GRAVITATIONAL LENSING

7 - TIME DELAYS

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GRAVITATIONAL TIME DELAY

- ➤ In a lensing phenomenon, light travels with an effective velocity *c*′<*c*. As seen, this implies an effective refractive index *n*>1
- ➤ The effective refractive index is expressed in terms of the Newtonian potential
- If we compare the travel times of two photons, one traveling at velocity c and the other at velocity c', we notice that the second accumulates a time delay t_{grav}
- This time delay is called *gravitational* time delay, or *Shapiro* time delay (Shapiro, 1964)

$$n = 1 - \frac{2\Phi}{c^2}$$

$$t_{grav} = \int \frac{dz}{c'} - \int \frac{dz}{c}$$
$$= \frac{1}{c} \int (n-1)dz$$
$$= -\frac{2}{c^3} \int \Phi dz$$

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$$\hat{\Psi}(\vec{\theta}) = \frac{D_{LS}}{D_L D_S} \frac{2}{c^2} \int \Phi(\vec{\theta}, z) dz$$

$$t_{grav} = -\frac{1}{c} \frac{D_S D_L}{D_{LS}} \hat{\Psi}$$

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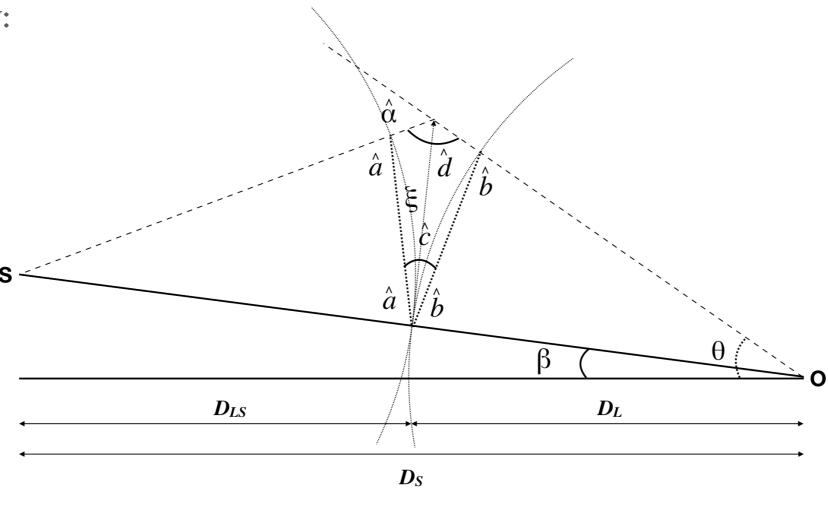
$$t_{grav} = -\frac{1}{c} \frac{D_S D_L}{D_{LS}} \hat{\Psi}$$

This time delay does not account yet for the different path of photons!

GEOMETRICAL TIME DELAY

➤ We need to combine the gravitational time delay to the so called *geometrical*

time delay:

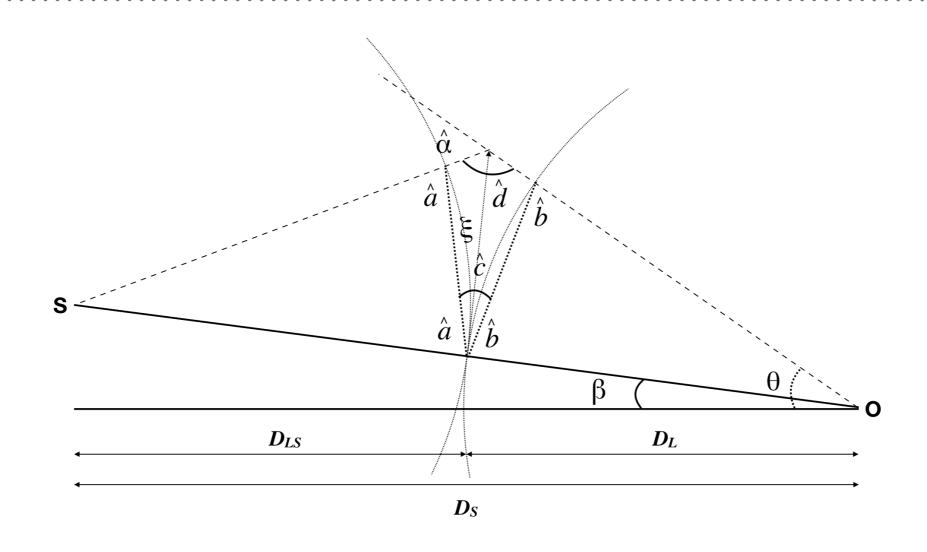


$$(\pi - \hat{a}) + (\pi - \hat{b}) + \hat{c} + \hat{d} = 2\pi \Rightarrow \hat{a} + \hat{b} = \hat{c} + \hat{d}$$

$$\hat{a} + \hat{b} + \hat{c} = \pi \Rightarrow 2\hat{c} = \pi - \hat{d}$$

$$\hat{\alpha} + \hat{d} = \pi \Rightarrow \hat{d} = \pi - \hat{\alpha}$$

GEOMETRICAL TIME DELAY

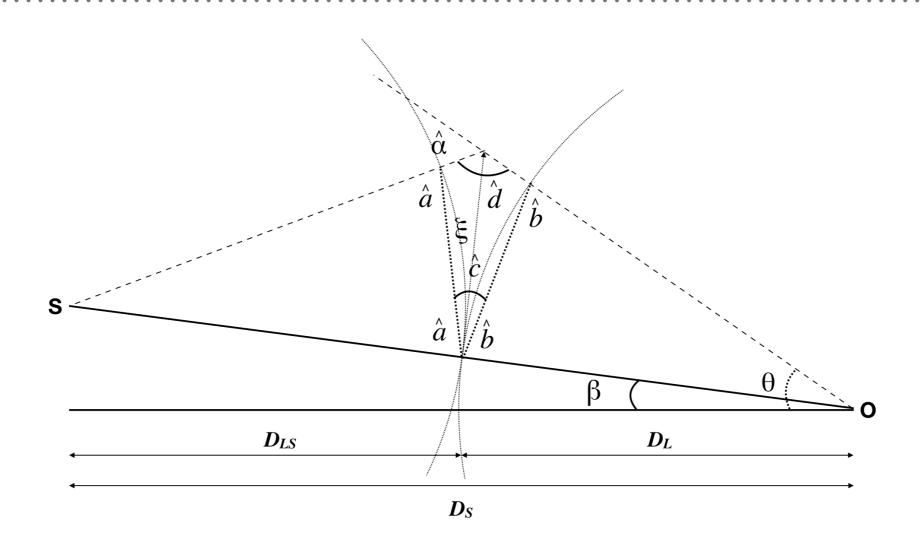


$$(\pi - \hat{a}) + (\pi - \hat{b}) + \hat{c} + \hat{d} = 2\pi \Rightarrow \hat{a} + \hat{b} = \hat{c} + \hat{d} \qquad \Rightarrow \hat{c} = \frac{\alpha}{2}$$

$$\hat{a} + \hat{b} + \hat{c} = \pi \Rightarrow 2\hat{c} = \pi - \hat{d} \qquad = \frac{1}{2} \frac{D_S}{D_{LS}} \alpha$$

$$\hat{\alpha} + \hat{d} = \pi \Rightarrow \hat{d} = \pi - \hat{\alpha} \qquad = \frac{1}{2} \frac{D_S}{D_{LS}} (\theta - \beta)$$

GEOMETRICAL TIME DELAY



$$\Rightarrow \hat{c} = \frac{\hat{\alpha}}{2}$$

$$= \frac{1}{2} \frac{D_S}{D_{LS}} \alpha$$

$$= \frac{1}{2} \frac{D_S}{D_{LS}} (\theta - \beta)$$

$$\xi = D_L(\theta - \beta)$$

$$t_{geom} = \frac{1}{c}\xi\hat{c}$$

$$= \frac{1}{2c}\frac{D_S D_L}{D_{LS}}(\theta - \beta)^2$$

TOTAL TIME DELAY

$$t_{geom} = \frac{1}{2c} \frac{D_S D_L}{D_{LS}} (\theta - \beta)^2 \qquad t_{grav} = -\frac{1}{c} \frac{D_S D_L}{D_{LS}} \hat{\Psi}$$

$$t_{tot} = t_{geom} + t_{grav}$$

$$= \frac{1}{2c} \frac{D_S D_L}{D_{LS}} (\theta - \beta)^2 - \frac{1}{c} \frac{D_S D_L}{D_{LS}} \hat{\Psi}(\theta)$$

$$= \frac{1}{c} \frac{D_S D_L}{D_{LS}} \left[\frac{1}{2} (\theta - \beta)^2 - \hat{\Psi}(\theta) \right]$$

TOTAL TIME DELAY

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$$= \frac{1}{c} \frac{D_S D_L}{D_{LS}} \left[\frac{1}{2} (\theta - \beta)^2 - \hat{\Psi}(\theta) \right]$$

Accounting for the expansion of the universe and for the fact that this is a surface:

$$t_{tot}(\vec{\theta}) = \frac{1 + z_L}{c} \frac{D_S D_L}{D_{LS}} \left[\frac{1}{2} (\vec{\theta} - \vec{\beta})^2 - \hat{\Psi}(\vec{\theta}) \right]$$

TOTAL TIME DELAY

$$t_{tot}(\vec{\theta}) = \frac{1 + z_L}{c} \frac{D_S D_L}{D_{LS}} \left[\frac{1}{2} (\vec{\theta} - \vec{\beta})^2 - \hat{\Psi}(\vec{\theta}) \right]$$

$$\tau(\vec{\theta}) = \frac{1}{2}(\vec{\theta} - \vec{\beta})^2 - \hat{\Psi}(\vec{\theta}) \qquad D_{\Delta t} = (1 + z_L) \frac{D_S D_L}{D_{LS}}$$

Fermat potential

Time delay distance

$$t(\vec{\theta}) = t_{geom} + t_{grav} \propto \left(\frac{1}{2}(\vec{\theta} - \vec{\beta})^2 - \hat{\Psi}\right)$$

$$\vec{\nabla}t(\vec{\theta}) \propto \left(\vec{\theta} - \vec{\beta} - \vec{\nabla}\hat{\Psi}\right)$$

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Lens equation!

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Lens equation!

Images form at the stationary points of t!

$$t(\vec{\theta}) = t_{geom} + t_{grav} \propto \left(\frac{1}{2}(\vec{\theta} - \vec{\beta})^2 - \hat{\Psi}\right)$$

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Lens equation!

Images form at the stationary points of t!

$$T_{ij} = \frac{\partial^2 t(\vec{\theta})}{\partial \theta_i \partial \theta_j} \propto (\delta_{ij} - \Psi_{ij})$$

 $t(\vec{\theta}) = t_{geom} + t_{grav} \propto \left(\frac{1}{2}(\vec{\theta} - \vec{\beta})^2 - \hat{\Psi}\right)$

$$\vec{\nabla}t(\vec{\theta}) \propto \left(\vec{\theta} - \vec{\beta} - \vec{\nabla}\hat{\Psi}\right)$$



Lens equation!

Images form at the stationary points of t!

$$T_{ij}=rac{\partial^2 t(ec{ heta})}{\partial heta_i \partial heta_j} \propto (\delta_{ij}-\Psi_{ij})$$
 This is the Jacobian!

TYPES OF IMAGES

- minima (eigenvalues of A are both positive, hence detA>0 and Tr A>0; positive magnification)
- ➤ saddle (eigenvalues have opposite signs, thus detA < 0; negative magnification)
- ➤ maxima (eigenvalues are both negative, hence detA>0 and Tr A<0; positive magnification)
- ➤ Let see some examples...