# Outliers & Robust Bayesian Regression

Readings: Hoff Chapter 9, West JRSSB 1984, Fúquene, Pérez & Pericchi 2015

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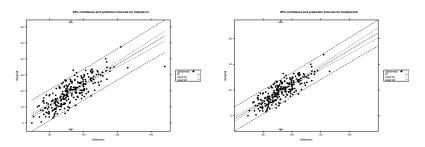
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## Outliers in Regression

- ► Hoeting, Madigan and Raftery (in various permutations) consider the problem of simultaneous variable selection and outlier identification.
- ➤ This is implemented in the package BMA in the function MC3.REG. This has the advantage that more than 2 points may be considered as outliers at the same time.
- The function uses a Markov chain to identify both important variables and potential outliers, but is coded in Fortran so should run reasonably quickly.
- Can also use BAS or other variable selection programs

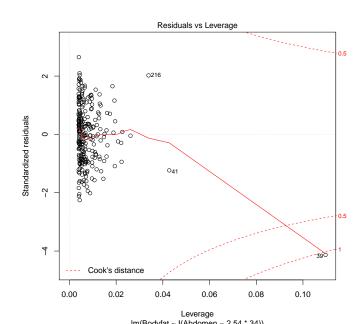
## Body Fat Data: Intervals w/ All Data

### Response % Body Fat and Predictor Waist Circumference



Which analysis do we use? with Case 39 or not – or something different?

## Cook's Distance



## Options for Handling Influential Cases

- Are there scientific grounds for eliminating the case?
- ► Test if the case has a different mean than population
- Report results with and without the case
- Model Averaging to Account for Model Uncertainty?
- Full model  $Y = X\beta + I_n\delta + \epsilon$
- ▶  $2^n$  submodels  $\gamma_i = 0 \Leftrightarrow \delta_i = 0$
- If  $\gamma_i = 1$  then case i has a different mean "mean shift" outliers.

## Mean Shift = Variance Inflation

- ► Model  $Y = X\beta + I_n\delta + \epsilon$
- ► Prior

$$\delta_i \mid \gamma_i \sim N(0, V\sigma^2\gamma_i)$$
  
 $\gamma_i \sim \text{Ber}(\pi)$ 

Then  $\epsilon_i$  given  $\sigma^2$  is independent of  $\delta_i$  and

$$\epsilon_i^* \equiv \epsilon_i + \delta_i \mid \sigma^2 \begin{cases} N(0, \sigma^2) & wp \quad (1 - \pi) \\ N(0, \sigma^2(1 + V)) & wp \quad \pi \end{cases}$$

Model Y = X $m{eta} + \epsilon^*$  "variance inflation" V+1=K=7 in the paper by Hoeting et al. package BMA

### Simultaneous Outlier and Variable Selection

```
MC3.REG(all.y = bodyfat$Bodyfat, all.x = as.matrix(bodyfat$Abdom
       num.its = 10000, outliers = TRUE)
Model parameters: PI=0.02 K=7 nu=2.58 lambda=0.28 phi=2.85
     models were selected
Best 5 models (cumulative posterior probability = 0.9939):
          prob
                  model 1 model 2 model 3 model 4 model 5
variables
 all.x
                    х
                            х
                                     X
                                                       х
                                              Х
outliers
 39
       0.94932
                    X
                             х
                                              Х
 204
        0.04117
                                              Х
          0.10427
 207
                             х
                                                       Х
                 0.815
                         0.095
                                  0.044
                                           0.035
                                                    0.004
post prob
```

# Change Error Assumptions

$$Y_i \stackrel{\text{ind}}{\sim} t(\nu, \alpha + \beta x_i, 1/\phi)$$

$$L(\alpha, \beta, \phi) \propto \prod_{i=1}^n \phi^{1/2} \left( 1 + \frac{\phi(y_i - \alpha - \beta x_i)^2}{\nu} \right)^{-\frac{(\nu+1)}{2}}$$

Use Prior  $p(\alpha, \beta, \phi) \propto 1/\phi$ 

Posterior distribution

$$p(\alpha, \beta, \phi \mid Y) \propto \phi^{n/2-1} \prod_{i=1}^{n} \left( 1 + \frac{\phi(y_i - \alpha - \beta x_i)^2}{\nu} \right)^{-\frac{(\nu+1)}{2}}$$

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# Bounded Influence - West 1984 (and references within)

Treat  $\sigma^2$  as given, then *influence* of individual observations on the posterior distribution of  $\beta$  in the model where  $E[Y_i] = x_i^T \beta$  is investigated through the score function:

$$\frac{d}{d\beta}\log p(\beta \mid \mathsf{Y}) = \frac{d}{d\beta}\log p(\beta) + \sum_{i=1}^{n} \mathsf{x}_{i}g(y_{i} - \mathsf{x}_{i}^{\mathsf{T}}\beta)$$

where

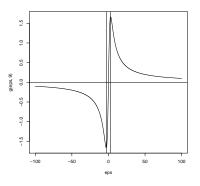
$$g(\epsilon) = -\frac{d}{d\epsilon} \log p(\epsilon)$$

is the influence function of the error distribution (unimodal, continuous, differentiable, symmetric)

An outlying observation  $y_j$  is accommodated if the posterior distribution for  $p(\beta \mid Y_{(i)})$  converges to  $p(\beta \mid Y)$  for all  $\beta$  as  $|Y_i| \to \infty$ . Requires error models with influence functions that go to zero such as the Student t (O'Hagan, 1979)

## Choice of df

 $\triangleright$  Score function for t with  $\alpha$  degrees of freedom has turning points at  $\pm \sqrt{\alpha}$ 



- $g'(\epsilon)$  is negative when  $\epsilon^2 > \alpha$  (standardized errors)
- Contribution of observation to information matrix is negative and the observation is doubtful
- Suggest taking  $\alpha = 8$  or  $\alpha = 9$  to reject errors larger than  $\sqrt{8}$ or 3 sd.

## Scale-Mixtures of Normal Representation

$$Z_i \stackrel{\mathrm{iid}}{\sim} t(\nu, 0, \sigma^2) \Leftrightarrow$$

$$Z_i \mid \lambda_i \stackrel{\mathrm{ind}}{\sim} N(0, \sigma^2/\lambda_i)$$

$$\lambda_i \stackrel{\mathrm{iid}}{\sim} G(\nu/2, \nu/2)$$

Integrate out "latent"  $\lambda$ 's to obtain marginal distribution.

## Latent Variable Model

$$Y_i \mid \alpha, \beta, \phi, \lambda \stackrel{\text{ind}}{\sim} N(\alpha + \beta x_i, \frac{1}{\phi \lambda_i})$$

$$\lambda_i \stackrel{\text{iid}}{\sim} G(\nu/2, \nu/2)$$

$$p(\alpha, \beta, \phi) \propto 1/\phi$$

Joint Posterior Distribution:

$$p((\alpha, \beta, \phi, \lambda_1, \dots, \lambda_n \mid Y) \propto \phi^{n/2} \exp \left\{ -\frac{\phi}{2} \sum_i \lambda_i (y_i - \alpha - \beta x_i)^2 \right\} \times \phi^{-1}$$

$$\prod_{i=1}^n \lambda_i^{\nu/2-1} \exp(-\lambda_i \nu/2)$$

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# Model Specification via R2jags

```
rr.model = function() {
  for (i in 1:n) {
    mu[i] <- alpha0 + alpha1*(X[i] - Xbar)</pre>
    lambda[i] ~ dgamma(9/2, 9/2)
    prec[i] <- phi*lambda[i]</pre>
    Y[i] ~ dnorm(mu[i], prec[i])
  }
  phi ~ dgamma(1.0E-6, 1.0E-6)
  alpha0 ~ dnorm(0, 1.0E-6)
  alpha1 \sim dnorm(0,1.0E-6)
```

# Specifying which Parameters to Save

The parameters to be monitored and returned to R are specified with the variable parameters

- ➤ All of the above (except lambda) are calculated from the other parameters. (See R-code for definitions of these parameters.)
- mu34 and y34 are the mean functions and predictions for a man with a 34 in waist.
- ▶ lambda[39] saves only the 39th case of  $\lambda$
- To save a whole vector (for example all lambdas, just give the vector name)

## Output

	mean	sd	2.5%	50%	97.5%
beta0	-41.70	2.75	-46.91	-41.67	-36.40
beta1	0.66	0.03	0.60	0.66	0.71
sigma	4.48	0.23	4.05	4.46	4.96
mu34	15.10	0.35	14.43	15.10	15.82
y34	14.94	5.15	4.37	15.21	24.65
lambda[39]	0.33	0.16	0.11	0.30	0.72

95% HPD interval for expected bodyfat (14.5, 15.8) 95% HPD interval for bodyfat (5.1, 25.3)

## Comparison

- ▶ 95% Probability Interval for  $\beta$  is (0.60, 0.71) with  $t_9$  errors
- ▶ 95% Confidence Interval for  $\beta$  is (0.58, 0.69) (all data normal model)
- ▶ 95% Confidence Interval for  $\beta$  is (0.61, 0.73) ( normal model without case 39)

Results intermediate without having to remove any observations Case 39 down weighted by  $\lambda_{39}$ 

# Full Conditional for $\lambda_j$

$$\begin{split} \rho(\lambda_j \mid \mathsf{rest}, Y) & \propto & \rho(\alpha, \beta, \phi, \lambda_1, \dots, \lambda_n \mid Y) \\ & \propto & \phi^{n/2 - 1} \prod_{i = 1}^n \exp\left\{-\frac{\phi}{2} \lambda_i (y_i - \alpha - \beta x_i)^2\right\} \times \\ & \prod_{i = 1}^n \lambda_i^{\frac{\nu + 1}{2} - 1} \exp(-\lambda_i \frac{\nu}{2}) \end{split}$$

Ignore all terms except those that involve  $\lambda_j$ 

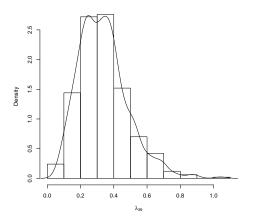
$$\lambda_j \mid \mathsf{rest}, Y \sim G\left(rac{
u+1}{2}, rac{\phi(y_j - lpha - eta x_j)^2 + 
u}{2}
ight)$$

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## Weights

Under prior  $E[\lambda_i]=1$  Under posterior, large residuals are down-weighted (approximately those bigger than  $\sqrt{\nu}$ )

#### Posterior Distribution



#### Prior Distributions on Parameter

As a general recommendation, the prior distribution should have "heavier" tails than the likelihood

- with  $t_9$  errors use a  $t_\alpha$  with  $\alpha < 9$
- also represent via scale mixture of normals
- Horseshoe, Double Pareto, Cauchy all have heavier tails

## Sumary

- Classical diagnostics useful for EDA (checking data, potential outliers/influential points) or posterior predictive checks
- BMA/BVS and Bayesian robust regression avoid interactive decision making about outliers
- Robust Regression (Bayes) can still identify outliers through distribution on weights
- continuous versus mixture distribution on scale parameters
- ▶ Other mixtures (sub populations?) on scales and  $\beta$ ?