

# GRAVITATIONAL LENSING

## LECTURE 8

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*AA 2016-2017*

# CONTENTS

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- second order lensing effects

# SECOND ORDER LENS EQUATION

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$$\beta_i \simeq \frac{\partial \beta_i}{\partial \theta_j} \theta_j$$

$A_{ij}$



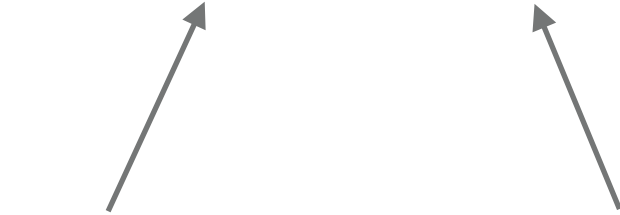
*Thus, second order lens mapping is described by a rank-3 tensor, which can be written in terms of the derivatives of the shear.*

# SECOND ORDER LENS EQUATION

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$$\beta_i \simeq \frac{\partial \beta_i}{\partial \theta_j} \theta_j + \frac{1}{2} \frac{\partial^2 \beta_i}{\partial \theta_j \partial \theta_k} \theta_j \theta_k$$

$A_{ij}$                        $\frac{\partial A_{ij}}{\partial \theta_k} = D_{ijk}$



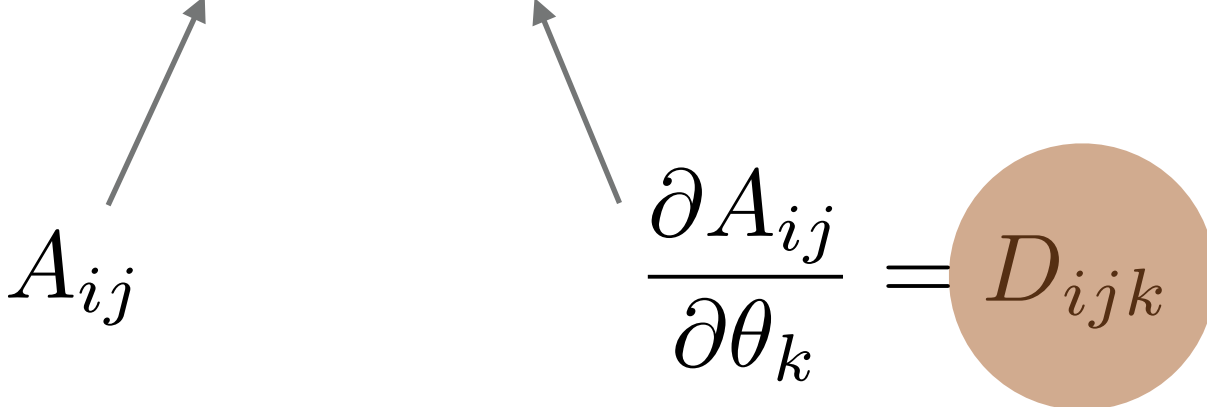
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The diagram shows the equation  $\beta_i \simeq \frac{\partial \beta_i}{\partial \theta_j} \theta_j + \frac{1}{2} \frac{\partial^2 \beta_i}{\partial \theta_j \partial \theta_k} \theta_j \theta_k$  at the top. Below it, the expression  $A_{ij}$  is positioned under the first derivative term, and  $\frac{\partial A_{ij}}{\partial \theta_k} = D_{ijk}$  is positioned under the second derivative term. Two arrows point from  $A_{ij}$  to the first derivative term and from  $\frac{\partial A_{ij}}{\partial \theta_k}$  to the second derivative term. The  $D_{ijk}$  is enclosed in a brown circle.


*Thus, second order lens mapping is described by a rank-3 tensor, which can be written in terms of the derivatives of the shear.*

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$A_{ij}$ 


$\frac{\partial A_{ij}}{\partial \theta_k} = D_{ijk}$ 


$$D_{ij1} = \begin{pmatrix} -2\gamma_{1,1} - \gamma_{2,2} & -\gamma_{2,1} \\ -\gamma_{2,1} & -\gamma_{2,2} \end{pmatrix} \quad D_{ij2} = \begin{pmatrix} -\gamma_{2,1} & -\gamma_{2,2} \\ -\gamma_{2,2} & 2\gamma_{1,2} - \gamma_{2,1} \end{pmatrix}$$

*Thus, second order lens mapping is described by a rank-3 tensor, which can be written in terms of the derivatives of the shear.*

# COMPLEX NOTATION

---

*It is sometimes very convenient to use a complex notation to describe quantities on the lens and on the source planes:*

$$v = (v_1, v_2) \longrightarrow v = v_1 + iv_2$$

*With this notation,*

$$\alpha = \alpha_1 + i\alpha_2$$

$$\gamma = \gamma_1 + i\gamma_2.$$

*We can also define complex differential operators. They turn out to be “spin ladder” operators:*

$$\partial = \partial_1 + i\partial_2$$

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$$\partial = \partial_1 + i\partial_2$$

*Spin raising operator*

$$\partial^\dagger = \partial_1 - i\partial_2$$

*Spin lowering operator*



# COMPLEX NOTATION

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$$\partial\hat{\Psi} = \partial_1\hat{\Psi} + i\partial_2\hat{\Psi} = \alpha_1 + i\alpha_2 = \alpha$$

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vector field (deflection angle)*

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$$\partial^\dagger\partial = \partial_1^2 + \partial_2^2 = \Delta$$

$$\partial^\dagger\partial\hat{\Psi} = \Delta\hat{\Psi} = 2\kappa$$

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*From spin-1 vector field to spin-0  
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$$\partial^\dagger\partial = \partial_1^2 + \partial_2^2 = \Delta$$

*From spin-1 vector field to spin-0 scalar field*

$$\partial^\dagger\partial\hat{\Psi} = \Delta\hat{\Psi} = 2\kappa$$

$$\frac{1}{2}\partial\partial\hat{\Psi} = \frac{1}{2}\partial\alpha = \gamma$$

*The shear is a spin-2 tensor field*

$$\partial^{-1}\partial^\dagger\gamma = \frac{1}{2}\partial^{-1}\partial^\dagger\partial\partial\hat{\Psi} = \partial^\dagger\partial\hat{\Psi} = \kappa$$

# COMPLEX NOTATION

---

$$F = \frac{1}{2} \partial \partial^\dagger \partial \hat{\Psi} = \partial \kappa$$

$$G = \frac{1}{2} \partial \partial \partial \hat{\Psi} = \partial \gamma$$

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$$F = \frac{1}{2} \partial \partial^\dagger \partial \hat{\Psi} = \partial \kappa \qquad \text{Spin-1}$$

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$$F = F_1 + iF_2 = (\gamma_{1,1} + \gamma_{2,2}) + i(\gamma_{2,1} - \gamma_{1,2})$$

$$G = G_1 + iG_2 = (\gamma_{1,1} - \gamma_{2,2}) + i(\gamma_{2,1} + \gamma_{1,2})$$

$$D_{ij1} = \begin{pmatrix} -2\gamma_{1,1} - \gamma_{2,2} & -\gamma_{2,1} \\ -\gamma_{2,1} & -\gamma_{2,2} \end{pmatrix} \quad D_{ij2} = \begin{pmatrix} -\gamma_{2,1} & -\gamma_{2,2} \\ -\gamma_{2,2} & 2\gamma_{1,2} - \gamma_{2,1} \end{pmatrix}$$



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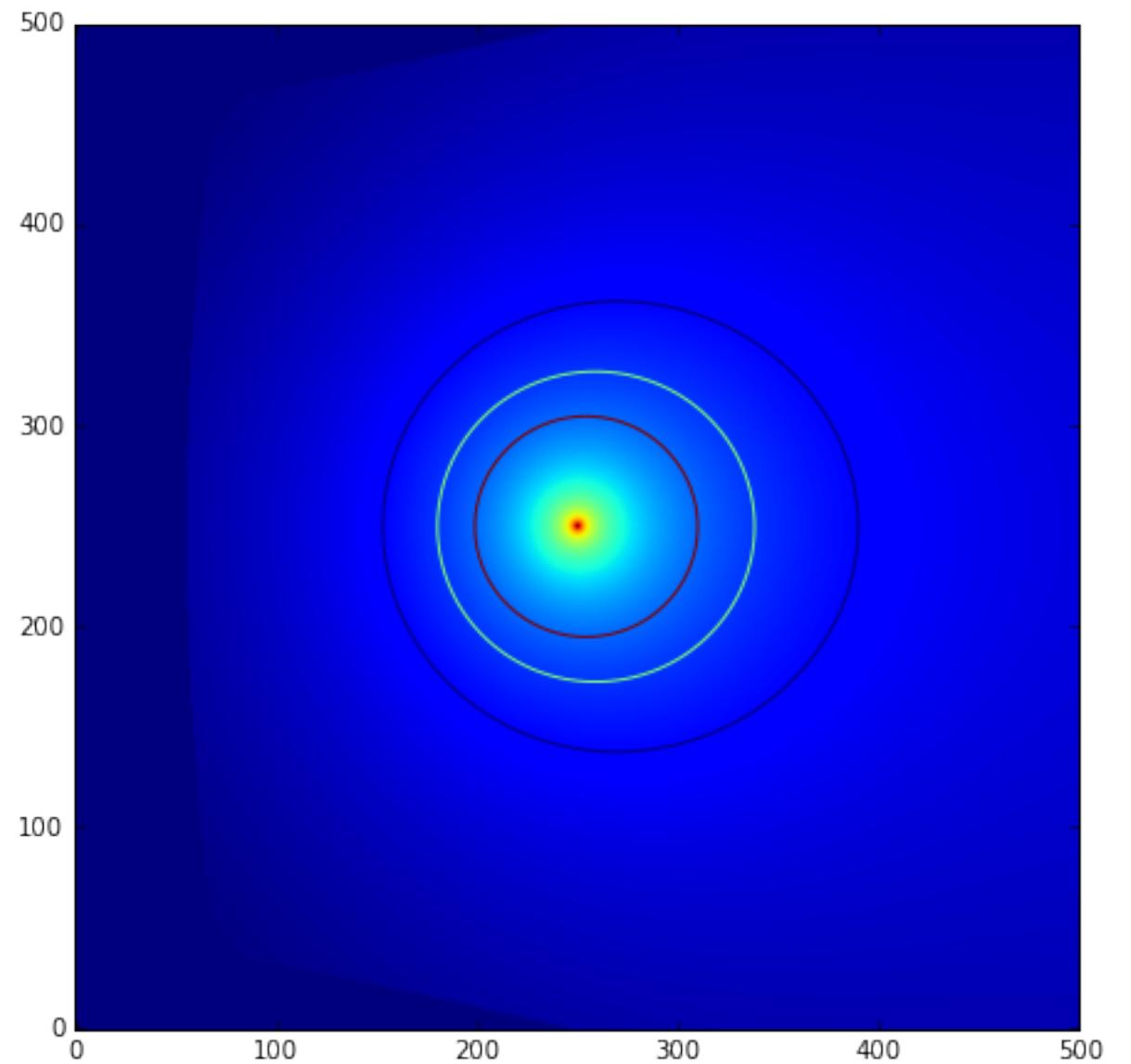
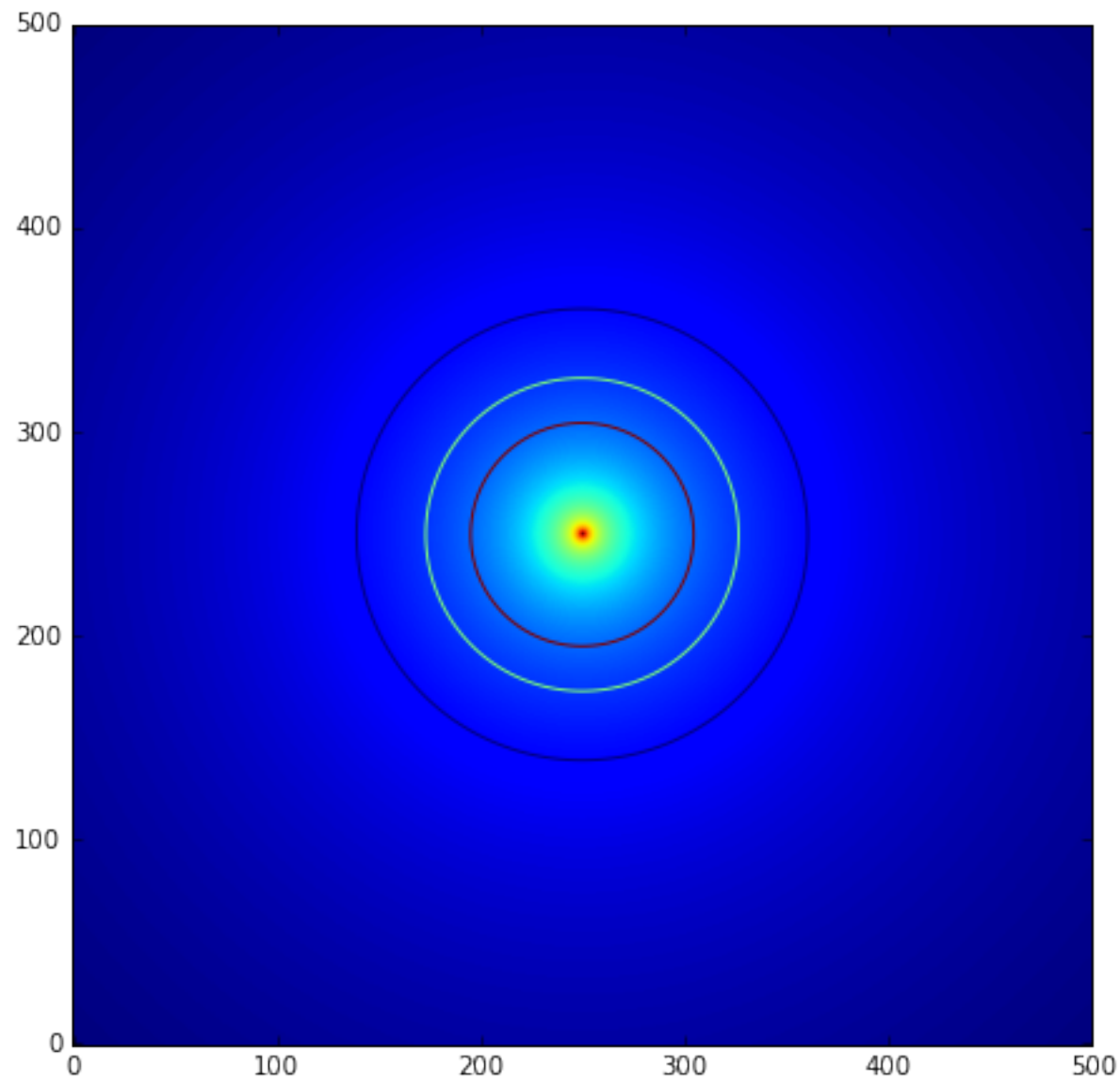
$$D_{ij1} = \begin{pmatrix} -2\gamma_{1,1} - \gamma_{2,2} & -\gamma_{2,1} \\ -\gamma_{2,1} & -\gamma_{2,2} \end{pmatrix} \quad D_{ij2} = \begin{pmatrix} -\gamma_{2,1} & -\gamma_{2,2} \\ -\gamma_{2,2} & 2\gamma_{1,2} - \gamma_{2,1} \end{pmatrix}$$

Thus, the second order term in the lens equation can be written in terms of  $F$  and  $G$ .

$$\begin{aligned} \beta_1 &= A_{11}\theta_1 + A_{12}\theta_2 + \frac{1}{2}(D_{111}\theta_1^2 + 2D_{112}\theta_1\theta_2 + D_{221}\theta_2^2) \\ \beta_2 &= A_{22}\theta_2 + A_{12}\theta_1 + \frac{1}{2}(D_{222}\theta_2^2 + 2D_{221}\theta_1\theta_2 + D_{112}\theta_1^2) \end{aligned}$$

# SECOND ORDER DISTORTIONS OF A CIRCULAR SOURCE

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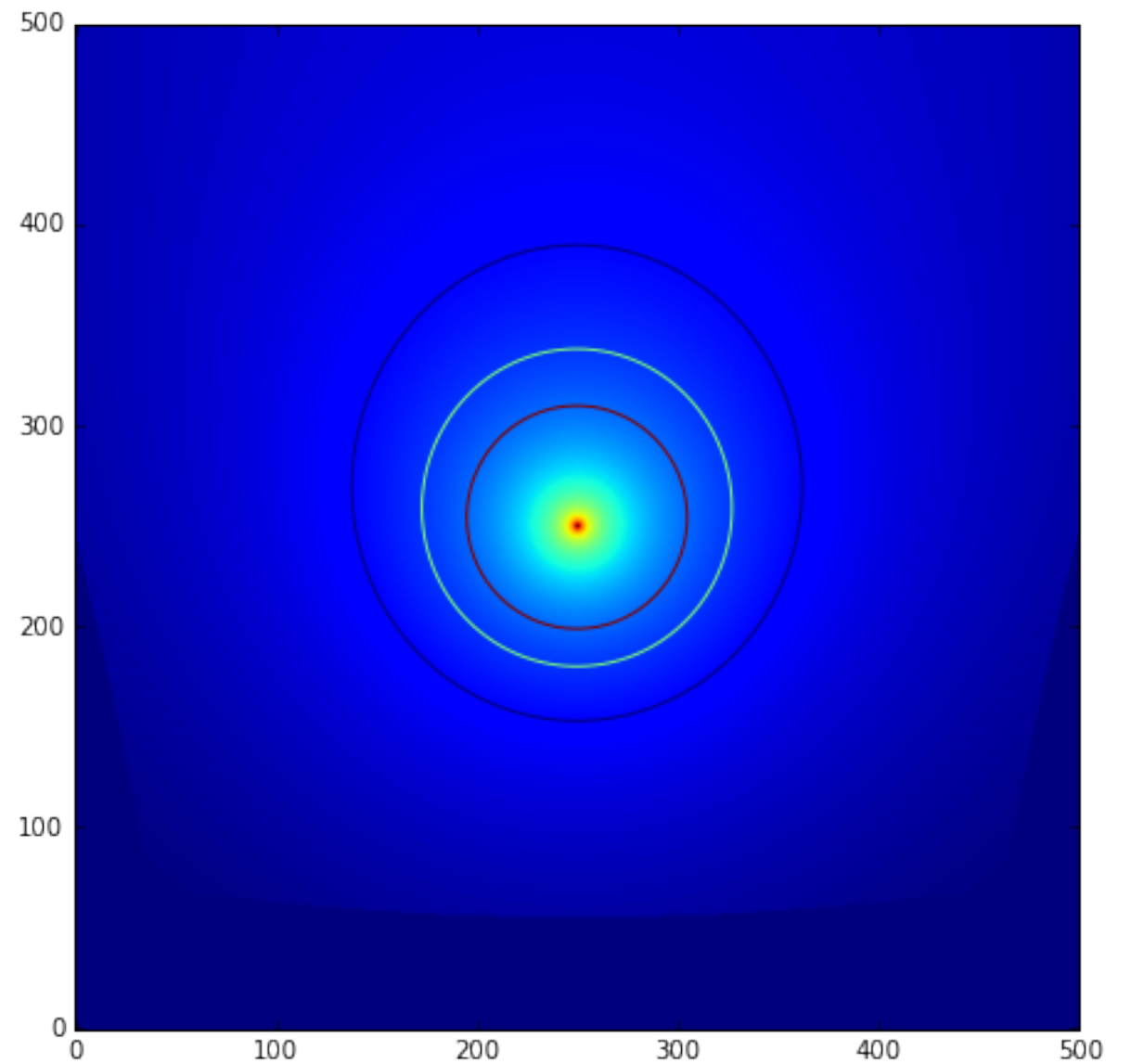
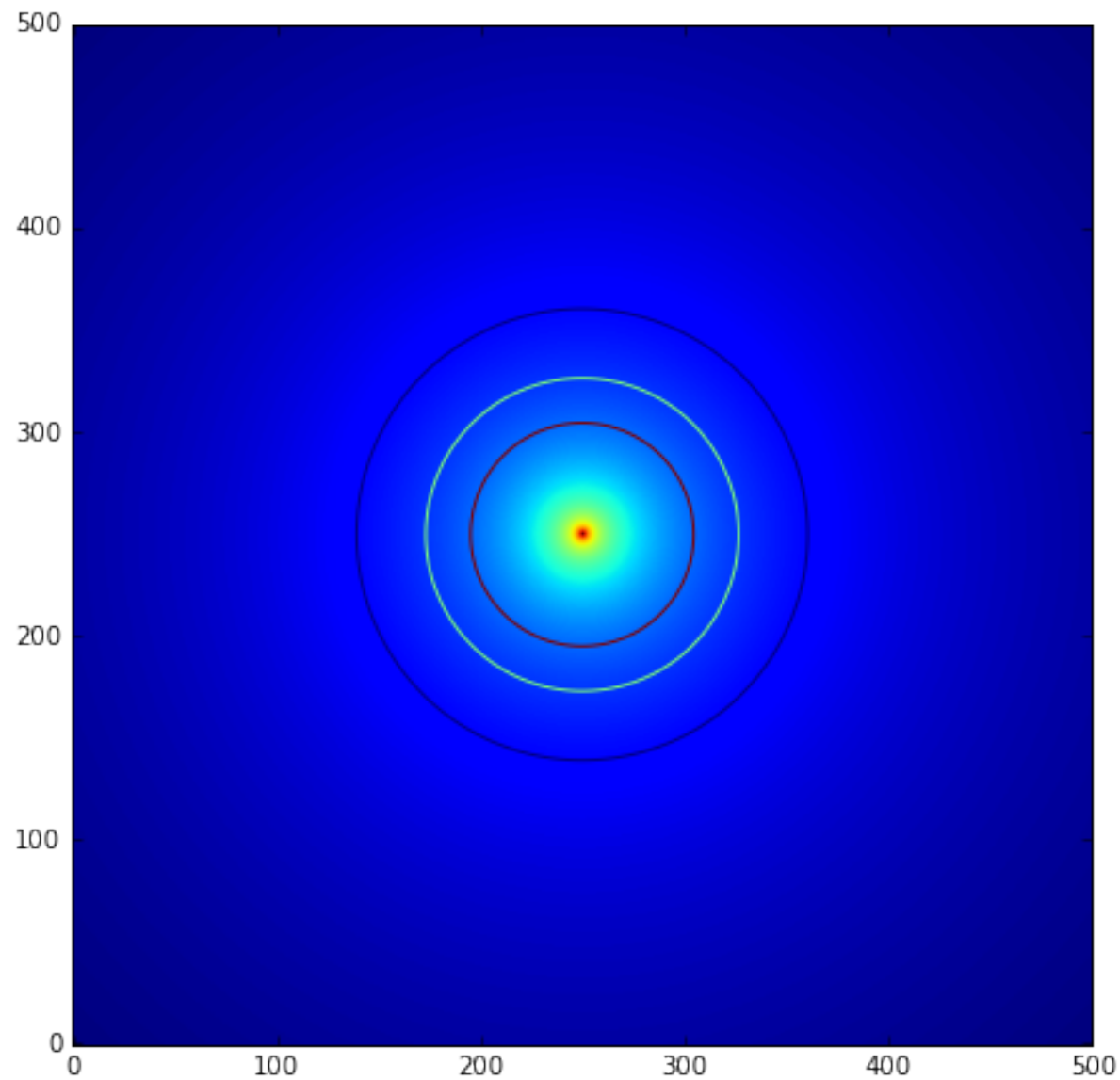


$$F_1 = 0.5 \quad G_1 = 0$$

$$F_2 = 0 \quad G_2 = 0$$

# SECOND ORDER DISTORTIONS OF A CIRCULAR SOURCE

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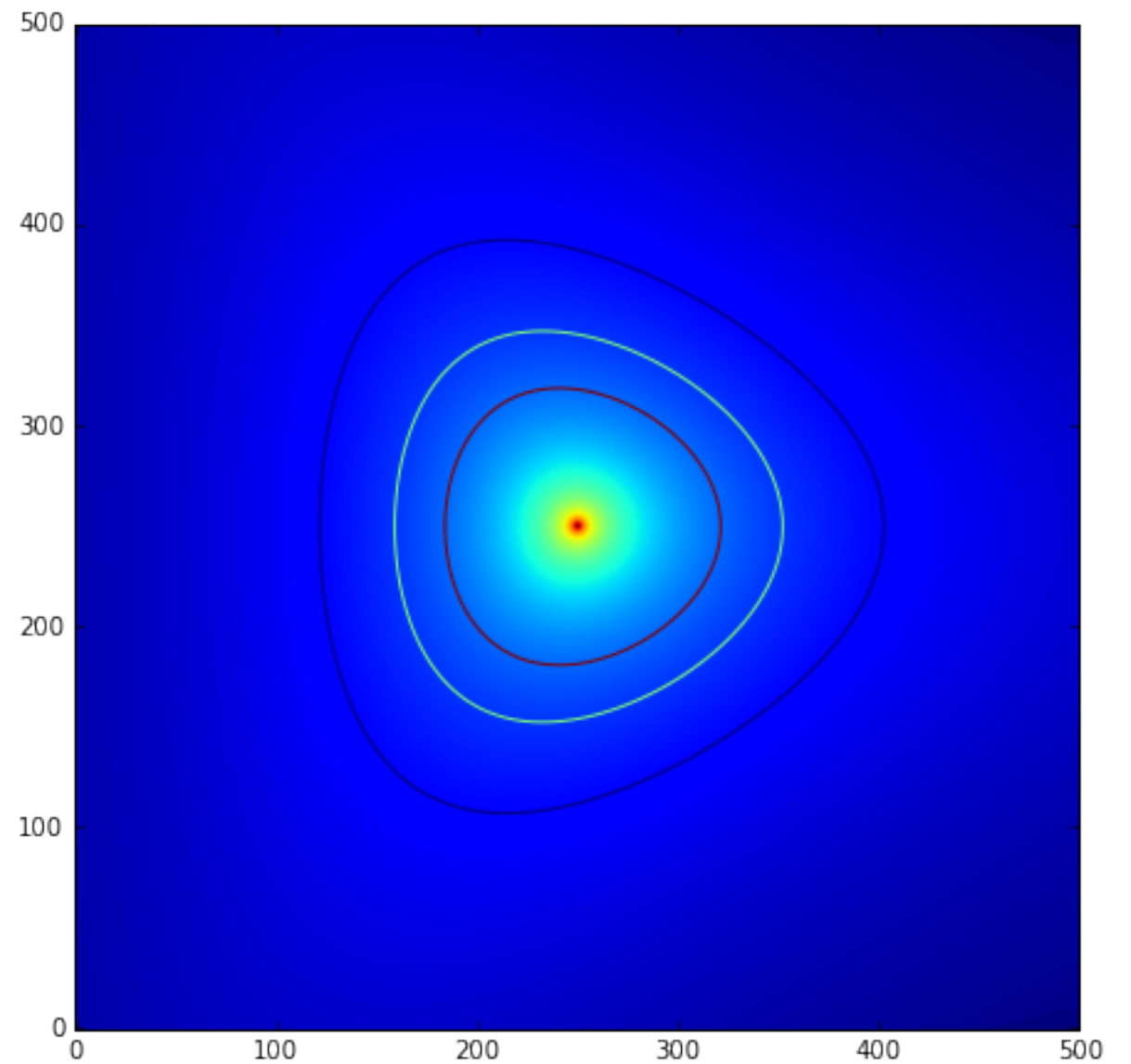
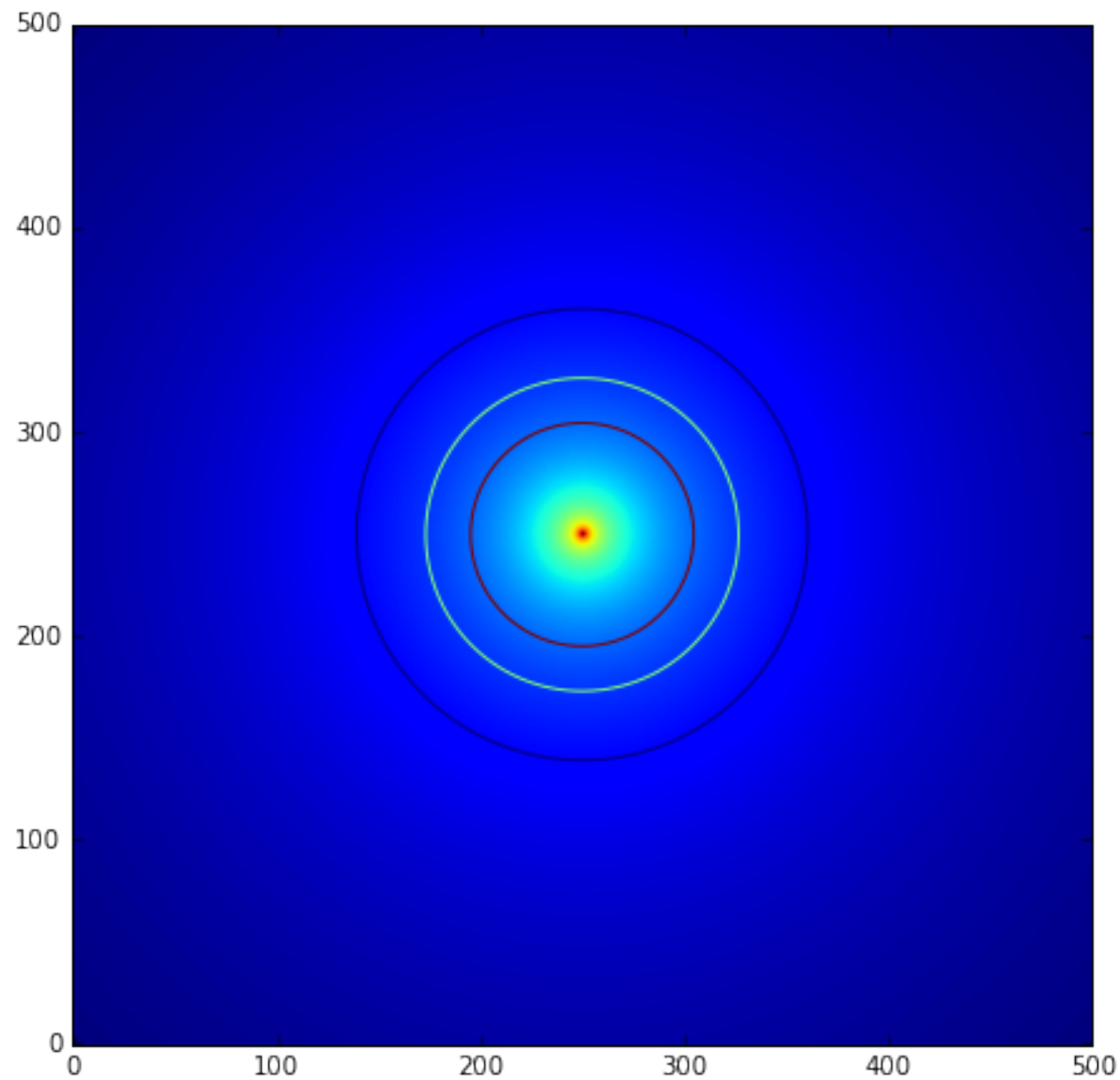


$$F_1=0 \quad G_1=0$$

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# SECOND ORDER DISTORTIONS OF A CIRCULAR SOURCE

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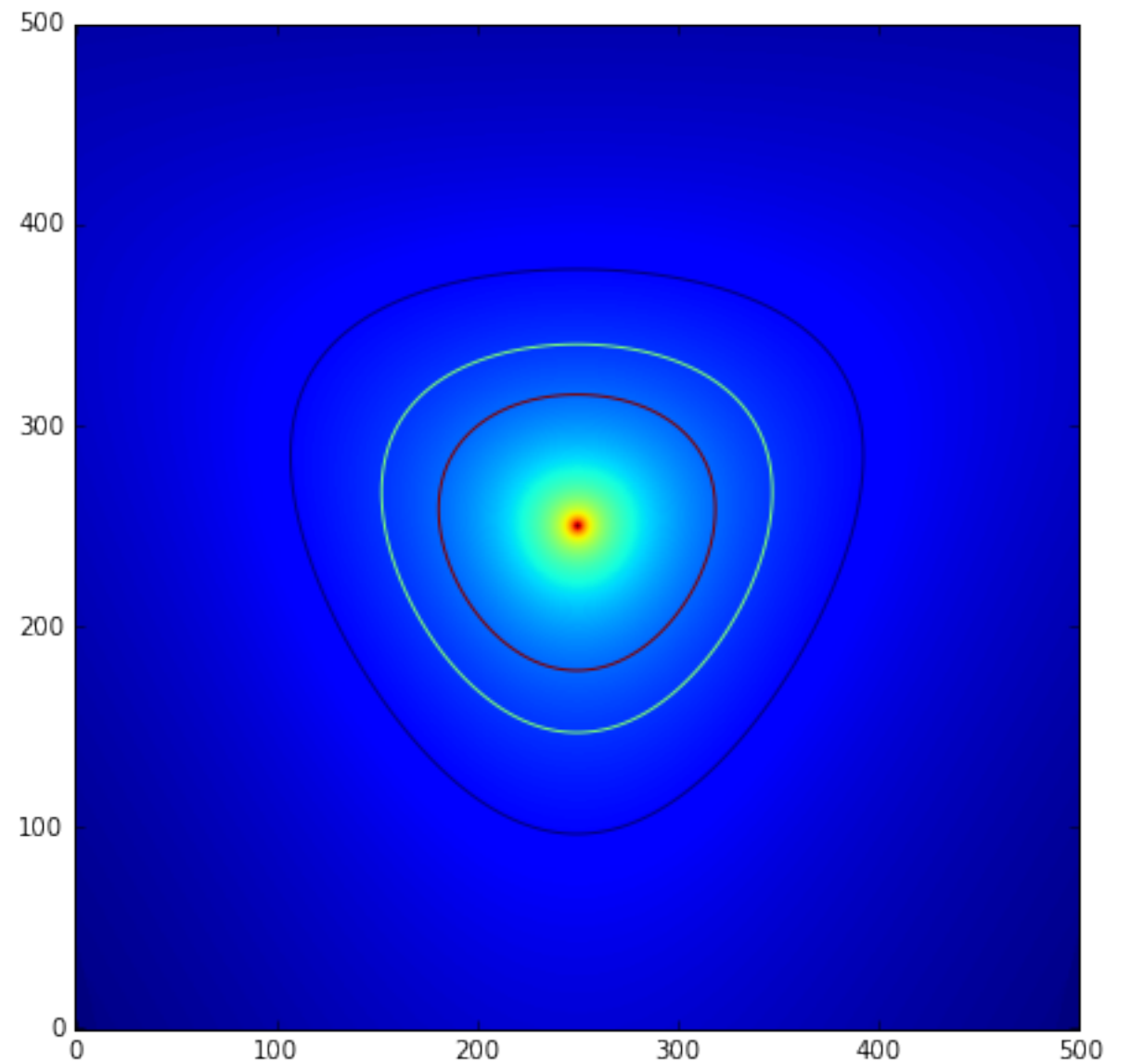
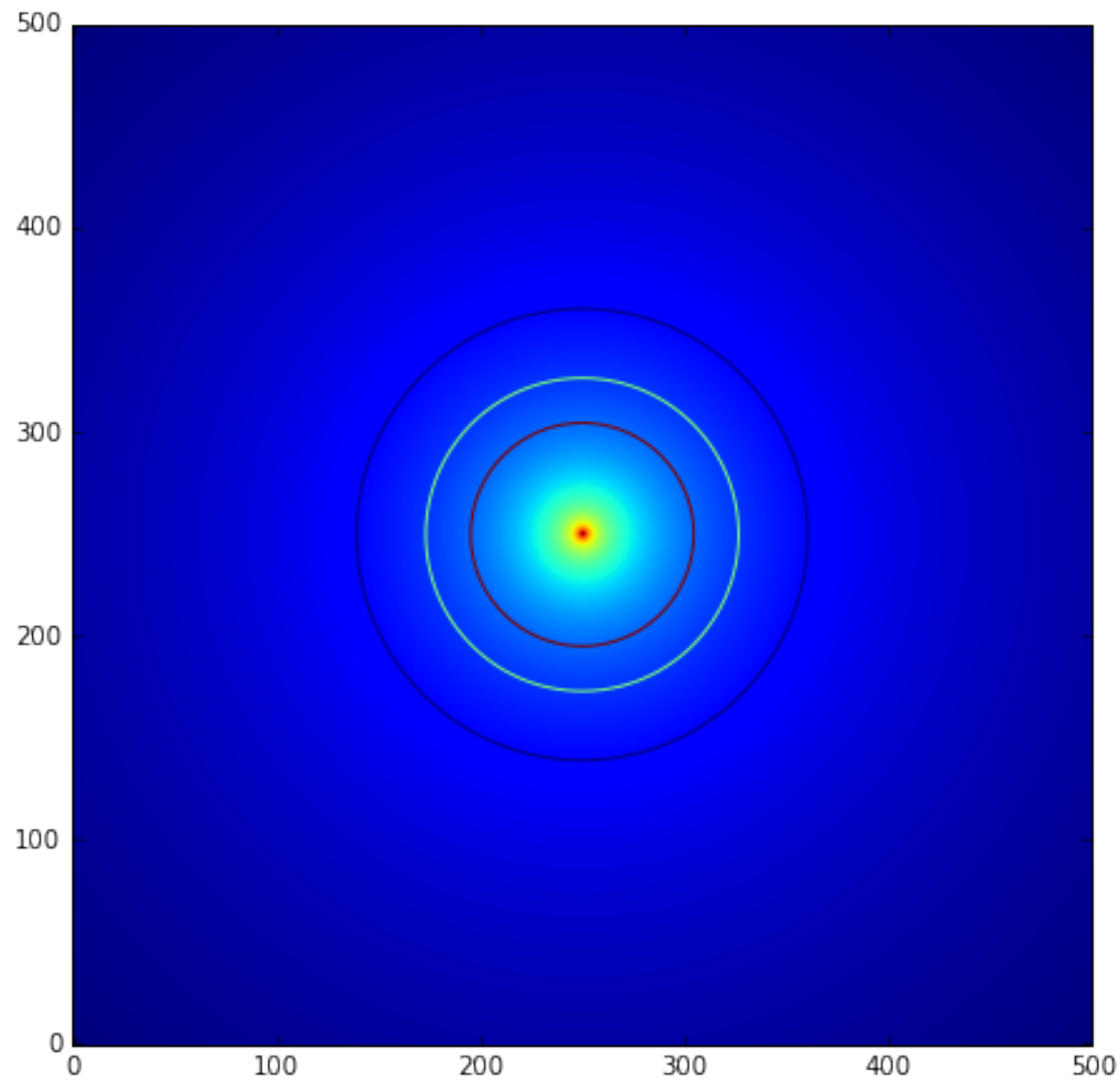


$$F_1=0 \quad G_1=0.5$$

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# SECOND ORDER DISTORTIONS OF A CIRCULAR SOURCE

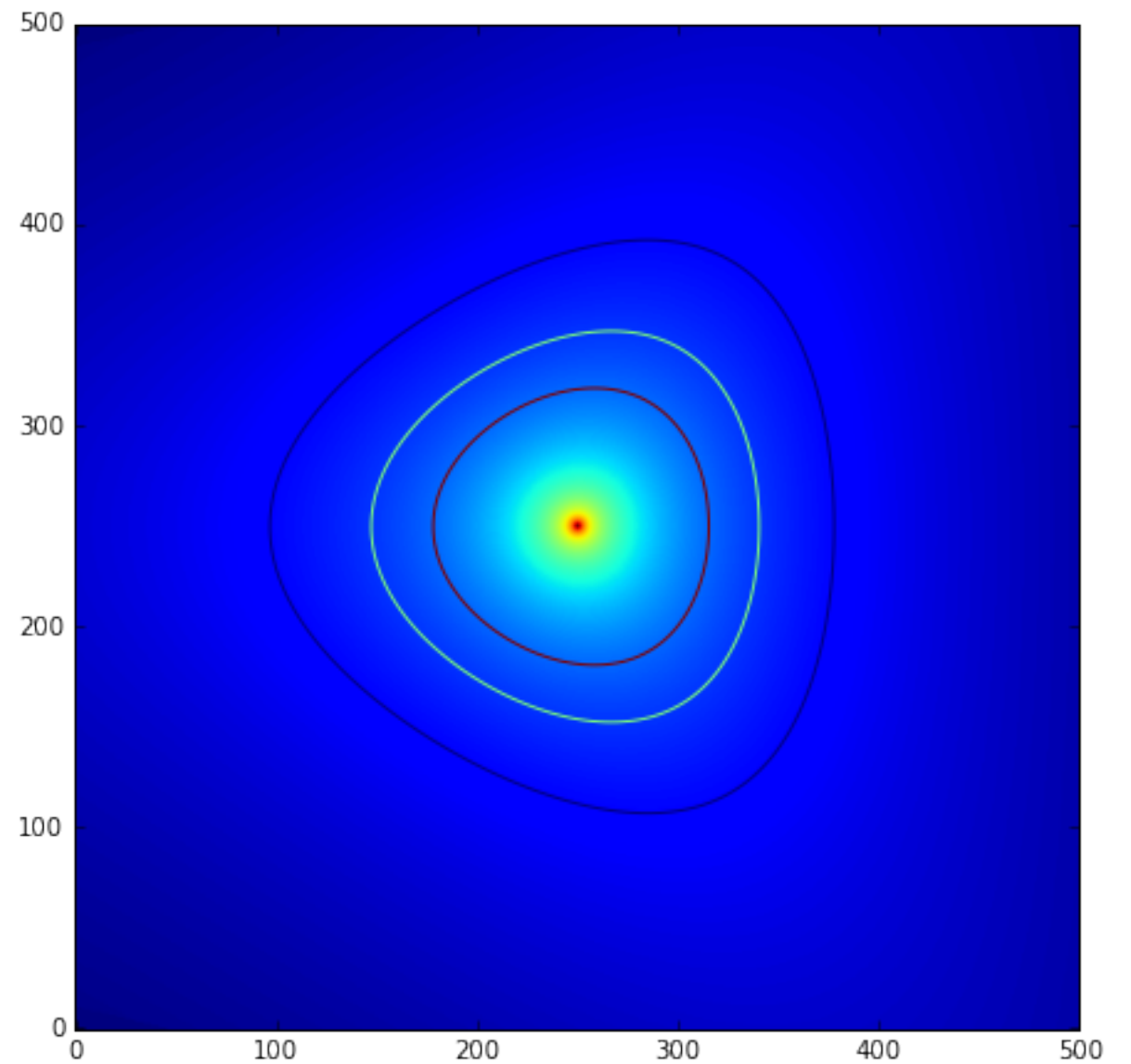
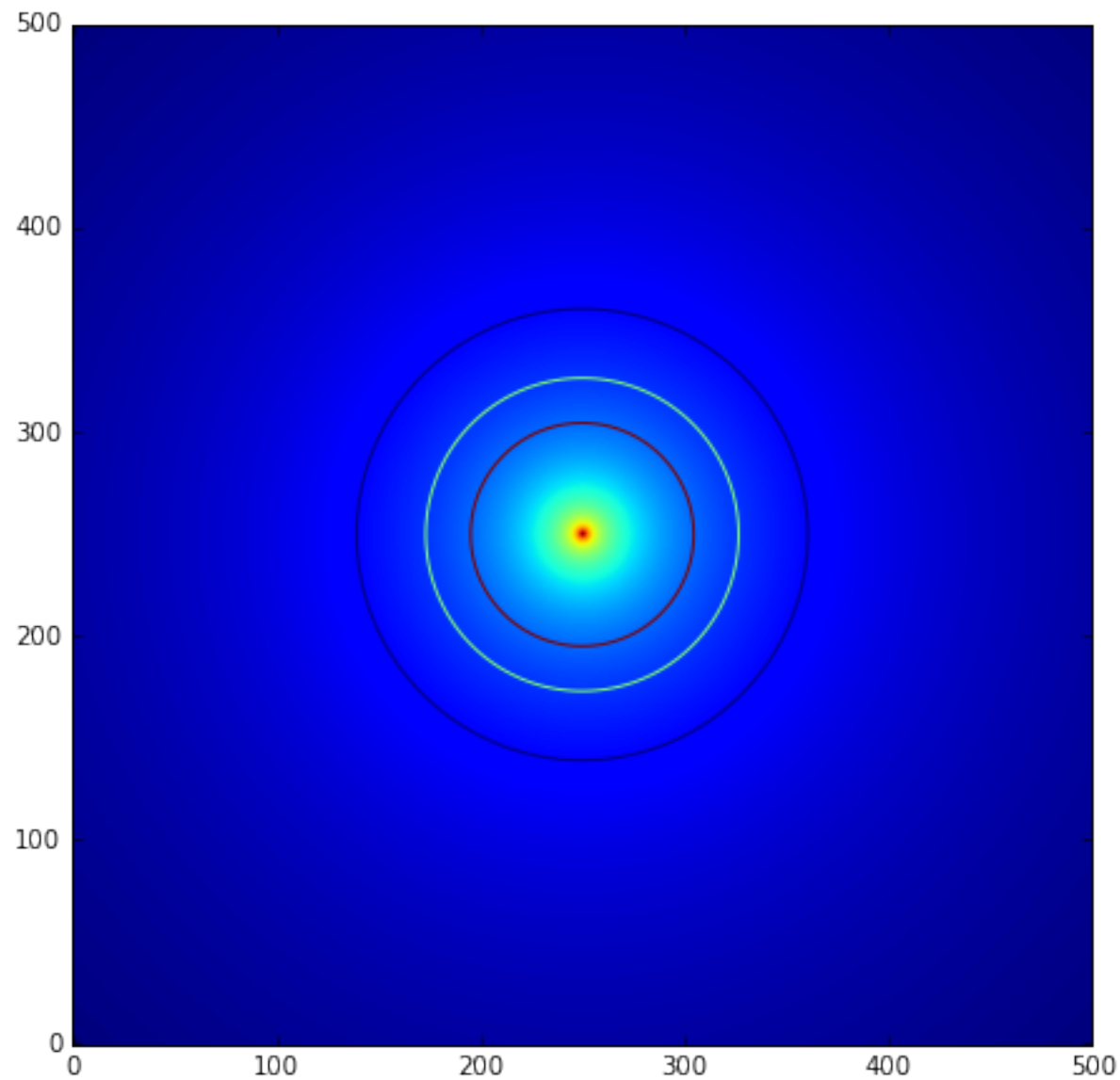
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$$\begin{array}{ll} F_1=0 & G_1=0 \\ F_2=0 & G_2=0.5 \end{array}$$

# SECOND ORDER DISTORTIONS OF A CIRCULAR SOURCE

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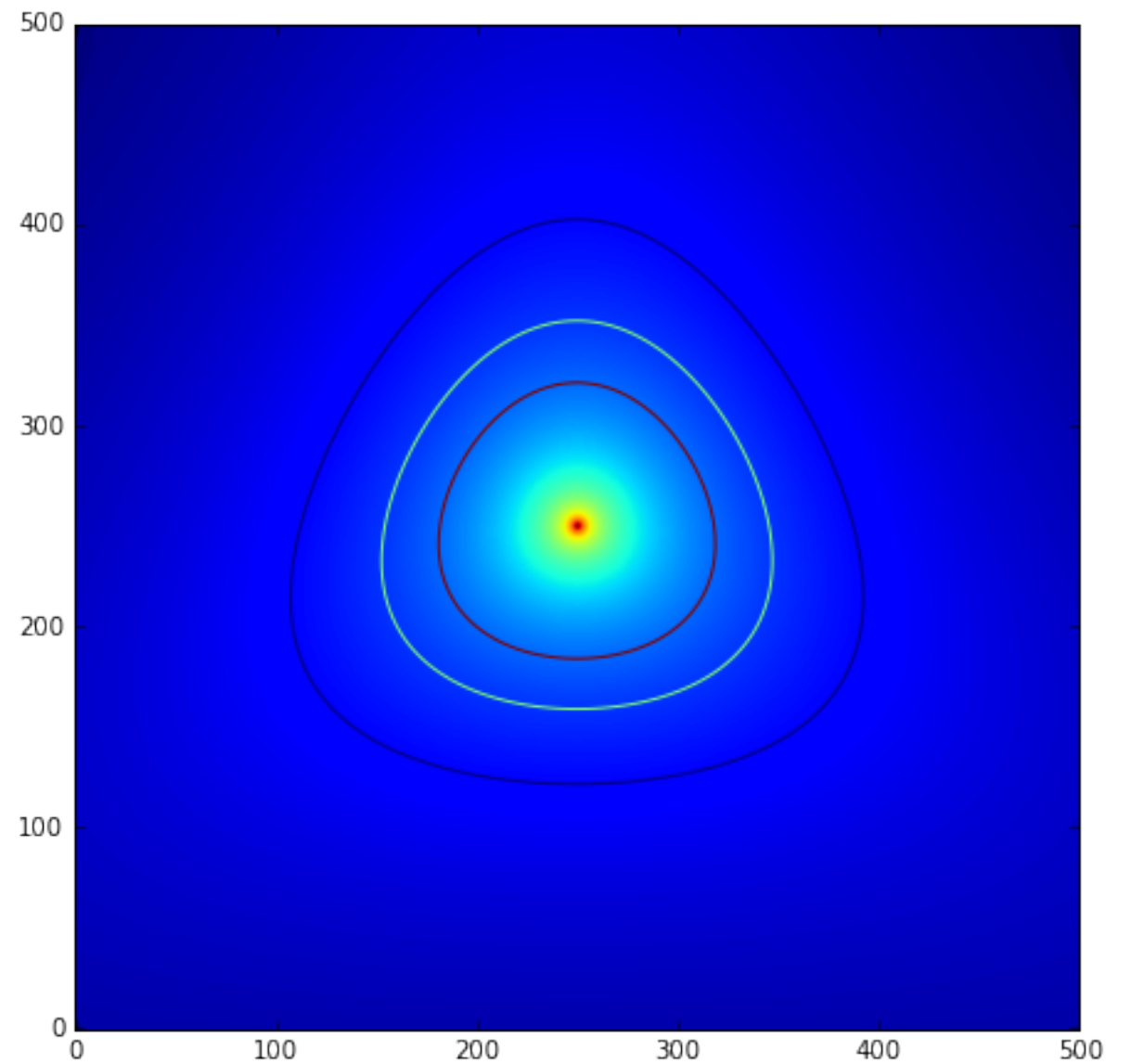
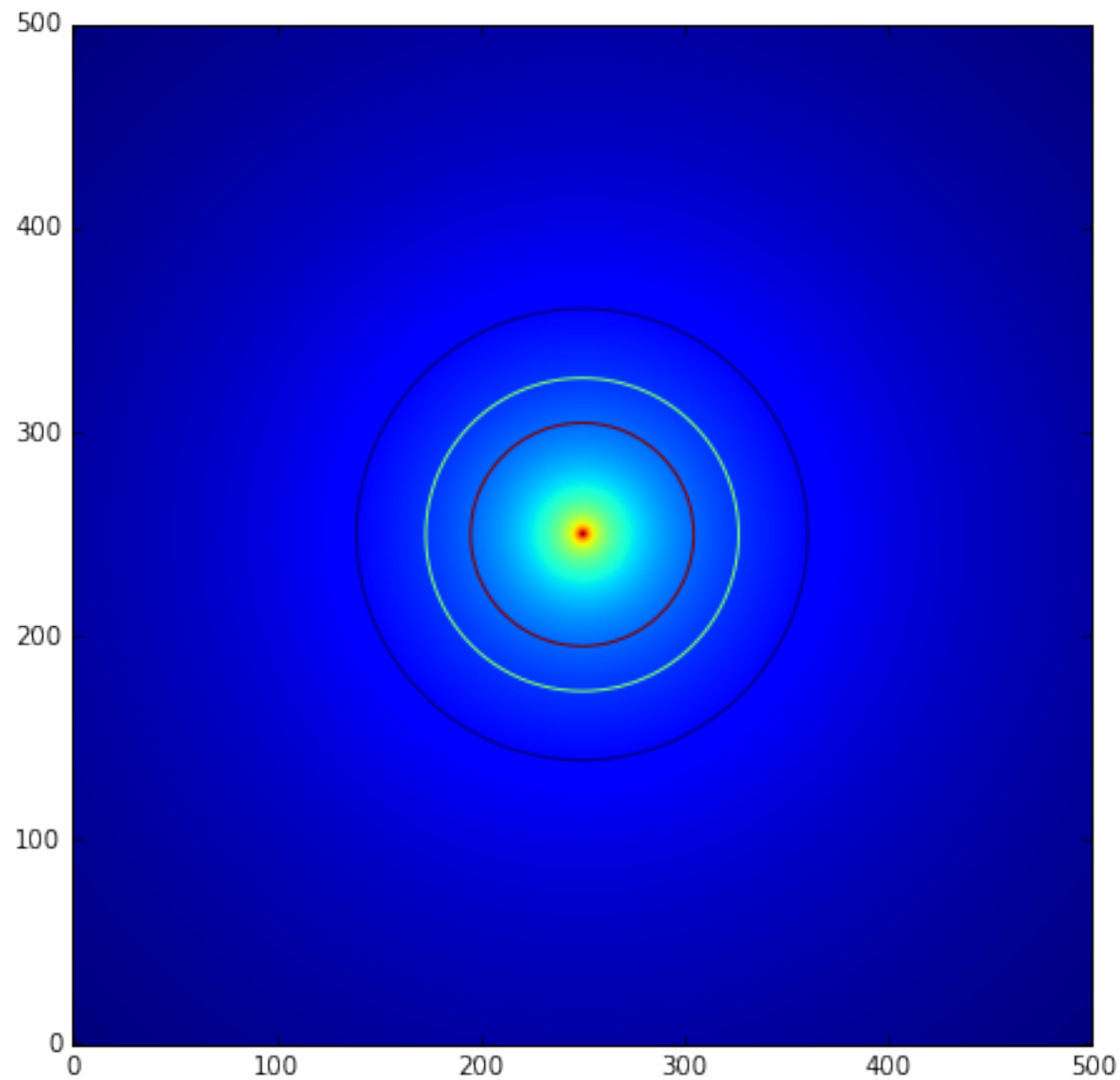


$$F_1=0 \quad G_1=-0.5$$

$$F_2=0 \quad G_2=0$$

# SECOND ORDER DISTORTIONS OF A CIRCULAR SOURCE

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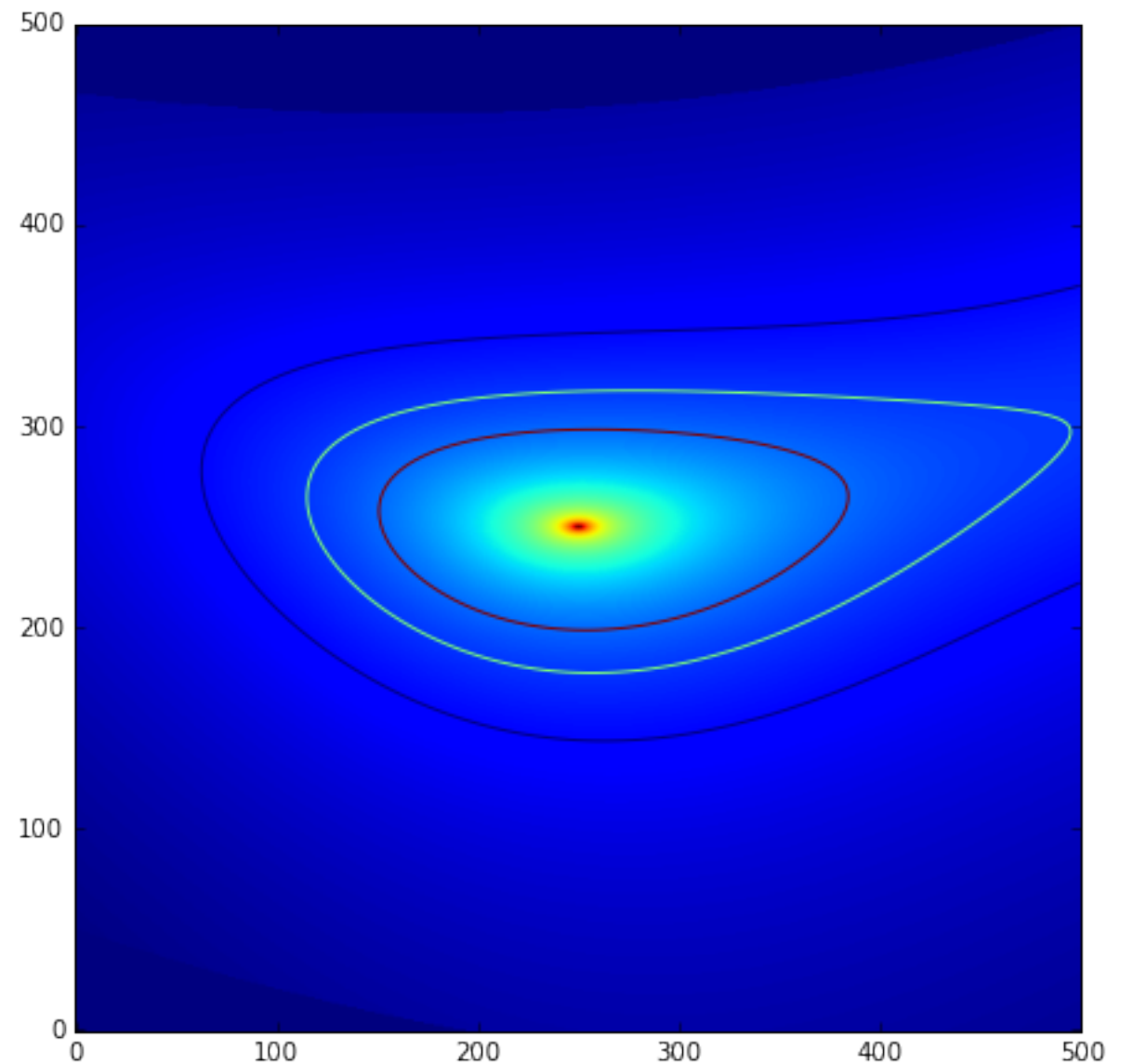
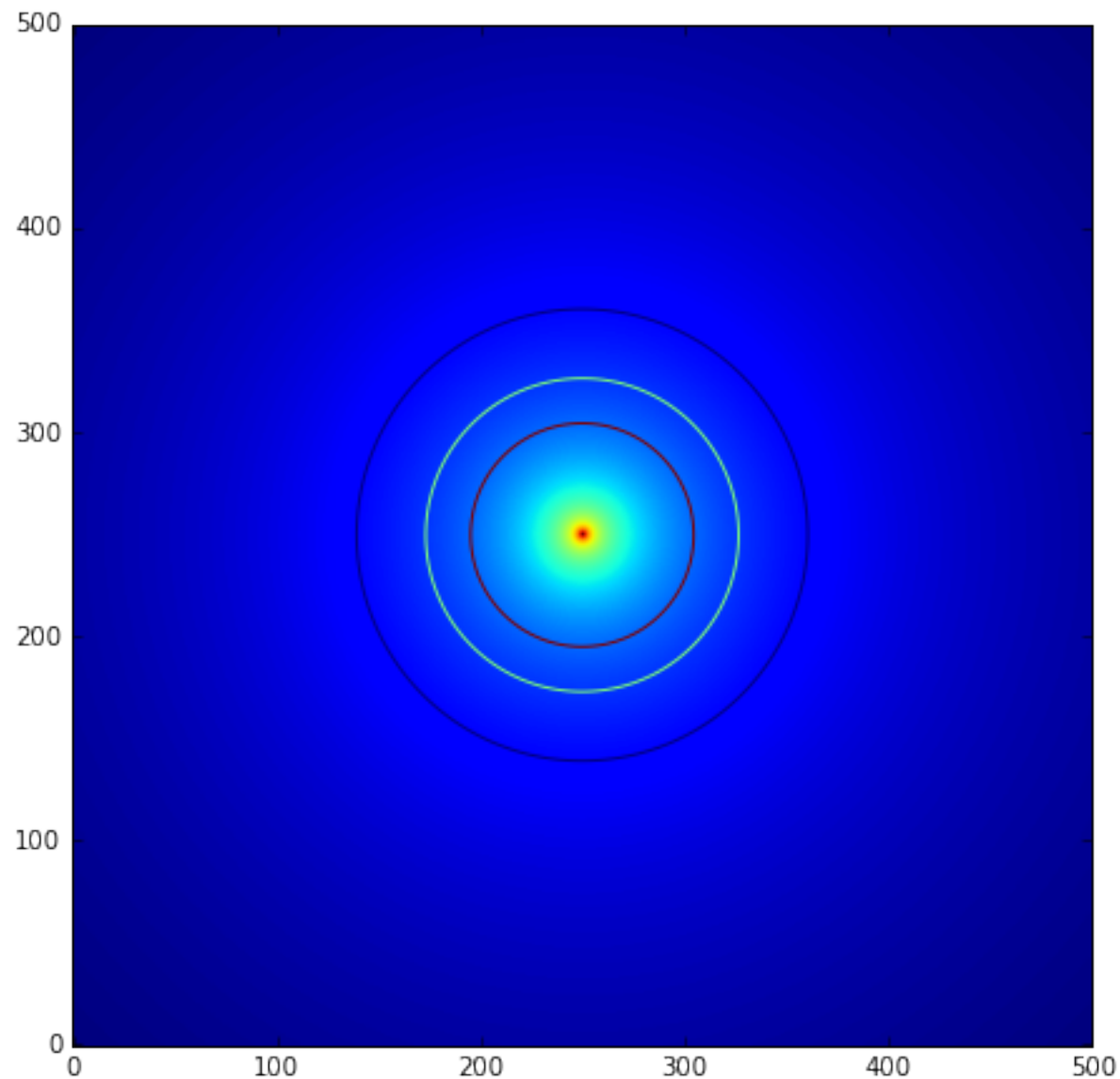


$$\begin{array}{ll} F_1 = 0 & G_1 = 0 \\ F_2 = 0 & G_2 = -0.5 \end{array}$$



# SECOND ORDER DISTORTIONS OF A CIRCULAR SOURCE

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$$\begin{array}{lll} \gamma_1 = 0.3 & F_1 = 0.2 & G_1 = 0 \\ \gamma_2 = 0 & F_2 = 0 & G_2 = 0.5 \end{array}$$



# GRAVITATIONAL TIME DELAY

---

*In Lecture 1:*  $n = 1 - \frac{2\Phi}{c^2}$

$$t_{\text{grav}} = \int \frac{dz}{c'} - \int \frac{dz}{c} = \frac{1}{c} \int (n - 1) dz = -\frac{2}{c^3} \int \Phi dz$$

*Remember that*  $\hat{\Psi}(\vec{\theta}) = \frac{D_{\text{LS}}}{D_{\text{L}} D_{\text{S}}} \frac{2}{c^2} \int \Phi(D_{\text{L}} \vec{\theta}, z) dz$

*Therefore,*  $t_{\text{grav}} = -\frac{D_{\text{L}} D_{\text{LS}}}{D_{\text{S}}} \frac{1}{c} \hat{\Psi}$

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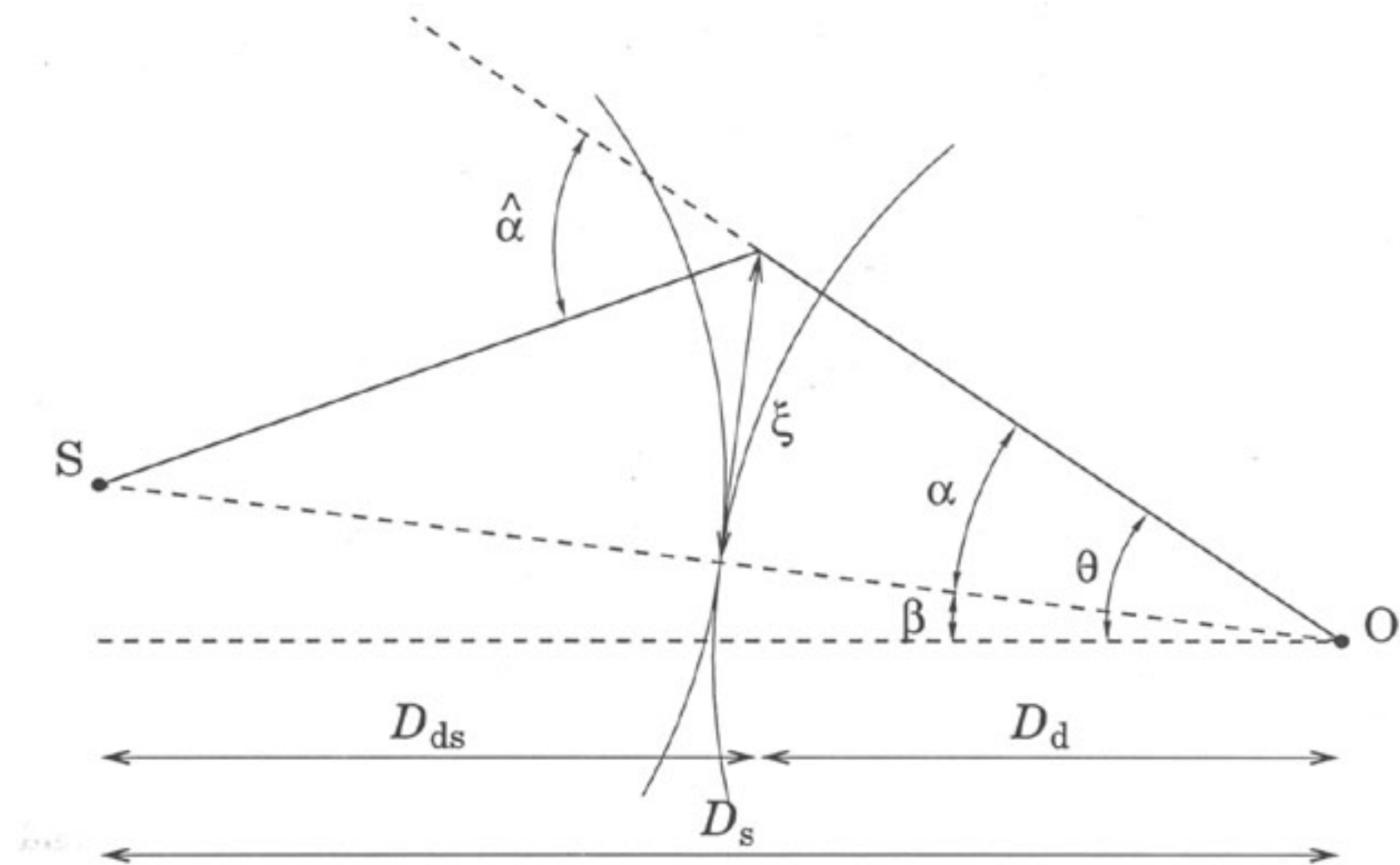
*Therefore,*  $t_{\text{grav}} = -\frac{D_{\text{L}} D_{\text{LS}}}{D_{\text{S}}} \frac{1}{c} \hat{\Psi}$



*Integrating along the line of sight!*

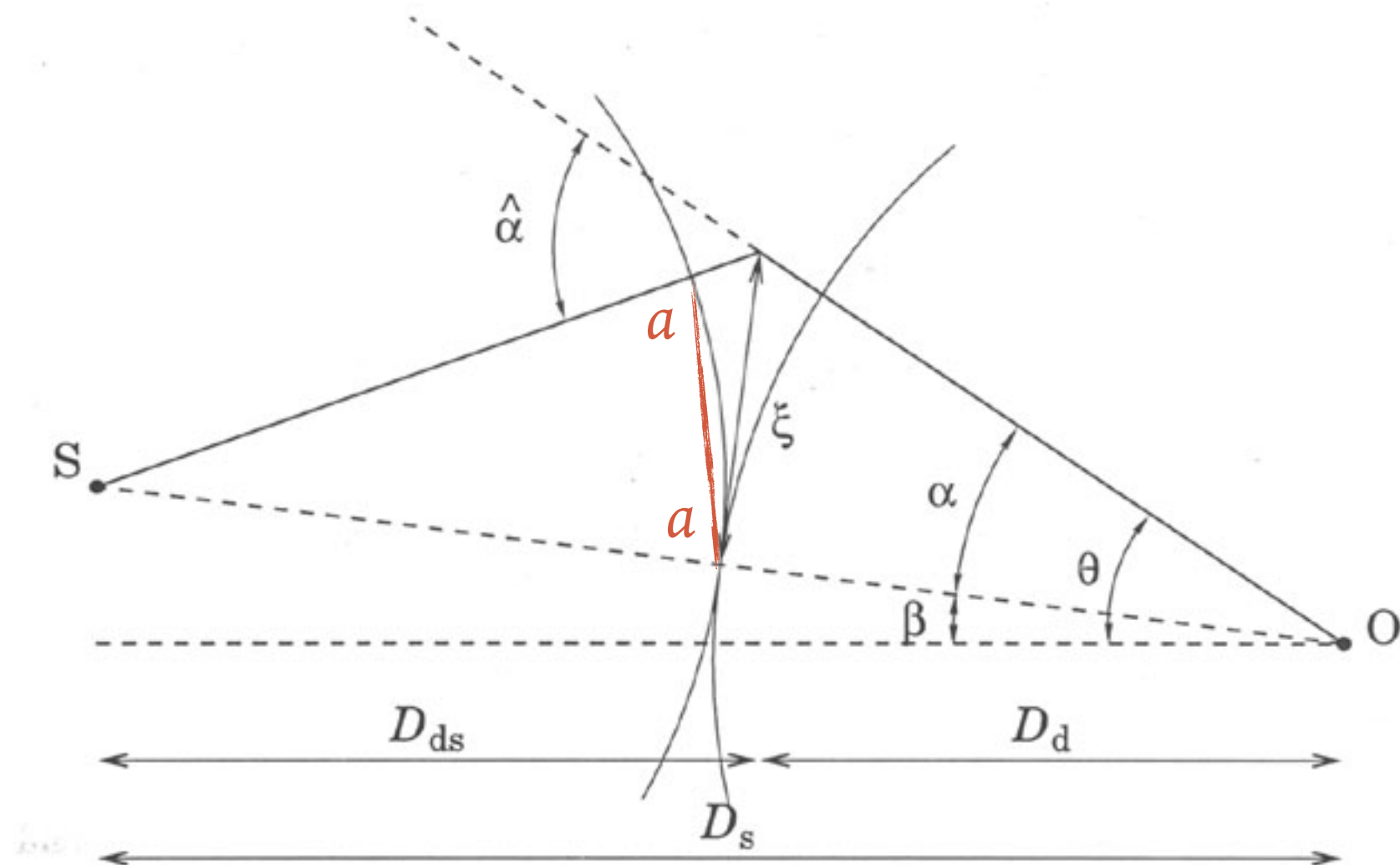
# GEOMETRICAL TIME DELAY

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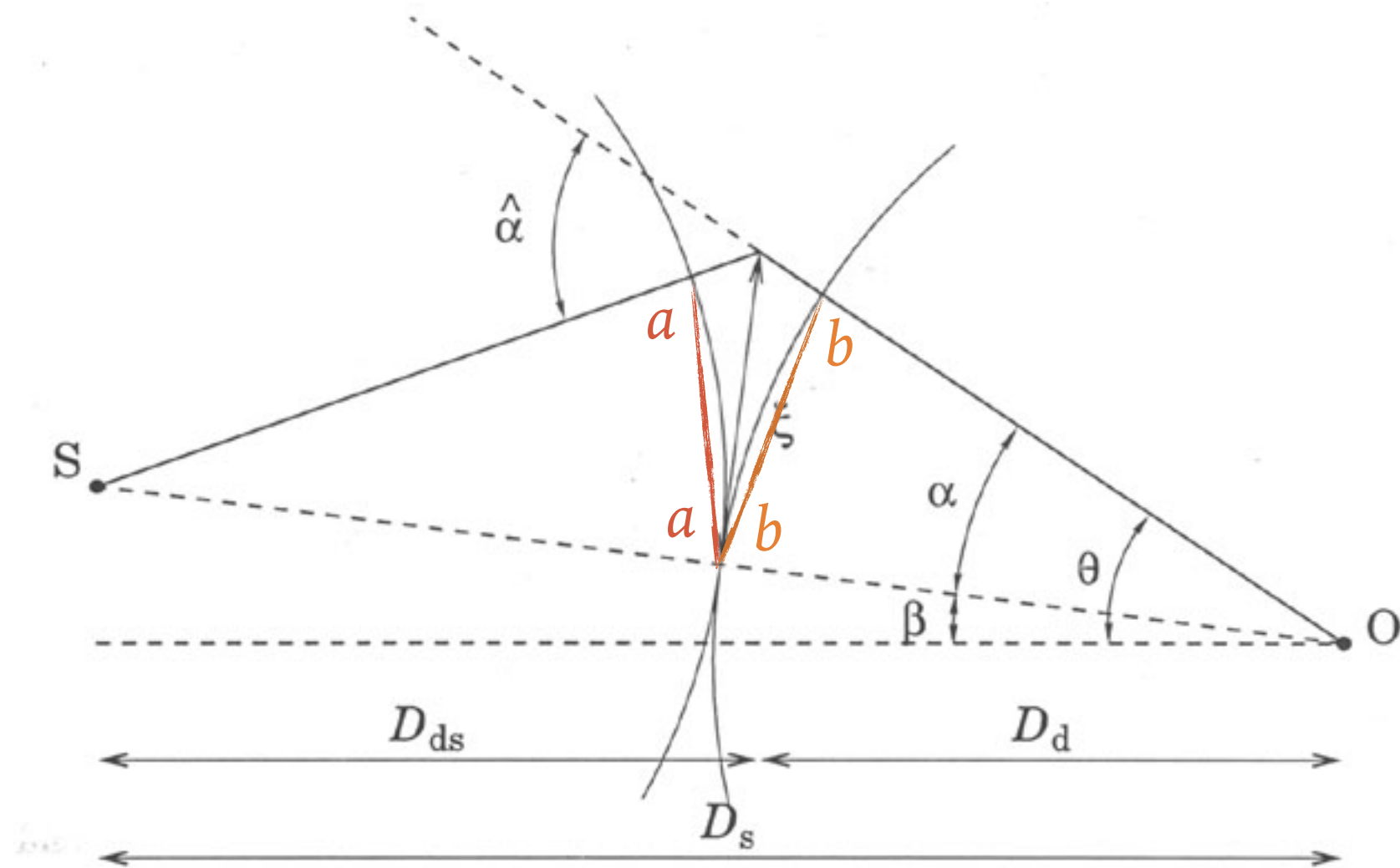
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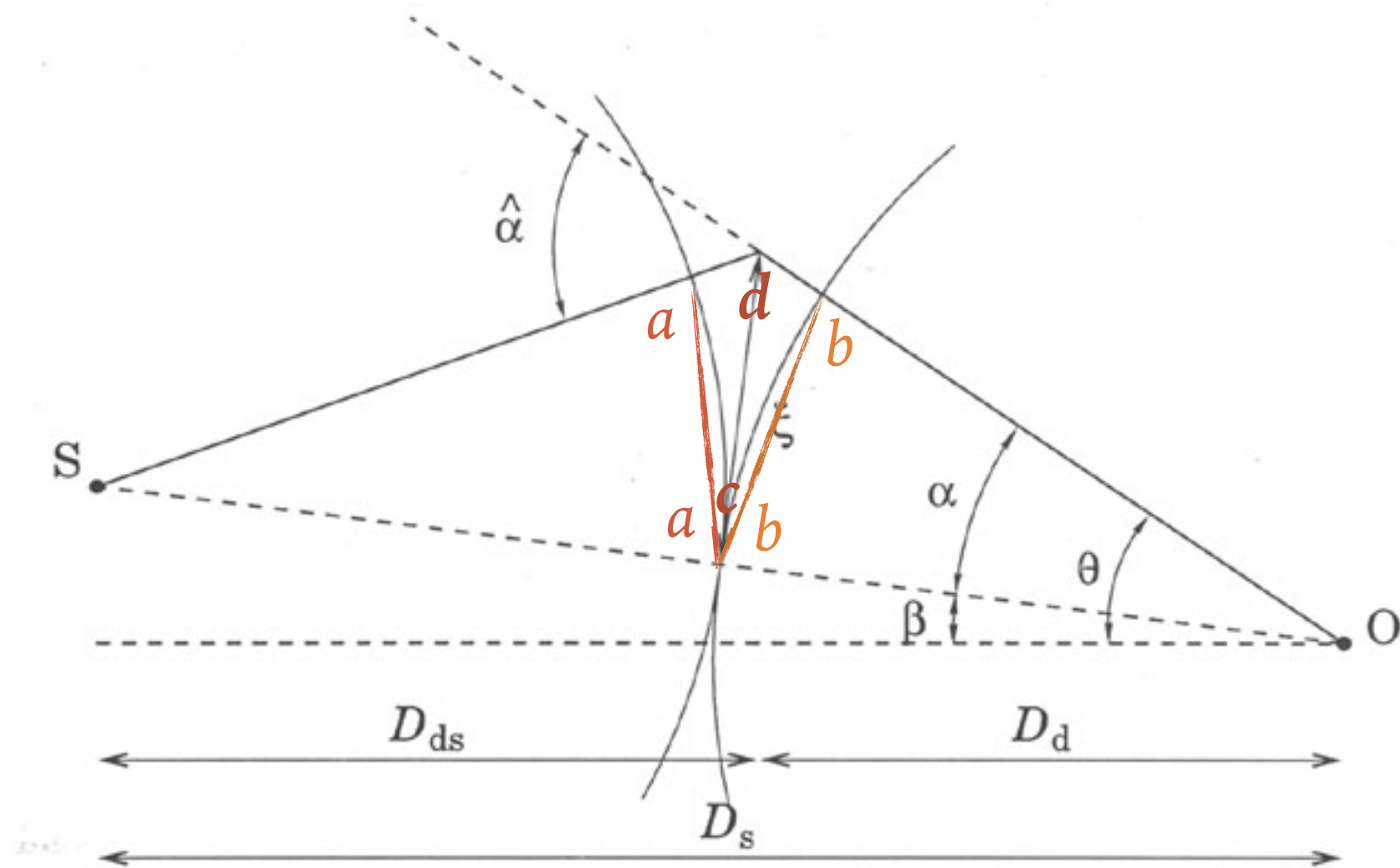
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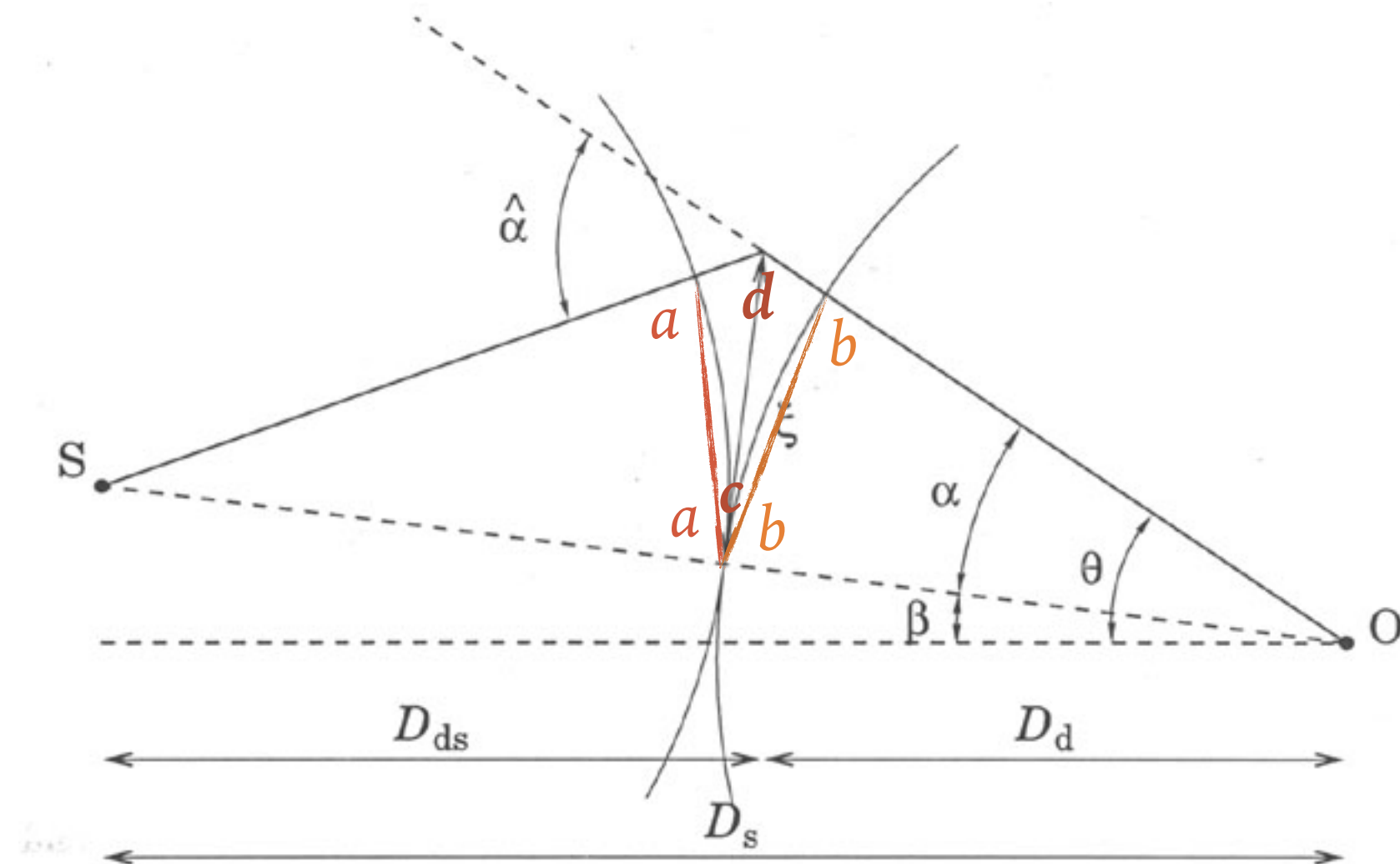


# GEOMETRICAL TIME DELAY

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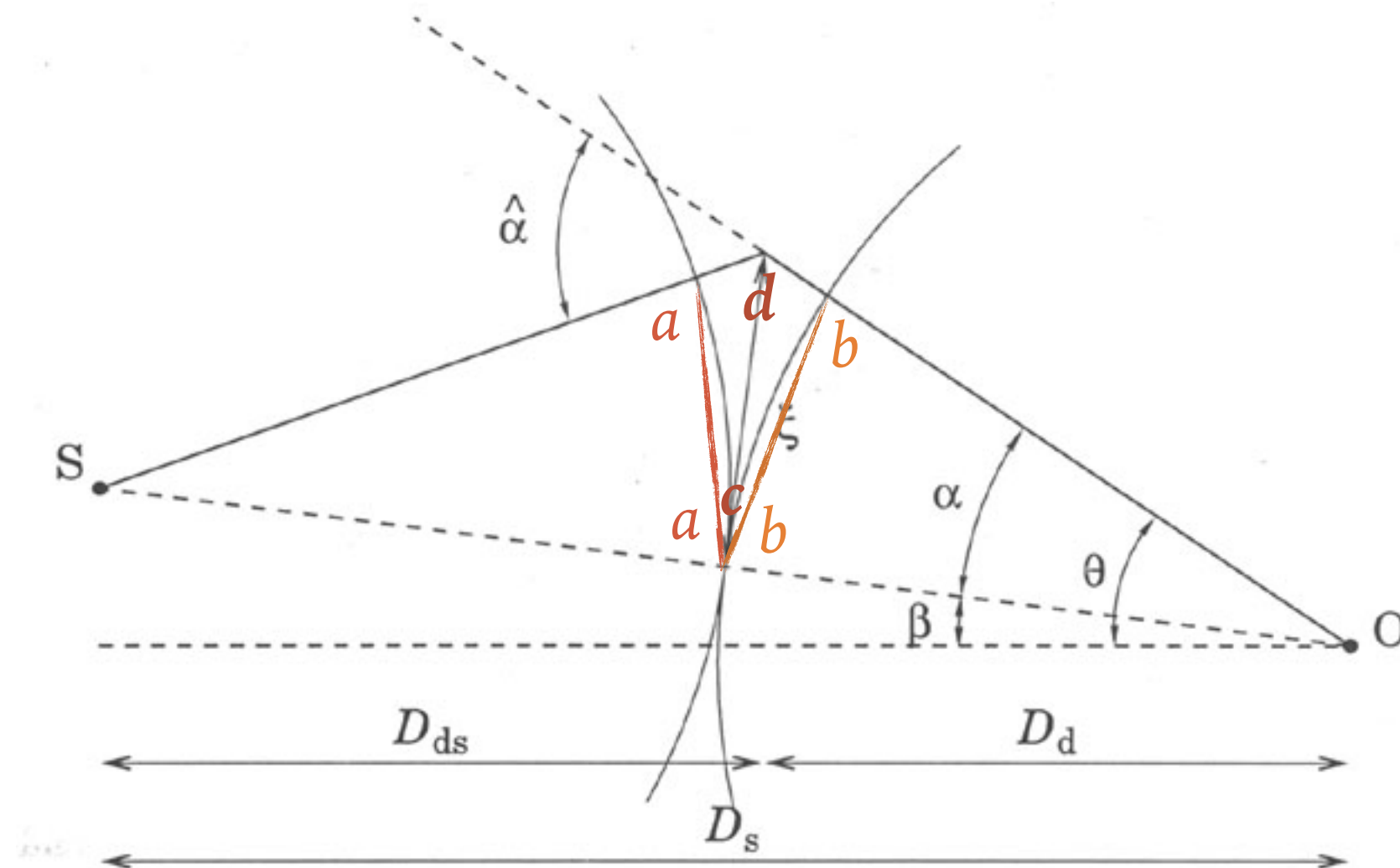
# GEOMETRICAL TIME DELAY



$$c + d + \pi - a + \pi - b = 2\pi$$

$$\Rightarrow c + d = a + b$$

# GEOMETRICAL TIME DELAY



$$c + d + \pi - a + \pi - b = 2\pi$$

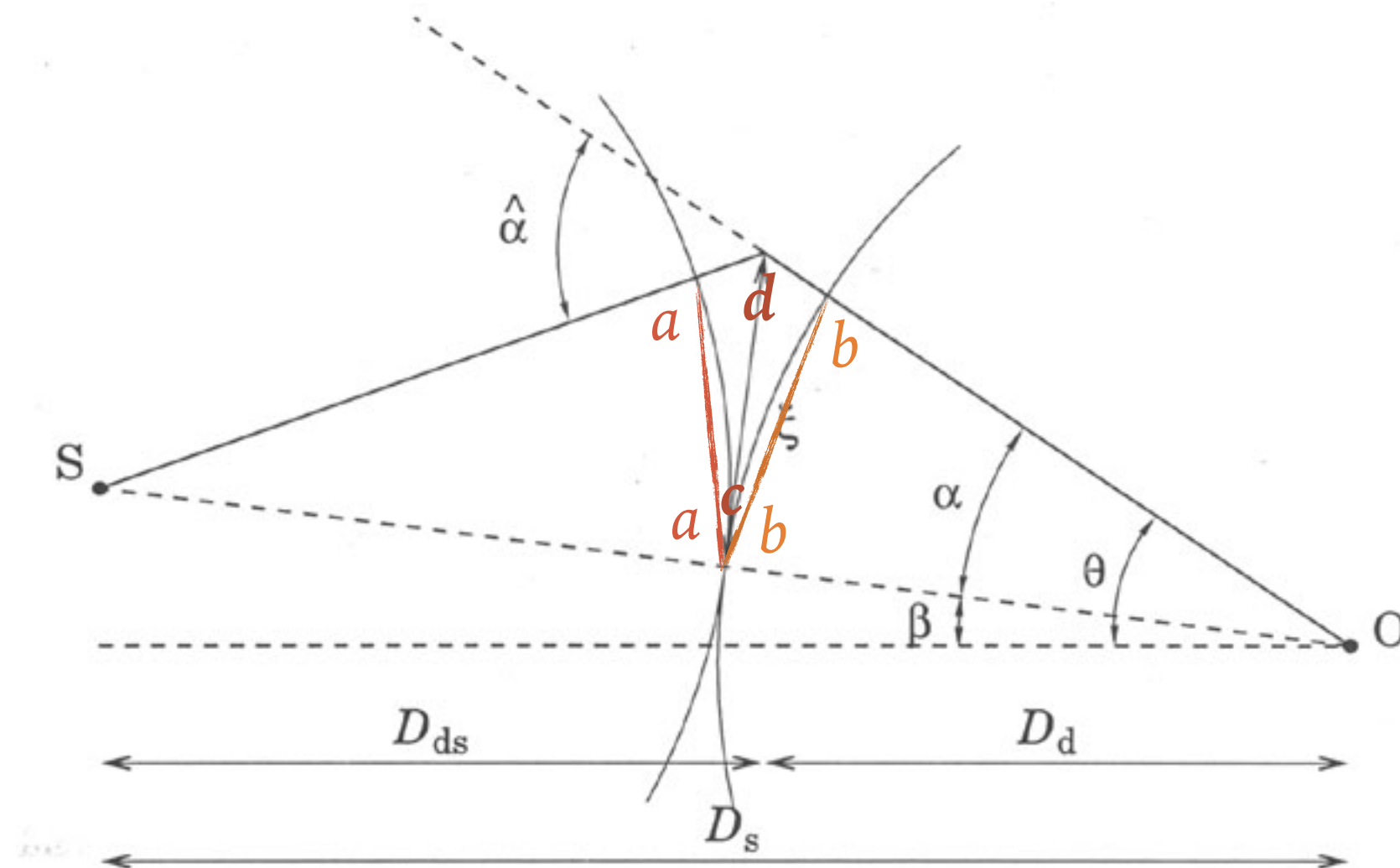
$$\Rightarrow c + d = a + b$$

$$d + \hat{\alpha} = \pi$$

$$\Rightarrow d = \pi - \hat{\alpha}$$



# GEOMETRICAL TIME DELAY



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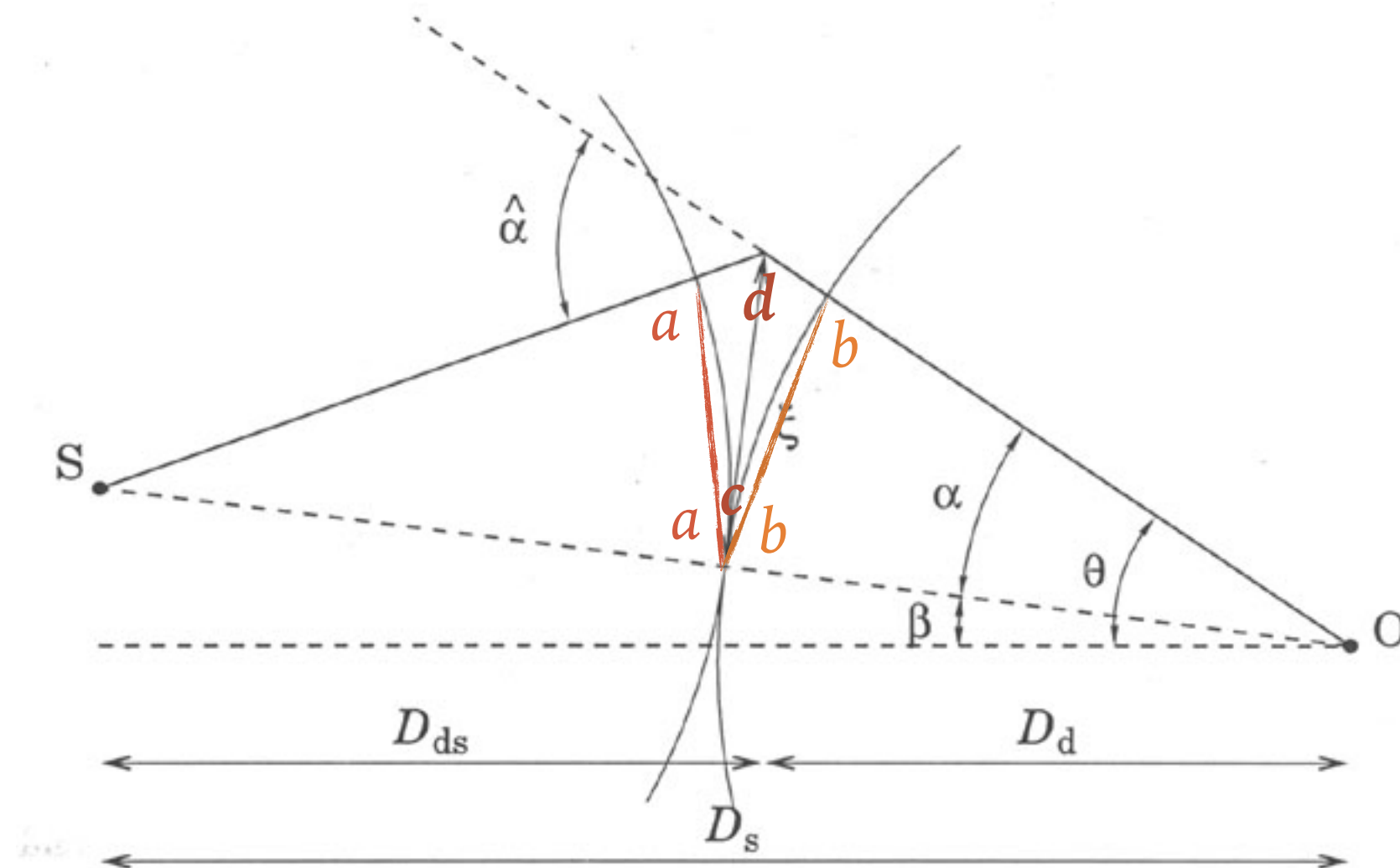
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$$\Rightarrow d = \pi - \hat{\alpha}$$

$$a + b + c = \pi$$

$$\Rightarrow 2c + d = \pi$$

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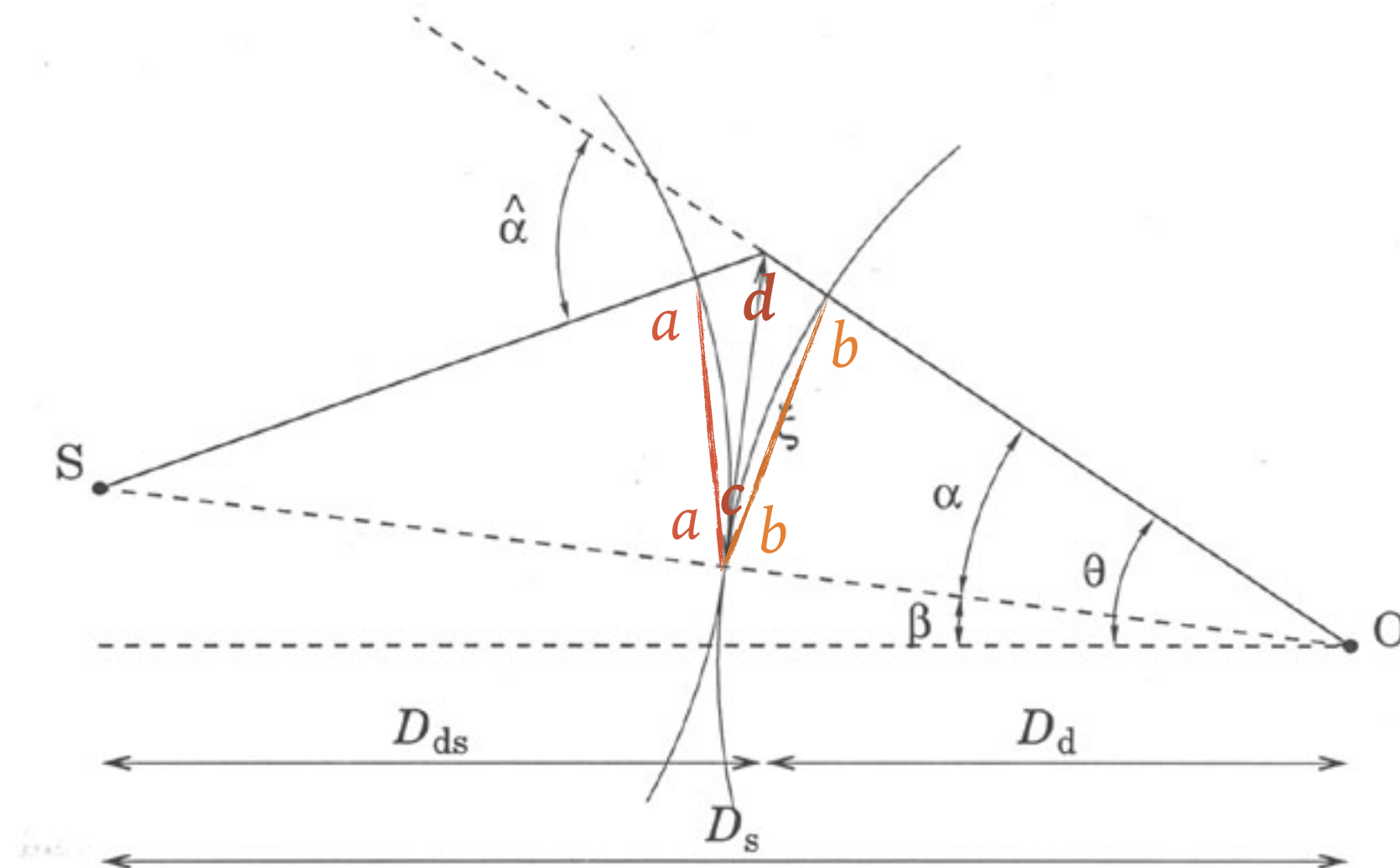
$$\Rightarrow d = \pi - \hat{\alpha}$$

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$$\Rightarrow c = \frac{\hat{\alpha}}{2}$$

# GEOMETRICAL TIME DELAY



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$$\Rightarrow d = \pi - \hat{\alpha}$$

$$a + b + c = \pi$$

$$\Rightarrow 2c + d = \pi$$

$$\Rightarrow c = \frac{\hat{\alpha}}{2}$$

$$\Delta l = \xi \frac{\hat{\alpha}}{2} = (\vec{\theta} - \vec{\beta}) \frac{D_L D_{LS}}{D_S} \frac{\vec{\alpha}}{2} = (\vec{\theta} - \vec{\beta})^2 \frac{D_L D_{LS}}{2D_S}$$

# TIME DELAY SURFACE

---

$$t(\vec{\theta}) = t_{geom} + t_{grav} \propto \left( \frac{1}{2} (\vec{\theta} - \vec{\beta})^2 - \hat{\Psi} \right)$$

$$\vec{\nabla} t(\vec{\theta}) \propto \left( \vec{\theta} - \vec{\beta} - \vec{\nabla} \hat{\Psi} \right)$$

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*Lens equation!*

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*Lens equation!*



*Images form at the stationary points of  $t$ !*

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*Lens equation!*



*Images form at the stationary points of  $t$ !*

$$T_{ij} = \frac{\partial^2 t(\vec{\theta})}{\partial \theta_i \partial \theta_j} \propto (\delta_{ij} - \Psi_{ij})$$

# HESSIAN OF THE TIME DELAY SURFACE

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