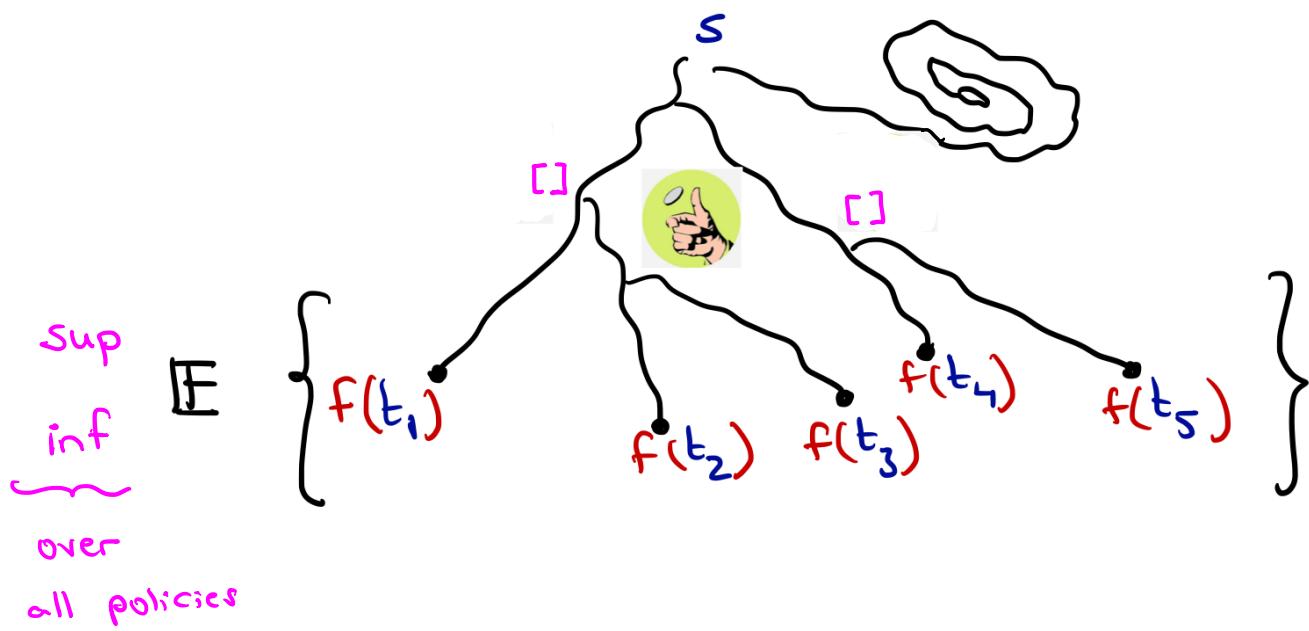
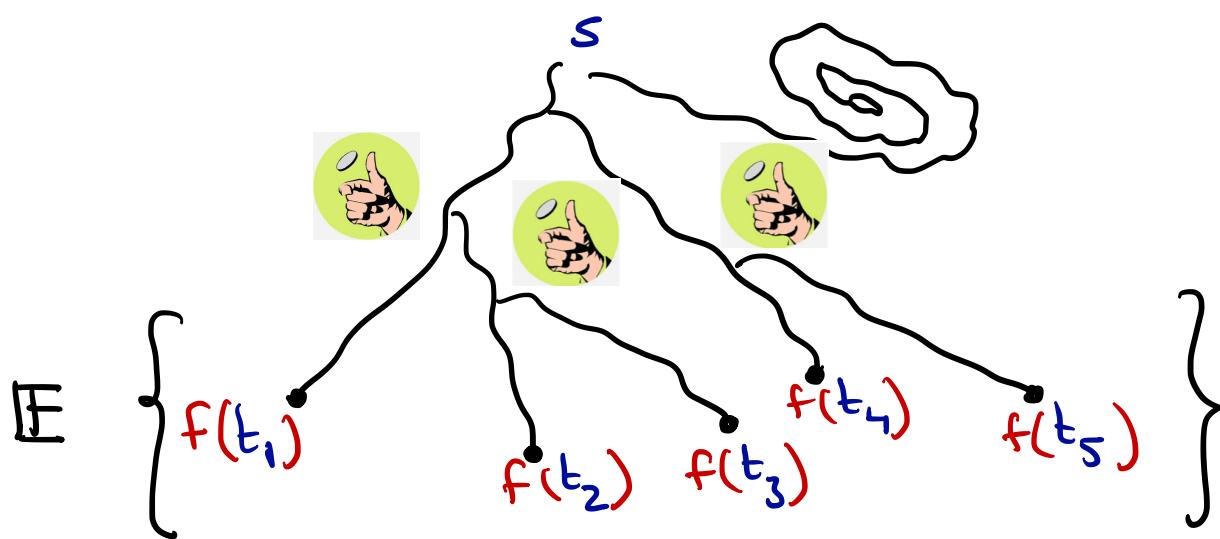
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Pictorially:





# How to obtain wp for a program?

Syntax probabilistic program  $P$

$\text{skip}$

$x := E$

$x \approx \mu$

$P; Q$

substitution

Semantics  $wp[\![P]\!](f)$

$f[x := E]$

$$\lambda s. \int_{\mathbb{Q}} (\lambda v. f(s[x := v])) d\mu_s$$

$wp[\![P]\!](wp[\![Q]\!](f))$

backwards!

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$\text{if } (\varphi) P \text{ else } Q$

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$wp[\![P]\!](wp[\![Q]\!](f))$

$[\varphi] \cdot wp[\![P]\!](f) + [\neg\varphi] \cdot wp[\![Q]\!](f)$

$p \cdot wp[\![P]\!](f) + (1-p) \cdot wp[\![Q]\!](f)$

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`if` ( $\varphi$ )  $P$  `else`  $Q$

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`while` ( $\varphi$ )  $\{P\}$

Semantics  $wp[\![P]\!](f)$

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$p \cdot wp[\![P]\!](f) + (1-p) \cdot wp[\![Q]\!](f)$

$\text{lfp } X. \underbrace{([\varphi] \cdot wp[\![P]\!](X)) + [\neg\varphi] \cdot f}_{\text{loop characteristic function } \Phi_f(X)}$

where lfp is the least fixed point wrt. the ordering  $\sqsubseteq$  on  $\mathbb{E}$ .

# Examples

1. Consider again program  $P$ :

$x := x+5 \quad [4/5] \quad x := 10$

For  $f = x$ , we have:

$$\begin{aligned} wp[\![P]\!](x) &= \frac{4}{5} \cdot wp[\![x := 5]\!](x) + \frac{1}{5} \cdot wp[\![x := 10]\!](x) \\ &= \frac{4}{5} \cdot (x+5) + \frac{1}{5} \cdot 10 = \boxed{\frac{4x}{5} + 6} \end{aligned}$$

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2. For program  $P$  (again) and  $f = [x = 10]$ , we have:

$$\begin{aligned} wp[\![P]\!](\{x=10\}) &= \frac{4}{5} \cdot wp[\![x := x+5]\!](\{x=10\}) + \frac{1}{5} \cdot wp[\![x := 10]\!](\{x=10\}) \\ &= \frac{4}{5} \cdot [x+5 = 10] + \frac{1}{5} \cdot [10 = 10] \\ &= \boxed{\frac{4 \cdot [x = 5] + 1}{5}} \end{aligned}$$

# Loops

$$wp[\![\text{while } (\varphi) \{ P \}]\!](f) = \text{lfp } X. \underbrace{([\varphi] \cdot wp[\![P]\!](X) + [\neg\varphi] \cdot f)}_{\text{loop characteristic function } \Phi_f(X)}$$

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- ▶ Function  $\Phi_f : \mathbb{E} \rightarrow \mathbb{E}$  is **Scott continuous** on  $(\mathbb{E}, \sqsubseteq)$
- ▶ By Kleene's fixed point theorem:  $\text{lfp } \Phi_f = \sup_{n \in \mathbb{N}} \Phi_f^n(\mathbf{0})$
- ▶  $\Phi_f^n(\mathbf{0})$  is  $f$ 's expected value after  $n$  times running  $P$ , starting in  $\mathbf{0}$

# Examples

```
x := 1;
while (x > 0) {
    x += 2 [1/2] x -= 1
}
```

post-expectation: 1

```
x := geometric(1/4);
y := geometric(1/4);
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# Examples

weakest pre-expectation:  $\frac{\sqrt{5}-1}{2}$

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post-expectation:  $[r = 1]$

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weakest pre-expectation:  $\left(\frac{1}{\pi}\right)$

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post-expectation: [r = 1]

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$$wlp[\text{while } (\varphi) \{ P \}](f) = \text{gfp } X, \underbrace{([\varphi] \cdot wlp[P](X) + [\neg\varphi] \cdot f)}_{\text{loop characteristic function } \Phi_f(X)}$$

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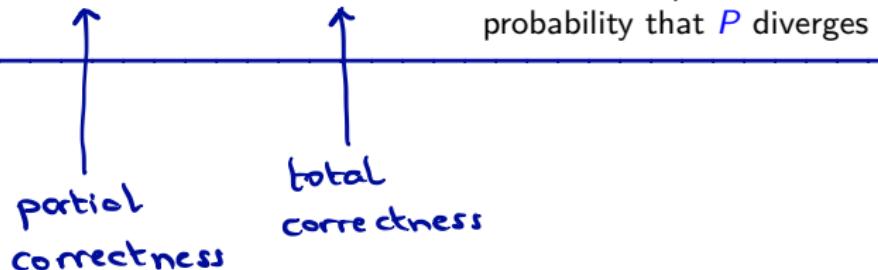
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Relating weakest liberal preconditions to wp:

$$wlp[P](f) = wp[P](f) + \underbrace{(1 - wp[P](1))}_{\text{probability that } P \text{ diverges}}$$



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$$wlp[P](f) = wp[P](f) + \underbrace{(1 - wp[P](1))}_{\text{probability that } P \text{ diverges}}$$

If program  $P$  is AST:

$$wlp[P](f) = wp[P](f) + (1 - \underbrace{wp[P](1)}_{=1}) = wp[P](f)$$

# Bayesian learning by example

---

```
{ w := 0 } [5/7] { w := 1 };
if (w = 0) { c := poisson(6) }
else { c := poisson(2) };
observe (c = 5)
```

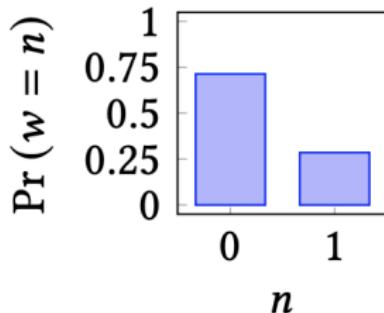
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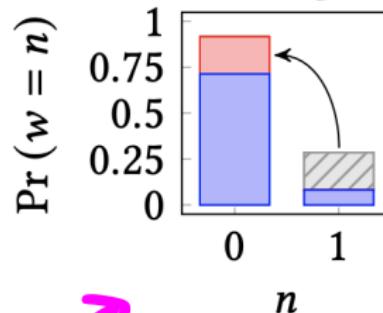
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---



prior



posterior

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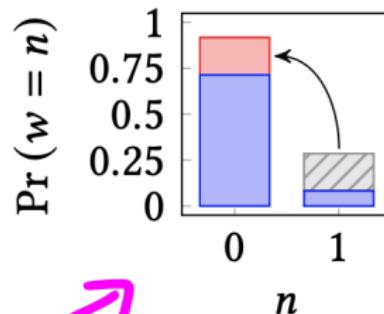
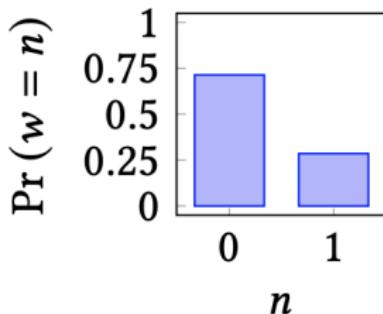
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---

prior

posterior



Probability mass is **normalised** by the probability of feasible runs

# Learning [Nori *et al*, AAAI 2014; Olmedo, K., *et al*, TOPLAS 2018]

The probability of feasible program runs:

$$wp[\![P]\!](1) = 1 - Pr\{ P \text{ violates an observation} \}$$

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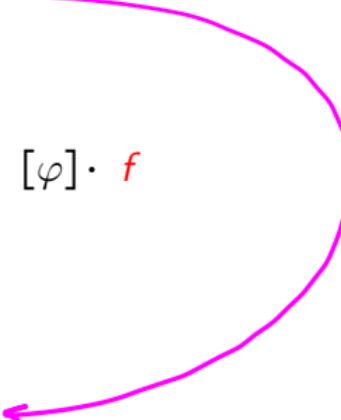
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Normalisation:

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Fine point: under possible **program divergence**:  $\frac{wp[\![P]\!](f)}{wp[\![P]\!](1)}$

# Extensions of probabilistic wp

- ▶ ..... for recursion [LICS 2016]
- ▶ ..... for exact inference [TOPLAS 2018]
- ▶ ..... for continuous distributions [SETTS 2019]
- ▶ ..... for probabilistic separation logic [POPL 2019]
- ▶ ..... for weighted programs [OOPSLA 2022]
- ▶ ..... for expected runtime analysis [JACM 2018]
- ▶ ..... for amortised runtime analysis [POPL 2023]

---

# HOW TO TREAT LOOPS?

---



# Upper bounds

Recall:

$$wp[\text{while } (\varphi) \{ P \}](f) = \text{lfp } X. \underbrace{([\varphi] \cdot wp[P](X) + [\neg\varphi] \cdot f)}_{\Phi_f(X)}$$

By Park's lemma: for  $\text{while}(\varphi)\{P\}$  and expectations  $f$  and  $I$ :

$$\underbrace{\Phi_f(I) \sqsubseteq I}_{\text{"upper" invariant } I} \quad \text{implies} \quad \underbrace{wp[\text{while}(\varphi)\{P\}](f)}_{\text{lfp } \Phi_f} \sqsubseteq I$$

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Example: `while(c = 0) { x++ [p] c := 1 }`

$I = x + [c = 0] \cdot \frac{p}{1-p}$  is an “upper”-invariant w.r.t.  $f = x$

# Lower bounds

[Hark, K. et al, POPL 2020]

$$(\textcolor{blue}{I} \sqsubseteq \Phi_{\textcolor{red}{f}}(\textcolor{blue}{I}) \wedge \text{ side conditions}) \quad \text{implies} \quad \textcolor{blue}{I} \sqsubseteq \text{lfp } \Phi_{\textcolor{red}{f}}$$

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$$(I \sqsubseteq \Phi_f(I) \wedge \underbrace{\text{side conditions}}_{\text{side conditions}}) \quad \text{implies} \quad I \sqsubseteq \text{lfp } \Phi_f$$

where the side conditions for the loop  $\text{while}(\varphi)\{P\}$  are:

1. the loop is PAST, and
2. for any  $s \models \varphi$ ,  $\underbrace{\text{wp}[\![P]\!](|I(s) - I|)(s)}_{\text{conditional difference boundedness}} \leq c$  for some  $c \in \mathbb{R}_{\geq 0}$

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Example. Program:  $\text{while}(c = 0)\{x++[p]c := 1\}$  satisfies the conditions.

$$I = x + [c = 0] \cdot \frac{p}{1-p} \text{ is a "lower"-invariant w.r.t. } f = x$$

# A proof rule for AST

[McIver, K. et al, POPL 2018]

Consider the loop  $\text{while}(\varphi)\{\text{body}\}$  and let:

- ▶  $V : \mathbb{S} \rightarrow \mathbb{R}_{\geq 0}$  with  $[\neg V] = [\neg \varphi]$   $V$  indicates termination
- ▶  $p : \mathbb{R}_{\geq 0} \rightarrow (0, 1]$  antitone probability
- ▶  $d : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$  antitone decrease

$$\leftarrow x \leq y \rightsquigarrow d(y) \leq d(x)$$

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If:

$$[\varphi] \cdot wp[\text{body}](V) \leq V$$

expected value of  $V$  does not decrease by an iteration  
in

and

$$[\varphi] \cdot (p \circ V) \leq \lambda s. wp[\text{body}](|V \leq V(s) - d(V(s))|)(s)$$

with at least prob.  $p$ ,  $V$  decreases at least by  $d$

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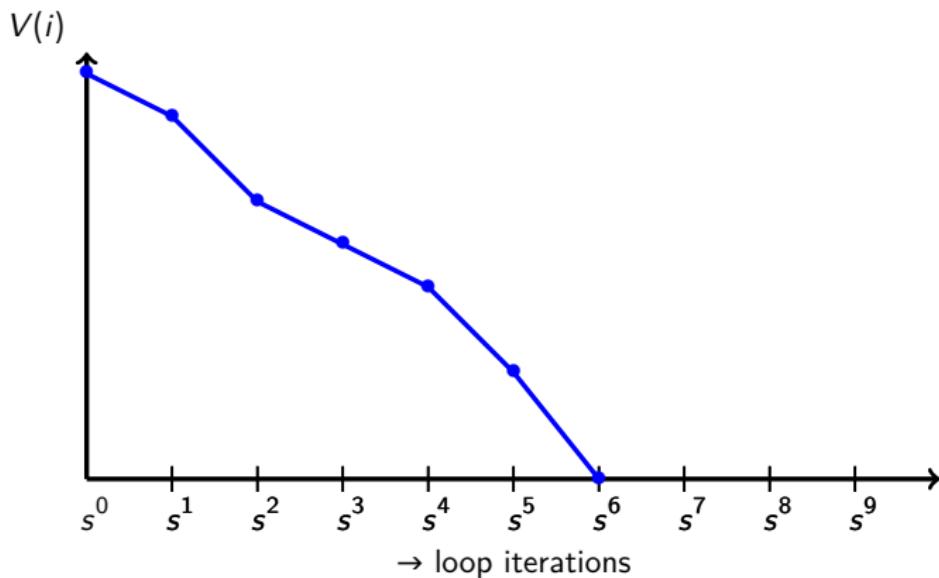
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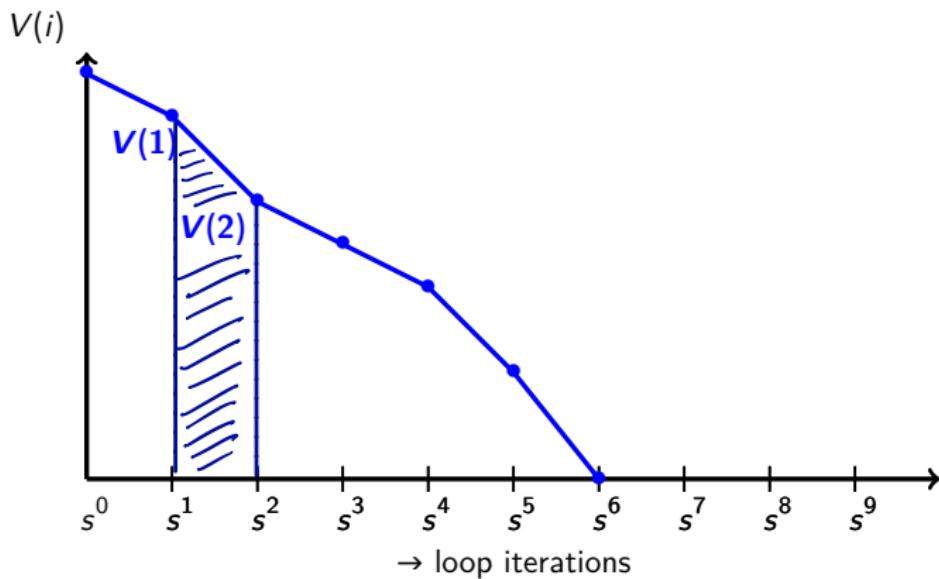
Then:

$wp[\text{loop}](1) = 1 \text{ i.e., loop is AST}$

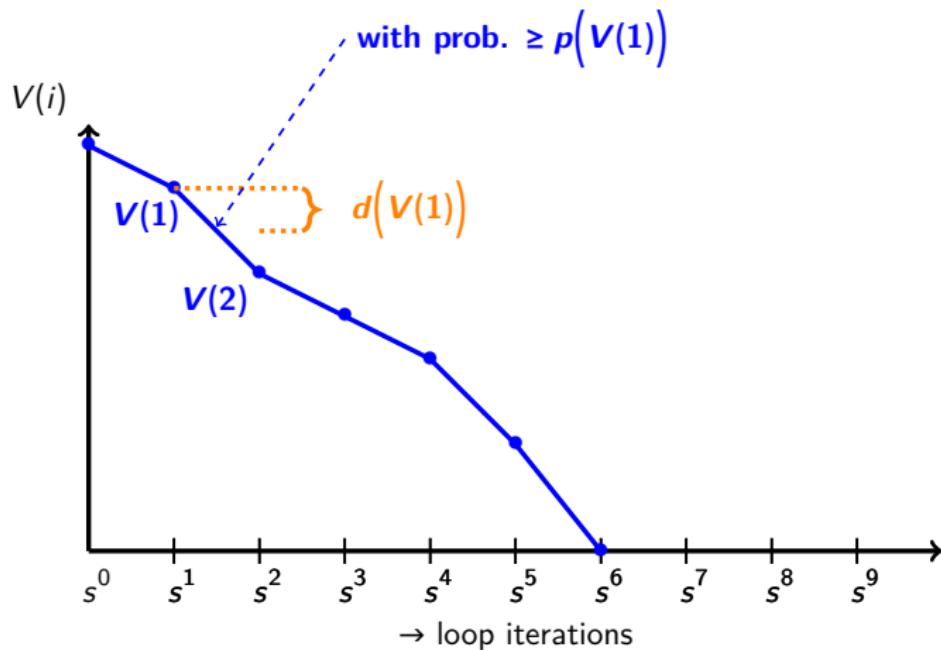
# Intuition



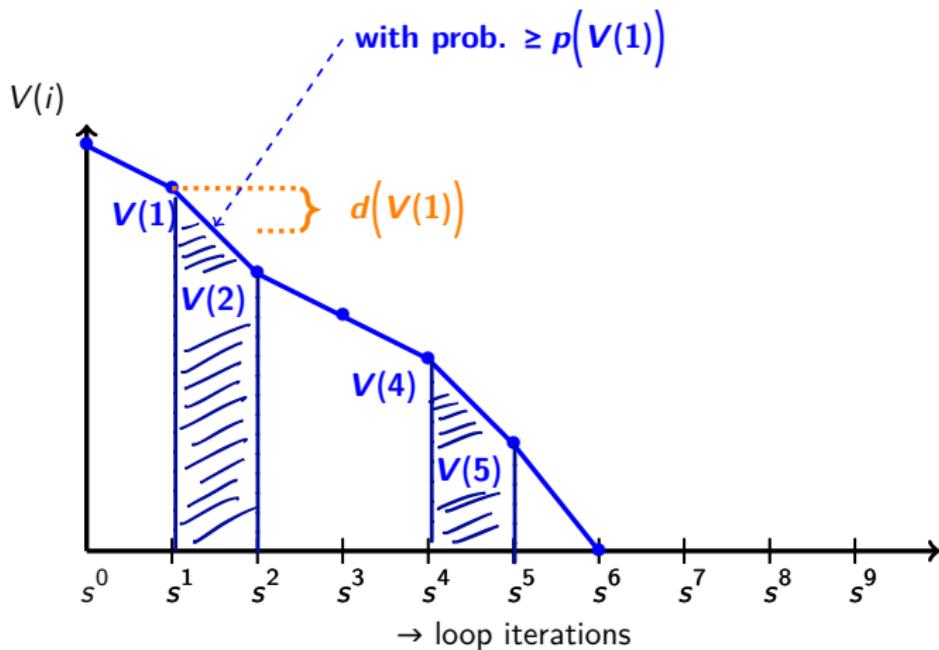
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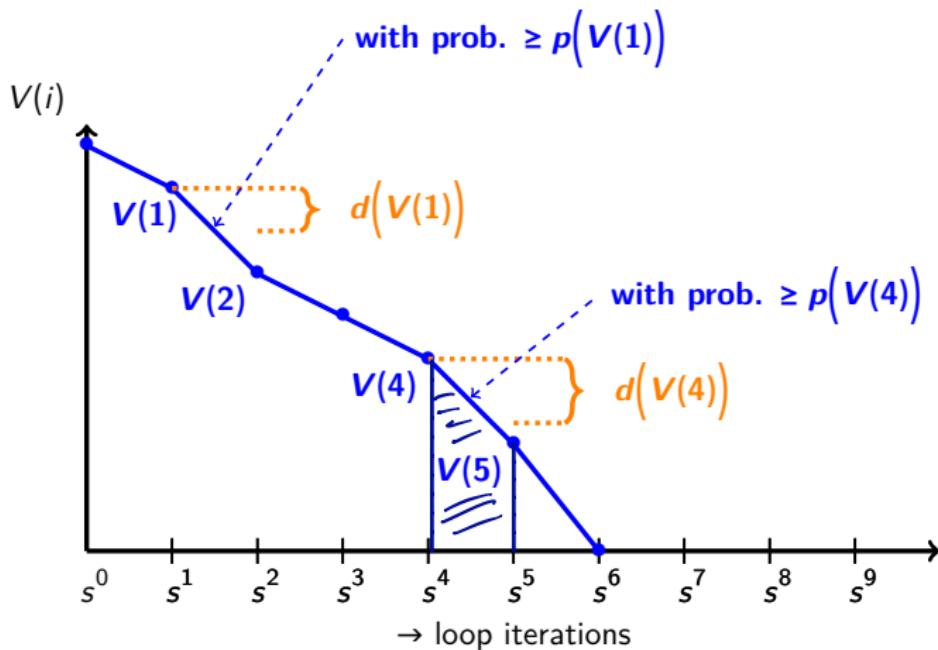
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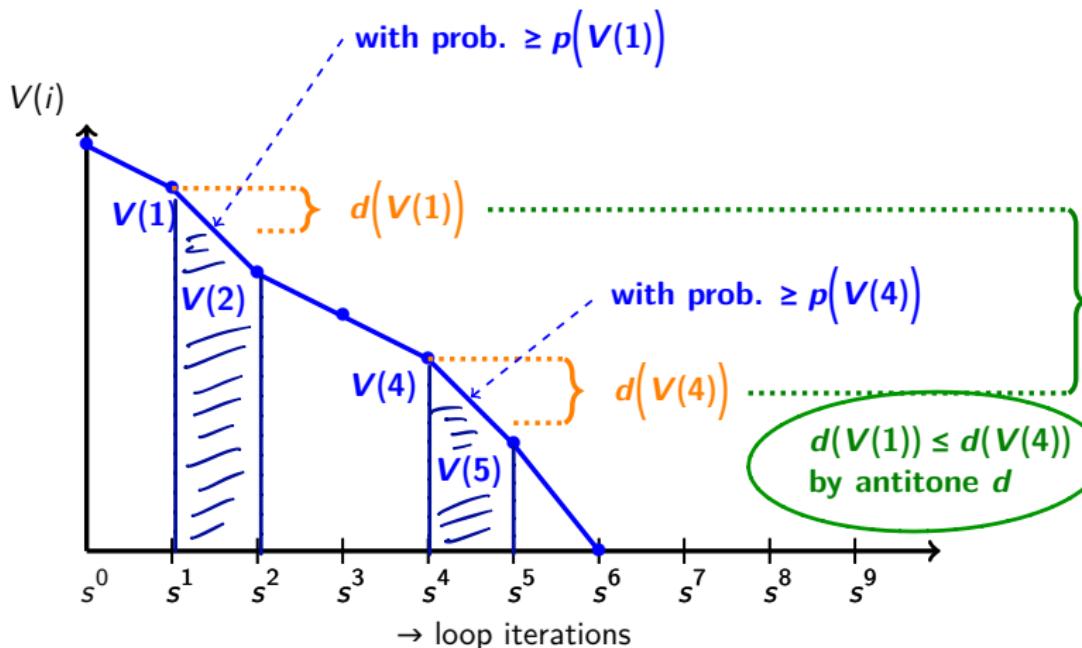
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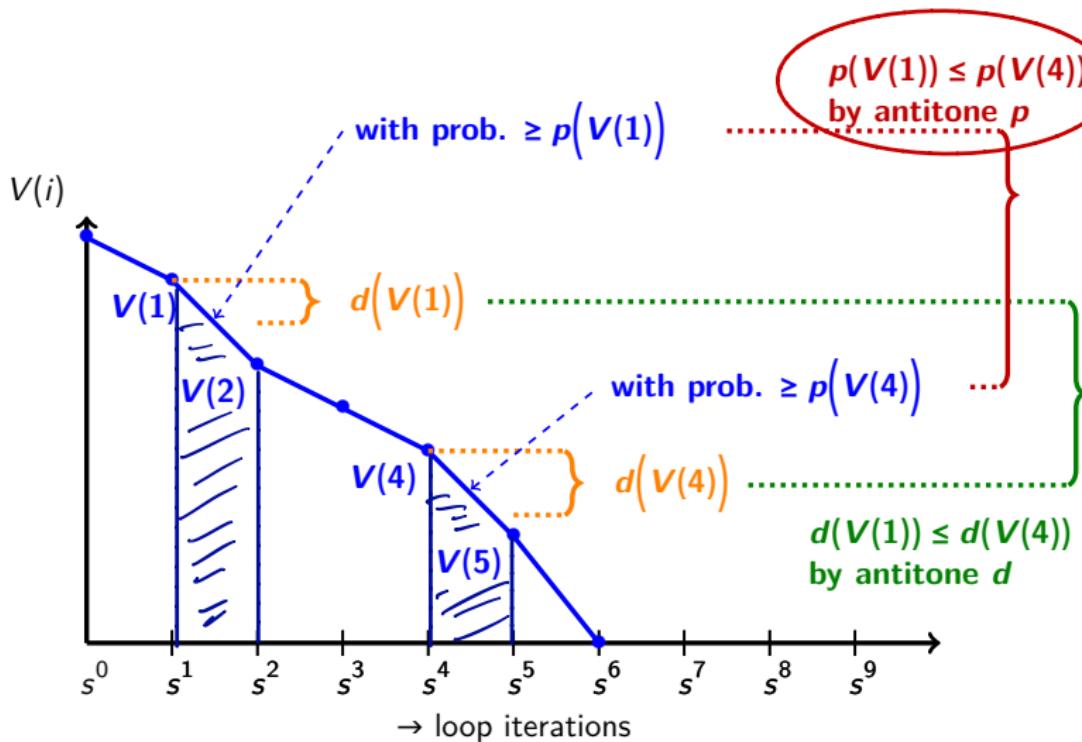
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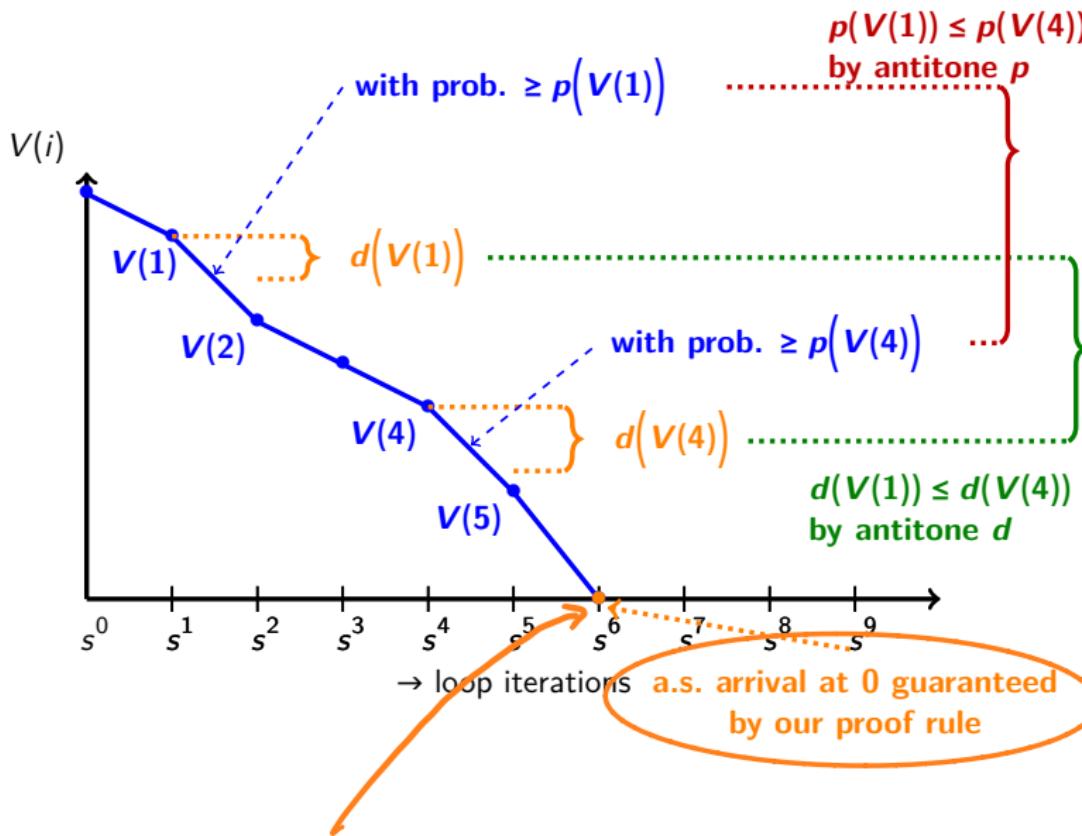
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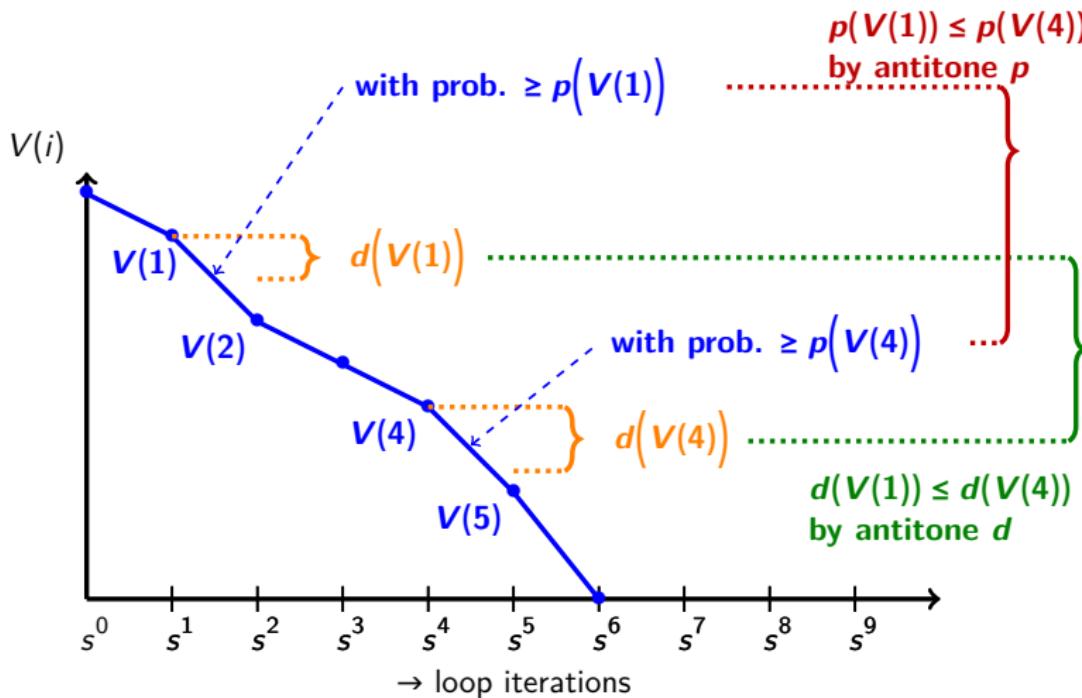
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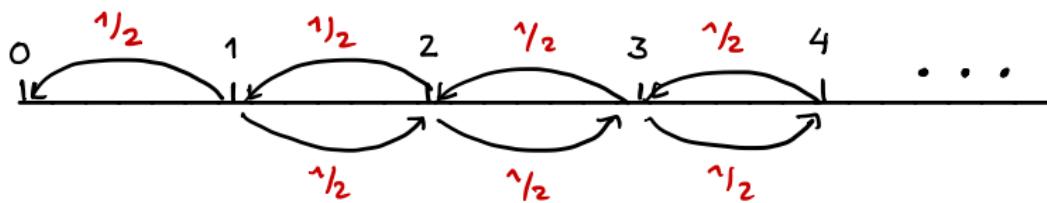
# Intuition



The closer to termination, the more  $V$  decreases and this becomes more likely

# Example: symmetric 1D random walk

```
while (x > 0) {
    x := x-1 [1/2] x := x+1
}
```



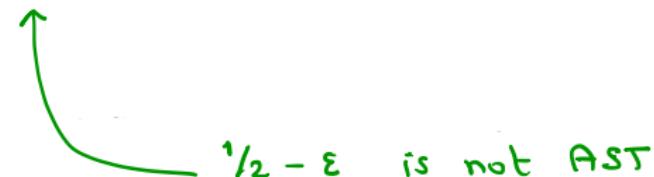
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- ▶ Terminates almost surely
- ▶ Witness of almost-sure termination:
  - ▶  $V = x$
  - ▶  $p = 1/2$  and
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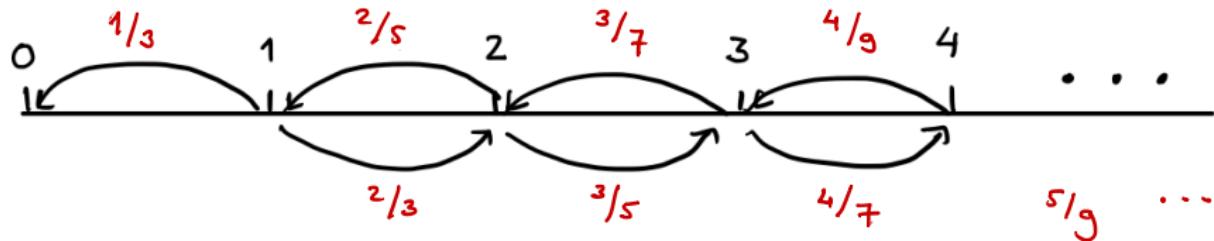


- ▶ Terminates almost surely
- ▶ Witness of almost-sure termination:
  - ▶  $V = x$
  - ▶  $p = \frac{1}{2}$  and
  - ▶  $d = 1$

That's all you need to prove almost-sure termination!

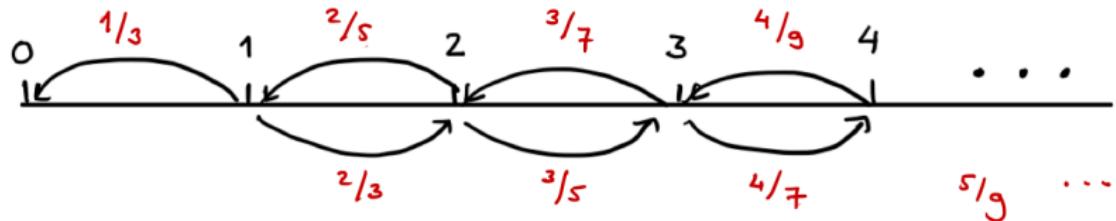
# Example: fair-in-the-limit 1D random walk

```
while (x > 0) {
    q := x/(2*x+1);
    x-- [q] x++
}
```



The closer to 0, the more unfair — drifting away from 0 — it gets

# Example: fair-in-the-limit 1D random walk



- ▶ The closer to 0, the more unfair — drifting away from 0 — it gets
  
  
  
- ▶ Witness of almost-sure termination:
  - ▶  $V = H_x$ , the  $x$ -th Harmonic number  $1 + \frac{1}{2} + \dots + \frac{1}{x}$
  - ▶  $d(v) = \begin{cases} \frac{1}{n} & \text{if } H_{n-1} < v \leq H_n \\ 1 & \text{if } v = 0 \end{cases}$ , and
  - ▶  $p = \frac{1}{3}$

So far we studied several proof rules to verify whether  
a given expectation (or triple  $V, p, d$ ) meets  
constraints that imply upper/lower bounds on weakest pre-expectations

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This can be extended to expected runtimes too

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This can be extended to expected runtimes too

To automate, we need a **concrete syntax** for expectations!

# RELATIVE COMPLETENESS

SIAM J. COMPUT.  
Vol. 7, No. 1, February 1978

## SOUNDNESS AND COMPLETENESS OF AN AXIOM SYSTEM FOR PROGRAM VERIFICATION\*

STEPHEN A. COOK†

**Abstract.** A simple ALGOL-like language is defined which includes conditional, while, and procedure call statements as well as blocks. A formal interpretation, an axiomatic semantics, and a Hoare style axiom system are given for the language. The axiom system is proved to be sound and in a certain sense complete, relative to the interpretive semantics. The main new results are the completeness theorem, and a careful treatment of the procedure call rules for procedures with global variables in their declarations.

**Key words.** program verification, semantics, axiomatic semantics, interpretive semantics, consistency, completeness

**1. Introduction.** The axiomatic approach to program verification along the lines formulated by C. A. R. Hoare (see, for example, [6] and [7]) has received a great deal of attention in the last few years. My purpose here is to pick a simple programming language with a few basic features, give a Hoare style axiom system for the language, and then give a clean and careful justification for both the soundness and adequacy (i.e., completeness) of the axiom system. The justification is done by introducing an interpretive semantics for the language, rather like that in [10] and [8]. These two papers also have outlined soundness arguments for axiom systems, but for somewhat different language features, axioms, and interpretive models. The completeness claim and argument presented here is new (although completeness and incompleteness proofs inspired by an earlier version of this paper [2] appear in [3], [11], [12], [13], and [14]). I have tried to choose the axioms and rules of the formal system to be as simple as possible, subject to the constraints that they be sound, complete, and in the style and spirit of Hoare's rules.

SIAM J. on Computing, 1978



Stephen Cook

# Relative complete verification

## Ordinary Programs

$F \in \text{FO-Arithmetic}$

implies

$\text{wp}[\![P]\!](F) \in \text{FO-Arithmetic}$

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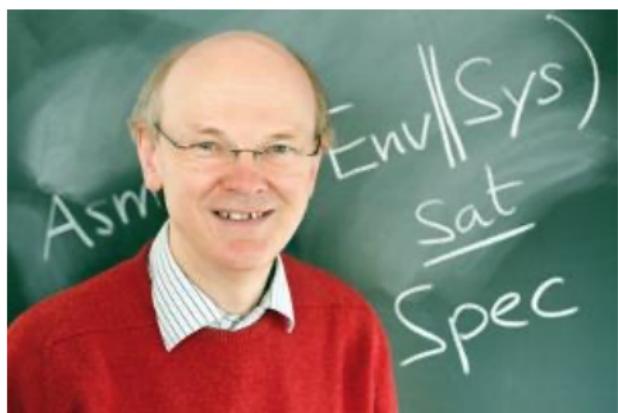
Q: How does the  $\text{SomeSyntax}$  look like?

# 50 years of Hoare logic

“Completeness is a subtle manner and requires a careful analysis”



Krzysztof R. Apt



Ernst-Rüdiger Olderog

# Requirements on a syntax

$\frac{\sqrt{5}-1}{2}$

```
x := 1;
while (x > 0) {
    x +=: 2 [1/2] x -:= 1
}
```

1

$\frac{1}{\pi}$

```
x := geometric(1/4);
y := geometric(1/4);
t := x+y+1 [5/9] t := x+y;
r := 1;
for i in 1..3 {
    s := 0
    for j in 1..2t {
        s := s+1 [1/2] skip
    }
    r := (s == t)
}
```

[ $r = 1$ ]

rational numbers, algebraic numbers, transcendental numbers, etc.

# Syntax of expectations

- ▶ The set [Exp of syntactic expectations](#)

$f$	$\longrightarrow$	$a$	arithmetic expressions
		$[\varphi] \cdot f$	guarding
		$f + f$	addition
		$f \cdot f$	multiplication
		$\exists x: f$	<u>supremum</u> over variable $x$
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$$\exists x:[x \cdot x < y] \cdot x \equiv \sqrt{y}$$

$$\exists z:[z \cdot (x+1) = 1] \cdot z \equiv \frac{1}{x+1}$$

## Examples

# Expressiveness

[Batz, K. et al, POPL 2021]

The set  $\text{Exp}$  of syntactic expectations is **expressive**.

For all pGCL programs  $P$  and  $f \in \text{Exp}$  it holds:

$$\text{wp}[\![P]\!](\![f]\!) = \![g]$$

for some syntactic expectation  $g \in \text{Exp}$ .

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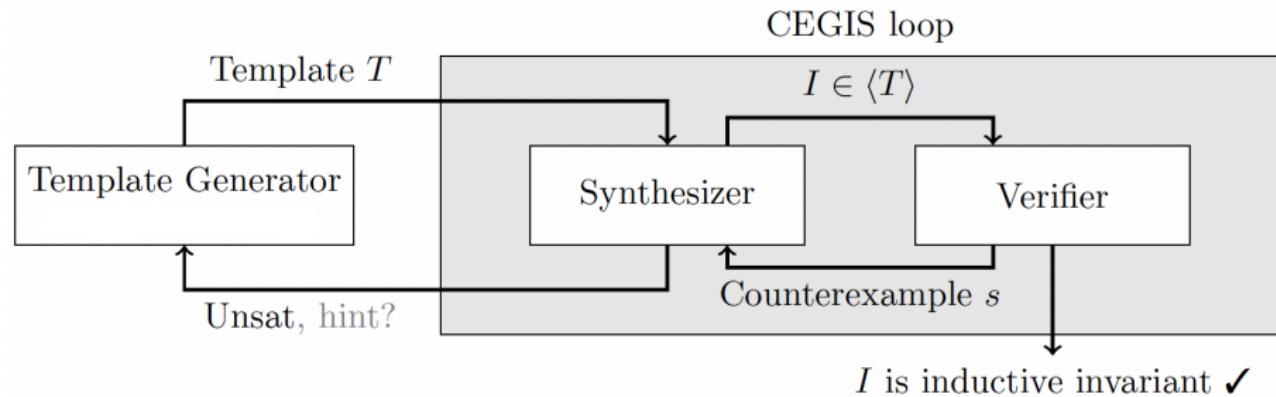
for some syntactic expectation  $g \in \text{Exp}$ .



Expressiveness does not mean decidability, e.g.,  
 for  $f, g \in \text{Exp}$ , does  $\![g]\! \sqsubseteq wp[\!P]\!(\![f]\!)$  is **undecidable**

# Inductive invariant synthesis

## Automated synthesis of inductive invariants



# Bounded retransmission protocol [Helmink et al, 1993]

- ▶ Send file of  $N \approx 10^{10}$  packets via **lossy** channel
- ▶ Packet **loss probability**  $\frac{1}{100}$ , say
- ▶ # packet retransmissions  $\leq 10$ ; otherwise file transmission **fails**

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```

sent := 0; fail := 0;
while (sent < N ∧ fail < F) {
    { fail := fail + 1 }[0.01] { fail := 0 ; sent := sent + 1 }
        failed transmission           successful transmission
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```

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```

sent := 0; fail := 0;                                BRP
while (sent < N ∧ fail < F) {
    { fail := fail + 1 } [0.01] { fail := 0 ; sent := sent + 1 }
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}

```

We verify  $wp[BRP](fail = 10) \leq \frac{1}{1000}$  in 11 seconds. Fully automatically.

**Impossible** for probabilistic model checkers!

## An upper bound

# Synthesising inductive invariants

Problem: find a piece-wise linear inductive invariant  $I$  s.t.

$\underbrace{\Phi_f(I) \sqsubseteq I \text{ and } I \sqsubseteq g}_{I \text{ is inductive for } f \text{ and } g} \quad \text{or determine there is no such } I$

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Approach: use template-based invariants of the (simplified) form:

$$T = [b_1] \cdot a_1 + \cdots + [b_k] \cdot a_k$$

with

- ▶  $b_i$  is a boolean combination of linear inequalities over program vars
- ▶  $a_i$  a linear expression over the program variables with  $[b_i] \cdot a_i \geq 0$
- ▶ the  $b_i$ 's partition the state space, i.e.,  $s \models b_i$  for a unique  $i$

# Synthesising inductive invariants

Problem: find a piece-wise linear inductive invariant  $I$  s.t.

$\underbrace{\Phi_f(I) \sqsubseteq I \text{ and } I \sqsubseteq g}_{I \text{ is inductive for } f \text{ and } g} \quad \text{or determine there is no such } I$

Approach: use template-based invariants of the (simplified) form:

$$T = [b_1] \cdot a_1 + \cdots + [b_k] \cdot a_k$$

with

- ▶  $b_i$  is a boolean combination of linear inequalities over program vars
- ▶  $a_i$  a linear expression over the program variables with  $[b_i] \cdot a_i \geq 0$
- ▶ the  $b_i$ 's partition the state space, i.e.,  $s \models b_i$  for a unique  $i$

Example:  $[c=1] \cdot (2 \cdot x + 1) + [c \neq 1] \cdot x$  is in the above form,  
and  $[x \geq 1] \cdot x + [x \geq 2] \cdot y$  can be rewritten into it.

# Checking linear entailments

[K., McIver *et al*, SAS 2010]

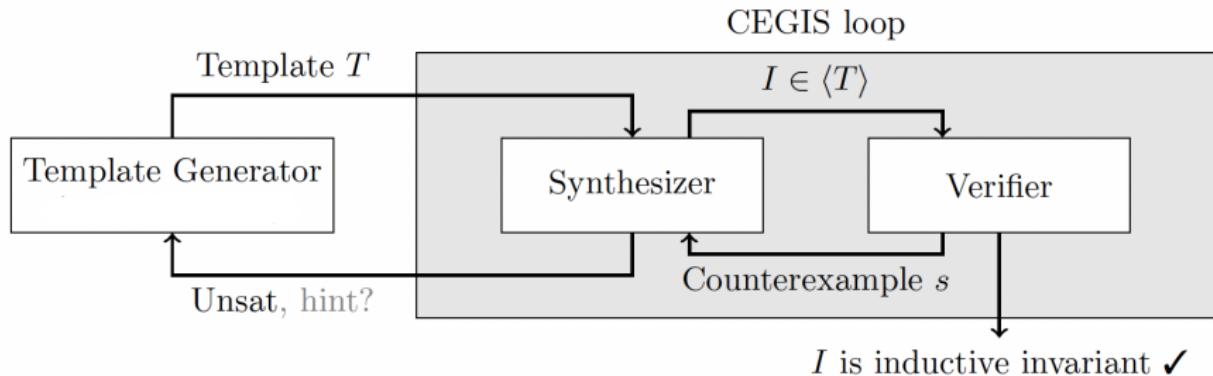
For piecewise linear expectations:

$$f = [b_1] \cdot a_1 + \cdots + [b_k] \cdot a_k \quad \text{and} \quad g = [c_1] \cdot e_1 + \cdots + [c_m] \cdot e_m$$

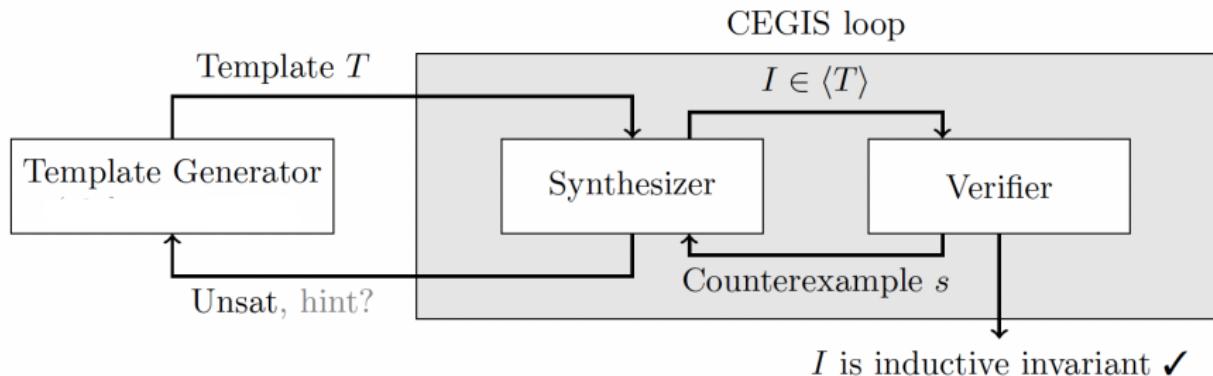
it is decidable whether the quantitative entailment  $f \sqsubseteq g$  holds

$$f \sqsubseteq g \quad \text{if and only if} \quad \underbrace{\bigwedge_{i=1}^k \bigwedge_{j=1}^m (b_i \wedge c_j) \rightarrow a_i \sqsubseteq e_j}_{\text{formula in quantifier-free linear arithmetic}} \quad \text{is valid}$$

# CEGIS for probabilistic invariants [Batz, K. et al, TACAS 2023]

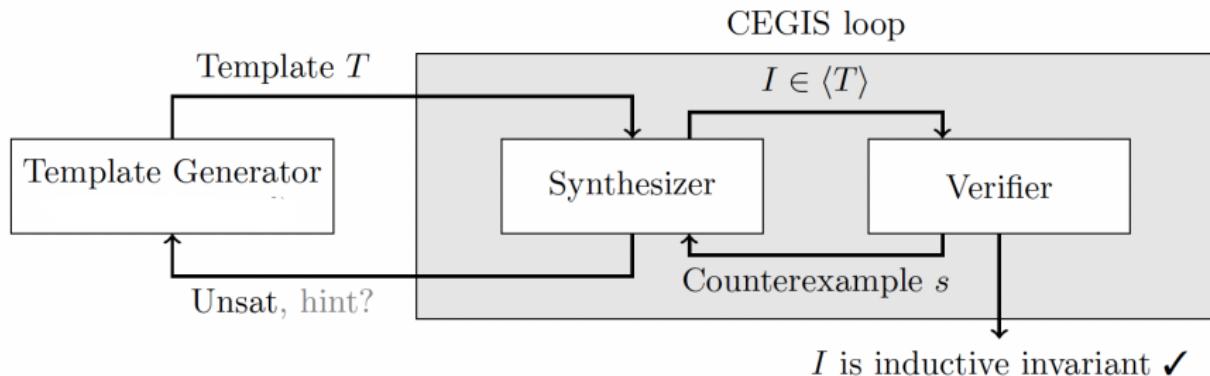


# CEGIS for probabilistic invariants [Batz, K. et al, TACAS 2023]



- ▶ For **finite-state** programs, synthesis is **sound and complete**
- ▶ Applicable to **lower bounds**: UPAST and difference boundedness
- ▶ Uses SMT with QF-LRA (the synthesiser) and QF-LIRA (the verifier)

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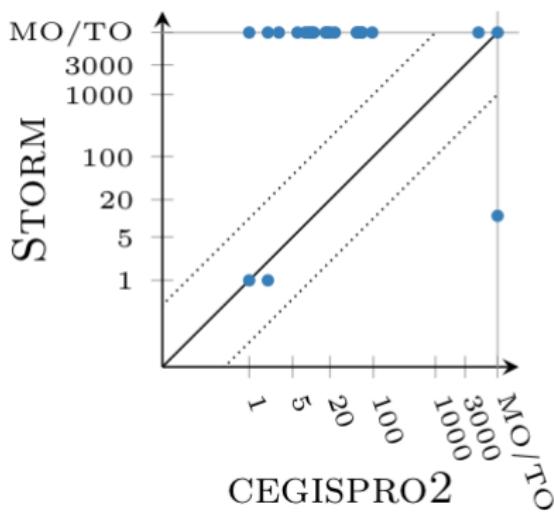
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CEGISPRO2 tool: <https://github.com/moves-rwth/cegispro2>

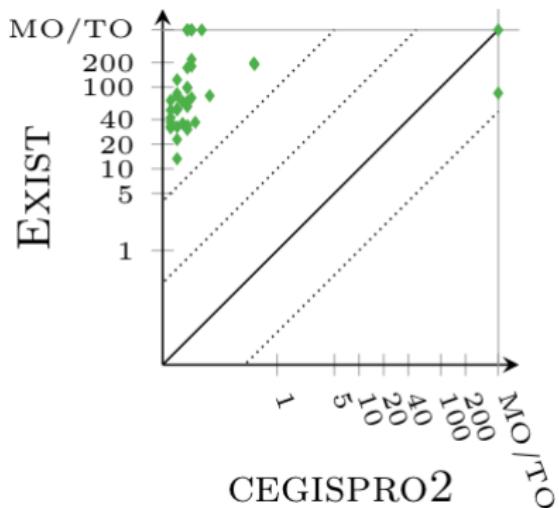
*check it out!*

# Experiments

Comparison to  
model checking



comparison to an  
ML technique



Synthesis of upper bounds  
for finite-state programs  
 $TO = 2\text{h}$ ,  $MO = 8\text{GB}$

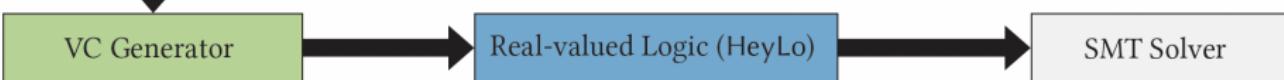
Synthesis of lower bounds  
 $TO = 5\text{min}$

# Outlook: a probabilistic Dafny? ?

expected run-times	partial correctness	expected resource consumption
martingales	positive almost-sure termination	almost-sure terminatioxn
amortised analysis	Park induction	conditional expected values
total correctness	k-induction	probabilistic sensitivity



## Quantitative Intermediate Verification Language (HeyVL)



Caesar: A verification infrastructure for probabilistic programs

[caesarverifier.org](http://caesarverifier.org)

check  
it out!

# A big thanks to my co-workers!



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