

Channel Controller Definition Of ST16				
Mode Type	Channel NO.	Physical Key	Value Range	Channel Definition
Single Mode(Master)	Thr(Ch1)	J1	000%~100%	油门调节 Min:683 Max:3414
	Ail(Ch2)	J4	-100%~100%	副翼调节 Min:683 Max:3414
	Ele(Ch3)	J3	-100%~100%	升降舵调节 Min:683 Max:3414
	Rud(Ch4)	J2	-080%~079%	方向舵调节 Min:956 Max:3126
	A01(Ch5)	S4	000%~100%	飞行模式切换 Angle:2048 Smart:3414
	A02(Ch6)		000%~150%	飞行模式切换 Angle:2048 Home:4095
	A03(Ch7)	K2	-100%~100%	相机俯仰调节 Min:683 Max:3414
	A04(Ch8)	K1	-100%~100%	相机水平调节 Min:683 Max:3414
	A05(Ch9)	S1	010%~100%	Pitch Mode Angle 及中间键:2184 Velocity:3414
	A06(Ch10)	S2	-100%~100%	Yaw Mode Follow:683 Follow(Control):1502 Global:3414
Team Mode(Slave)	A05(Ch9)	S1	010%~100%	Pitch Mode Angle 及中间键:010% Velocity:100%
	A02(Ch6)、A03(Ch7)	K2、J3	-100%~100%	Pitch Mode Angle:K2 相机俯仰调节 Velocity:J3 相机俯仰调节
	A06(Ch10)	S2、J4	-100%~100%	Yaw Mode Follow:-100% Follow(Control):-45% Global:100%
	A04(Ch8)			Yaw Mode Follow(Control)/Global:J4 相机水平调节
Single Mode(Master)	A07(Ch11)	S5	-100%~100%	收放起落架键 Up:-100% Down:100%
Team Mode(Slave)	A08(Ch12)	B2	-100%~100%	Aux 开关设置 On:-100% Off: 100%
<b>Notes:</b> 1. 鱼兔按钮可能会造成通道值叠加, 请以兔子最大值验证实际通道值范围。  2. J1/J2/J3/J4 默认使用 Mode Select 中 MODE 2, MODE 1/MODE 2/MODE 3/MODE 4 下通道对应关系如下:  MODE 1: Thr(Ch1)→J3 Ail(Ch2) →J4 Ele(Ch3) →J1 Rud(Ch4) →J2  MODE 2: Thr(Ch1)→J1 Ail(Ch2) →J4 Ele(Ch3) →J3 Rud(Ch4) →J2  MODE 3: Thr(Ch1)→J3 Ail(Ch2) →J2 Ele(Ch3) →J1 Rud(Ch4) →J4  MODE 4: Thr(Ch1)→J1 Ail(Ch2) →J2 Ele(Ch3) →J3 Rud(Ch4) →J4				
Pulsed Value Definition Of Ch10				
Ch10 Button	Ch10 Value	Ch10 Definition		
Default	2048	Ch10 默认值		
SETTING CALIBRATION→GPS	4	关闭飞机 GPS 开关		
	8	打开飞机 GPS 开关		
SETTING CALIBRATION→ CALLIBRATION→COMPASS	12	执行飞机 Compass 校准		
SETTING CALIBRATION→ CALLIBRATION→ACCELEROMETER	16	执行飞机 Accelerometer 校准		
SETTING CALIBRATION→ CALLIBRATION→GIMBAL	24	执行飞机 Gimbal 校准		
Follow/Watch Me	28	禁用 Follow Me 状态		
Follow/Watch Me	32	启用 Follow Me 状态, 但相机镜头没有跟踪		
Follow/Watch Me	36	启用 Follow Me 状态, 且相机镜头进行跟踪(Watch Me)		
OBS.AVOID	40	打开飞机 OBS 开关		
OBS.AVOID	44	关闭飞机 OBS 开关		

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**Release Notes:**

1. Simply Pitch and Yaw Mode modules description information;
2. Add MODE1/MODE2/MODE3/MODE4 complementary description notes;