Tampere University

LED matrix block diagram

COMP.CE.100 Introduction to Embedded Systems

LED MATRIX BLOCK DIAGRAM

setup()

Initialize:

Set addresses 0x41220008 and 0x41220000 to 0.

Toggle RSTn bit (wait 500 μs in between sets):

Set bit0 **at address** 0x41220008 **to** 0.

Set bit0 **at address** 0x41220008 **to** 1.

Set SDA bit:

Set bit4 **at address** 0x41220008 **to** 1.

Set 6-bit values in a loop (more

info on next page):

Set bit3 at address

0x41220008 to 0 .

Set bit3 **at address** 0x41220008 **to** 1

Rising edge of SCK

Set SB bit:

Set bit2 **at address** 0x41220008 **to** 1.

SetPixel()

Set colors to dots array:

Blue is already set in the exercise template.

Set green to first element of dots array.

Set red to second element of dots array.

latch()

Toggle LAT bit:

Set bit1 at address 0x41220008 to 1. Set bit1 at address 0x41220008 to 0. LAT goes H->L.

run()

open_line()

Open channels:

Set bit[7:0] in address 0x41220000 to 1, one bit at a time.

Hint: Use switch-case.

Put new data to LED matrix in nested loops.

(more info on next page) Ensure that $\mathtt{LAT} = 0$ at first. Set SDA HIGH.

Use rising edge of SCK in the loop.

latch() the data at the end.

REMEMBER: bit order

..., bit3, bit2, bit1, bit0
Also, dots[0] is the zeroth element.

setup():

- This function will make the necessary initializations to setup the LED matrix for further use.
- Address 0×41220008 is for control signals and address 0×41220000 is for channels. We need to first initialize them by setting them to zero.
- After initializing the addresses, the LED matrix should be reset. This is done by toggling the RSTn bit from LOW to HIGH because it is active when low. We can operate with the matrix after the screen has been reset and it is not ON anymore.
- SDA bit should be set to 1 to be able to send serial data.
- Next 6-bit values should be set in the register of the DM163 chip. All bits in the register should be set to 1 because the values in the 6-bit register will be multiplied with an 8-bit register. 24 (3*8, for R, G and B) "bytes" should be transferred, so in total 24*6 bits should be sent in a loop structure.
- When sending the data, use the rising clock edge.
- Finally, the SB bit should be set to 1 to transfer the data to the serial bank.
- For setting the bits, see for example COMP.CE.100_exercise_guide.pdf, pages 16, 19-20.

SetPixel():

- In this function the color and location of the pixels in LED matrix is set in the dots array.
- The blue color is already set in the example. Green and red colors should be set (in this order) to the matrix as well.

latch():

- We need to toggle the latch bit from HIGH to LOW to store the pixel data values to the register bank.
- Latch bit is bit1 of control signals.

run():

- Here we need to write the pixel data to the LED matrix driver.
- 3 nested loops are needed:
- Before loops, latch should be 0 (see latch ())
- ----the outermost loop should loop through pixels.
- -----The next loop should loop for colors (in order B, G, R) and
- -----the innermost loop should loop through the actual color data.
- In the innermost loop SDA should be set to 1 if there is still data to be sent. SDA bit is the bit4 of the control signal address.
- Else, SDA should be set to 0.
- Finally, SCK should be toggled from 0 to 1 and the dots array should be shifted left by 1. SCK is the bit3 of the control signal address.

open_line():

- We need to set the corresponding channel bit to 1 at the channel address to open the columns and show the pixel data on the matrix.
- To do this, a switch-case statement can be used. The cases should be channel numbers from 0 to 7 and the channel bits should be set to 1 accordingly: channel number is the bit position, so channel 0 is bit0, etc.
- The default case should close all channels, so channels should be set to 0.

INTERRUPT HANDLERS

BUTTON/SWITCH INTERRUPT

ButtonHandler()

Check Status variable for button presses and switch toggles:

Buttons are bit [3:0].

Switches are bit [5:4].

Hint: Use if-statement.

REMEMBER: bit order

..., bit3, bit2, bit1, bit0

TIMER INTERRUPTS

TickHandler()

Refresh the LED matrix screen:

The channels should be turned ON individually.

Check if channels are inside the screen.

Close all channels.

Call run() and open_line() on channel.

Increment channel.

TickHandler1()

Handle alien and shooting:

Call functions for alien movement and shooting here, according to your game logic.

Interrupt basics:

- Do not have to wait for button presses etc. in a loop (this is called *polling*).
- Instead, the normal program execution will be stopped and the execution time is given to interrupt handlers.
- After the interrupt, the normal program execution will continue from the point where it was before calling the interrupt.
- Some info is available in the exercise guide COMP.CE.100_exercise_guide.pdf, page 11 and in the Project work extra material PDF.
- More information will be given in the course EE.ELE.250 Microcontrollers (5 cr).

TickHandler():

- This function is the timer interrupt handler for the LED matrix screen. The refresh rate is 800 Hz.
- This makes it look like there are many LEDs on at the same time, although they are ON individually and just updated very fast.
- To update the matrix, it should be first checked that the channel is not greater than 7 (over the screen). If it is, zero it.
- Next, all channels should be closed with the default case of open line().
- After this, the current channel should be run and opened, and the channel should be incremented.

TickHandler1():

- This function is the timer interrupt for the gameplay, i.e. moving the alien, shooting with the gun etc. The refresh rate is 10 Hz by default.
- The refresh rate can be changed by calling <code>change_freq()</code> function inside <code>ButtonHandler()</code>. It can be assigned to <code>SW1</code>, for example.
- It would be good to implement the gameplay functions in Pixel.c or your own custom file and call them in this timer interrupt function.

ButtonHandler():

- This function is the button/switch interrupt for the gameplay controls, i.e. moving the alien, shooting with the gun etc. The frequency is 10 Hz by default.
- Use Status parameter to check which button caused the interrupt.
- BTNO is bit0, BTN1 is bit1, BTN2 is bit2, BTN3 is bit3, SWO is bit4, SW1 is bit5
- Bank information is not needed.
- Call ship movement functions accordingly.
- The frequency can be changed with <code>change_freq()</code> function. It can be assigned to <code>SW1</code>, for example.