

# Bayesian Variable Selection & Bayesian Model Averaging

Hoff Chapter 9, Liang et al 2008, Hoeting et al (1999), Clyde & George (2004)

October 31, 2022

## Zellner's $g$ -prior

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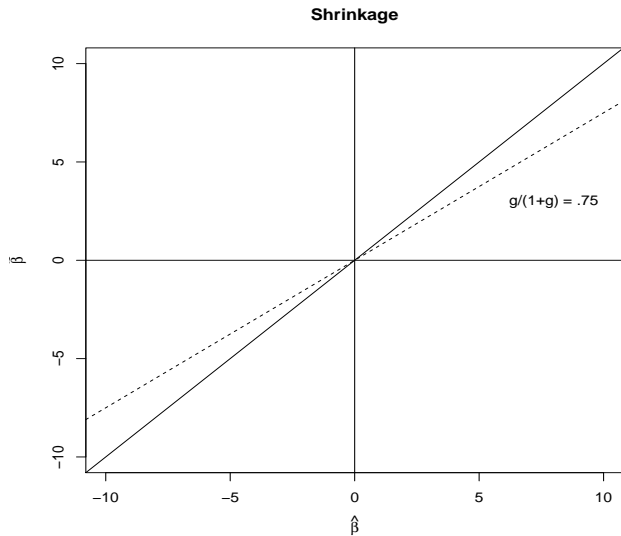
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- ▶ Choice of  $g$ ?
- ▶  $\frac{g}{1+g}$  weight given to the data
- ▶ Fixed  $g$  effect does not vanish as  $n \rightarrow \infty$
- ▶ Use  $g = n$  or place a prior distribution on  $g$

# Shrinkage

Posterior mean under  $g$ -prior with  $b_0 = 0$   $\frac{g}{1+g}\hat{\beta}$





# Ridge Regression

- ▶ If  $X^T X$  is nearly singular, certain elements of  $\beta$  or (linear combinations of  $\beta$ ) may have huge variances under the  $g$ -prior (or flat prior) as the MLEs are highly unstable!
- ▶ **Ridge regression** protects against the explosion of variances and ill-conditioning with the conjugate prior:

$$\beta \mid \phi \sim N(0, \frac{1}{\phi\lambda} I_p)$$

- ▶ Posterior for  $\beta$  (conjugate case)

$$\beta \mid \phi, \lambda, Y \sim N \left( (\lambda I_p + X^T X)^{-1} X^T Y, \frac{1}{\phi} (\lambda I_p + X^T X)^{-1} \right)$$

- ▶ induces shrinkage as well!

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- ▶ Some variables may not be relevant ( $\beta_j = 0$ )
- ▶ Can we infer a "good" model from the data?
- ▶ Expand model hierarchically to introduce another latent variable  $\gamma$  that encodes models  $\mathcal{M}_\gamma$   $\gamma = (\gamma_1, \gamma_2, \dots, \gamma_p)^T$  where

$$\gamma_j = 0 \Leftrightarrow \beta_j = 0$$

$$\gamma_j = 1 \Leftrightarrow \beta_j \neq 0$$

- ▶ Find Bayes factors and posterior probabilities of models  $\mathcal{M}_\gamma$
- ▶  $2^p$  models!

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which leads to marginal likelihood of  $\gamma$  that is proportional to

$$p(Y \mid \gamma) = C(1 + g)^{\frac{n-p-1}{2}} (1 + g(1 - R_\gamma^2))^{-\frac{(n-1)}{2}}$$

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Trade-off of model complexity versus goodness of fit

Lastly, assign distribution to space of models

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- ▶ Integrate out  $\phi$  (gamma)
- ▶ algebra to simplify quadratic forms to  $R_\gamma^2$

Or integrate  $\alpha$ ,  $\beta_\gamma$  and  $\phi$  (complete the square!)

# Posteriors

$$\alpha \mid \phi, y \sim \mathcal{N}\left(\bar{y}, \frac{1}{n\phi}\right)$$

$$\beta_\gamma \mid \gamma, \phi, g, y \sim \mathcal{N}\left(\frac{g}{1+g}\hat{\beta}_\gamma, \frac{g}{1+g}\frac{1}{\phi}\left[X_\gamma^T X_\gamma\right]^{-1}\right)$$

$$\phi \mid \gamma, y \sim \text{Gamma}\left(\frac{n-1}{2}, \frac{\text{TotalSS} - \frac{g}{1+g}\text{RegSS}}{2}\right)$$

$$p(\gamma \mid y) \propto p(y \mid \gamma)p(\gamma)$$

$$\text{TotalSS} \equiv \sum_i (y_i - \bar{y})^2 \quad \text{RegSS} \equiv \hat{\beta}_\gamma^T X_\gamma^T X_\gamma \hat{\beta}_\gamma$$

$$R_\gamma^2 = \frac{\text{RegSS}}{\text{TotalSS}} = 1 - \frac{\text{ErrorSS}}{\text{TotalSS}}$$



# Priors on Model Space

$$p(\mathcal{M}_\gamma) \Leftrightarrow p(\gamma)$$

- ▶  $p(\gamma_j = 1) = .5 \Rightarrow P(\mathcal{M}_\gamma) = .5^p$  Uniform on space of models

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 $p_\gamma \sim \text{Bin}(p, .5)$
- ▶  $\gamma_j \mid \pi \stackrel{\text{iid}}{\sim} \text{Ber}(\pi)$  and  $\pi \sim \text{Beta}(a, b)$  then  $p_\gamma \sim \text{BB}_p(a, b)$

$$p(p_\gamma \mid p, a, b) = \frac{\Gamma(p+1)\Gamma(p_\gamma+a)\Gamma(p-p_\gamma+b)\Gamma(a+b)}{\Gamma(p_\gamma+1)\Gamma(p-p_\gamma+1)\Gamma(p+a+b)\Gamma(a)\Gamma(b)}$$

- ▶  $p_\gamma \sim \text{BB}_p(1, 1) \sim \text{Unif}(0, p)$

# Posterior Probabilities of Models

- Calculate analytically under enumeration

$$p(\mathcal{M}_\gamma | Y) = \frac{p(Y | \gamma)p(\gamma)}{\sum_{\gamma' \in \Gamma} p(Y | \gamma')p(\gamma')}$$

Express as a function of Bayes factors and prior odds!

- Use MCMC over  $\Gamma$  - Gibbs, Metropolis Hastings if  $p$  is large
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- Use MCMC over  $\Gamma$  - Gibbs, Metropolis Hastings if  $p$  is large
- slow convergence/poor mixing with high correlations
- Metropolis Hastings algorithms more flexibility (swap pairs of variables)
- Do we need to run MCMC over  $\gamma$ ,  $\beta_\gamma$ ,  $\alpha$ , and  $\phi$ ?

## Choice of $g$ : Bartlett's Paradox

The Bayes factor for comparing  $\gamma$  to the null model:

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- ▶ why is this a paradox?

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- ▶ BF converges to a fixed constant  $(1 + g)^{n-1-p_\gamma/2}$  (does not go to infinity)

“Information Inconsistency” see Liang et al JASA 2008

## Mixtures of $g$ priors & Information consistency

- ▶ Need  $BF \rightarrow \infty$  if  $R_\gamma^2 \rightarrow 1$
- ▶ Put a prior on  $g$

$$BF(\gamma : \gamma_0) = \frac{C \int (1+g)^{(n-1-p_\gamma)/2} (1+g(1-R_\gamma^2))^{-(n-1)/2} \pi(g) dg}{C}$$

- ▶ interchange limit and integration as  $R^2 \rightarrow 1$  want

$$E_g[(1+g)^{(n-1-p_\gamma)/2}]$$

to diverge

- ▶ hyper- $g$  prior (Liang et al JASA 2008)

$$p(g) = \frac{a-2}{2} (1+g)^{-a/2}$$

or  $g/(1+g) \sim \text{Beta}(1, (a-2)/2)$

- ▶ prior expectation converges if  $a > n + 1 - p_\gamma$
- ▶ Consider minimal model  $p_\gamma = 1$  and  $n = 3$  (can estimate intercept, one coefficient, and  $\sigma^2$ , then  $a > 3$  integral exists)
- ▶ For  $2 < a \leq 3$  integral diverges and resolves the information paradox!



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- ▶ robust prior (Bayarri et al Annals of Statistics 2012)
- ▶ Intrinsic prior (Womack et al JASA 2015)

All have prior tails for  $\beta$  that behave like a Cauchy distribution and (the latter 4) marginal likelihoods that can be computed using special hypergeometric functions ( ${}_2F_1$ , Appell  $F_1$ )

# USair Data

```
> library(BAS)
> data(usair, package="HH")
> poll.bma = bas.lm(log(SO2) ~ temp + log(mfgfirms) +
+                    log(popn) + wind +
+                    precip + raindays,
+                    data=usair,
+                    prior="JZS", #Jeffrey-Zellner-Siow
+                    alpha=nrow(usair), # n
+                    n.models=2^6,
+                    modelprior = uniform(),
+                    method="deterministic")
```



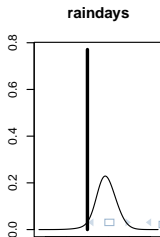
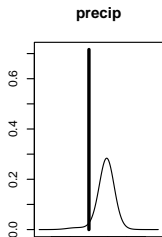
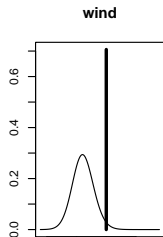
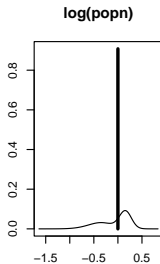
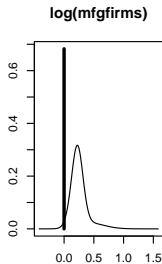
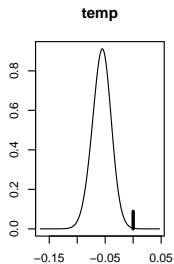
# Summary

```
> summary(poll.bma)
```

	P(B != 0   Y)	model 1	model 2	model 3	model
Intercept	1.00000000	1.00000	1.0000000	1.0000000	1.000000
temp	0.91158530	1.00000	1.0000000	1.0000000	1.000000
log(mfgfirms)	0.31718916	0.00000	0.0000000	0.0000000	1.000000
log(popn)	0.09223957	0.00000	0.0000000	0.0000000	0.000000
wind	0.29394451	0.00000	0.0000000	0.0000000	1.000000
precip	0.28384942	0.00000	1.0000000	0.0000000	1.000000
raindays	0.22903262	0.00000	0.0000000	1.0000000	0.000000
BF	NA	1.00000	0.3286643	0.2697945	0.265587
PostProbs	NA	0.29410	0.0967000	0.0794000	0.078100
R2	NA	0.29860	0.3775000	0.3714000	0.542700
dim	NA	2.00000	3.0000000	3.0000000	5.000000
logmarg	NA	3.14406	2.0313422	1.8339656	1.818248

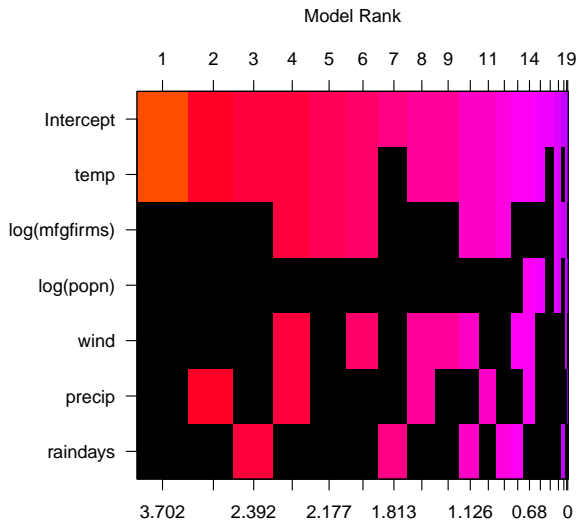
## Plots

```
> beta = coef(poll.bma)  
> par(mfrow=c(2,3)); plot(beta, subset=2:7, ask=F)
```



# Posterior Distribution with Uniform Prior on Model Space

```
> image(poll.bma, rotate=FALSE)
```

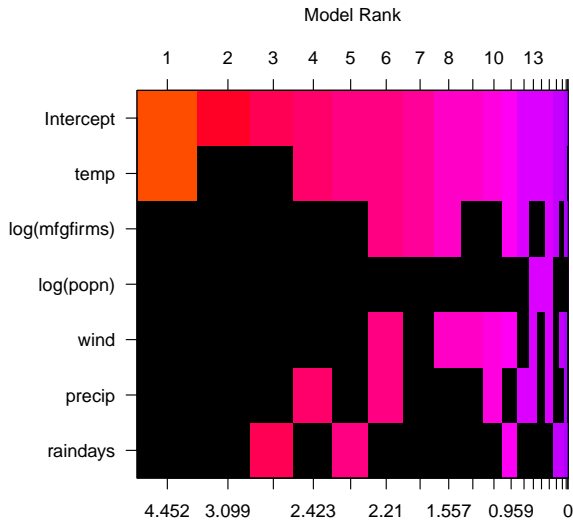


## Posterior Distribution with BB(1,1) Prior on Model Space

```
> poll.bb.bma = bas.lm(log(SO2) ~ temp + log(mfgfirms) +  
+                        log(popn) + wind +  
+                        precip + raindays,  
+                        data=usair,  
+                        prior="JZS",  
+                        alpha=nrow(usair),  
+                        n.models=2^6, #enumerate  
+                        modelprior=beta.binomial(1,1))
```

# BB(1,1) Prior on Model Space

```
> image(poll.bb.bma, rotate=FALSE)
```



# Summary

- ▶ Choice of prior on  $\beta_\gamma$
- ▶ g-priors or mixtures of  $g$  (sensitivity)
- ▶ priors on the models (sensitivity)
- ▶ posterior summaries - select a model or "average" over all models