

# The Woolz Internet Image Protocol (IIP) Server (Version 1.0.2)

Zsolt Husz \*      Bill Hill †

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## **Abstract**

The Woolz Internet Imaging Protocol (IIP) server (WlzIIPsrv) extends the IIP to allow views of 3D Woolz objects with multiple components. This manual describes these extensions for both users and developers of the WlzIIPsrv.

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\*Supported by NIH under grant #1R01MH070370-01A2.

†bill.hill@igmm.ed.ac.uk

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# 1 Introduction

The Internet Imaging Protocol IIP provides quick access to large image databases allowing large images to be viewed remotely. It makes use of tile-based delivery so that panning and zooming within large images is possible without needing to download the entire image. The computational requirements of the client machine for viewing are low, allowing viewers to be implemented within web browsers. However, it is limited to 2D images. In biomedical imaging (and many other fields) 3D images are routinely used. A set of extensions to the IIP server was developed within the Edinburgh Mouse Atlas Project [EMA] to allow the remote visualization of sections through large 3D objects. These extensions make use of many of the features of Woolz, an image processing system with its own efficient image representation [WOO].

This document assumes understanding of the IIP [4].

For clarity, in the rest of this document IIPsrv will refer to the original IIP server, with code version 0.9.7 [Pillay and Pitzalis], WlzIIPsrv will refer to the extended server, while IIP will point to the protocol standard of [4].

The coordinate system convention used in this document is shown in Figure 1. The object coordinate is defined by the object and the section coordinates result after sectioning. Then, the translated section coordinates with the section's minimum at (0,0) are the display coordinates. Further, the section is divided into non-overlapping tiles covering the whole section. Tiles are numbered with 0, 1, 2, etc., with the 0<sup>th</sup> coordinates matching the display coordinates. The 1<sup>st</sup>, 2<sup>nd</sup>, etc. tiles continue from left to right and top to bottom. A client can visualise a section with reduced viewing area. This has the view coordinates and is client dependent.

# 2 Extension overview

In addition to the IIPsrv commands, a WlzIIPsrv command specifies an object, sets the viewing section parameters and requests image or meta data of the object. Tile request are similar to the TIFF requests, however for a Woolz object the resolution number used in **JTL/TIL** is ignored.

The extended command list that sets query parameters are summarised in Table 1, while Table 2 shows the new objects that may be queried with the **OBJ** command.

Command	Purpose	Syntax
<b>CVT</b>	Request an image to be returned as a composed image. CVT accepts now also PNG and WLZ format requests.	CVT= <i>format</i>
<b>DST</b>	Specify the distance of the sectioning plane	DST= <i>dis</i>
<b>FXP</b>	Specify the fixed point of the viewing section rotation	FXP= <i>X,Y,Z</i>
<b>FXT</b>	Specify the second fixed point of the viewing section rotation	FXT= <i>X,Y,Z</i>
<b>MAP</b>	Define a colour or grey value mapping	MAP= <i>mspec[,mspec[,mspec[,mspec]]]</i> where <i>mspec=t,il,iu,ol,ou,p0,p1</i>
<b>MOD</b>	Specify the projection mode	MOD= <i>mode</i>
<b>PAB</b>	Specify the 3D query point absolute in the object coordinate	PAB= <i>X,Y,Z</i>
<b>PIT</b>	Specify the pitch angle of the sectioning rotation	PIT= <i>angle</i>
<b>PRL</b>	Specify the 2D query point relative in tile or display or tile coordinate	PRL= <i>T,X,Y</i>
<b>PTL</b>	Retrieve a tile as a PNG image	PTL= <i>res,tile</i>
<b>ROL</b>	Specify the roll angle of the sectioning rotation	ROL= <i>angle</i>
<b>SCL</b>	Specify the scale used in the sectioning transformation	SCL= <i>scale</i>
<b>SEL</b>	Specify a component of a compound object to be displayed and its colour. See <a href="#">2.4</a> .	SEL= <i>E,R,G,B,A</i>
<b>UPV</b>	Specify the up vector for the <b>UP_IS_UP</b> mode	UPV= <i>X,Y,Z</i>
<b>WLZ</b>	Specify the Woolz object	WLZ= <i>path</i>
<b>YAW</b>	Specify the yaw angle of the sectioning rotation	YAW= <i>angle</i>

Table 1: Extended command overview

<b>Object</b>	<b>Purpose</b>
<b>IIP-server</b>	Identify if WLZ-IIP is running
<b>Max-size</b>	The size of the section
<b>Tile-size</b>	The size of a tile
<b>Wlz-true-voxel-size</b>	The voxel size of the object
<b>Wlz-volume</b>	The volume of the object
<b>Wlz-n-component</b>	The number of components in a compound object
<b>Wlz-distance-range</b>	The range of the sectioning plane distance
<b>Wlz-sectioning-angles</b>	The pitch, yaw and roll angles of of the sectioning plane
<b>Wlz-coordinate-3D</b>	The 3D coordinates defined in 2D by the <b>PRL</b> command
<b>Wlz-grey-stats</b>	Simple statistics of the Woolz object image values.
<b>Wlz-grey-value</b>	The grey or RGB value of a point specified either the <b>PRL</b> or the <b>PAB</b> commands
<b>Wlz-transformed-coordinate-3d</b>	The display coordinates and displacement from the sectioning plane of a 3D point defined by <b>PAB</b>
<b>Wlz-foreground-objects</b>	The components of the compound object that 2D/3D query point is a foreground

Table 2: Extended object overview

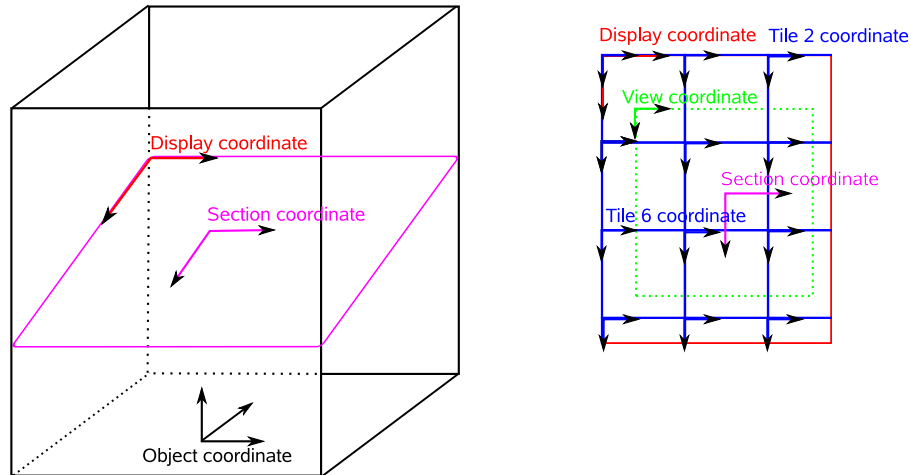


Figure 1: Coordinate systems

## 2.1 Woolz object specification

<b>WLZ</b>	<b>Purpose</b>	Specify the Woolz object. It is similar to the <b>FIF</b> command, however instead of loading Pyramidal Tiled TIFF images, it specifies a Woolz object. Compared with <b>FIF</b> , the Woolz object is not loaded until a later operation requires this. The Woolz objects are cached. 3D domain and value objects, and compound objects with 3D domain or value components are supported. For a compound object the domain of the first object must include all other object domains. If file name ends with <b>.gz</b> , gzipped Woolz object is expected.
	<b>Syntax</b>	<b>WLZ=</b> <i>path</i>
	<b>Input Parameters</b>	<b>PATH</b> <i>path</i> Full path of the Woolz object.
	<b>Response</b>	<b>WLZ</b> returns nothing when accompanied by other commands
	<b>Example</b>	$\Rightarrow$ <b>WLZ</b> =/home/bill/pics/lobster3d.wlz
	<b>Notes</b>	Equivalent if <b>FIF</b> [4, p.25]

## 2.2 Setting sectioning and query parameters

The next commands are optional and can be used in any combination.

<b>DST</b>	<b>Purpose</b>	Specify the distance of the sectioning plane
	<b>Syntax</b>	DST= <i>dis</i>
	<b>Input Parameters</b>	FLOAT <i>dis</i> The distance to the sectioning plane
	<b>Response</b>	none
	<b>Example</b>	⇒DST=12.5
	<b>Default value</b>	0.0
<b>FXP</b>	<b>Purpose</b>	Specify the view rotation fixed point in the object coordinate system.
	<b>Syntax</b>	FXP= <i>x,y,z</i>
	<b>Input Parameters</b>	FLOAT <i>x</i> The x coordinate FLOAT <i>y</i> The y coordinate FLOAT <i>z</i> The z coordinate
	<b>Response</b>	none
	<b>Example</b>	⇒FXP=10.5,20,15.0
	<b>Default value</b>	0.0,0.0,0.0
<b>FXT</b>	<b>Purpose</b>	Specify the second fixed point in the object coordinate system of the viewing section rotation used only with MOD=FIXED_LINE.
	<b>Syntax</b>	FXT= <i>x,y,z</i>
	<b>Input Parameters</b>	FLOAT <i>x</i> The x coordinate FLOAT <i>y</i> The y coordinate FLOAT <i>z</i> The z coordinate
	<b>Response</b>	none
	<b>Example</b>	⇒FXT=30,-20.2,15.0
	<b>Default value</b>	0.0,0.0,0.0

MAP	<b>Purpose</b>	Defines a colour or grey value mapping. Grey values outside the mapped region are clamped to the minimum and maximum output colour component or grey values. There may be 1,2,3 or 4 mapping specifications given; with a single mapping specification meaning a grey value mapping, two specifications a grey with alpha mapping, three an RGB mapping and four an RGB $\alpha$ mapping.
	<b>Syntax</b>	MAP= <i>mspec</i> [, <i>mspec</i> [, <i>mspec</i> [, <i>mspec</i> ]]] where <i>mspec</i> = <i>t</i> , <i>il</i> , <i>iu</i> , <i>ol</i> , <i>ou</i> , <i>p0</i> , <i>p1</i>
	<b>Input Parameters</b>	<i>t</i> $\in$ <i>IDENTITY</i>   <i>LINEAR</i>   <i>GAMMA</i>   <i>SIGMOID</i> The mapping function FLOAT <i>il</i> Input lower grey value FLOAT <i>iu</i> Input upper grey value FLOAT <i>ol</i> Output lower colour component or grey value FLOAT <i>ou</i> Output upper colour component or grey value FLOAT <i>p0</i> Gamma ( $\gamma$ ) or first sigmoid parameter ( $\mu$ ) FLOAT <i>p1</i> Second sigmoid parameter ( $\sigma$ )
	<b>Response Example</b>	none $\Rightarrow$ MAP=LINEAR,0,4095,0,255 Input grey values in the range 0-4095 are mapped to output values with the range 0-255
	<b>Default value</b>	IDENTITY

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<b>MOD</b>	<b>Purpose</b>	Specify projection mode.
	<b>Syntax</b>	MOD= <i>mode</i>
	<b>Input Parameters</b>	<i>mode</i> ∈ STATUE   UP_IS_UP   FIXED_LINE   ZERO_ZETA   ZETA The projection mode
	<b>Response</b>	none
	<b>Example</b>	⇒MOD=FIXED_LINE
	<b>Default value</b>	UP_IS_UP
<b>PIT</b>	<b>Purpose</b>	Specify the pitch angle of the sectioning rotation
	<b>Syntax</b>	PIT= <i>angle</i>
	<b>Input Parameters</b>	FLOAT <i>angle</i> rotation angle in degrees
	<b>Response</b>	none
	<b>Example</b>	⇒PIT=180.0
	<b>Range</b>	0.0-180.0
<b>PAB</b>	<b>Default value</b>	0.0
	<b>Purpose</b>	Specify a 3D query point absolute in the object coordinate system.
	<b>Syntax</b>	PAB= <i>X,Y,Z</i>
	<b>Input Parameters</b>	FLOAT <i>x</i> The x coordinate FLOAT <i>y</i> The y coordinate FLOAT <i>z</i> The z coordinate
	<b>Notes</b>	If both <b>PRL</b> and <b>PAB</b> are specified then <b>PRL</b> has priority of feature queries
	<b>Response</b>	none
	<b>Example</b>	⇒PAB=200,-50,30

<b>PRL</b>	<b>Purpose</b>	Specify a 2D query point relative to tile or display coordinate system.
	<b>Syntax</b>	<b>PRL</b> = <i>T,X,Y</i>
	<b>Input Parameters</b>	<b>RANGE</b> <i>T</i> The <i>T</i> tile number <b>RANGE</b> <i>X</i> The <i>x</i> coordinate <b>RANGE</b> <i>Y</i> The <i>y</i> coordinate
	<b>Notes</b>	<b>PRL</b> either specified a coordinate in a given tile, or if the tile number <i>T</i> =-1 then in the display coordinates
	<b>Response</b>	none
	<b>Range</b>	<i>T</i> =-1 .. <b>maxtile</b> <i>X,Y</i> are limited to the tile or section size
<b>ROL</b>	<b>Example</b>	⇒ <b>PRL</b> =2,20,1
	<b>Default value</b>	none
	<b>Purpose</b>	Specify the roll angle of the sectioning rotation
	<b>Syntax</b>	<b>ROL</b> = <i>angle</i>
	<b>Input Parameters</b>	<b>FLOAT</b> <i>angle</i> rotation angle in degrees
	<b>Response</b>	none
<b>SCL</b>	<b>Example</b>	⇒ <b>ROL</b> =20.0
	<b>Range</b>	0.0-360.0
	<b>Default value</b>	0.0
	<b>Purpose</b>	Specify the scale used in the sectioning transformation.
<b>SCL</b>	<b>Syntax</b>	<b>SCL</b> = <i>scale</i>
	<b>Input Parameters</b>	<b>FLOAT</b> <i>scale</i> the scale. A values over one is up, while lower than one is down-scaling.
	<b>Response</b>	none
	<b>Example</b>	⇒ <b>SCL</b> =2.5
	<b>Range</b>	positive
	<b>Default value</b>	1.0

UPV	<b>Purpose</b>	Specify the up vector for the UP_IS_UP mode.
	<b>Syntax</b>	UPV= <i>X,Y,Z</i>
	<b>Input Parameters</b>	FLOAT <i>X</i>
		The x component
		FLOAT <i>Y</i>
		The y component
		FLOAT <i>Z</i>
		The z component
	<b>Response</b>	none
	<b>Example</b>	⇒UPV=0,-1,2
	<b>Default value</b>	0.0,0.0,-1.0
YAW	<b>Purpose</b>	Specify the yaw angle of the sectioning rotation.
	<b>Syntax</b>	YAW= <i>angle</i>
	<b>Input Parameters</b>	FLOAT <i>angle</i> rotation angle in degrees
	<b>Response</b>	none
	<b>Example</b>	⇒YAW=2.0
	<b>Range</b>	0.0-360.0
	<b>Default value</b>	0.0
PTL	<b>Purpose</b>	Retrieve a tile as a PNG image. This command is equivalent to the JTL command returning JPEG tiles.
	<b>Syntax</b>	PTL= <i>res,tile</i>
	<b>Input Parameters</b>	INT <i>res</i> resolution
		INT <i>tile</i> tile number
	<b>Response</b>	Requested tile <i>tile</i> on the resolution <i>res</i>
	<b>Example</b>	⇒PTL=1,2
	<b>Default value</b>	0,0
CVT	<b>Purpose</b>	Request an image to be returned as a composed image. CVT accept now also PNG format requests.
	<b>Syntax</b>	CVT= <i>format</i>
	<b>Input Parameters</b>	PNG JPEG <i>format</i> output format
	<b>Response</b>	Requested image
	<b>Example</b>	⇒CVT=png
	<b>Default value</b>	jpeg

<b>SEL</b>	<b>Purpose</b>	Specify a component of a compound object to be displayed and its colour. The component can be specified either by it's index or by a image processing expression which can combine the components through the use of image processing operators. Where a Woolz object is not a compound object, the SEL command will regard it as a compound object with a single component of index zero. Image processing expressions are explained in <a href="#">2.4</a> . If the command is not present then the first object is returned. Multiple <b>SEL</b> will stack up the section in the request order.
	<b>Syntax</b>	SEL= <i>E,R,G,B,A</i> SEL= <i>E,R,G,B</i> SEL= <i>E,A</i> SEL= <i>E</i>
	<b>Input Parameters</b>	UINT <i>E</i> compound object index or image processing expression UINT <i>R</i> red value UINT <i>G</i> green value UINT <i>B</i> blue value UINT <i>A</i> alpha value
	<b>Response</b>	none
	<b>Example</b>	⇒SEL=0,255,0,255,127
	<b>Default value</b>	0,0,0,0,0

### 2.3 Extended object reference

<b>IIP-server</b>	<b>Purpose</b>	Identify if WlzIIPsrv is running.
	<b>Syntax</b>	IIP-server
	<b>Response</b>	IIP-server:255.552255
	<b>Example</b>	⇒OBJ=IIP-server ⇐IIP-server:255.552255
	<b>Note</b>	This object should be used to verify if the IIP server has Woolz sectioning capabilities

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<b>Max-size</b>	<b>Purpose</b>	Return the size of the section. For a Woolz object, the size is dependent on the sectioning parameters
	<b>Syntax</b>	<b>Max-size</b>
	<b>Response</b>	<b>Max-size:width height</b> INT <i>width</i> The width in pixels of the section at the current scale INT <i>height</i> The height in pixels of the section at the current scale
	<b>Example</b>	$\Rightarrow$ OBJ=Max-size $\Leftarrow$ Max-size:512 1024
	<b>Note</b>	The size is dependent on the viewing plane defining parameters
<b>Tile-size</b>	<b>Purpose</b>	Return the size of a tile.
	<b>Syntax</b>	<b>Tile-size</b>
	<b>Response</b>	<b>Tile-size:width height</b> INT <i>width</i> The width in pixels of the tile INT <i>height</i> The height in pixels of the tile
	<b>Example</b>	$\Rightarrow$ OBJ=Tile-size $\Leftarrow$ Tile-size:64 64
	<b>Note</b>	The size is constant throughout the life of the server (see also section <a href="#">6.4</a> ).

<b>Wlz-true-voxel-size</b>	<b>Purpose</b>	Returns the voxel size of the object.
	<b>Syntax</b>	<code>Wlz-true-voxel-size</code>
	<b>Response</b>	<code>Wlz-true-voxel-size:X Y Z</code> <code>FLOAT X</code> The x size <code>FLOAT Y</code> The y size <code>FLOAT Z</code> The z size
	<b>Example</b>	<code>⇒OBJ=Wlz-true-voxel-size</code> <code>⇐Wlz-true-voxel-size:2 1 2.2</code>
	<b>Note</b>	The voxel size is object specific, but view independent.
<b>Wlz-volume</b>	<b>Purpose</b>	Returns the volume of the object.
	<b>Syntax</b>	<code>Wlz-volume</code>
	<b>Response</b>	<code>Wlz-volume:volume</code> <code>INT volume</code> The volume of the Woolz object
	<b>Example</b>	<code>⇒OBJ=Wlz-volume</code> <code>⇐Wlz-volume:748</code>
	<b>Note</b>	The volume is object specific, but view independent.

<b>Wlz-n-components</b>	<b>Purpose</b>	Returns the number of components of a compound object.
	<b>Syntax</b>	<code>Wlz-n-components</code>
	<b>Response</b>	<code>Wlz-n-components:n</code> <code>INT n</code> The number of components of the Woolz object
	<b>Example</b>	<code>⇒OBJ=Wlz-n-components</code> <code>⇐Wlz-n-components:3</code>
	<b>Note</b>	The number of components will be 1 if the object is not a compound object or is compound and only has a single component; in other cases the number of components will be greater for a valid object.
<b>Wlz-distance-range</b>	<b>Purpose</b>	Returns the range of the sectioning plane distance.
	<b>Syntax</b>	<code>Wlz-distance-range</code>
	<b>Response</b>	<code>Wlz-distance-range:min max</code> <code>FLOAT min</code> The minimum distance <code>FLOAT max</code> The maximum distance
	<b>Example</b>	<code>⇒OBJ=Wlz-distance-range</code> <code>⇐Wlz-distance-range:-20 80</code>
	<b>Note</b>	The distance range is view-dependent.
<b>Wlz-sectioning-angles</b>	<b>Purpose</b>	Returns in degrees pitch, yaw and roll angles of the rotation of the sectioning plane.
	<b>Syntax</b>	<code>Wlz-sectioning-angles</code>
	<b>Response</b>	<code>Wlz-sectioning-angles:pitch yaw roll</code> <code>FLOAT pitch</code> The pitch angle of viewing plane rotation <code>FLOAT yaw</code> The yaw angle of viewing plane rotation <code>FLOAT roll</code> The roll angle of viewing plane rotation
	<b>Example</b>	<code>⇒OBJ=Wlz-sectioning-angles</code> <code>⇐Wlz-sectioning-angles:0 40 30</code>

<b>Wlz-3d-bounding-box</b>	<b>Purpose</b>	Returns The first and last plane, line and column number of the object.
	<b>Syntax</b>	Wlz-3d-bounding-box
	<b>Response</b>	Wlz-3d-bounding-box:plane1 lastpl line1 lastln column1 lastcl FLOAT plane1 The first plane number of the object FLOAT lastpl The last plane number of the object FLOAT line1 The first line number of the object FLOAT lastln The last line number of the object FLOAT column1 The first column number of the object FLOAT lastcl The last column number of the object
	<b>Example</b>	⇒OBJ=Wlz-3d-bounding-box ⇐Wlz-3d-bounding-box:0 10 -15 15 30 90

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<b>Wlz- transformed- 3d- bounding- box</b>	<b>Purpose</b>	Returns The first and last plane, line and column number of the object after a section transform.
	<b>Syntax</b>	<b>Wlz-transformed-3d-bounding-box</b>
	<b>Response</b>	<b>Wlz-transformed-3d-bounding-box:plane1</b> <i>lastpl line1 lastln colum1 lastcl</i> <b>FLOAT plane1</b> The first section plane number <b>FLOAT lastpl</b> The last section plane number <b>FLOAT line1</b> The first line number of the section <b>FLOAT lastln</b> The last line number of the section <b>FLOAT colum1</b> The first column number of the section <b>FLOAT lastcl</b> The last column number of the section
	<b>Example</b>	⇒OBJ=Wlz-transformed-3d-bounding-box ⇐Wlz-transformed-3d-bounding-box:10 100 -23 12 308 490
<b>Wlz- coordinate- 3D</b>	<b>Purpose</b>	Returns the 3D object coordinates defined in 2D by the <b>PRL</b> command.
	<b>Syntax</b>	<b>Wlz-coordinate-3D</b>
	<b>Response</b>	<b>Wlz-coordinate-3D:X Y Z</b> <b>FLOAT x</b> The x coordinate <b>FLOAT y</b> The y coordinate <b>FLOAT z</b> The z coordinate
	<b>Example</b>	⇒OBJ=Wlz-coordinate-3D ⇐Wlz-coordinate-3D:20 30 10

<b>Wlz-grey-stats</b>	<b>Purpose</b>	Computes and returns simple statistics of the grey values of a Woolz object.
	<b>Syntax</b>	<code>Wlz-grey-stats</code>
	<b>Response</b>	<p><code>Wlz-grey-stats:n t gl gu sum ss mean stddev</code> or</p> <p><code>Wlz-grey-stats:NULL</code></p> <p>UINT <i>n</i> Number of image values in the Woolz object.</p> <p>WlzGreyType <i>t</i> The Woolz image value type, with  <math>t \in \text{WLZ\_GREY\_INT} \mid \text{WLZ\_GREY\_SHORT} \mid \text{WLZ\_GREY\_UBYTE} \mid \text{WLZ\_GREY\_FLOAT} \mid \text{WLZ\_GREY\_DOUBLE} \mid \text{WLZ\_GREY\_RGBA}</math></p> <p>FLOAT <i>gl</i> Minimum image value.</p> <p>FLOAT <i>gu</i> Maximum image value.</p> <p>FLOAT <i>sum</i> Sum of image values.</p> <p>FLOAT <i>ss</i> Sum of squares of image values.</p> <p>FLOAT <i>mean</i> Mean image value.</p> <p>FLOAT <i>stddev</i> Standard deviation of image values.</p>
	<b>Example</b>	$\Rightarrow \text{OBJ} = \text{Wlz-grey-value}$ $\Leftarrow \text{Wlz-grey-stats: } 489600 \text{ UBYTE } 0 \text{ } 255 \text{ } 8.5857\text{e}+06 \text{ } 1.42684\text{e}+09 \text{ } 17.5362 \text{ } 51.0567$
	<b>Note</b>	<p>For RGB<math>\alpha</math> Woolz objects the computed values will be for the modulus of the image values.</p> <p>When the object does not have image values <i>NULL</i> will be returned.</p>

---

<b>Wlz-grey-value</b>	<b>Purpose</b>	Returns in grey or RGB value of a point specified either the <b>PRL</b> or the <b>PAB</b> commands.
	<b>Syntax</b>	<b>Wlz-grey-value</b>
	<b>Response</b>	<b>Wlz-grey-value:grey</b> or <b>Wlz-grey-value:R G B</b> INT <i>grey</i> The grey value of the pixel INT <i>R</i> The red channel of the pixel INT <i>G</i> The green channel of the pixel INT <i>B</i> The blue channel of the pixel
	<b>Example</b>	⇒OBJ=Wlz-grey-value ⇐Wlz-grey-value:0 255 10
	<b>Note</b>	The returned values are in the range of 0 to 255.
<b>Wlz-transformed-coordinate-3d</b>	<b>Purpose</b>	Returns the the display coordinates and displacement from the sectioning plane of a 3D point defined by <b>PAB</b>
	<b>Syntax</b>	<b>Wlz-transformed-coordinate-3d</b>
	<b>Response</b>	<b>Wlz-transformed-coordinate-3d:X Y D</b> INT <i>X</i> The x coordinate in display frame INT <i>Y</i> The y coordinate in display frame FLOAT <i>D</i> The the signed distance from the sectioning plane
	<b>Example</b>	⇒OBJ=Wlz-transformed-coordinate-3d ⇐Wlz-transformed-coordinate-3d:30 40 60.0002

<b>Wlz-foreground-objects</b>	<b>Purpose</b>	The components of the compound object that 2D/3D query point is a foreground
	<b>Syntax</b>	Wlz-foreground-objects
	<b>Response</b>	Wlz-transformed-coordinate-3d: $O_1$ $O_2$ ... $O_n$ INT $O_1$ The compound object index that a point is a foreground pixel
	<b>Example</b>	$\Rightarrow$ OBJ=Wlz-foreground-objects $\Leftarrow$ Wlz-foreground-objects: 0 2 5 10

Object queries **Author**, **Copyright**, **Create-dtm**, **Subject** and **App-name** return *author/ copyright/ create-dtm/ subject/ app-name unknown* since they are not defined for a Woolz object.

## 2.4 Image Processing Expressions

Image processing expressions may be built using the components of Woolz compound objects and basic image processing operators. The operators supported are: difference dilation, domain, erosion, intersection, occupancy, threshold and union. Image processing expressions are built from compound object indices and the image processing operators. Two of the image processing operators (occupancy and union) may given a list indices in their expressions. The occupancy operator may also be given no indices which implies all components of the compound object. The image processing expressions can be written using the syntax defined in table 3. This allows expressions such as:

`erosion(1,2)` erodes the domain of the object with index one in the compound object by two voxels.

`diff(dilation(1,2),3)` dilates the domain of the object with index one in the compound object by two voxels and then computes the difference between that and the object with index 3.

`domain(threshold(0,ge,200))` creates a domain from the object with index 0 where all voxels have values greater than or equal to 200. Without the domain operator threshold would give a object with image values.

The image processing operators available and their parameters are described in table 4.

<i>exp list</i>	$:=$	$(exp   idx\ list) (, exp\ list)$
<i>exp</i>	$:=$	$idx  $ $diff(exp, exp)  $ $dilation(exp, uint)  $ $domain(exp)  $ $erosion(exp, uint)  $ $intersect(exp\ list, exp\ list)  $ $occupancy(index\ list?)  $ $threshold(exp, val, cmp)$ $union(exp\ list   idx\ list, exp\ list   idx\ list)  $
<i>idx list</i>	$:=$	$(uint   idx\ range   idx\ list, idx\ list)$
<i>idx range</i>	$:=$	$uint - uint$
<i>idx</i>	$:=$	$[0-9]^+$
<i>uint</i>	$:=$	$[1-9][0-9]^*$
<i>val</i>	$:=$	$[-+]?[0-9]^*.[0-9]^+([eE] [-+]?[0-9]^+)?$
<i>cmp</i>	$:=$	$(lt)   (le)   (eq)   (ge)   (gt)$

Table 3: Syntax for image processing expressions.

### 3 HTML query examples

#### Tile request

```
http://localhost/cgi-bin/iipsrv.fcgi?
  WLZ=/home/bill/pics/lobster3d.wlz&
  QLT=50&JTL=1,0
```

Returns a jpeg tile 0 with a quality factor of 50%. The section default parameters, mode UP\_IS\_UP and zero distance and viewing angles are used.

#### Sectioning plane distance

```
http://localhost/cgi-bin/iipsrv.fcgi?
  WLZ=/home/bill/pics/lobster3d.wlz&DST=8&QLT=50&PTL=1,0
```

As above, but the sectioning plane distance is 8 and the returned tile has been compressed with png not jpeg format.

#### Sectioning mode, plane distance and angle

```
http://localhost/cgi-bin/iipsrv.fcgi?DST=40&YAW=61.5&PIT=3&ROL=0&MOD=ZETA&
  WLZ=/home/zsolth/small.wlz&QLT=50&CVT=jpeg
```

Returns the whole section with the distance 40, yaw angle 61.5, pitch 3, roll 0 degrees, for a plane at distance 40

<b>Operator</b>	<b>Description</b>
<code>diff(<i>exp</i>,<i>exp</i>)</code>	The difference between the two given domains.
<code>dilation(<i>exp</i>,<i>radius</i>)</code>	The dilation of the domain by <i>radius</i> voxels.
<code>domain(<i>exp</i>)</code>	The domain of an object.
<code>erosion(<i>exp</i>,<i>radius</i>)</code>	The erosion of the domain by <i>radius</i> voxels.
<code>intersect(<i>exp list</i>)</code>	The intersection of the domains in the given lists.
<code>occupancy(<i>idx list</i>?)</code>	The domain occupancy in the optional list.
<code>threshold(<i>exp</i>,<i>value</i>,<i>comparison</i>)</code>	Creates an object where the image values satisfy the given <i>value</i> and <i>comparison</i> . Here the value is floating point and valid comparisons are <b>lt</b> (less than), <b>le</b> (less than or equal), <b>eq</b> (equal), <b>ge</b> (greater than or equal) and <b>gt</b> (greater than).
<code>union(<i>exp list</i>   <i>idx list</i>, <i>exp list</i>   <i>idx list</i>)</code>	The union of the domains in the given lists.

Table 4: Descriptions of image processing operators

### **Distance range query**

```
http://localhost/cgi-bin/iipsrv.fcgi?YAW=61&PIT=3&ROL=0&MOD=ZETA&
WLZ=/home/zsolth/small.wlz&OBJ=Wlz-distance-range
```

results in

```
Wlz-distance-range:0 171
```

### **3D object coordinate query**

```
http://localhost/cgi-bin/l.fcgi?WLZ=/home/zsolth/fif/wlz/ts14.wlz&
DST=200&YAW=10&PIT=3&PRL=0,30,40&OBJ=Wlz-coordinate-3d
```

results in

```
Wlz-coordinate-3d:418.43 53.5708 15.9916
```

The (30,40) display coordinate in sectioning plane DST=200 has 3D object coordinates (418.43,53.5708,15.9916).

### **3D coordinate projection to a section**

```
http://localhost/cgi-bin/l.fcgi?WLZ=/home/zsolth/fif/wlz/ts14.wlz&
DST=130&YAW=10&PIT=3&PAB=418.43,53.5708,15.9916&OBJ=Wlz-transformed-coordinate-
```

results in

```
Wlz-transformed-coordinate-3d:30 40 70.0002
```

The (418.43,53.5708,15.9916) object coordinate in sectioning plane DST=130 has display coordinates (30,40) and has a distance 70.0002 from the plane.

### **Sectioning, selection and image processing operations**

```
http://localhost/cgi-bin/iipsrv.fcgi?DST=40&YAW=61.5&PIT=3&ROL=0&MOD=ZETA&
WLZ=/home/bill/compound.wlz&
SEL=(dilation(union(1-3)),255,0,0,255)&
QLT=50&CVT=jpeg
```

The section is selected as described above and a domain is created that is the dilated union of components 1, 2 and 3 of the compound object.

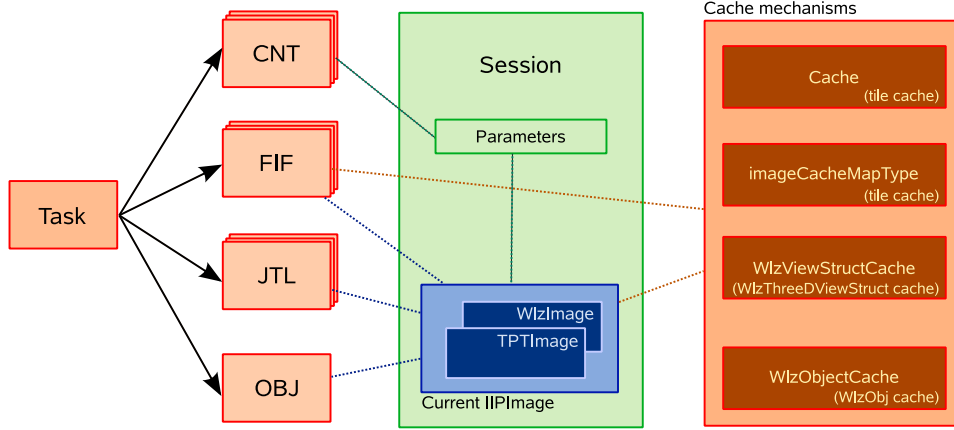


Figure 2: wliipsrv version 0.9.7 architecture

## 4 WlzIIPsRv coding

### 4.1 Architecture

Figure 2 depicts the architecture of the WlzIIPsRv this being inherited from the original IIPsRv and explaining both. Blocks in the figure represent either C++ classes or structures.

The **Task** class is the base of all command classes that serve independently each IIP command. Its static `factory(string type)` method creates an instance of the appropriate class that serves the `type` IIP command.

Figure 2 shows some of the classes implementing the IIP commands, all derived from the **Task**. Four command types can be identified:

**Parameter setting commands** such **CNT** and **ROL** pass a parameter to the server. The parameter value is stored by the command in the **Session** structure.

**Object defining commands** such **FIF** and **WLZ** receive the file name of an object and creates the necessary structures to handle an object. In WlzIIPsRv, either **TPTImage** and **WlzImage** classes store Tiled Pyramidal TIFFs and Woolz objects.

**Image providers** such **JTL**, **PTL** and **CVT** generate a tile or a full image corresponding to the previously set parameters, stored in the **Session** structure.



**Parameter enquiry** with **OBJ** command returns an parameter computed or previously specified.

The **Session** structure stores all session related parameters, including the current image object.

To reduce the computation overhead, three types of caches are used:

- for tiles (**RawTile**),
- for flat images (**IIPImage**)
- for Woolz objects and view structures (**WlzObj**).

The interactions between classes, figure 2, are multiple:

- task creates the requested command class,
- commands set session related parameters and the current object
- the **OBJ** command provides the current object parameters,
- before loading from disc, when an operation requires access object data the appropriate cache structure is checked first. Also, when a tile is requested, if it parameters result in a cache hit then the cached tile is returned. The a Woolz view structures are cached and looked before a section is generated.

#### 4.2 IIPsrv and WlzIIPsrv beside the IIP specification

IIP [4, p.25] defines a set of mandatory and optional commands that an IIP server should implements. The IIPsrv implements a subset of this commands, while also adds extra commands. WlzIIPsrv further extends the command set, while some of the original IIP commands are incompatible with Woolz objects.

The list of commands from Table 5 compares command sets of the IIP specification, the IIPsrv and the WlzIIPsrv with supported (S), unsupported (N), partially implemented (P) and commands in an unknown, an undocumented or nonfunctional state (U).

## 5 Woolz IIP Proxy

The Woolz IIP Proxy filters and forwards IIP requests to one or more WlzIIP servers. The requests conform the FCGI protocol. Though it was designated

Command	IIP spec	IIPSrv	WlzIIPSrv
AFN	S	N	N
CIN	S	N	N
CNT	S	S	S
CTW	S	N	N
CVT	S	S	S
FIF	S	S	S
FTR	S	N	N
HEI	S	U	U
ICC	S	S	U
JTL	S	S	P
OBJ	S	S	S
QLT	S	S	S
RAR	S	N	N
RFM	S	N	N
RGN	S	S	S
ROI	S	S	S
RST	S	N	N
SDS	S	S	N
TIL	S	S	P
WID	S	U	U
JTLS	N	S	N
SHD	N	S	U
DST	N	N	S
FXP	N	N	S
FXT	N	N	S
MAP	N	N	S
MOD	N	N	S
PAB	N	N	S
PIT	N	N	S
PRL	N	N	S
PTL	N	N	S
ROL	N	N	S
SCL	N	N	S
SEL	N	N	S
UPV	N	N	S
WLZ	N	N	S
YAW	N	N	S
Affine-transform	S	N	N
App-name	S	U	P
Aspect-ratio	S	N	N
Author	S	U	N
Basic-info	S	S	S
Colorspace	S	S	U
Color-twist	S	N	N
Comment	S	U	N
Comp-group	S	N	N
Contrast-adjust	S	N	N
Copyright	S	U	S
Create-dtm	S	U	N
Edit-time	S	U	N
File-class-id	S	N	N
Filtering-value	S	N	N
ICC-profile	S	N	N
IIP-opt-comm	S	S	S
IIP-opt-obj	S	S	S
IIP-server	S	S	S
IIP-socket	S	N	N
IIP	S	P	P
Keywords	S	U	N
Last-author	S	U	N
Last-printed	S	U	N
Last-save-dtm	S	U	N
Max-size	S	S	S
Property	S	N	N
Render-path	S	N	N
Resolution-number	S	S	S
Rev-number	S	U	N
ROI	S	N	N
Security	S	N	N
Stream	S	N	N
Subject	S	U	P
Summary-info	S	U	P
Title	S	U	N
View-info	S	N	N
Horizontal-views	N	S	U
Tile-size	N	S	S
Vertical-views	N	S	U
Wlz-3d-bounding-box	N	N	S
Wlz-coordinate-3D	N	N	S
Wlz-distance-range	N	N	S
Wlz-foreground-objects	N	N	S
Wlz-grey-stats	N	N	S
Wlz-grey-value	N	N	S
Wlz-n-components	N	N	S
Wlz-sectioning-angles	N	N	S
Wlz-transformed-3d-bounding-box	N	N	S
Wlz-transformed-coordinate-3d	N	N	S
Wlz-true-voxel-size	N	N	S
Wlz-volume	N	N	S

Table 5: Command and object request support by IIP protocol, iipsrv0.9.7 and WlzIIPSrv. S: supported; N: not supported; P: partially supported; U:

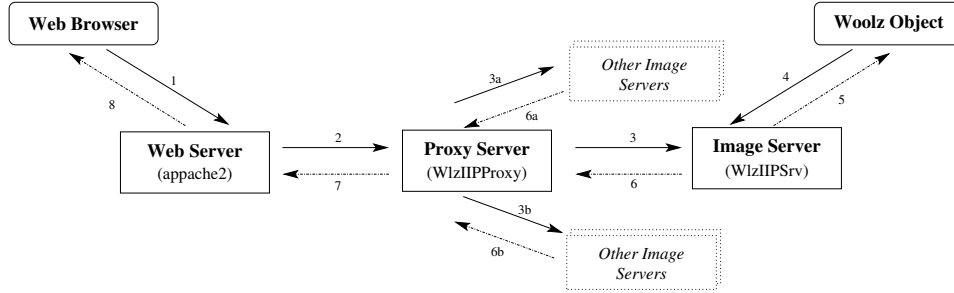


Figure 3: Architecture of Woolz IIP Server using a proxy server. The proxy forwards the user web requests served first by apache to the individual IIP Servers that have direct access to the Woolz Object. The numbered lines show the ordering of the requests (continuous line) and the replies (dotted lines).

to work for IIP and Woolz requests, it is generic and can be applied to any FCGI request. Therefore, it is possible to chain multiple proxies.

The WlzIIPProxy is an independent program running on the proxy server. Apache2 server forwards the FCGI request to this sever, on a configurable port. WlzIIPSrv check the html request string (the FCGI\_PARAMS packet QUERY\_STRING parameter) and if any remote FCGI server definition string is a substring of the request then request is forwarded to this server. If there is no hit then the request is forwarded to the first FCGI remote server. The default setup of the WlzIIPProxy architecture is shown in figure3

## 5.1 WlzIIPProxy options

Usage:

```
WlzIIPProxy [-p<portnumber>] [-c<conf_filename>] [-l<log_filename>] [-v<loglevel>] [-
```

where the options are:

- -p Port number. Default value: 123777
- -c Configuration file containing WLZ name to server name mapping. Default value: WlzIIPProxy.conf
- -l Log file name. -v with a value greater than 0 must be used. Default value: /tmp/WlzIIPProxy.log

- -v Log level. Default value: 0
- -h Help, prints usage message.

The log level is 0 to 3 with

- 0 – no log,
- 1 – system startup, shutdown, error messages,
- 2 – as fcgi connection messages,
- 3 – as level 2 and received/sent packet types.

The configuration file has three columns for:

1. search string,
2. server name (or ip),
3. port number.

## 6 WlzIIPsrv installation

### 6.1 Install FastCGI

Download and install FastCGI [[LIB](#)]. WlzIIPsrv was tested with fcgi-2.4.0 only.

### 6.2 Source code

Obtain the source files from github:

<https://github.com/ma-tech/WlzIIPsrv>

The following packages are also required:

<https://github.com/ma-tech/External>

<https://github.com/ma-tech/Woolz>

### 6.3 Compiling

Having already built the required external libraries including the Woolz libraries; within the WlzIIPsrv root directory edit and execute the build script:

```
cp build.sh mybuild.sh
vi mybuild.sh
./mybuild.sh
```

The build script can be edited, but most often this will only need to be done to change the install prefix. The Woolz libraries should be build with external file format support enabled.

For doxygen documentation run `make doc`. The documentation is generated into the `Docs` directory.

Installing implies moving the `src/wlziipsrv.fcgi` into the server's fcgi directory:

```
cp src/wlziipsrv.fcgi /opt/apache/fcgi-bin/
```

Do not forget to set read and execute access modes!

### 6.4 Customisable parameters

In addition to the IIPsrv [Pillay and Pitzalis, p.25] configuration parameters, WlzIIPsrv allows with the parameters from Table 6 changing the default cache and tile sizes.

Parameter	Description	Default value
MAX_WLZOBJ_CACHE_SIZE	Maximum Woolz object cache size in MBs	1024
MAX_WLZOBJ_CACHE_COUNT	Maximum number of Woolz object in cache	100
WLZ_TILE_WIDTH	Tile width in pixels	100
WLZ_TILE_HEIGHT	Tile height in pixels	100

Table 6: WlzIIPsrv extra configuration parameters

The example configuration from appendix A defines a view structure cache with 200 structures, a 1500MB Woolz object cache and  $100 \times 100$  tile size.

## 7 WlzIIPProxy installation

- Download and compile / install FastCGI [\[LIB\]](#).
- Get WlzIIPProxy source code from the CVS repository:

```
cvs checkout -P src/Applications/WlzIIPProxy
```

- Configure and compile WlzIIPProxy: Run from the WlzIIPsrv root directory

```
aclocal; autoheader; automake; autoconf; ./configure; make
```

- Run WlzIIPProxy on the desired port and using the configuration file.

```
WlzIIPProxy -p <portnumber> -c <config_file>
```

- Configure apache2 on the web server:
  1. install mod\_fastcgi (you might need to reinstall apache2) **Note:** the mod\_fcgi module, provided in SUSE 10.3 can not make remote FCGI request therefore is not compatible with WlzIIPsrv. mod\_fastcgi must be used.
  2. add to httpd.conf (/opt/apache/conf/httpd.conf):

```
FastCgiExternalServer <virtual_path_to_fcgi> -host <hostname>:<portnumber>
```

## 8 Acknowledgement

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## A fcgi configuration

An example of the apache2 configuration (/opt/apache/conf/httpd.conf) is<sup>1</sup>

---

<sup>1</sup>This configuration file is compatible with mod\_fcgi. For mod\_fastcgi alternative format must be used (see IIPsrv web-page).

```

# Create a directory for the iipsrv binary
ScriptAlias /fcgi-bin/ "/opt/apache/fcgi-bin/"

# Set the options on that directory
<Directory "/opt/apache/fcgi-bin">
    AllowOverride None
    Options None
    Order allow,deny
    Allow from all
    # Set the module handler
    AddHandler fcgid-script .fcgi
</Directory>

# Initialise the FCGI server and set some default values
FastCgiServer /opt/apache/fcgi-bin/wlziipsrv.fcgi \
-initial-env LOGFILE=/opt/apache/logs/wlziipsrv.log \
-initial-env LOGLEVEL=WARN \
-initial-env JPEG_QUALITY=50 \
-initial-env MAX_CVT=3000 \
-initial-env MAX_IMAGE_CACHE_SIZE=1000 \
-initial-env MAX_WLZOBJ_CACHE_COUNT=100 \
-initial-env WLZ_TILE_WIDTH="100" \
-initial-env WLZ_TILE_HEIGHT="100"

```

## References

- [EMA] The e-mouse atlas project.
- [LIB] Fastcgi api (libfcgi).
- [WOO] Woolz image processing system.
- [4] I3A (1997). Internet imaging protocol.
- [Pillay and Pitzalis] Pillay, R. and Pitzalis, D. IIPsRv.