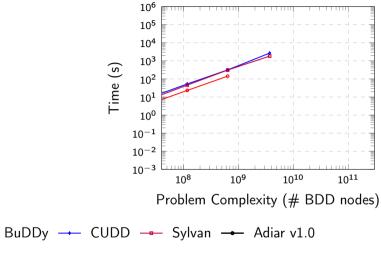
# Predicting Memory Demands of BDD Operations using Maximum Graph Cuts

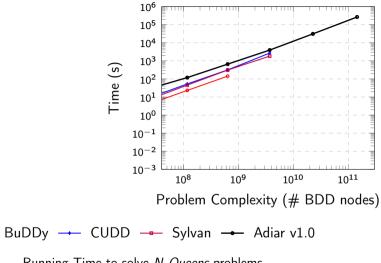
Steffan Christ Sølvsten and Jaco van de Pol

ATVA 2023

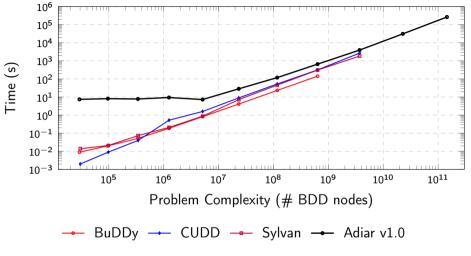




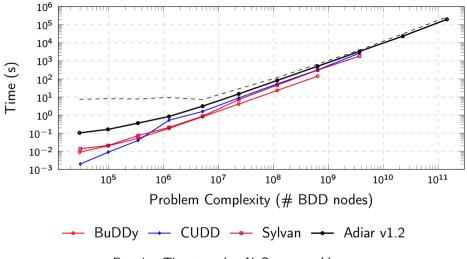
Running Time to solve *N-Queens* problems.



Running Time to solve *N-Queens* problems.



Running Time to solve *N-Queens* problems.

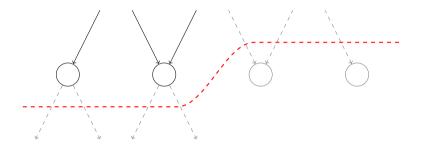


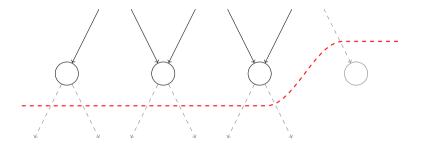
Running Time to solve *N-Queens* problems.

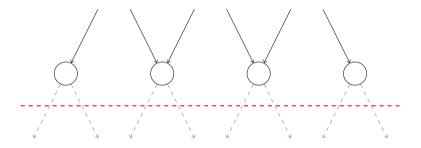




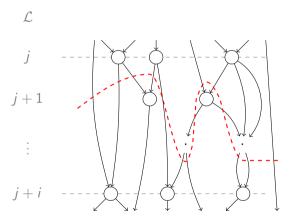




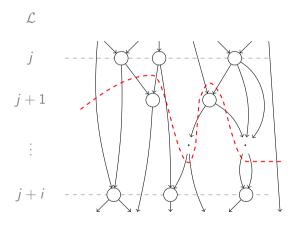




## *i*-level cut



### *i*-level cut

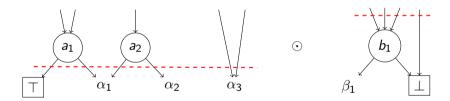


Lemma (Sølvsten, Van de Pol 2023) The maximum i-level cut problem is in P for  $i \in \{1, 2\}$ .

Theorem (Lampis, Kaouri, Mitsou 2011) The maximum i-level cut problem is NP-complete for  $i \ge 4$ .

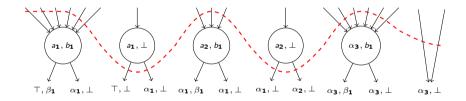
**Theorem (Sølvsten, Van de Pol 2023)** Given maximum 2-level cuts size  $C_f$  for f and  $C_g$  for g, the maximum 2-level cut for  $f \odot g$  is less than or equal to  $C_f \cdot C_g$ .

#### Proof.



**Theorem (Sølvsten, Van de Pol 2023)** Given maximum 2-level cuts size  $C_f$  for f and  $C_g$  for g, the maximum 2-level cut for  $f \odot g$  is less than or equal to  $C_f \cdot C_g$ .

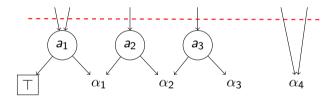
#### Proof.



#### Lemma (Sølvsten, Van de Pol 2023)

The maximum 2-level cut for f is at most  $\frac{3}{2}$  larger than its maximum 1-level cut.

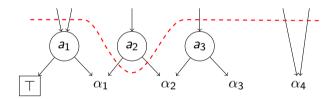
#### Proof.



#### Lemma (Sølvsten, Van de Pol 2023)

The maximum 2-level cut for f is at most  $\frac{3}{2}$  larger than its maximum 1-level cut.

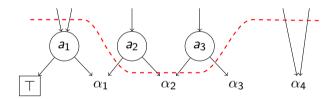
#### Proof.



#### Lemma (Sølvsten, Van de Pol 2023)

The maximum 2-level cut for f is at most  $\frac{3}{2}$  larger than its maximum 1-level cut.

#### Proof.



		+ <b>Ŏ</b>	WHA
		Overhead	Precision
1-level cut	:	1.0%	76.5%
2-level cut	:	3.3%	77.4%

Possible to process a

# 1.1 GiB BDD

with only

128 MiB Memory



#### Running Time

Adiar v1.0 : 56.5 hours

Verification of the 15 smallest EPFL circuits.



#### Running Time

Adiar v1.0 : 56.5 hours

Adiar v1.2 :  $4.0 \text{ hours } (-93\%)^1$ 

Verification of the 15 smallest EPFL circuits.

<sup>&</sup>lt;sup>1</sup> 52.1 of these hours were saved on just verifying the sin circuit alone.

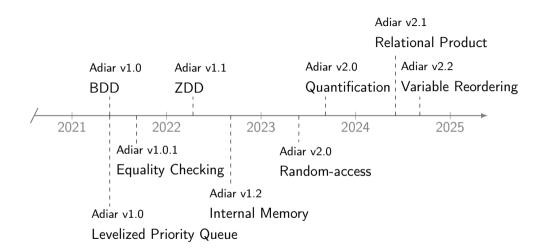
## Steffan Christ Sølvsten

- soelvsten@cs.au.dk
- ssoelvsten.github.io

#### **Adiar**

- github.com/ssoelvsten/adiar
- ssoelvsten.github.io/adiar





	<b>¥</b> ≡	+ <b>Č</b>			2
	Sufficient?	Overhead	Memory <sup>2</sup>	Disk R/W	Transition Cost
DF ▶ Adiar ( <b>===</b> ▶ <b>=</b> )	×	3×	_	2×	_
DF    Adiar (🌉    🛢)	<b>~</b>	_	$3 \times$	$2\times$	_
DF → Adiar 1.0	<b>X</b> 1	_	_	_	$\Omega(N \log N)$
State Pattern ( <b>프 → </b> 号)	<b>✓</b> 4	$\sim$ 20% $^3$	2×	_	$\Omega(N)$
i-level cut (🌉 / 🛢)	<b>✓</b> 4	1%	_	_	_

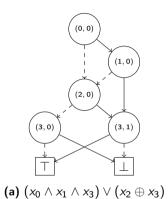
Comparison of possible solutions.

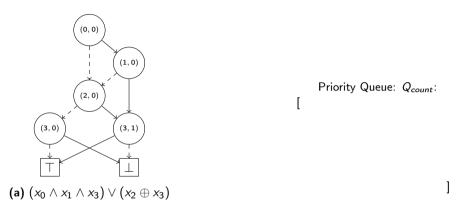
<sup>&</sup>lt;sup>1</sup>There can be a gap between when depth-first runs out of memory and Adiar 1.0 has no overhead.

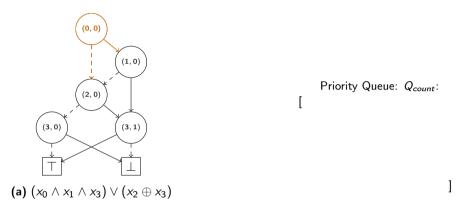
 $<sup>^{\</sup>mathbf{2}}$ Decreasing the memory dedicated to an external memory data structure impacts its performance.

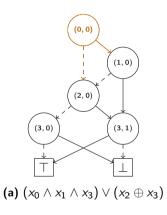
<sup>&</sup>lt;sup>3</sup>Runtime polymorphism adds a 20% to 30% overhead [Stroustrup].

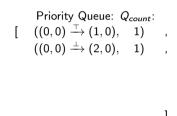
<sup>&</sup>lt;sup>4</sup>This solves the gap<sup>1</sup>; a *non-trivial* integration with depth-first algorithms can cover tiny cases.

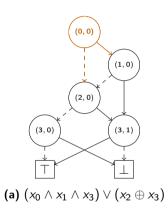




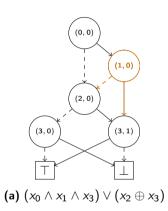




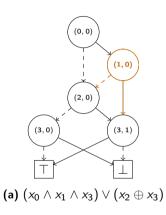


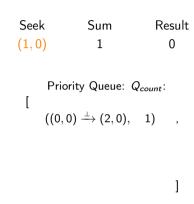


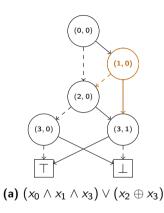
See (1,0		Sum 0	Re	sult 0
]	((0,0)	Queue: $\xrightarrow{\top} (1,0),$ $\xrightarrow{\bot} (2,0),$	1)	,

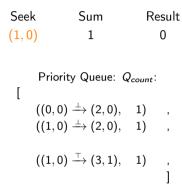


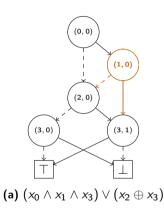
Seel (1, 0		Re	sult 0
[	Priority Queue: Q $((0,0) \xrightarrow{\top} (1,0),$ $((0,0) \xrightarrow{\bot} (2,0),$	1)	,
			]

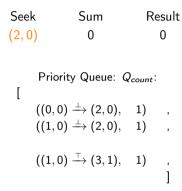


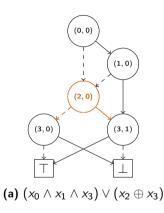


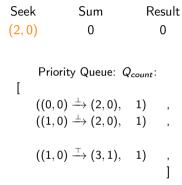














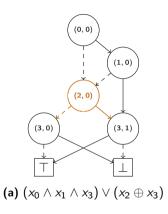
Seek Sum Result 
$$(2,0)$$
 1 0

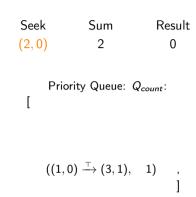
Priority Queue:  $Q_{count}$ :

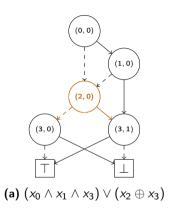
[

 $((1,0) \xrightarrow{\top} (2,0), 1)$  ,

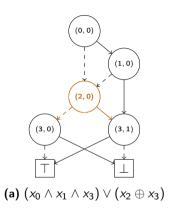
 $((1,0) \xrightarrow{\top} (3,1), 1)$  ,



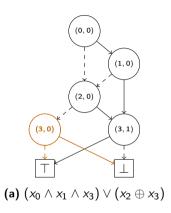




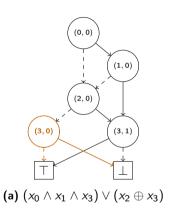
Seek (2,0)	Sum 2	Resul 0
Pric [	ority Queue: G	?count∶
((1,	$0) \xrightarrow{\perp} (3,0),$ $0) \xrightarrow{\top} (3,1),$ $0) \xrightarrow{\top} (3,1),$	2) , 1) , 2) ]

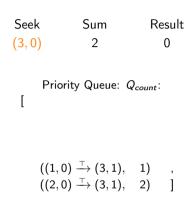


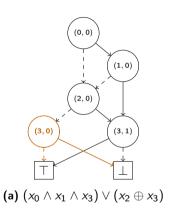
Seek (3,0)	Sum 0	Resul 0
Prio [	ority Queue:(	Q <sub>count</sub> :
((1,	$0) \xrightarrow{\perp} (3,0),$ $0) \xrightarrow{\top} (3,1),$ $0) \xrightarrow{\top} (3,1),$	2) , 1) , 2) ]

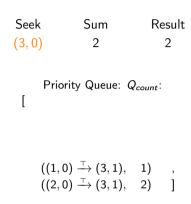


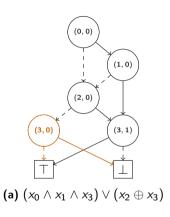
Seek (3,0)	Sum 0	Resu 0	ıl
Prio [	rity Queue: (	Q <sub>count</sub> :	
((1,	$0) \xrightarrow{\perp} (3,0),$ $0) \xrightarrow{\top} (3,1),$ $0) \xrightarrow{\rightarrow} (3,1),$	2) , 1) , 2) ]	

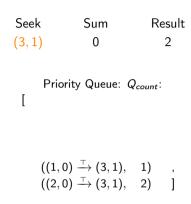


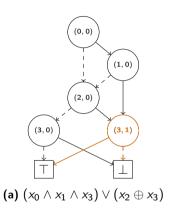


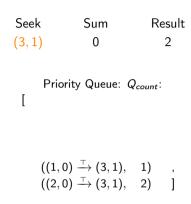


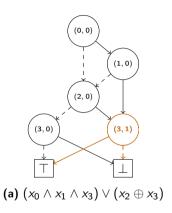


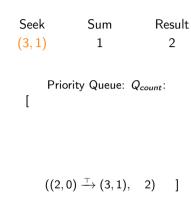


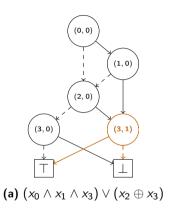


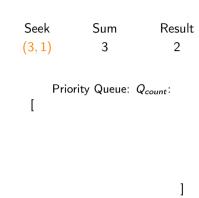


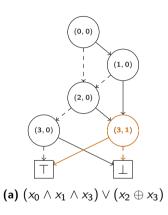


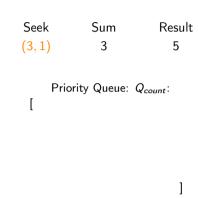














## Steffan Christ Sølvsten

- soelvsten@cs.au.dk
- ssoelvsten.github.io

## **Adiar**

- github.com/ssoelvsten/adiar
- ssoelvsten.github.io/adiar

