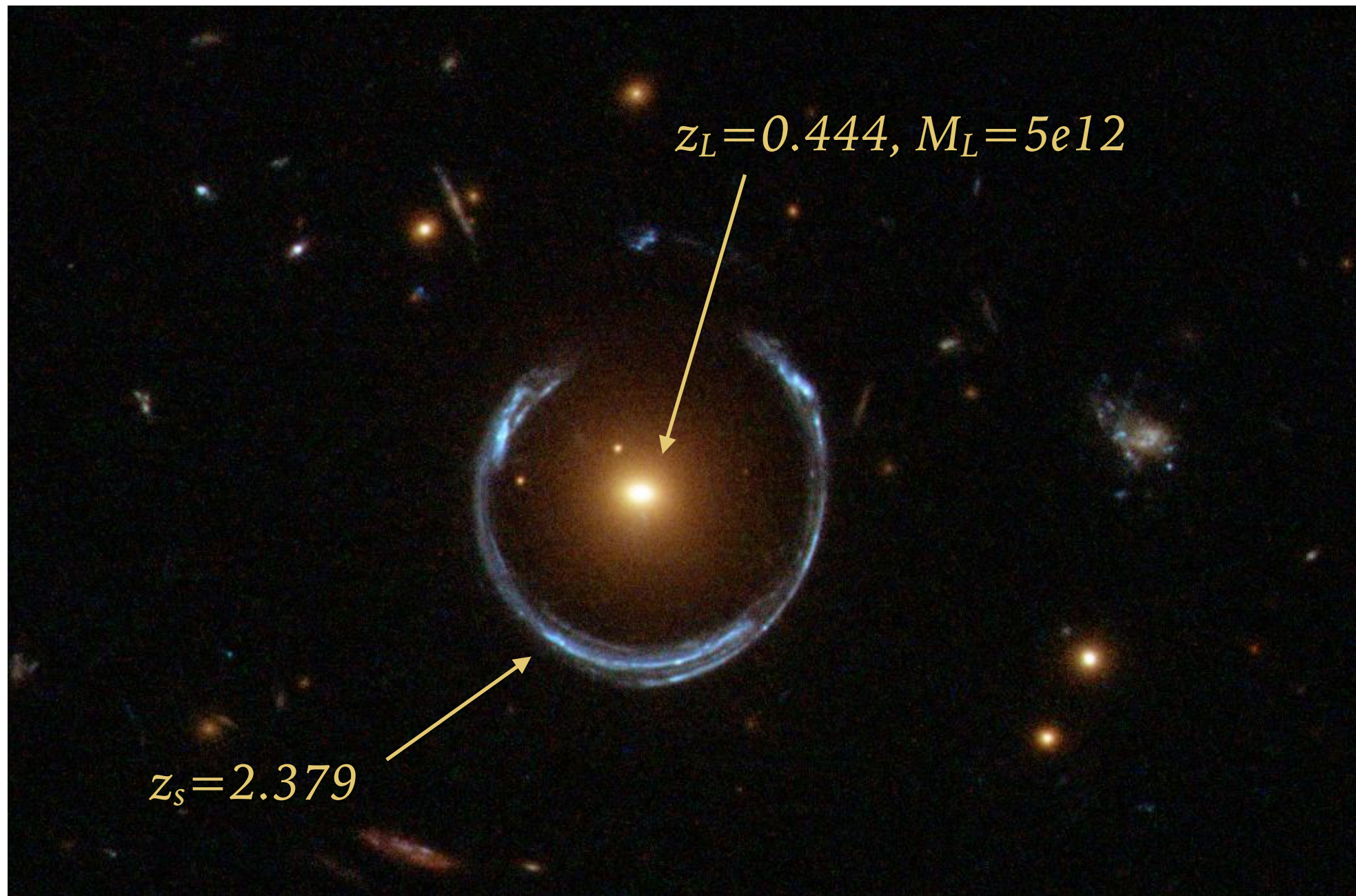


GRAVITATIONAL LENSING

18 – AXIALLY SYMMETRIC LENSES

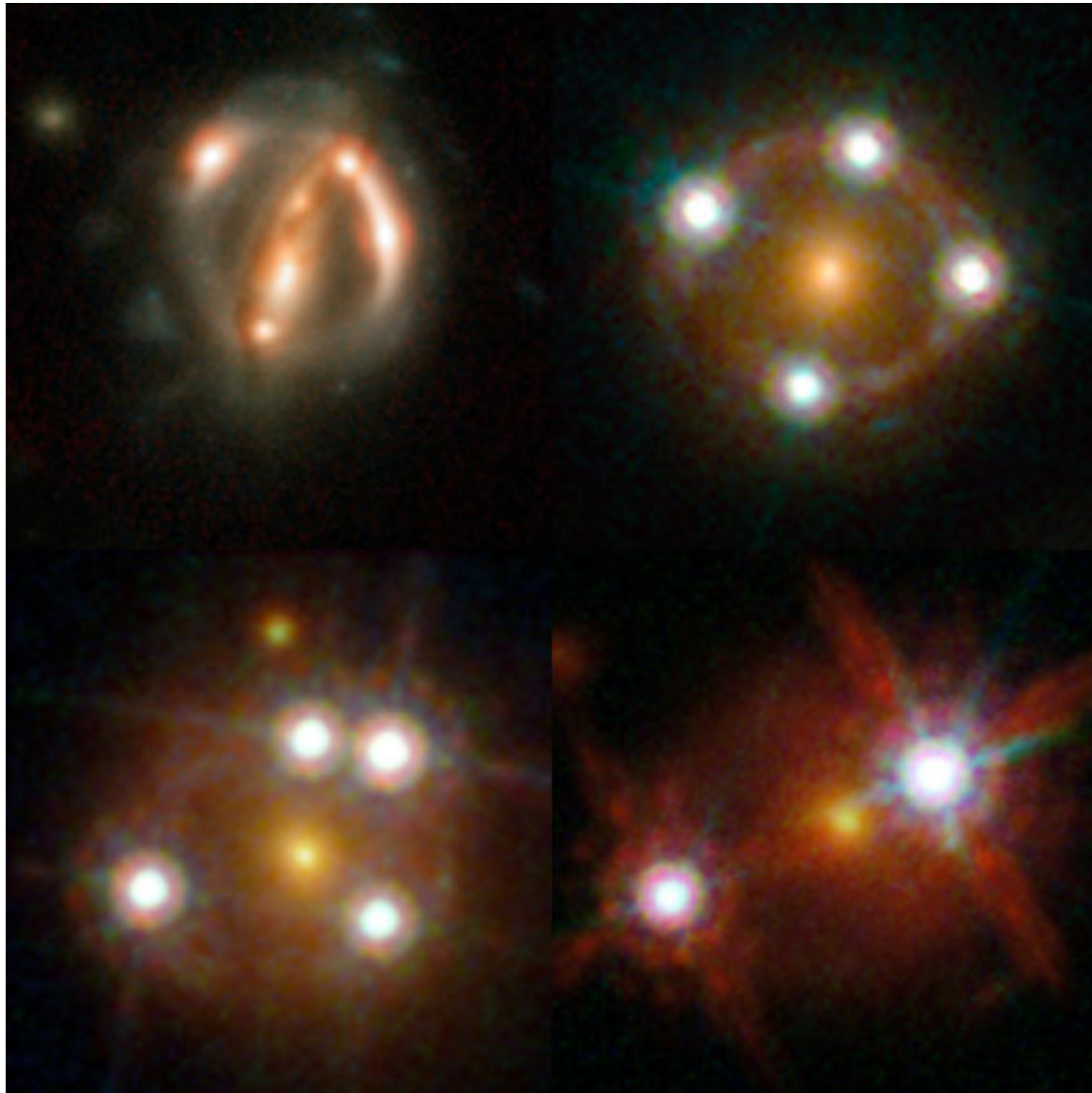
Massimo Meneghetti
AA 2017-2018

EXTENDED LENSES

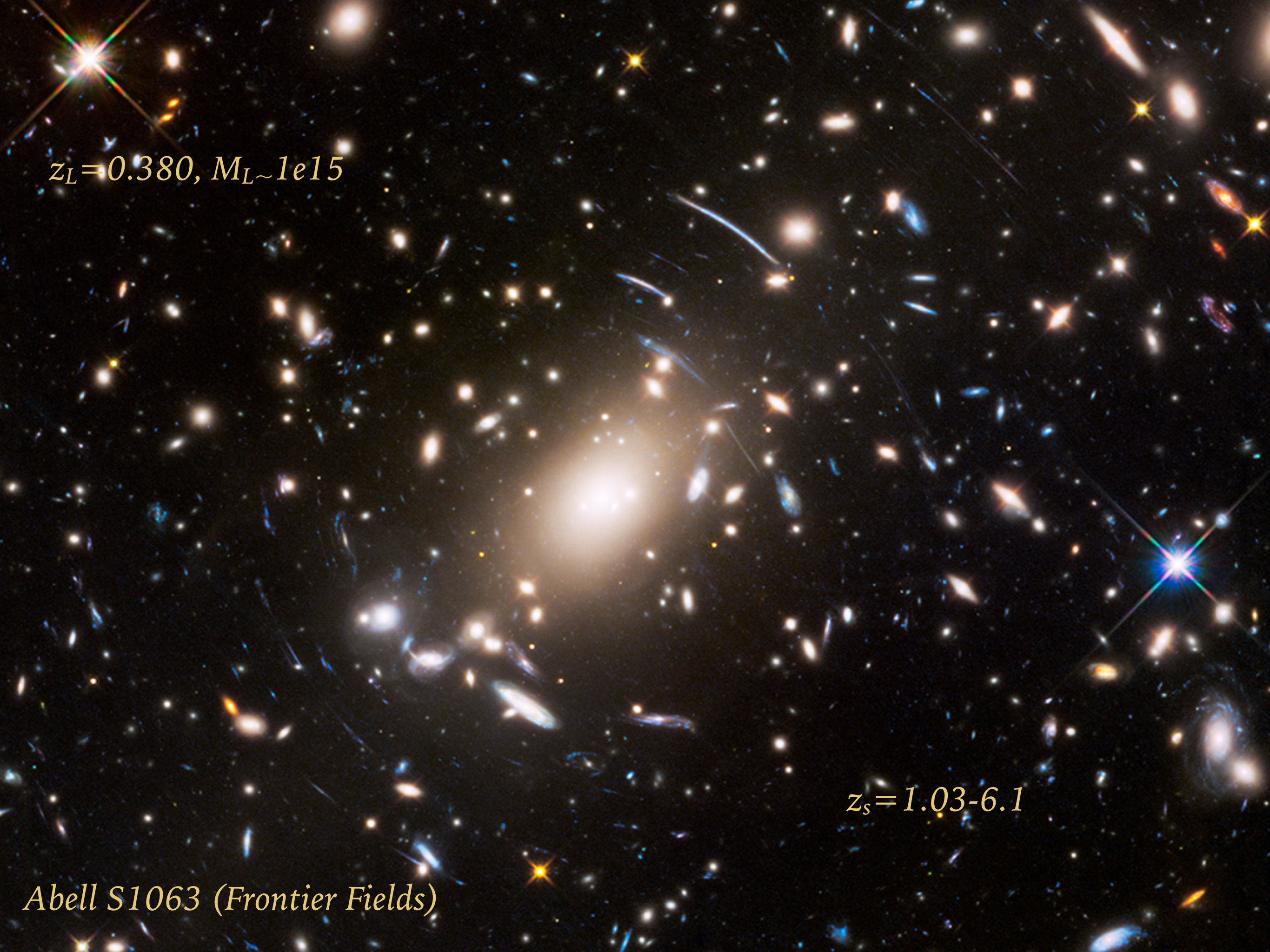


Cosmic horseshoe (Belokurov et al. 2007)

EXTENDED LENSES



Suyu et al. (H0LiCOW team)



$z_L=0.380, M_L\sim 1e15$

$z_s=1.03-6.1$

Abell S1063 (Frontier Fields)

EXTENDED LENSES

- Cosmic structures like galaxies and galaxy clusters are characterized by bound mass distributions, which cannot be approximated by point lenses
- Indeed these are *extended lenses*, and their lensing properties are determined by e.g. their surface mass density:

$$\Sigma(\vec{\xi}) = \int \rho(\vec{\xi}, z) \, dz$$

$$\vec{\alpha}(\vec{\xi}) = \frac{4G}{c^2} \int \frac{(\vec{\xi} - \vec{\xi}') \Sigma(\vec{\xi}')}{|\vec{\xi} - \vec{\xi}'|^2} \, d^2\xi'$$

EXTENDED LENSES

- Recall that the surface density is related to the lensing potential by

$$\Delta_{\theta} \Psi(\vec{\theta}) = 2\kappa(\vec{\theta})$$

$$\kappa(\vec{\theta}) \equiv \frac{\Sigma(\vec{\theta})}{\Sigma_{\text{cr}}} \quad \text{with} \quad \Sigma_{\text{cr}} = \frac{c^2}{4\pi G} \frac{D_S}{D_L D_{LS}}$$

WHAT ARE THE RELEVANT PROPERTIES OF THE LENSES?

- The surface density distribution of a lens (and its potential) can be characterized by means of
 - the profile
 - the shape of the iso-density (iso-potential) contours
 - the smoothness
 - the environment where the lens resides
- In this and in the following lessons, we will study how these features determine the ability of a mass distribution to produce lensing effects.
- We will do that by building analytical models with increasing level of complexity.

AXIALLY SYMMETRIC, CIRCULAR LENSES

- Axially symmetric, circular models are the simplest lens models for describing extended mass distributions
- For these lenses $\hat{\Psi}(\vec{\theta}) = \hat{\Psi}(\theta)$
- Several quantities relevant for lensing can be derived in a simple manner by using the symmetry properties of the lens.
- One example is the deflection angle...

DEFLECTION ANGLE OF AN AXIALLY SYMMETRIC LENS

$$\vec{\nabla}_\theta \equiv D_L \left(\frac{\partial}{\partial \xi} \vec{e}_\xi + \frac{1}{\xi} \frac{\partial}{\partial \phi} \vec{e}_\phi \right) = \left(\frac{\partial}{\partial \theta} \vec{e}_\theta + \frac{1}{\theta} \frac{\partial}{\partial \phi} \vec{e}_\phi \right)$$

$$\nabla_\theta \hat{\Psi}(\vec{\theta}) = \hat{\Psi}'(\theta) \vec{e}_\theta = \vec{\alpha}(\vec{\theta}) = \alpha(\theta) \vec{e}_\theta$$

For an axially symmetric lens, the deflection is “radial”: it depends only on the distance from the lens center.

DEFLECTION ANGLE OF AN AXIALLY SYMMETRIC LENS

$$\nabla_{\theta}^2 = \frac{1}{\theta} \frac{\partial}{\partial \theta} \left(\theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\theta^2} \frac{\partial^2}{\partial \phi^2}$$

$$\frac{1}{\theta} \frac{\partial}{\partial \theta} \left(\theta \frac{\partial}{\partial \theta} \right) \hat{\Psi}(\theta) = 2\kappa(\theta)$$

From this equation, we obtain

$$\begin{aligned} \alpha(\theta) &= \frac{2 \int_0^{\theta} \kappa(\theta') \theta' d\theta'}{\theta} \\ &= \frac{2 \int_0^{\theta} \Sigma(\theta') \theta' d\theta'}{\theta \Sigma_{\text{cr}}} \\ &= \frac{D_{\text{LS}}}{D_{\text{S}}} \frac{4GM(\theta)}{c^2 D_{\text{L}} \theta} \\ &= \frac{D_{\text{LS}}}{D_{\text{S}}} \hat{\alpha}(\theta) . \end{aligned}$$

DEFLECTION ANGLE OF AN AXIALLY SYMMETRIC LENS

$$\nabla_{\theta}^2 = \frac{1}{\theta} \frac{\partial}{\partial \theta} \left(\theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\theta^2} \frac{\partial^2}{\partial \phi^2}$$

$$\frac{1}{\theta} \frac{\partial}{\partial \theta} \left(\theta \frac{\partial}{\partial \theta} \right) \hat{\Psi}(\theta) = 2\kappa(\theta)$$

From this equation, we obtain

$$\begin{aligned} \alpha(\theta) &= \frac{2 \int_0^{\theta} \kappa(\theta') \theta' d\theta'}{\theta} \\ &= \frac{2 \int_0^{\theta} \Sigma(\theta') \theta' d\theta'}{\theta \Sigma_{\text{cr}}} \\ &= \frac{D_{\text{LS}}}{D_{\text{S}}} \frac{4GM(\theta)}{c^2 D_{\text{L}} \theta} \\ &= \frac{D_{\text{LS}}}{D_{\text{S}}} \hat{\alpha}(\theta) . \end{aligned}$$

Identical to point-mass lens!

DEFLECTION ANGLE OF AN AXIALLY SYMMETRIC LENS

Dimensionless form:

$$\begin{aligned}\alpha(x) &= \frac{D_L D_{LS}}{\xi_0 D_S} \hat{\alpha}(\xi_0 x) \\ &= \frac{D_L D_{LS}}{\xi_0 D_S} \frac{4GM(\xi_0 x)}{c^2 \xi} \frac{\pi \xi_0}{\pi \xi_0} \\ &= \frac{M(\xi_0 x)}{\pi \xi_0^2 \Sigma_{\text{cr}}} \frac{1}{x} \equiv \frac{m(x)}{x}, \quad \text{Dimensionless mass}\end{aligned}$$

$$\alpha(x) = \frac{2}{x} \int_0^x x' \kappa(x') dx' \Rightarrow m(x) = 2 \int_0^x x' \kappa(x') dx'$$

LENS EQUATION

$$\vec{y} = \vec{x} - \vec{\alpha}(\vec{x}) \qquad \vec{\alpha}(\vec{x}) = \frac{m(\vec{x})}{x^2} \vec{x}$$

Given that the deflection angle and x are parallel, so will be y !

$$y = x - \frac{m(x)}{x}$$

CONVERGENCE

$$\frac{1}{\theta} \frac{\partial}{\partial \theta} \left(\theta \frac{\partial}{\partial \theta} \right) \hat{\Psi}(\theta) = 2\kappa(\theta)$$



$$\kappa(\theta) = \frac{1}{2} \left(\hat{\Psi}''(\theta) + \frac{\hat{\Psi}'(\theta)}{\theta} \right)$$



$$\hat{\Psi}'(\theta) = \alpha(\theta)$$

$$\kappa(\theta) = \frac{1}{2} \left(\alpha'(\theta) + \frac{\alpha(\theta)}{\theta} \right)$$



$$\alpha'(x) = \frac{m'(x)}{x} - \frac{m(x)}{x^2}$$

$$\kappa(x) = \frac{1}{2} \frac{m'(x)}{x}$$

SHEAR

The shear components are derived from the second derivatives of the potential or from the first derivatives of the deflection angle components:

$$\frac{\partial}{\partial \theta_1} = \cos \phi \frac{\partial}{\partial \theta} - \frac{\sin \phi}{\theta} \frac{\partial}{\partial \phi}$$

$$\frac{\partial}{\partial \theta_2} = \sin \phi \frac{\partial}{\partial \theta} + \frac{\cos \phi}{\theta} \frac{\partial}{\partial \phi}$$

$$\alpha_1 = \alpha \cos \phi$$

$$\alpha_2 = \alpha \sin \phi$$

SHEAR

$$\frac{\partial}{\partial \theta_1} = \cos \phi \frac{\partial}{\partial \theta} - \frac{\sin \phi}{\theta} \frac{\partial}{\partial \phi}$$

$$\alpha_1 = \alpha \cos \phi$$

$$\frac{\partial}{\partial \theta_2} = \sin \phi \frac{\partial}{\partial \theta} + \frac{\cos \phi}{\theta} \frac{\partial}{\partial \phi}$$

$$\alpha_2 = \alpha \sin \phi$$

$$\begin{aligned} \gamma_1(\theta) &= \frac{1}{2} \left[\frac{\partial}{\partial \theta_1} \alpha_1(\theta) - \frac{\partial}{\partial \theta_2} \alpha_2(\theta) \right] \\ &= \frac{1}{2} \left[(\cos^2 \phi - \sin^2 \phi) \alpha'(\theta) - (\cos^2 \phi - \sin^2 \phi) \frac{\alpha(\theta)}{\theta} \right] \\ &= \frac{\cos 2\phi}{2} \left[\alpha'(\theta) - \frac{\alpha(\theta)}{\theta} \right], \end{aligned}$$

SHEAR

$$\frac{\partial}{\partial \theta_1} = \cos \phi \frac{\partial}{\partial \theta} - \frac{\sin \phi}{\theta} \frac{\partial}{\partial \phi}$$

$$\alpha_1 = \alpha \cos \phi$$

$$\frac{\partial}{\partial \theta_2} = \sin \phi \frac{\partial}{\partial \theta} + \frac{\cos \phi}{\theta} \frac{\partial}{\partial \phi}$$

$$\alpha_2 = \alpha \sin \phi$$

$$\begin{aligned} \gamma_2(\theta) &= \frac{\partial}{\partial \theta_2} \alpha_1(\theta) \\ &= \left[\sin \phi \cos \phi \alpha'(\theta) - \sin \phi \cos \phi \frac{\alpha(\theta)}{\theta} \right] \\ &= \frac{\sin 2\phi}{2} \left[\alpha'(\theta) - \frac{\alpha(\theta)}{\theta} \right] . \end{aligned}$$

SHEAR

$$\begin{aligned}\gamma_1(\theta) &= \frac{1}{2} \left[\frac{\partial}{\partial \theta_1} \alpha_1(\theta) - \frac{\partial}{\partial \theta_2} \alpha_2(\theta) \right] \\ &= \frac{1}{2} \left[(\cos^2 \phi - \sin^2 \phi) \alpha'(\theta) - (\cos^2 \phi - \sin^2 \phi) \frac{\alpha(\theta)}{\theta} \right] \\ &= \frac{\cos 2\phi}{2} \left[\alpha'(\theta) - \frac{\alpha(\theta)}{\theta} \right],\end{aligned}$$

$$\begin{aligned}\gamma_2(\theta) &= \frac{\partial}{\partial \theta_2} \alpha_1(\theta) \\ &= \left[\sin \phi \cos \phi \alpha'(\theta) - \sin \phi \cos \phi \frac{\alpha(\theta)}{\theta} \right] \\ &= \frac{\sin 2\phi}{2} \left[\alpha'(\theta) - \frac{\alpha(\theta)}{\theta} \right].\end{aligned}$$

$$\begin{aligned}\alpha(x) &= \frac{D_L D_{LS}}{\xi_0 D_S} \hat{\alpha}(\xi_0 x) \\ &= \frac{D_L D_{LS}}{\xi_0 D_S} \frac{4GM(\xi_0 x)}{c^2 \xi} \frac{\pi \xi_0}{\pi \xi_0} \\ &= \frac{M(\xi_0 x)}{\pi \xi_0^2 \Sigma_{\text{cr}}} \frac{1}{x} \equiv \frac{m(x)}{x},\end{aligned}$$

$$\alpha'(x) = \frac{m'(x)}{x} - \frac{m(x)}{x^2}$$

$$\begin{aligned}\gamma(x) &= \frac{1}{2} \left| \frac{m'(x)}{x} - \frac{2m(x)}{x^2} \right| \\ &= |\kappa(x) - \overline{\kappa}(x)|,\end{aligned}$$

$$\overline{\kappa}(x) = \frac{m(x)}{x^2} = 2\pi \frac{\int_0^x x' \kappa(x') dx'}{\pi x^2}$$

LENSING JACOBIAN

$$A = \left[1 - \frac{m'(x)}{2x} \right] I - \frac{1}{2} \left[\frac{m'(x)}{x} - \frac{2m(x)}{x^2} \right] \begin{pmatrix} \cos 2\phi & \sin 2\phi \\ \sin 2\phi & -\cos 2\phi \end{pmatrix}$$



$$A = I + \frac{m}{x^2} C(\phi) - \frac{m'(x)}{2x} [I + C(\phi)]$$

$$\begin{aligned} C(\phi) &= \begin{pmatrix} \cos 2\phi & \sin 2\phi \\ \sin 2\phi & -\cos 2\phi \end{pmatrix} \\ &= \begin{pmatrix} \cos^2 \phi - \sin^2 \phi & 2 \sin \phi \cos \phi \\ 2 \sin \phi \cos \phi & \sin^2 \phi - \cos^2 \phi \end{pmatrix} \end{aligned}$$

$$\begin{aligned} I + C(\phi) &= \begin{pmatrix} 1 + \cos 2\phi & \sin 2\phi \\ \sin 2\phi & 1 - \cos 2\phi \end{pmatrix} \\ &= 2 \begin{pmatrix} \cos^2 \phi & \sin \phi \cos \phi \\ \sin \phi \cos \phi & \sin^2 \phi \end{pmatrix} \end{aligned}$$

LENSING JACOBIAN

$$A = I + \frac{m}{x^2} C(\phi) - \frac{m'(x)}{2x} [I + C(\phi)]$$

$$\begin{aligned} C(\phi) &= \begin{pmatrix} \cos 2\phi & \sin 2\phi \\ \sin 2\phi & -\cos 2\phi \end{pmatrix} & I + C(\phi) &= \begin{pmatrix} 1 + \cos 2\phi & \sin 2\phi \\ \sin 2\phi & 1 - \cos 2\phi \end{pmatrix} \\ &= \begin{pmatrix} \cos^2 \phi - \sin^2 \phi & 2 \sin \phi \cos \phi \\ 2 \sin \phi \cos \phi & \sin^2 \phi - \cos^2 \phi \end{pmatrix} & &= 2 \begin{pmatrix} \cos^2 \phi & \sin \phi \cos \phi \\ \sin \phi \cos \phi & \sin^2 \phi \end{pmatrix} \end{aligned}$$



$$\begin{aligned} A &= I + \frac{m(x)}{x^2} \begin{pmatrix} \cos^2 \phi - \sin^2 \phi & 2 \sin \phi \cos \phi \\ 2 \sin \phi \cos \phi & \sin^2 \phi - \cos^2 \phi \end{pmatrix} - \\ &\quad \frac{m'(x)}{x} \begin{pmatrix} \cos^2 \phi & \sin \phi \cos \phi \\ \sin \phi \cos \phi & \sin^2 \phi \end{pmatrix}. \end{aligned}$$

LENSING JACOBIAN (CARTESIAN COORDINATES)

$$A = I + \frac{m(x)}{x^2} \begin{pmatrix} \cos^2 \phi - \sin^2 \phi & 2 \sin \phi \cos \phi \\ 2 \sin \phi \cos \phi & \sin^2 \phi - \cos^2 \phi \end{pmatrix} - \frac{m'(x)}{x} \begin{pmatrix} \cos^2 \phi & \sin \phi \cos \phi \\ \sin \phi \cos \phi & \sin^2 \phi \end{pmatrix}.$$

$$(x_1, x_2) = (x \cos \phi, x \sin \phi).$$

$$A = I + \frac{m(x)}{x^4} \begin{pmatrix} x_1^2 - x_2^2 & 2x_1x_2 \\ 2x_1x_2 & x_2^2 - x_1^2 \end{pmatrix} - \frac{m'(x)}{x^3} \begin{pmatrix} x_1^2 & x_1x_2 \\ x_1x_2 & x_2^2 \end{pmatrix}.$$

DETERMINANT OF THE LENSING JACOBIN

$$y = x - \frac{m(x)}{x}$$

$$\begin{aligned}\det A &= \frac{y}{x} \frac{dy}{dx} = \left[1 - \frac{\alpha(x)}{x} \right] [1 - \alpha'(x)] \\ &= \left[1 - \frac{m(x)}{x^2} \right] \left[1 + \frac{m(x)}{x^2} - \frac{m'(x)}{x} \right] \\ &= [1 - \bar{\kappa}(x)] [1 + \bar{\kappa}(x) - 2\kappa(x)] .\end{aligned}$$

CRITICAL LINES

$$\begin{aligned}\det A &= \frac{y}{x} \frac{dy}{dx} = \left[1 - \frac{\alpha(x)}{x} \right] [1 - \alpha'(x)] \\ &= \left[1 - \frac{m(x)}{x^2} \right] \left[1 + \frac{m(x)}{x^2} - \frac{m'(x)}{x} \right] \\ &= [1 - \bar{\kappa}(x)] [1 + \bar{\kappa}(x) - 2\kappa(x)] .\end{aligned}$$

First critical line:

$$\alpha(x)/x = m(x)/x^2 = \bar{\kappa}(x) = 1$$

Second critical line:

$$\alpha'(x) = m'(x)/x - m/x^2 = 2\kappa(x) - \bar{\kappa}(x) = 1 .$$

CRITICAL LINES

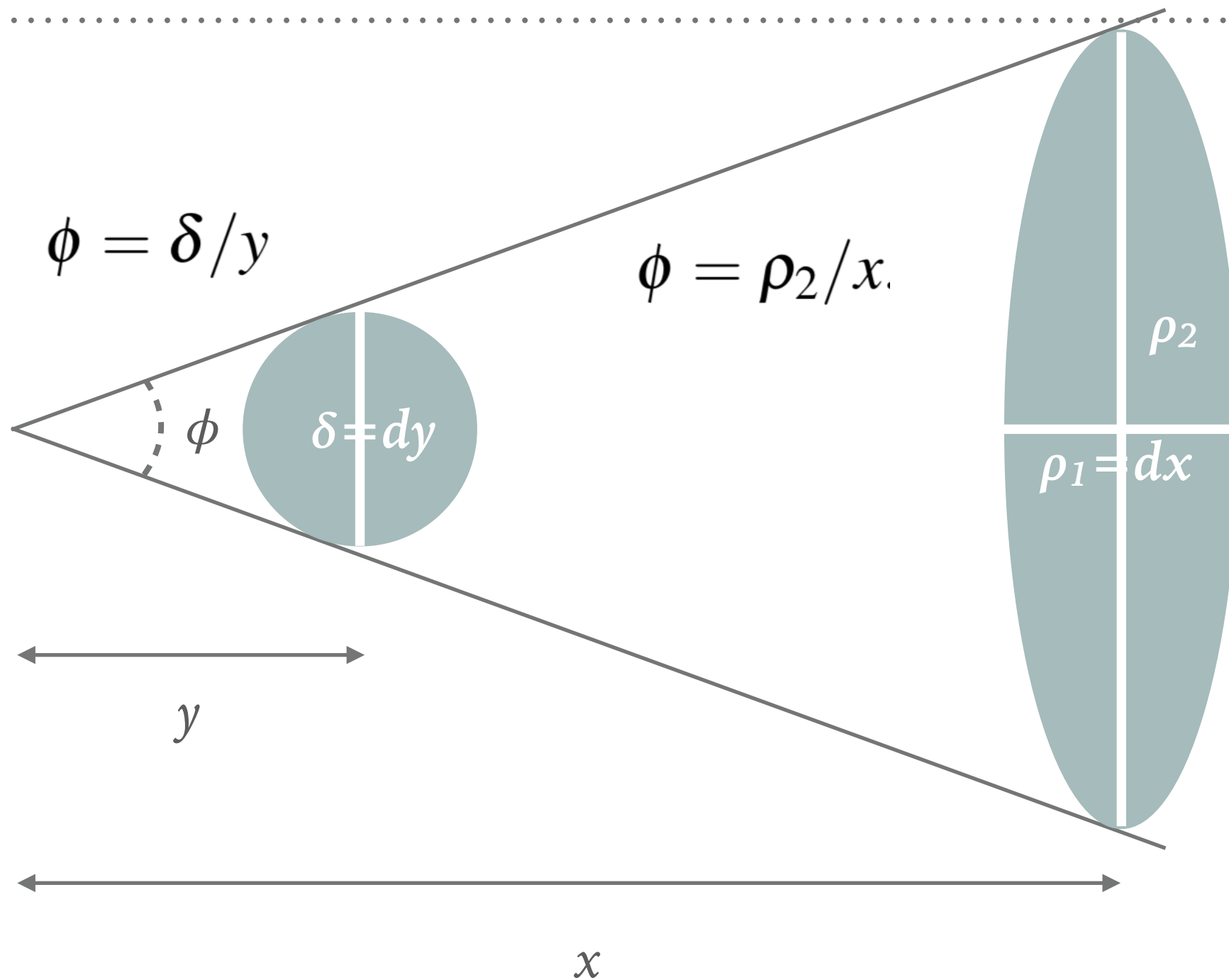
The tangential critical line occurs where $\alpha(x)/x = m(x)/x^2 = \overline{\kappa}(x) = 1$

$$\kappa(\vec{\theta}) \equiv \frac{\Sigma(\vec{\theta})}{\Sigma_{\text{cr}}} \quad \text{with} \quad \Sigma_{\text{cr}} = \frac{c^2}{4\pi G} \frac{D_{\text{S}}}{D_{\text{L}} D_{\text{LS}}}$$

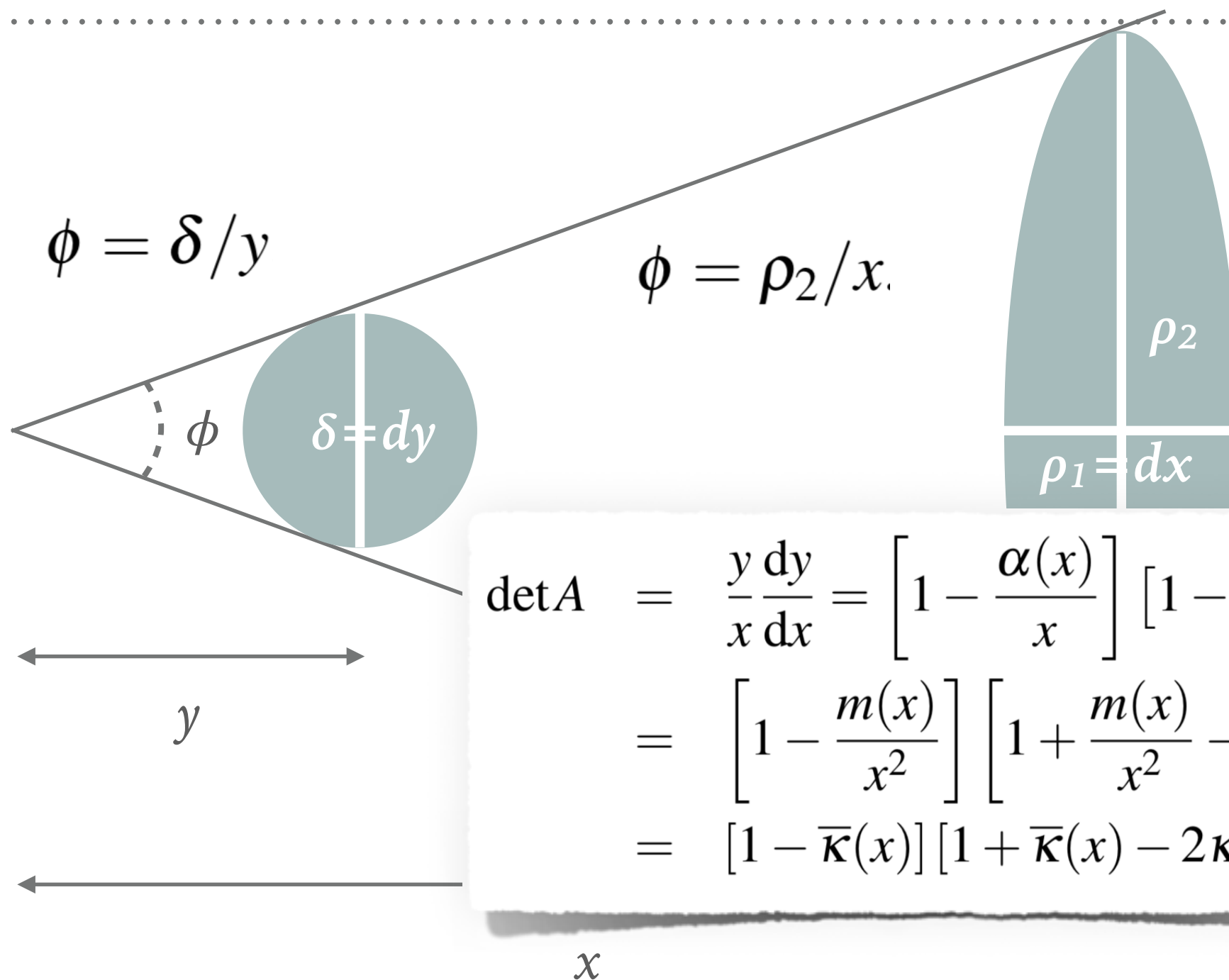
$$M(\theta_E) = \pi \Sigma_{\text{cr}} \theta_E^2 D_{\text{L}}^2$$

$$\theta_E = \sqrt{\frac{4GM(\theta_E)}{c^2} \frac{D_{\text{LS}}}{D_{\text{L}} D_{\text{S}}}}$$

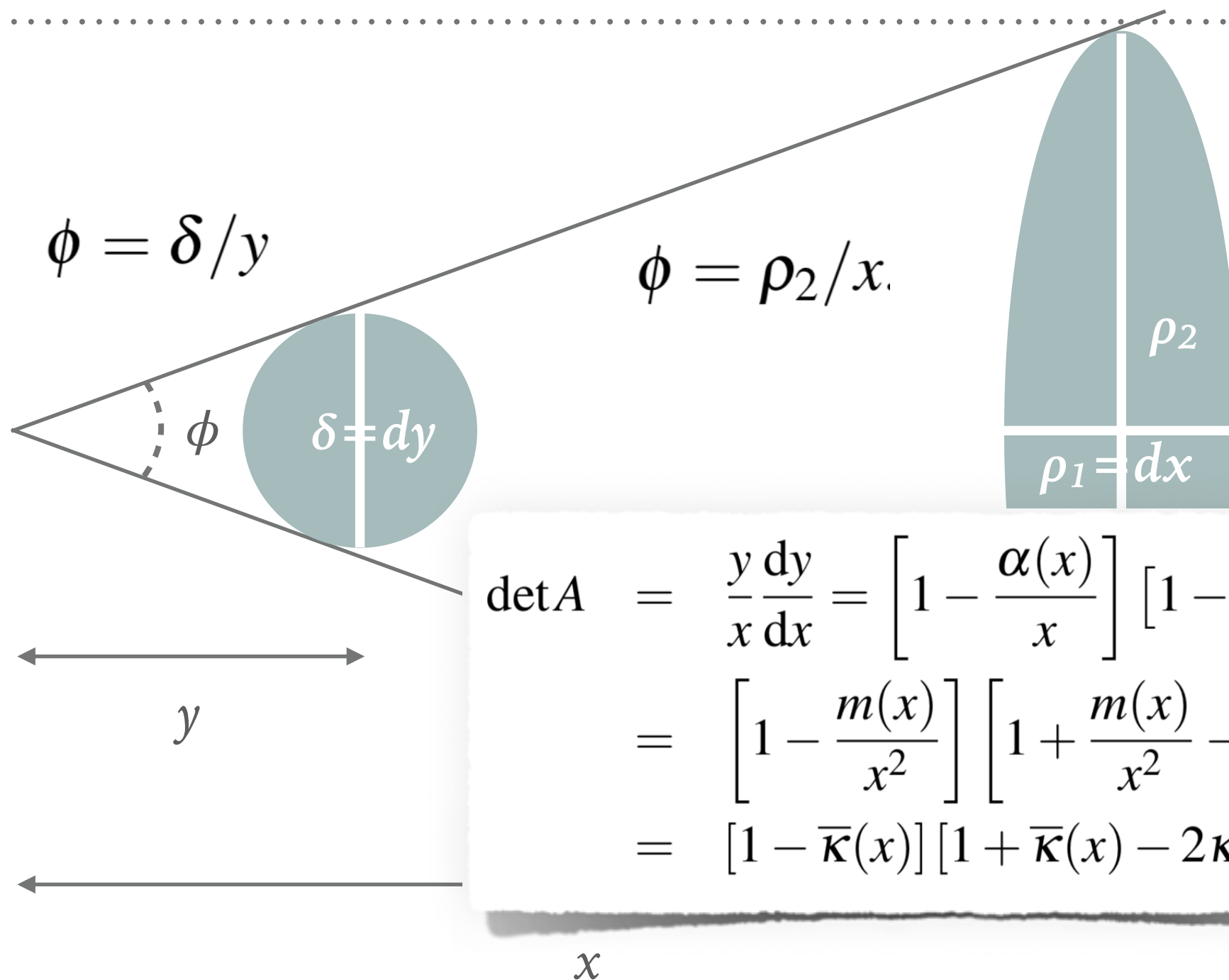
RADIAL AND TANGENTIAL MAGNIFICATION



RADIAL AND TANGENTIAL MAGNIFICATION



RADIAL AND TANGENTIAL MAGNIFICATION



$$\frac{\delta}{\rho_2} = 1 - \frac{m(x)}{x^2}$$

$$\frac{\delta}{\rho_1} = 1 + \frac{m(x)}{x^2} - 2\kappa(x)$$