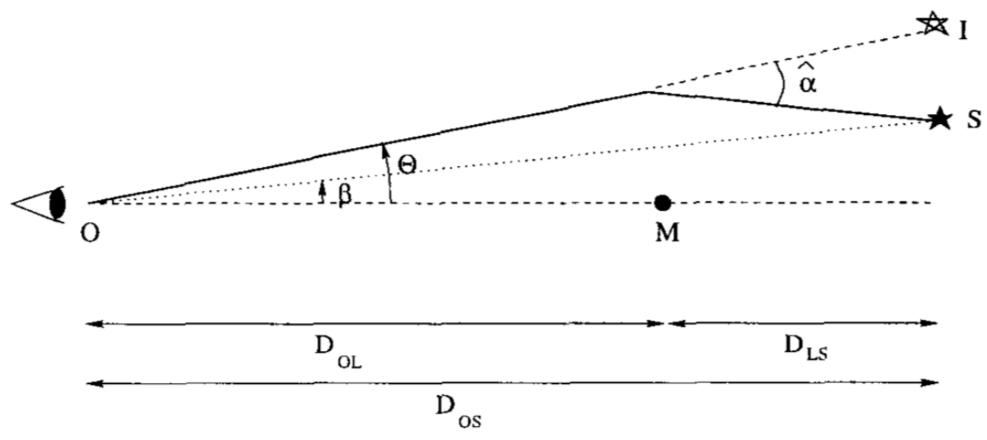
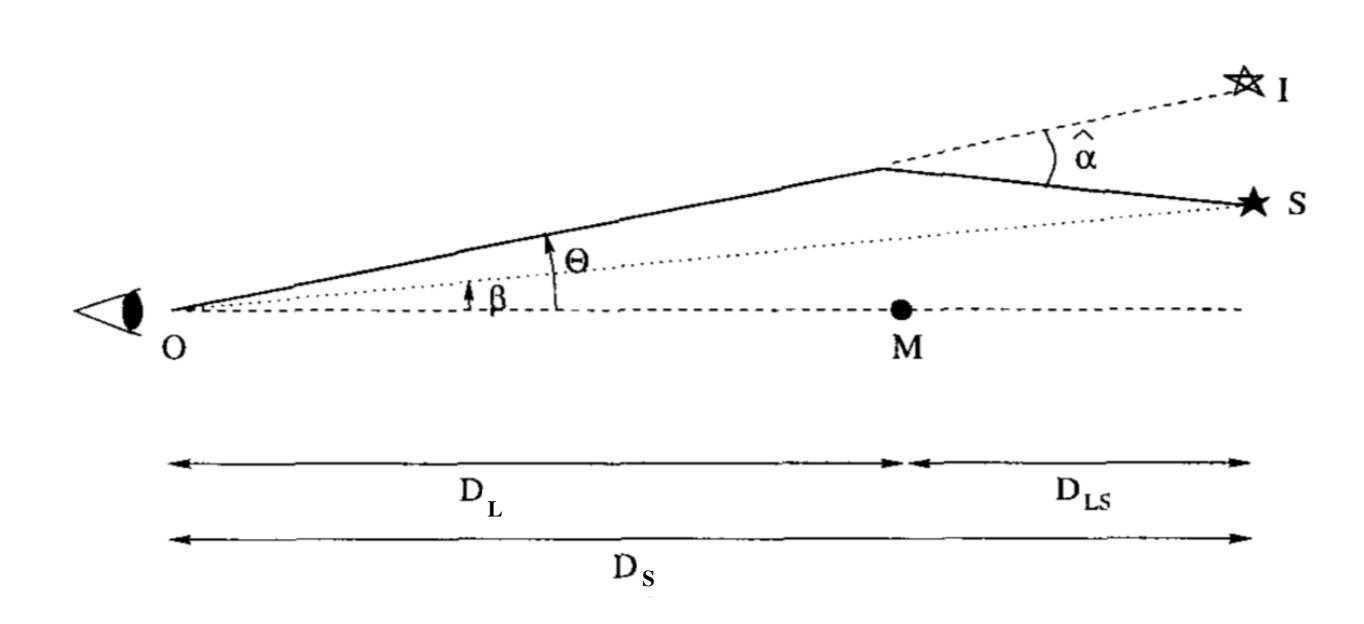
GRAVITATIONAL LENSING

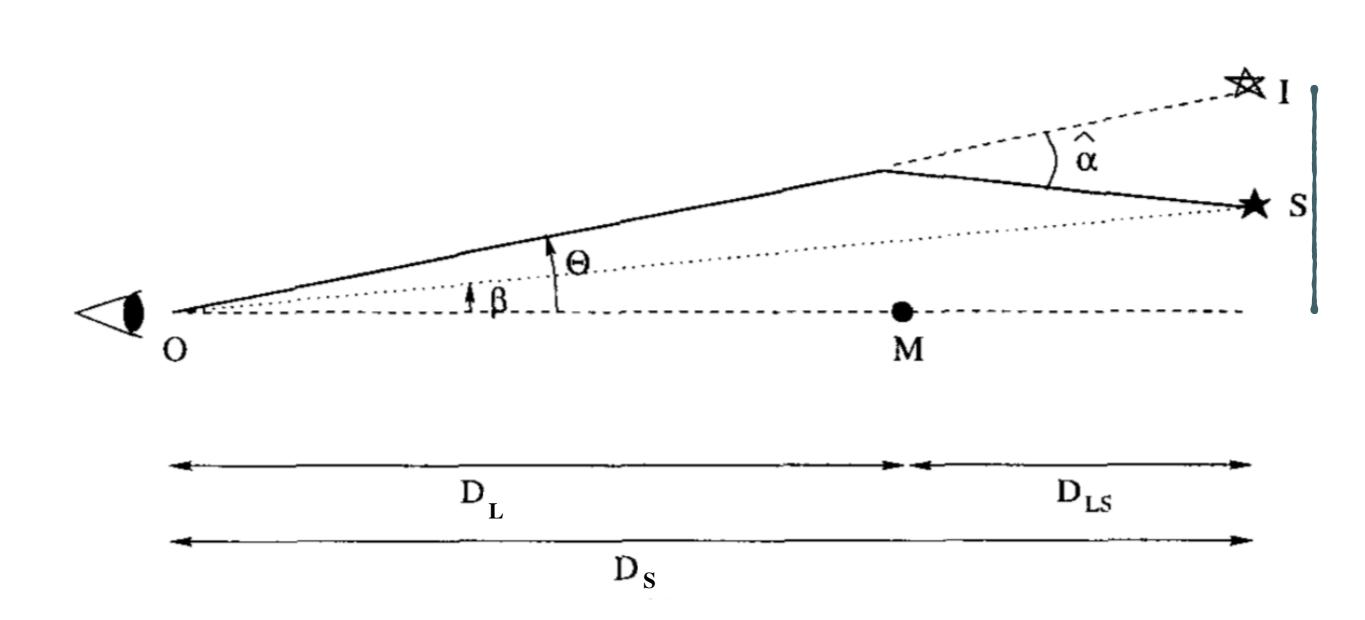
3 - LENS EQUATION & LENSING POTENTIAL

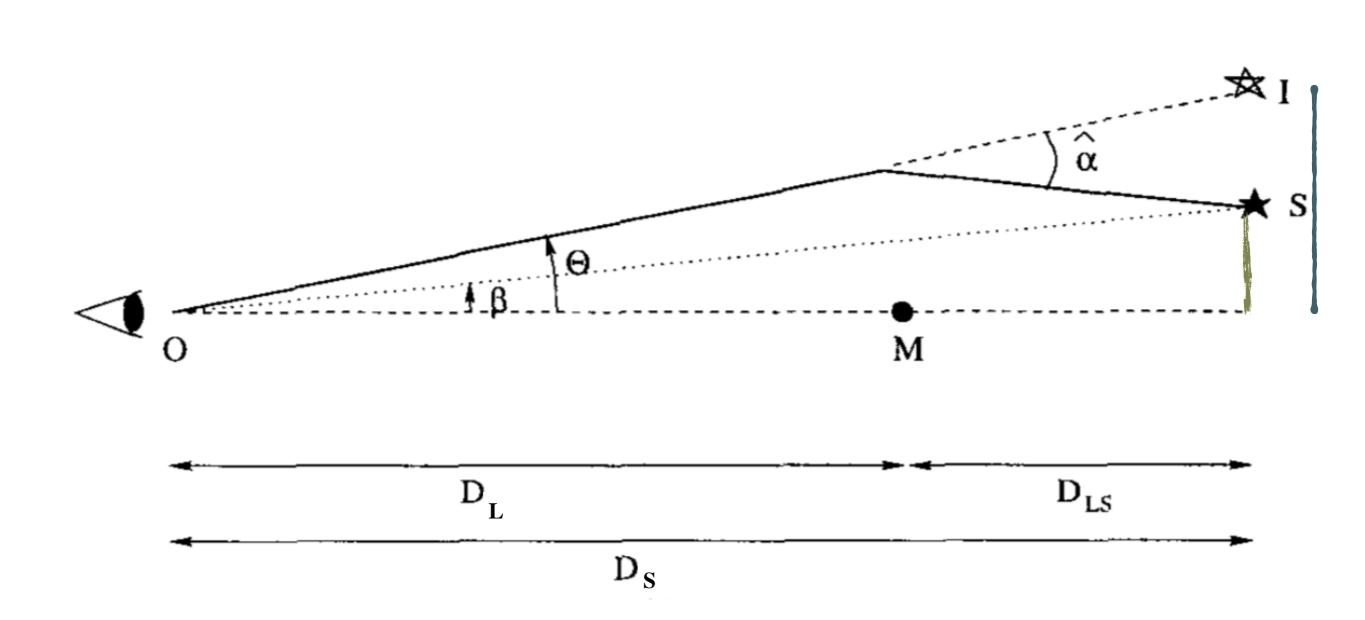
Massimo Meneghetti AA 2017-2018

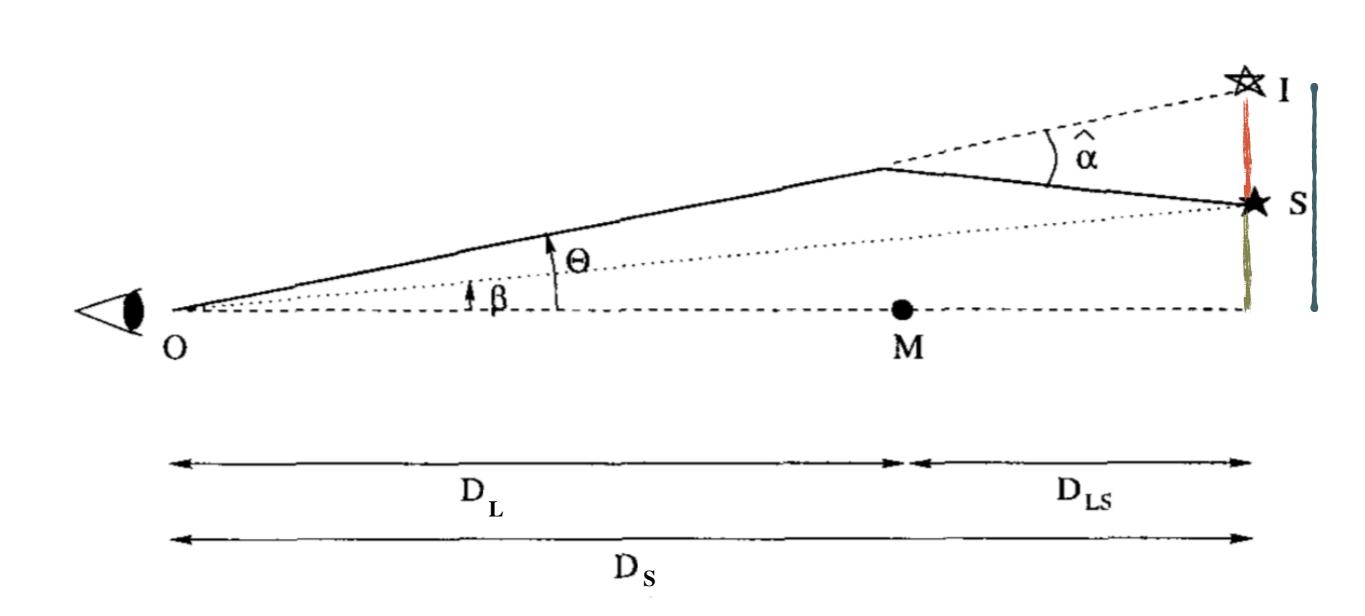


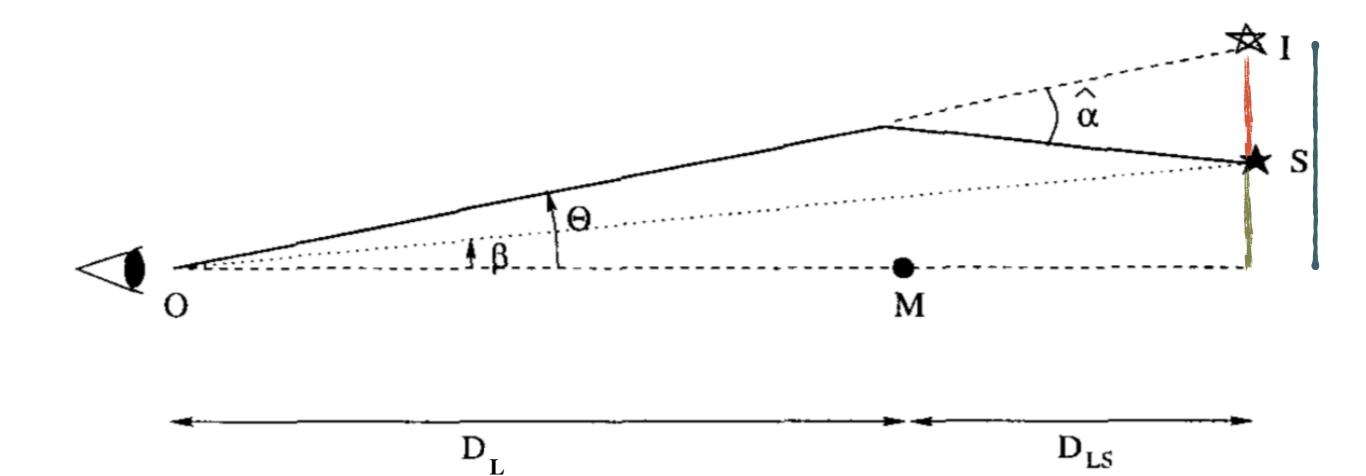
- ➤ We seek a relationship between observed and intrinsic positions of a source in a gravitational lensing event
- ➤ In absence of the lens, the light emitted by a distant source reaches the observer along a line-of-sight, which identifies the *source' intrinsic position* on the sky
- ➤ If there is a deflector, the source won't appear at the same position anymore: photons originally emitted in a different direction are deflected such to reach the observer, who will see the source at a different position, called the *observed position of the image*





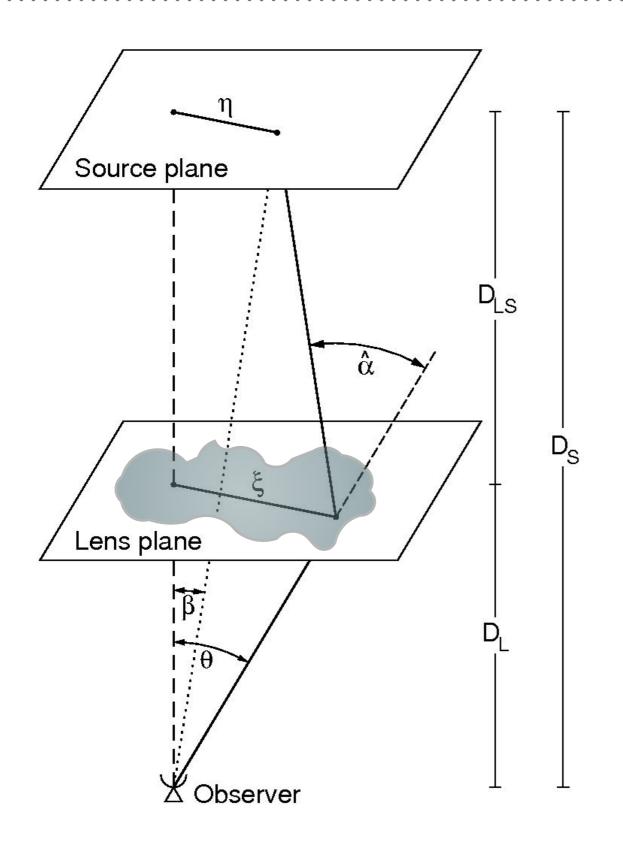






 D_{S}

$$D_S \theta = D_S \beta + D_{LS} \hat{\alpha} \Rightarrow \beta = \theta - \frac{D_{LS}}{D_S} \hat{\alpha}(\theta)$$



Remember that:

- 1) we are using the "Thin Screen Approximation"
- 2) positions on the lens and source planes are defined by vectors
- 3) the deflection angle itself is a vector

$$\vec{\beta} = \vec{\theta} - \frac{D_{LS}}{D_S} \hat{\vec{\alpha}}(\vec{\theta})$$

$$\vec{\theta} = \frac{\vec{\xi}}{D_L} \qquad \vec{\beta} = \frac{\vec{\eta}}{D_S}$$

$$\vec{\beta} = \vec{\theta} - \vec{\alpha} \qquad \vec{\alpha}(\vec{\theta}) = \frac{D_{LS}}{D_S} \hat{\vec{\alpha}}(\vec{\theta})$$

OTHER NOTATIONS

Quite often, an alternative way is chosen to write the lens equation: the so called "dimension-less" notation.

This implies the choice of a reference angle (or length) to scale the source and image positions and the deflection angle:

$$\vec{\theta} = \frac{\vec{\xi}}{D_L} \qquad \vec{\beta} = \frac{\vec{\eta}}{D_S} \qquad \vec{\alpha}(\vec{\theta}) = \frac{D_{LS}}{D_S} \hat{\vec{\alpha}}(\vec{\theta}) \qquad \vec{\beta} = \vec{\theta} - \vec{\alpha}$$

$$heta_0 = rac{\xi_0}{D_L} = rac{\eta_0}{D_S}$$
 the reference angle subtends the reference scales on the lens and on the source planes



dividing both members of the lens equation by the reference angle...

$$\vec{y} = \vec{x} - \vec{\alpha}(\vec{x}) \qquad \qquad \vec{\alpha}(\vec{x}) = \frac{\vec{\alpha}(\theta)}{\theta_0} = \frac{D_L}{\xi_0} \frac{D_{LS}}{D_S} \hat{\vec{\alpha}}(\vec{\theta})$$

LENSING POTENTIAL

$$\hat{\vec{\alpha}} = \frac{2}{c^2} \int_{-\infty}^{+\infty} \vec{\nabla}_{\perp} \Phi dz$$

This formula tells us that the deflection is caused by the projection of the Newtonian gravitational potential on the lens plane.

$$\hat{\Psi}(\vec{\theta}) = \frac{D_{LS}}{D_L D_S} \frac{2}{c^2} \int \Phi(D_L \vec{\theta}, z) dz$$
 We introduce the effective lensing potential

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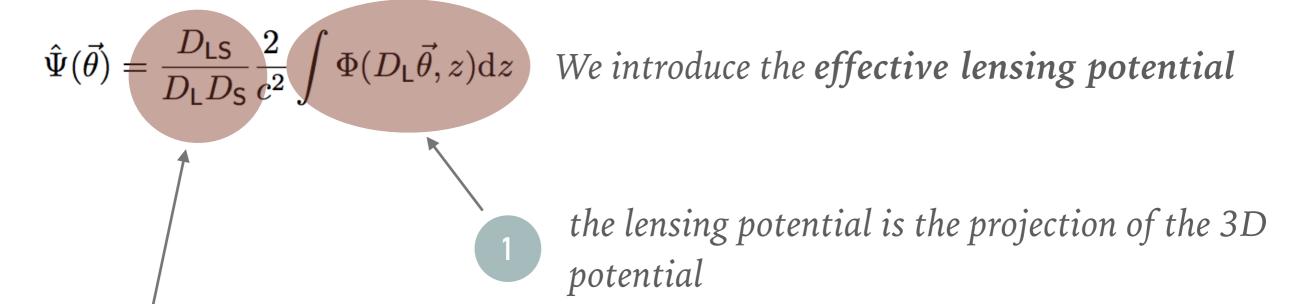
$$\hat{\Psi}(\vec{\theta}) = \frac{D_{\rm LS}}{D_{\rm L}D_{\rm S}} \frac{2}{c^2} \int \Phi(D_{\rm L}\vec{\theta},z) {\rm d}z \quad \text{We introduce the effective lensing potential}$$

the lensing potential is the projection of the 3D potential

LENSING POTENTIAL

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This formula tells us that the deflection is caused by the projection of the Newtonian gravitational potential on the lens plane.



the lensing potential scales with distances

$$\vec{\nabla}_{\theta} \hat{\Psi}(\vec{\theta}) = \vec{\alpha}(\vec{\theta})$$

The reduced deflection angle is the gradient of the lensing potential

$$\begin{split} \vec{\nabla}_{\theta} \hat{\Psi}(\vec{\theta}) &= D_{L} \vec{\nabla}_{\perp} \hat{\Psi} = \vec{\nabla}_{\perp} \left(\frac{D_{LS}}{D_{S}} \frac{2}{c^{2}} \int \hat{\Phi}(\vec{\theta}, z) dz \right) \\ &= \frac{D_{LS}}{D_{S}} \frac{2}{c^{2}} \int \vec{\nabla}_{\perp} \Phi(\vec{\theta}, z) dz \\ &= \vec{\alpha}(\vec{\theta}) \end{split}$$

NOTE THAT...

.....

... the same result holds if we use the dimension-less notation:

$$ec{
abla}_{x}=rac{\xi_{0}}{D_{
m L}}ec{
abla}_{ heta}$$



$$ec{
abla}_{x}\hat{\Psi}=rac{\xi_{0}}{D_{\mathrm{L}}}ec{
abla}_{ heta}\hat{\Psi}=rac{\xi_{0}}{D_{\mathrm{L}}}ec{lpha}$$

By multiplying both sides of the equation by $D_{\rm L}^2/\xi_0^2$ we obtain:

$$\frac{D_{\mathrm{L}}^2}{\xi_0^2} \vec{\nabla}_x \hat{\Psi} = \frac{D_{\mathrm{L}}}{\xi_0} \vec{\alpha} \qquad \qquad \Psi = \frac{D_{\mathrm{L}}^2}{\xi_0^2} \hat{\Psi} \qquad \qquad \vec{\nabla}_x \Psi(\vec{x}) = \vec{\alpha}(\vec{x})$$

We have introduced the dimensionless counter-part of the lensing potential!

$$\triangle_{\theta} \hat{\Psi}(\vec{\theta}) = 2\kappa(\vec{\theta})$$

The laplacian of the lensing potential is twice the convergence:

$$\kappa(\vec{\theta}) \equiv \frac{\Sigma(\vec{\theta})}{\Sigma_{\rm cr}}$$
 with $\Sigma_{\rm cr} = \frac{c^2}{4\pi G} \frac{D_{\rm S}}{D_{\rm L}D_{\rm LS}}$

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$$[G] = L^3/M/T^2$$

$$[c^2] = L^2/T^2$$

$$[D_X] = L$$

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The critical surface density is a characteristic density to distinguish between strong and weak gravitational lenses!

 $\triangle_{\theta} \hat{\Psi}(\vec{\theta}) = 2\kappa(\vec{\theta})$

The laplacian of the lensing potential is twice the convergence:

We start from the poisson equation

$$\triangle \Phi = 4\pi G\rho$$

The surface mass density is then:

$$\Sigma(\vec{\theta}) = \frac{1}{4\pi G} \int_{-\infty}^{+\infty} \triangle \Phi \mathrm{d}z$$

$$\kappa(\vec{\theta}) = \frac{1}{c^2} \frac{D_{\rm L}D_{\rm LS}}{D_{\rm S}} \int_{-\infty}^{+\infty} \triangle \Phi dz$$

Let's introduce the Laplacian operator on the lens plane:

$$\triangle_{\theta} = \frac{\partial^{2}}{\partial \theta_{1}^{2}} + \frac{\partial^{2}}{\partial \theta_{2}^{2}} = D_{L}^{2} \left(\frac{\partial^{2}}{\partial \xi_{1}^{2}} + \frac{\partial^{2}}{\partial \xi_{2}^{2}} \right) = D_{L}^{2} \left(\triangle - \frac{\partial^{2}}{\partial z^{2}} \right)$$

Then:

$$\triangle \Phi = \frac{1}{D_{\rm L}^2} \triangle_{\theta} \Phi + \frac{\partial^2 \Phi}{\partial z^2}$$

With this substitution:

$$\kappa(\vec{\theta}) = \frac{1}{c^2} \frac{D_{\rm LS}}{D_{\rm S} D_{\rm L}} \left[\triangle_{\theta} \int_{-\infty}^{+\infty} \Phi dz + D_{\rm L}^2 \int_{-\infty}^{+\infty} \frac{\partial^2 \Phi}{\partial z^2} dz \right]$$

where the second term in the sum is zero, if the lens if gravitationally bound!

Given the definition of lensing potential:

$$\kappa(\boldsymbol{\theta}) = \frac{1}{2} \triangle_{\boldsymbol{\theta}} \hat{\Psi}$$

Note that:

$$\triangle_{m{ heta}} = D_{
m L}^2 \triangle_{m{\xi}} = rac{D_{
m L}^2}{m{\xi}_0^2} \triangle_x$$

$$\triangle_{\theta} = D_{\mathrm{L}}^2 \triangle_{\xi} = \frac{D_{\mathrm{L}}^2}{\xi_0^2} \triangle_x \qquad \kappa(\theta) = \frac{1}{2} \triangle_{\theta} \hat{\Psi} = \frac{1}{2} \frac{\xi_0^2}{D_{\mathrm{L}}^2} \triangle_{\theta} \Psi$$



$$\kappa(\vec{x}) = \frac{1}{2} \triangle_x \Psi(\vec{x})$$

DIMENSIONLESS NOTATION

From

$$\vec{\hat{\alpha}}(\vec{\xi}) = \frac{4G}{c^2} \int \frac{(\vec{\xi} - \vec{\xi'}) \Sigma(\vec{\xi'})}{|\vec{\xi} - \vec{\xi'}|^2} d^2 \xi'$$

we obtain

$$\vec{\alpha}(\vec{x}) = \frac{1}{\pi} \int_{\mathbf{R}^2} d^2 x' \kappa(\vec{x}') \frac{\vec{x} - \vec{x}'}{|\vec{x} - \vec{x}'|}$$

Using

$$\vec{\nabla}_x \Psi(\vec{x}) = \vec{\alpha}(\vec{x})$$

$$\Psi(\vec{x}) = \frac{1}{\pi} \int_{\mathbf{R}^2} \kappa(\vec{x}') \ln |\vec{x} - \vec{x}'| d^2 x'$$

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Using

$$\vec{\nabla}_x \Psi(\vec{x}) = \vec{\alpha}(\vec{x})$$

Convolution kernels

$$\Psi(\vec{x}) = \frac{1}{\pi} \int_{\mathbf{R}^2} \kappa(\vec{x}') \ln |\vec{x} - \vec{x}'| \mathrm{d}^2 x'$$