GRAVITATIONAL LENSING

8 - MICROLENSING

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MICROLENSING

- ➤ Microlensing is a lensing regime which include effects produced by a broad range of masses: from planets to ensembles of stars
- ➤ given the small sizes of the lens, these are (to first-order) assimilated to point masses.
- ➤ microlensing effects are mostly detectable and searched within our own galaxy, in particular by monitoring huge amounts of stars in the bulge of the MW or in the Magellanic Clouds
- ➤ nevertheless, microlensing effects are important also in extragalactic lenses. Small masses in distant galaxies, for example, introduce perturbations to the lensing signal of their hosts

THE POINT MASS LENS MODEL

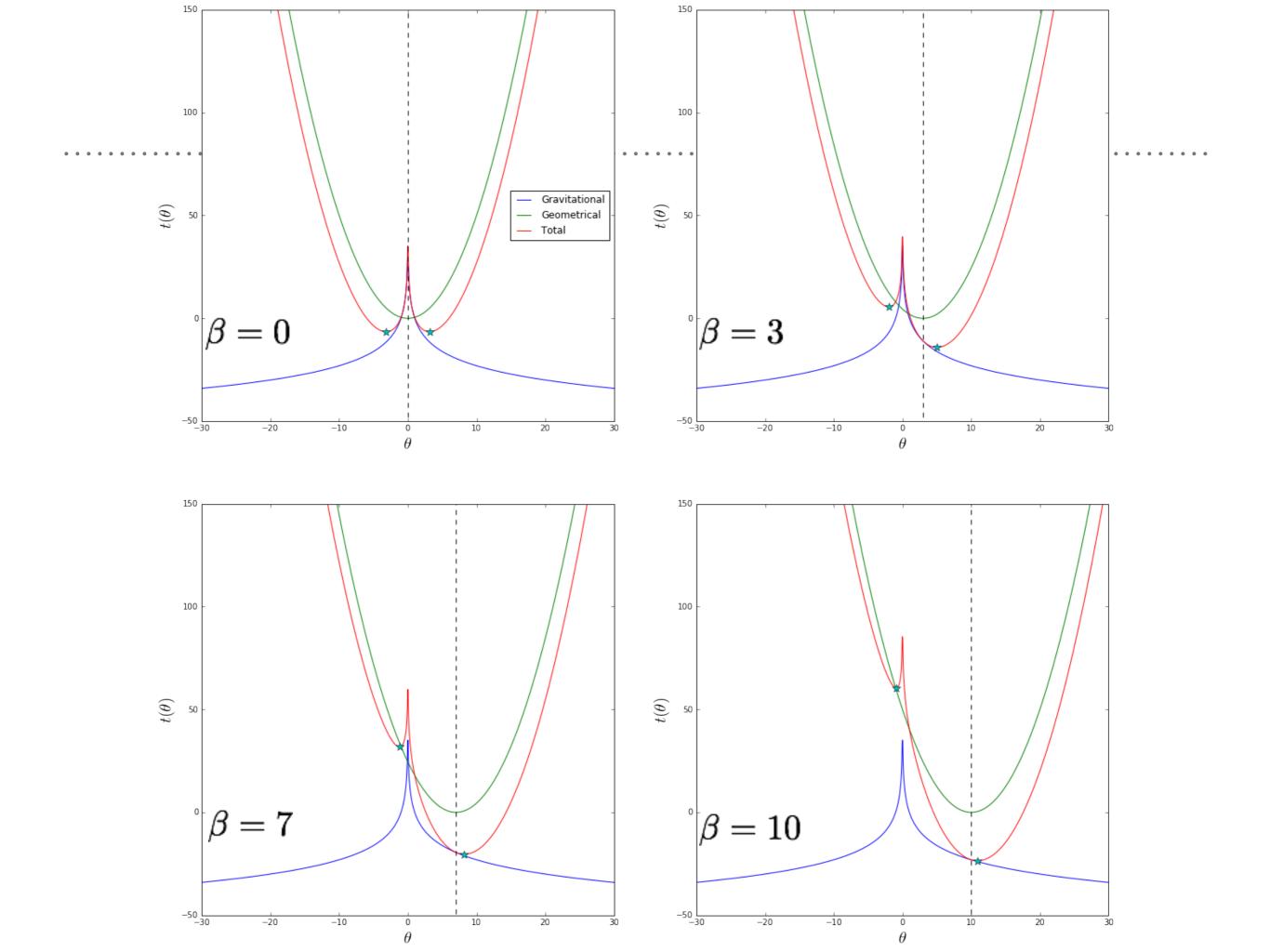
- ➤ The deflection angle of the point mass lens was derived in the first lecture
- ➤ the lensing potential can be readily derived

$$\hat{\vec{\alpha}} = \frac{4GM}{c^2} \frac{\vec{\xi}}{|\vec{\xi}|^2} = \frac{4GM}{c^2 D_{\rm L}} \frac{\vec{\theta}}{|\vec{\theta}|^2}$$

$$ec{lpha} = rac{D_{\mathrm{LS}}}{D_{\mathrm{S}}} \hat{ec{lpha}} = ec{
abla} \hat{\Psi}$$

$$abla \ln |ec{x}| = rac{ec{x}}{|ec{x}|^2}$$

$$\hat{\Psi}(ec{ heta}) = rac{4GM}{c^2} rac{D_{\mathrm{LS}}}{D_{\mathrm{L}}D_{\mathrm{S}}} \ln |ec{ heta}|$$



LENS EQUATION

- ➤ the deflection angle always points away from the lens
- given the symmetry of the lens, we can omit the vector notation in most equations
- > the lens equation reads:
- \triangleright this is clearly quadratic in θ
- so, for each source there are two images, whose positions can be determined by solving the lens equation

$$\hat{\pmb{lpha}} = rac{4GM}{c^2 \pmb{\xi}} = rac{4GM}{c^2 D_{
m L} \pmb{ heta}}$$

$$eta = heta - rac{4GM}{c^2 D_{
m L} heta} rac{D_{
m LS}}{D_{
m S}}$$

SOLUTIONS OF THE LENS EQUATION

- we introduce the Einstein radius:
- by inserting into the lens equation:
- \blacktriangleright if we divide by θ_E , we obtain an a-dimensional form of the lens equation
- ➤ this is a very convenient way of writing the lens equation, because we get rid of all constants.

$$heta_E \equiv \sqrt{rac{4GM}{c^2}rac{D_{
m LS}}{D_{
m L}D_{
m S}}}$$

$$eta = heta - rac{4GM}{c^2 D_{
m L} heta} rac{D_{
m LS}}{D_{
m S}}$$



$$oldsymbol{eta} = oldsymbol{ heta} - rac{oldsymbol{ heta}_E^2}{oldsymbol{ heta}}$$

$$y = x - \frac{1}{x}$$

SOLUTIONS OF THE LENS EQUATION

 $y = x - \frac{1}{x}$

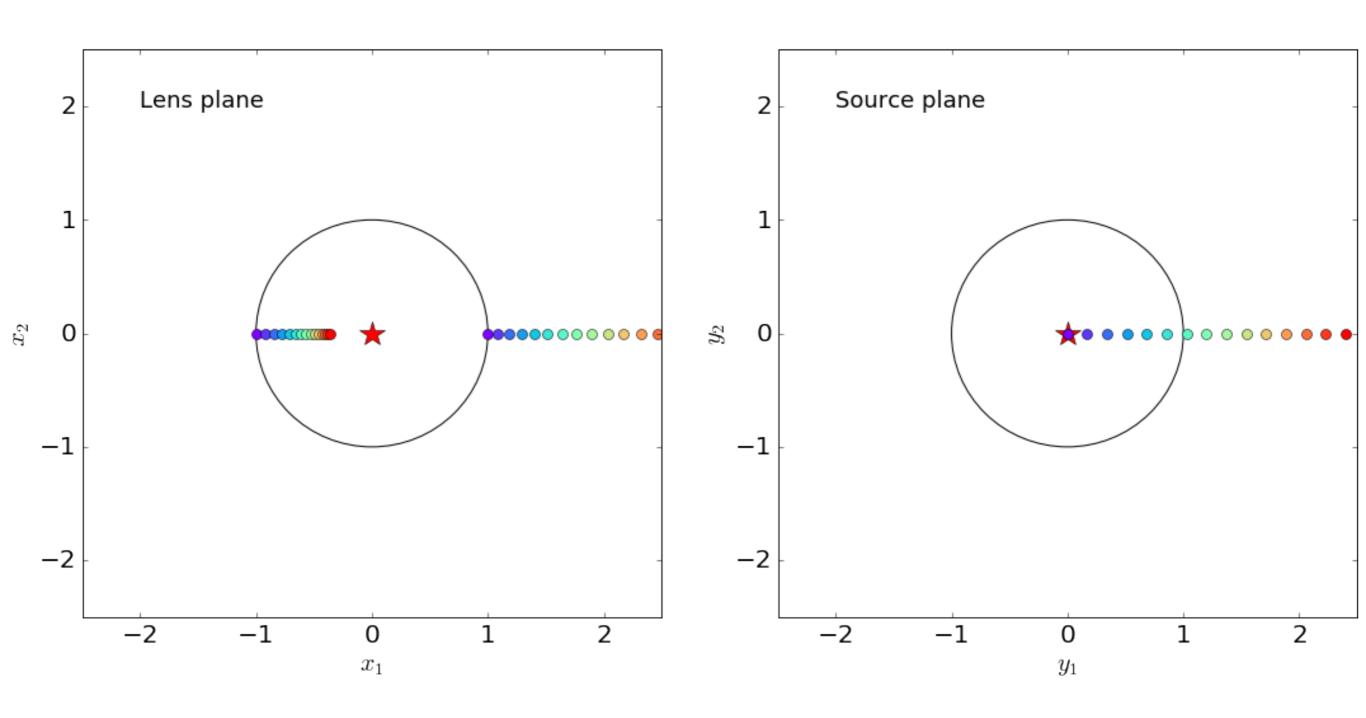


$$x^2 - xy - 1 = 0$$



$$x_{\pm} = \frac{1}{2} \left[y \pm \sqrt{y^2 + 4} \right]$$

SOLUTIONS OF THE LENS EQUATION



PROPERTIES OF THE IMAGES

Lens plane z Source plane z Source

One of the images is internal to the Einstein radius, the other is external

For y=0, the image is a full ring: $x_{\pm}=\pm 1$

This is the Einstein ring

SIZE OF THE EINSTEIN RADIUS

$$heta_{\!E} \equiv \sqrt{rac{4GM}{c^2}rac{D_{
m LS}}{D_{
m L}D_{
m S}}} \hspace{1cm} D \equiv rac{D_{
m L}D_{
m S}}{D_{
m LS}}$$

$$\theta_E \approx (10^{-3})'' \left(\frac{M}{M_{\odot}}\right)^{1/2} \left(\frac{D}{10 \text{kpc}}\right)^{-1/2},$$

$$\approx 1'' \left(\frac{M}{10^{12} M_{\odot}}\right)^{1/2} \left(\frac{D}{\text{Gpc}}\right)^{-1/2},$$

For a star like the sun within the MW, the Einstein radius is of the order of milli-arcseconds!

PROPERTIES OF THE IMAGES

$$eta
ightharpoonup \phi_- = x_- \theta_E
ightharpoonup 0, \qquad \theta_+ = x_+ \theta_E
ightharpoonup \beta$$

For large angular distances between the lens and the source, one image approaches the lens, while the other follows the source.