### Models

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# Problem Setting

- ▶ Data: Observe for each case  $i(Y_i, X_i)$
- ► Response or dependent variable Y<sub>i</sub>
- Predictor(s) or independent variable X<sub>i</sub>

#### Goals:

- **Exploring distribution of** p(y|X=x) **as a function of** x
- ▶ Understanding the mean in Y as a function of x: E(Y | X = x) = f(X)

### Special cases:

- regression (normal Y) or additive error model
- ▶ classification (binary or Bernoulli Y where probability  $p(Y = 1 \mid X)$  depends on x)
- exponential family models
  - Poisson regression (counts)
  - Gamma regression (continous, positive)
- Survival models

#### Additive Error Model

▶ Assume  $E[\epsilon_i] = 0$  for i = 1, ..., n,

$$Y_i = f(X_i) + \epsilon_i$$

- ▶ Regression function  $E(Y \mid x) = f(x)$
- ideal or optimal predictor of Y given X = x
- ▶ minimizes  $E[(Y g(x))^2 \mid X = x]$  over all functions g(x) at all points X = x
- for prediction  $\epsilon = Y f(x)$  is *irreducible error* as even if we know f(x) there are still errors in predicting Y
- for any estimator  $\hat{f}(x)$  we have

$$E[(Y - \hat{f}(x))^2 \mid X = x] = \underbrace{(f(x) - \hat{f}(x))^2}_{Reducible} + \underbrace{Var(\epsilon)}_{Irreducible}$$

## Linear Regression

ightharpoonup Taylors series expansion of regression function about point  $x_0$ 

$$f(x_i) = f(x_0) + f'(x_0)(x_i - x_0) +$$
Remainder

leads to locally linear approximation

$$Y_i = \beta_0 + X_i \beta_1 + \varepsilon_i$$

 $ightharpoonup arepsilon_i$ : errors (sampling/measurement errors  $\epsilon$ , lack of fit)

# Regression in Matrix Notation

Simple Linear Regression:

$$Y_i = \beta_0 + x_i \beta_1 + \epsilon_i$$
 for  $i = 1, \dots, n$ 

Rewrite in vectors:

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \beta_0 + \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \beta_1 + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$$

# Big Picture:

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon} \stackrel{iid}{\sim} N(0, \sigma^2)$$

- Estimate parameters  $(\beta, \sigma)$
- interpretation of parameters:  $\beta, \sigma$
- assess model fit adequate? good? if inadequate, how?
- move to more complicated model?
- ▶ predict new ("future") responses at new  $x_{n+1},...$
- ▶ how much variability does *x* explain?
- how important is X is predicting Y

### Body Fat Data

- For a group of 252 male subjects, various body measurements were obtained
- ► An accurate measurement of the percentage of body fat is recorded for each
- Goal is to use the other body measurements as a proxy for predicting body fat
- Understand how changing one measurement may lead to changes in Bodyfat

#### Data

```
library(BAS)
             #from BAS help(bodyfat)
data(bodyfat)
dim(bodyfat)
   [1] 252
##
```

<pre>summary(bodyfat)</pre>	#	anything	strange	?	

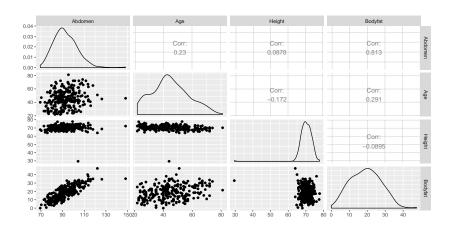
##	Density	Bodyfat	Age	Wei	
##	Min. :0.995	Min. : 0.00	Min. :22.00	Min.	
##	1st Qu.:1.041	1st Qu.:12.47	1st Qu.:35.75	1st Qu	
##	Median :1.055	Median :19.20	Median :43.00	Median	

## Mean :1.056 Mean :19.15 Mean :44.88 Mean 3rd Qu.:1.070 3rd Qu.:25.30 3rd Qu.:54.00 3rd Qu ## :1.109 :47.50 :81.00 Max. ## Max. Max. Max.

## Height Neck Chest Abo Min. :29.50 :31.10 Min. : 79.30 Min. ## Min. ## 1st Ou ·68 25 1st On ·36 40 1st Ou · 94 35 1st 0:

### Pairs Plots

```
library(GGally)
ggpairs(bodyfat, columns=c(8,3,5,2))
```



# Ordinary Least Squares

▶ OLS estimates of parameters  $\beta_0$  and  $\beta$  minimize sum of squared errors

$$\sum_{i=1}^n (Y_i - (\beta_0 + X_i \beta_1))^2$$

$$L(\beta) = (\mathbf{Y} - \mathbf{X}\beta)^T (\mathbf{Y} - \mathbf{X}\beta)$$

▶ OLS estimate of β

$$\hat{\boldsymbol{eta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$$

- Ad Hoc
- Equivalent to Maximum Likelihood Estimates with assumption that errors are iid Normal (Model based)

# Summarizing Model Fit

Fitted values

$$\hat{Y}_i = x_i^T \hat{\beta}$$

Residuals (estimates of errors)

$$e_i = Y_i - \hat{Y}_i = \hat{\epsilon}_i$$

Sum of Squared Errors

$$SSE = \sum e_i^2$$

- measures remaining residual variation in response
- ► MSE = SSE/(n -2) (or more generally n p) is an estimate of  $\sigma^2$
- degrees of freedom n-p

# Fitting Models in R

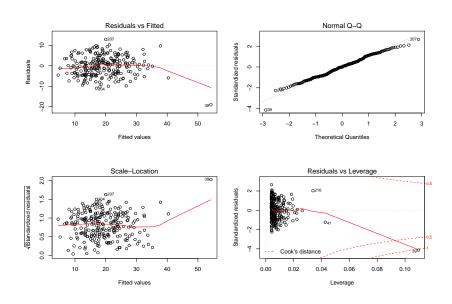
bodyfat.lm = lm(Bodyfat ~ Abdomen, data=bodyfat)
summary(bodyfat.lm) #summary of regression output

```
##
## Call:
## lm(formula = Bodyfat ~ Abdomen, data = bodyfat)
##
## Residuals:
## Min 1Q Median 3Q
                                      Max
## -19.0160 -3.7557 0.0554 3.4215 12.9007
##
## Coefficients:
             Estimate Std. Error t value Pr(>|t|)
##
## (Intercept) -39.28018 2.66034 -14.77 <2e-16 ***
## Abdomen 0.63130 0.02855 22.11 <2e-16 ***
```

## Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.05 '.' 0.3

## ---

### Residual Plots



### Diagnostic Plots

- Residuals versus fitted values
- Normal Quantile: check normality of residuals or look for heavier tails than normal where observed quantiles are larger than expected under normality
- Scale-Location plot:
   Detect if the spread of the residuals is constant over the range of fitted values. (Constant variance with mean)
- ▶ standardized residuals versus leverage with contours of Cook's distance: shows influential points where points greater than 1 or 4/n are considered influential

Case 39 appears to be influential!

#### Hat Matrix

predictions

$$\hat{Y} = X\hat{\beta} = X(X^TX)^{-1}X^TY$$
$$H = X(X^TX)^{-1}X^T$$

- Hat Matrix or Projection Matrix
  - ▶ idempotent HH = H
  - symmetric
  - ▶ leverage values are the diagonal elements  $h_{ii}$

$$Y_i = h_{ii}Y_i + \sum_{i \neq j} h_{ij}Y_j$$

- ▶ leverage values near 1 imply  $\hat{Y}_i = Y_i$
- potentially influential
- measure of how far x<sub>i</sub> is from center of data

# Residual Analysis

residuals

$$e = Y - \hat{Y} = (I - H)Y$$
$$var(e_i) = \hat{\sigma}^2(1 - h_{ii})$$

► Standardize:

$$r_i = e_i/\sqrt{\mathrm{var}(e_i)}$$

 if leverage is near 1 then residual is near 0 and variance is near 0 and r<sub>i</sub> is approximately 0 (may not be helpful)

### Cook's Distance

Measure of influence of case i on predictions

$$D_i = \frac{\|Y - \hat{Y}_{(i)}\|^2}{\hat{\sigma}^2 p}$$

after removing the ith case

Easier way to calculate

$$D_{i} = \frac{e_{i}^{2}}{\hat{\sigma}^{2} p} \left[ \frac{h_{ii}}{(1 - h_{ii})^{2}} \right],$$

$$D_{i} = \frac{r_{ii}}{p} \frac{h_{ii}}{1 - h_{ii}}$$

#### Model Assessment

- Always look at residual plots!
- Check constant variance, outliers, influence, normality assumption
- ► Treat e; as 'new data'' -- look at structure, other predictorsavplots'
- Case 39 looks influential!

How should we proceed?