What I've done:

Even though the vision system is not an important component for the first milestone, it will play a very important role in the overall robot performance. Together with An and Georgi K., I've investigated solutions from previous years. After choosing to use group 4 from last year I've helped to debug the solutions and actually get it to work. On a side note I also set up the group's main code repo and the group's code management tool – Trello.

Highlights:
- Set up code repository for the group on GitHub, set up repo for virtualen environment files, suggested and set up a Trello Board as our main project management tool;
- Helped Georgi K to set up the virtualenv for python, so we can use Python 2.7, which will give us a small performance benefit;
- Worked on the vision system in terms of analyzing and getting the chosen solution to work. After a small investigation we got it to work with 20+.

Future work:

I will continue working on the vision system until we get it ready and implement a socket server for it.
Maybe when we are completely happy with the vision system, if everyone else is happy I could try and help with the C++ AI/Strategy modules.