# Lecture 7: Introduction to Hierarchical Modelling, Empirical Bayes, and MCMC

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### **Normal Means Model**

Suppose we have normal data with

$$Y_i \stackrel{iid}{\sim} (\mu_i, \sigma^2)$$

separate mean for each observation!

**Question**: How can we possibly hope to estimate all these  $\mu_i$ ? One  $y_i$  per  $\mu_i$  and n observations!

**Naive estimator**: just consider only using  $y_i$  in estimating and not the other observations.

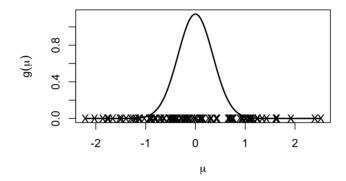
 $lacksquare \mathsf{MLE}\ \hat{\mu}_i = y_i$ 

**Hierarchical Viewpoint**: Let's borrow information from other observations!



### **Motivation**

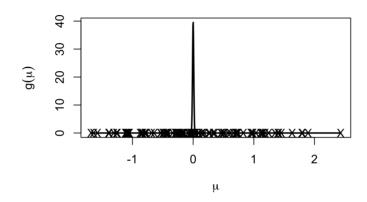
- Example  $y_i$  is difference in gene expression for the  $i^{th}$  gene between cancer and control lines
- may be natural to think that the  $\mu_i$  arise from some common distribution,  $\mu_i \stackrel{iid}{\sim} g$



• unbiased but high variance estimators of  $\mu_i$  based on one observation!



# **Low Variability**



- little variation in  $\mu_i$ s so a better estimate might be  $\bar{y}$
- Not forced to choose either what about some weighted average between  $y_i$  and  $\bar{y}$ ?



# Simple Example

Data Model

$$Y_i \mid \mu_i, \sigma^2 \stackrel{iid}{\sim} (\mu_i, \sigma^2)$$

Means Model

$$\mu_i \mid \mu, au \stackrel{iid}{\sim} (\mu, \sigma_\mu^2)$$

- not necessarily a prior!
- Now estimate  $\mu_i$  (let  $\phi = 1/\sigma^2$  and  $\phi_{\mu} = 1/\sigma_{\mu}^2$ )
- Calculate the "posterior"  $\mu_i \mid y_i, \mu, \phi, \phi_{\mu}$

### **Hiearchical Estimates**

- Posterior:  $\mu_i \mid y_i, \mu, \phi, \phi_\mu \stackrel{ind}{\sim} \mathsf{N}(\tilde{\mu}_i, 1/\tilde{\phi}_\mu)$
- estimator of  $\mu_i$  weighted average of data and population parameter  $\mu$

$$ilde{\mu}_i = rac{\phi_\mu \mu + \phi y_i}{\phi_\mu + \phi} \hspace{1cm} ilde{\phi}_\mu = \phi + \phi_\mu$$

- if  $\phi_{\mu}$  is large relative to  $\phi$  all of the  $\mu_{i}$  are close together and benefit by borrowing information
- lacksquare in limit as  $\sigma_{\mu}^2 o 0$  or  $\phi_{\mu} o \infty$  we have  $ilde{\mu}_i = \mu$  (all means are the same)
- if  $\phi_{\mu}$  is small relative to  $\phi$  little borrowing of information
- lacksquare in the limit as  $\phi_{\mu} 
  ightarrow 0$  we have  $ilde{\mu}_i = y_i$



### **Bayes Estimators and Bias**

Note: you often benefit from a hierarchical model, even if its not obvious that the  $\mu_i$ s are related!

- The MLE for the  $\mu_i$  is just the sample  $y_i$ .
- $y_i$  is unbiased for  $\mu_i$  but can have high variability!
- the posterior mean is actually biased.
- Usually through the weighting of the sample data and prior, Bayes procedures have the tendency to pull the estimate of  $\mu_i$  toward the prior or **shrinkage** mean.
- Why would we ever want to do this? Why not just stick with the MLE?
- MSE or Bias-Variance Tradeoff



### Modern relevance

- The fact that a biased estimator would do a better job in many estimation/prediction problems can be proven rigorously, and is referred to as **Stein's paradox**.
- Stein's result implies, in particular, that the sample mean is an inadmissible estimator of the mean of a multivariate normal distribution in more than two dimensions -- i.e. there are other estimators that will come closer to the true value in expectation.
- In fact, these are Bayes point estimators (the posterior expectation of the parameter  $\mu_i$ ).
- Most of what we do now in high-dimensional statistics is develop biased estimators that perform better than unbiased ones.
- Examples: lasso regression, ridge regression, various kinds of hierarchical Bayesian models, etc.



### **Population Parameters**

- we don't know  $\mu$  (or  $\sigma^2$  and  $\sigma^2_{\mu}$  for that matter)
- Find marginal likelihood  $\mathcal{L}(\mu, \sigma^2, \sigma_\mu^2)$  by integrating out  $\mu_i$  with respect to g

$$\mathcal{L}(\mu, \sigma^2, \sigma_\mu^2) \propto \prod_{i=1}^n \int \mathsf{N}(y_i; \mu_i, \sigma^2) \mathsf{N}(\mu_i; \mu, \sigma_\mu^2) \, d\mu_i$$

■ Product of predictive distributions for  $Y_i \mid \mu, \sigma^2, \sigma_\mu^2 \stackrel{iid}{\sim} \mathsf{N}(\mu, \sigma^2 + \sigma_\mu^2)$ 

$$\mathcal{L}(\mu,\sigma^2,\sigma_\mu^2) \propto \prod_{i=1}^n (\sigma^2+\sigma_\mu^2)^{-1/2} \exp \Biggl\{ -rac{1}{2} rac{(y_i-\mu)^2}{\sigma^2+\sigma_\mu^2} \Biggr\}$$

■ Find MLE's



### **MLEs**

$$\mathcal{L}(\mu,\sigma^2,\sigma_\mu^2) \propto (\sigma^2+\sigma_\mu^2)^{-n/2} \exp \left\{-rac{1}{2} \sum_{i=1}^n rac{(y_i-\mu)^2}{\sigma^2+\sigma_\mu^2}
ight\}$$

- lacksquare MLE of  $\mu$ :  $\hat{\mu} = \bar{y}$
- Can we say anything about  $\sigma_{\mu}^2$ ? or  $\sigma^2$  individually?
- MLE of  $\sigma^2 + \sigma_\mu^2$  is

$$\widehat{\sigma^2 + \sigma_\mu^2} = rac{\sum (y_i - ar{y})^2}{n}$$

• Assume  $\sigma^2$  is known (say 1)

$$\hat{\sigma}_{\mu}^2=rac{\sum(y_i-ar{y})^2}{n}-1$$



### **Empirical Bayes Estimates**

- plug in estimates of hyperparameters into the prior and pretend they are known
- resulting estimates are known as Empirical Bayes
- underestimates uncertainty
- Estimates of variances may be negative constrain to 0 on the boundary)
- Fully Bayes would put a prior on the unknowns



### **Bayes and Hierarchical Models**

- We know the conditional posterior distribution of  $\mu_i$  given the other parameters, lets work with the marginal likelihood  $\mathcal{L}(\theta)$
- need a prior  $\pi(\theta)$  for unknown parameters are  $\theta = (\mu, \sigma^2, \sigma_\mu^2)$  (details later)

**Posterior** 

$$\pi( heta \mid y) = rac{\pi( heta) \mathcal{L}( heta)}{\int_{\Theta} \pi( heta) \mathcal{L}( heta) \, d heta} = rac{\pi( heta) \mathcal{L}( heta)}{m(y)}$$

■ Except for simple cases (conjugate models) m(y) is not available analytically



### **Large Sample Approximations**

■ Appeal to BvM (Bayesian Central Limit Theorem) and approximate  $\pi(\theta \mid y)$  with a Gaussian distribution centered at the posterior mode  $\hat{\theta}$  and asymptotic covariance matrix

$$V_{ heta} = \left[ -rac{\partial^2}{\partial heta \partial heta^T} \{ \log(\pi( heta)) + \log(\mathcal{L}( heta)) \} 
ight]^{-1}$$

- we can try to approximate m(y) but this may involve a high dimensional integral
- Laplace approximation to integral (also large sample)

Stochastic methods



# **Stochastic Integration**

$$\mathsf{E}[h( heta) \mid y] = \int_{\Theta} h( heta) \pi( heta \mid y) \, d heta pprox rac{1}{T} \sum_{t=1}^T h( heta^{(t)}) \qquad heta^{(t)} \sim \pi( heta \mid y)$$

what if we can't sample from the posterior but can sample from some distribution q()

$$\mathsf{E}[h( heta) \mid y] = \int_{\Theta} h( heta) rac{\pi( heta \mid y)}{q( heta)} q( heta) \, d heta pprox rac{1}{T} \sum_{t=1}^T h( heta^{(t)}) rac{\pi( heta^{(t)} \mid y)}{q( heta^{(t)})}$$

where  $\theta^{(t)} \sim q(\theta)$ 

Without the denominator in  $\pi(\theta \mid y)$  we just have  $\pi(\theta \mid y) \propto \pi(\theta) \mathcal{L}(\theta)$ 

use twice for numerator and denominator



# **Important Sampling Estimate**

Estimate of m(y)

$$m(y) pprox rac{1}{T} \sum_{t=1}^{T} rac{\pi( heta^{(t)}) \mathcal{L}( heta^{(t)})}{q( heta^{(t)})} \qquad heta^{(t)} \sim q( heta)$$

$$\mathsf{E}[h( heta) \mid y] pprox rac{\sum_{t=1}^T h( heta^{(t)}) rac{\pi( heta^{(t)}) \mathcal{L}( heta^{(t)})}{q( heta^{(t)})}}{\sum_{t=1}^T rac{\pi( heta^{(t)}) \mathcal{L}( heta^{(t)})}{q( heta^{(t)})}} \qquad heta^{(t)} \sim q( heta)$$

$$\mathsf{E}[h( heta) \mid y] pprox \sum_{t=1}^T h( heta^{(t)}) w( heta^{(t)}) \qquad heta^{(t)} \sim q( heta)$$

with un-normalized weights  $w(\theta^{(t)}) \propto \frac{\pi(\theta^{(t)})\mathcal{L}(\theta^{(t)})}{q(\theta^{(t)})}$ 

(normalize to sum to 1)



# Markov Chain Monte Carlo (MCMC)

■ Typically  $\pi(\theta)$  and  $\mathcal{L}(\theta)$  are easy to evaluate

How do we draw samples only using evaluations of the prior and likelihood in higher dimensional settings?

■ construct a Markov chain  $\theta^{(t)}$  in such a way the the stationary distribution of the Markov chain is the posterior distribution  $\pi(\theta \mid y)$ !

$$\theta^{(0)} \stackrel{k}{\longrightarrow} \theta^{(1)} \stackrel{k}{\longrightarrow} \theta^{(2)} \cdots$$

- $k_t(\theta^{(t-1)}; \theta^{(t)})$  transition kernel
- initial state  $\theta^{(0)}$
- choose some nice  $k_t$  such that  $\theta^{(t)} \to \pi(\theta \mid y)$  as  $t \to \infty$
- biased samples initially but get closer to the target



# Metropolis Algorithm (1950's)

- Markov chain  $\theta^{(t)}$
- propose  $\theta^* \sim g(\theta^{(t-1)})$  where g() is a symmetric distribution centered at  $\theta^{(t-1)}$
- set  $\theta^{(t)} = \theta^*$  with some probability
- otherwise set  $\theta^{(t)} = \theta^{(t-1)}$

Acceptance probability is

$$lpha = \min \left\{ 1, rac{\pi( heta^*) \mathcal{L}( heta^*)}{\pi( heta^{(t-1)}) \mathcal{L}( heta^{(t-1)})} 
ight\}$$

ratio of posterior densities where normalizing constant cancels!



# **Example**

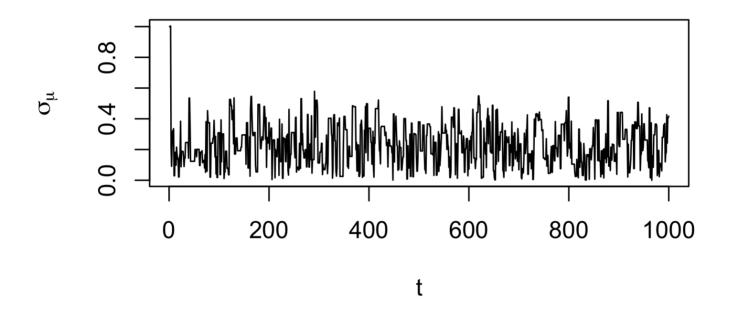
- Let's use a prior for  $p(\mu) \propto 1$
- Posterior for  $\mu \mid \sigma^2, \sigma_\mu^2$  is  $\mathsf{N}\left(\bar{y}, \frac{\sigma^2 + \sigma_\mu^2}{n}\right)$

$$\mathcal{L}(\sigma^2,\sigma_{ au}^2) \propto (\sigma^2+\sigma_{\mu}^2)^{-rac{n-1}{2}} \exp \Biggl\{-rac{1}{2} \sum_i rac{(y_i-ar{y})^2}{\sigma^2+\sigma_{\mu}^2)} \Biggr\}$$

- Take  $\sigma^2 = 1$
- Use a Cauchy(0,1) prior on  $\sigma_u$
- Symmetric proposal for  $\sigma_{\tau}$ ? Try a normal with variance  $\frac{2.4^2}{d} \text{var}(\sigma_{\mu})$  where d is the dimension of  $\theta$  (d = 1)



### **Trace Plots**

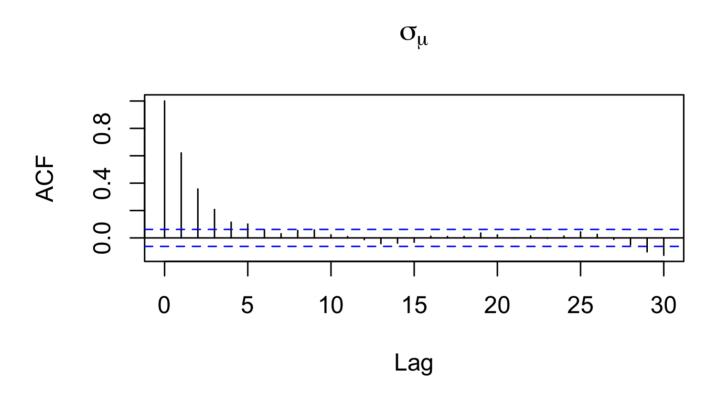


Acceptance probability is 0.57



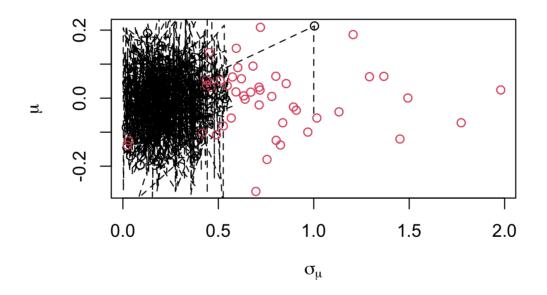
Goal is around 0.44 in 1 dimension to 0.23 in higher dimensions

### **AutoCorrelation Function**



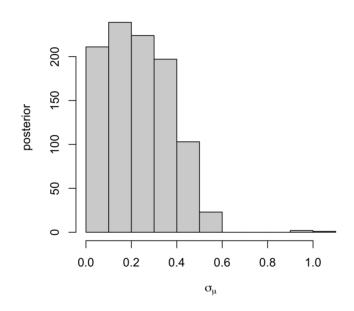


### **Joint Posterior**





# **Marginal Posterior**



MLE of  $\sigma_{\mu}$  is 0.11

