Bayesian Model Averaging

STA 721: Lecture 17

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Normal Regression Model

Centered regression model where \mathbf{X}^c is the $n \times p$ centered design matrix where all variables have had their means subtracted (may or may not need to be standardized)

$$\mathbf{Y} = \mathbf{1}_n \alpha + \mathbf{X}^c \boldsymbol{\beta} + \boldsymbol{\epsilon}$$



Priors

With 2^p models, subjective priors for β are out of the question for moderate p and improper priors lead to arbitrary Bayes factors leading to **conventional priors** on model specific parameters



Sketch for Marginal

- Integrate out $oldsymbol{eta}_{\gamma}$ using sums of normals
- Find inverse of ${f I}_n+g{f P}_{{f X}_\gamma}$ (properties of projections or Sherman-Woodbury-Morrison Theorem)
- Find determinant of $\phi(\mathbf{I}_n + g\mathbf{P}_{\mathbf{X}_{\gamma}})$
- Integrate out intercept (normal)
- Integrate out ϕ (gamma)
- ullet algebra to simplify quadratic forms to $R^2_{oldsymbol{\gamma}}$
- in the following slides we will assume that ${\bf X}_{\gamma}$ is centered so that ${\bf 1}_n^T{\bf X}_{\gamma}={\bf 0}_p$ for all models \mathcal{M}_{γ}

Or integrate α , β_{γ} and ϕ (complete the square!)



Posterior Distributions on Parameters

$$egin{aligned} lpha \mid m{\gamma}, \phi, y &\sim \mathsf{N}\left(ar{y}, rac{1}{n\phi}
ight) \ m{eta}_{m{\gamma}} \mid m{\gamma}, \phi, g, y &\sim \mathsf{N}\left(rac{g}{1+g}\hat{m{eta}}_{m{\gamma}}, rac{g}{1+g}rac{1}{\phi}igl[m{X}_{m{\gamma}}^Tm{X}_{m{\gamma}}igr]^{-1}igr) \ m{\phi} \mid m{\gamma}, y &\sim \mathsf{Gamma}\left(rac{n-1}{2}, rac{\mathsf{TotalSS} - rac{g}{1+g}\mathsf{RegSS}}{2}
ight) \ \mathsf{TotalSS} \equiv \sum_i (y_i - ar{y})^2 \ \mathsf{RegSS} \equiv \hat{m{eta}}_{m{\gamma}}^Tm{X}_{m{\gamma}}^Tm{X}_{m{\gamma}}\hat{m{\beta}}{m{\gamma}} \ m{R}_{m{\gamma}}^2 = rac{\mathsf{RegSS}}{\mathsf{TotalSS}} = 1 - rac{\mathsf{ErrorSS}}{\mathsf{TotalSS}} \end{aligned}$$



Priors on Model Space

$$p(\mathcal{M}_{\gamma}) \Leftrightarrow p(oldsymbol{\gamma})$$

- ullet Fixed prior probability $\gamma_j \, p(\gamma_j = 1) = .5 \Rightarrow P(\mathcal{M}_\gamma) = .5^p$
- Uniform on space of models $p_{m{\gamma}} \sim \mathsf{Bin}(p,.5)$
- Hierarchical prior

$$\gamma_j \mid \pi \stackrel{ ext{iid}}{\sim} \mathsf{Ber}(\pi) \ \pi \sim \mathsf{Beta}(a,b) \ ext{then } p_{oldsymbol{\gamma}} \sim \mathsf{BB}_p(a,b)$$

$$p(p_{m{\gamma}} \mid p, a, b) = rac{\Gamma(p+1)\Gamma(p_{m{\gamma}} + a)\Gamma(p-p_{m{\gamma}} + b)\Gamma(a+b)}{\Gamma(p_{m{\gamma}} + 1)\Gamma(p-p_{m{\gamma}} + 1)\Gamma(p+a+b)\Gamma(a)\Gamma(b)}$$

- Uniform on Model Size $\Rightarrow p_{oldsymbol{\gamma}} \sim \mathsf{BB}_p(1,1) \sim \mathsf{Unif}(0,p)$



Posterior Probabilities of Models

Calculate posterior distribution analytically under enumeration.

$$p(\mathcal{M}_{\gamma} \mid \mathbf{Y}) = rac{p(\mathbf{Y} \mid oldsymbol{\gamma})p(oldsymbol{\gamma})}{\sum_{oldsymbol{\gamma}' \in \Gamma} p(\mathbf{Y} \mid oldsymbol{\gamma}')p(oldsymbol{\gamma}')}$$

- Express as a function of Bayes factors and prior odds!
- Use MCMC over Γ Gibbs, Metropolis Hastings if p is large (depends on Bayes factors and prior odds)
- slow convergence/poor mixing with high correlations
- Metropolis Hastings algorithms more flexibility (swap pairs of variables or use adaptive Independent Metropolis!)



No need to run MCMC over γ , β_{γ} , α , and ϕ !



Choice of g: Bartlett's Paradox

The Bayes factor for comparing γ to the null model:

$$BF(m{\gamma}:m{\gamma}_0) = (1+g)^{(n-1-p_{m{\gamma}})/2}(1+g(1-R_{m{\gamma}}^2))^{-(n-1)/2}$$

- ullet For fixed sample size n and $R^2_{oldsymbol{\gamma}}$, consider taking values of g that go to infinity
- Increasing vagueness in prior
- What happens to BF as $g \to \infty$?



Bartlett Paradox

Why is this a paradox?



Information Paradox

The Bayes factor for comparing γ to the null model:

$$BF(m{\gamma}:m{\gamma}_0)=(1+g)^{(n-1-p_{m{\gamma}})/2}(1+g(1-R_{m{\gamma}}^2))^{-(n-1)/2}$$

- Let g be a fixed constant and take n fixed.
- Usual F statistic for testing $m{\gamma}$ versus $m{\gamma}_0$ is $F=rac{R_{m{\gamma}}^2/p_{m{\gamma}}}{(1-R_{m{\gamma}}^2)/(n-1-p_{m{\gamma}})}$
- As $R^2_{m{\gamma}} o 1, F o\infty$ Likelihood Rqtio test (F-test) would reject $m{\gamma}_0$ where F is the usual F statistic for comparing model $m{\gamma}$ to $m{\gamma}_0$
- BF converges to a fixed constant $(1+g)^{n-1-p_{\gamma}/2}$ (does not go to infinity!

Information Inconsistency of Liang et al JASA 2008



Mixtures of *g*-priors & Information consistency

- ullet Want $\mathsf{BF} o \infty$ if $\mathsf{R}^2_{oldsymbol{\gamma}} o 1$ if model is full rank
- Put a prior on g

$$BF(m{\gamma}:m{\gamma}_0) = rac{C\int (1+g)^{(n-1-p_{m{\gamma}})/2}(1+g(1-R_{m{\gamma}}^2))^{-(n-1)/2}\pi(g)dg}{C}$$

ullet interchange limit and integration as $R^2 o 1$ want

$$\mathsf{E}_g[(1+g)^{(n-1-p_\gamma)/2}]$$

to diverge under the prior



One Solution

hyper-g prior (Liang et al JASA 2008)

$$p(g) = rac{a-2}{2} (1+g)^{-a/2}$$

or
$$g/(1+g) \sim Beta(1,(a-2)/2)$$
 for $a>2$

- ullet prior expectation converges if $a>n+1-p_{oldsymbol{\gamma}}$ (properties of ${}_2F_1$ function)
- Consider minimal model $p_\gamma=1$ and n=3 (can estimate intercept, one coefficient, and σ^2 , then for a>3 integral exists
- For $2 < a \le 3$ integral diverges and resolves the information paradox! (see proof in Liang et al JASA 2008)



Examples of Priors on g

- hyper-g prior (Liang et al JASA 2008)
 - Special case is Jeffreys prior for g which corresponds to a=2 (improper)
- ullet Zellner-Siow Cauchy prior $1/g \sim \mathsf{Gamma}(1/2,n/2)$
- Hyper-g/n $(g/n)(1+g/n)\sim \mathsf{Beta}(1,(a-2)/2)$ (generalized Beta distribution)
- robust prior (Bayarri et al Annals of Statistics 2012)
- Intrinsic prior (Womack et al JASA 2015)

All have prior tails for β that behave like a Cauchy distribution and all except the Gamma prior have marginal likelihoods that can be computed using special hypergeometric functions (${}_2F_1$, Appell F_1)

No fixed value of g (i.e a point mass prior) will resolve this!



US Air Example



Summary

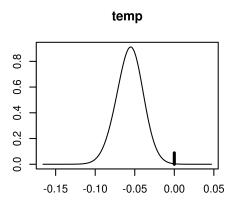
1 summary(poll.bma, n.models=4)

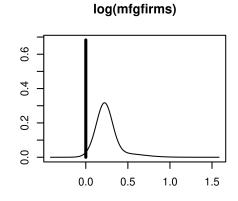
```
P(B != 0
                          Y) model 1
                                       model 2
                                                 model 3
                                                            model 4
                 1.00000000 1.00000 1.0000000 1.0000000 1.0000000
Intercept
                 0.91158530 1.00000 1.0000000 1.0000000
                                                          1.0000000
temp
                 0.31718916 0.00000 0.0000000 0.0000000 1.0000000
log(mfgfirms)
                 0.09223957 0.00000 0.0000000 0.0000000 0.0000000
log(popn)
wind
                 0.29394451 0.00000 0.0000000 0.0000000 1.0000000
                 0.28384942 0.00000 1.0000000 0.0000000 1.0000000
precip
raindays
                 0.22903262 0.00000 0.0000000 1.0000000 0.0000000
BF
                            1.00000 0.3286643 0.2697945 0.2655873
PostProbs
                             0.29410 0.0967000 0.0794000 0.0781000
R2
                             0.29860 \ 0.3775000 \ 0.3714000 \ 0.5427000
dim
                          NA 2.00000 3.0000000 3.0000000 5.0000000
logmarq
                          NA 3.14406 2.0313422 1.8339656 1.8182487
```

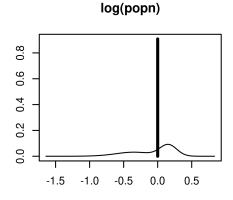


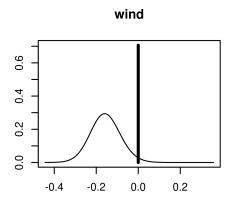
Plots of Coefficients

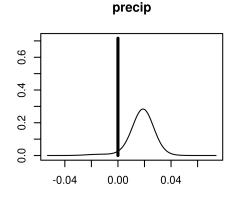
- beta = coef(poll.bma)
- 2 par(mfrow=c(2,3)); plot(beta, subset=2:7,ask=F)

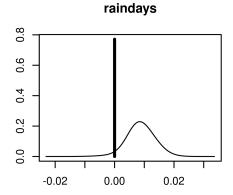








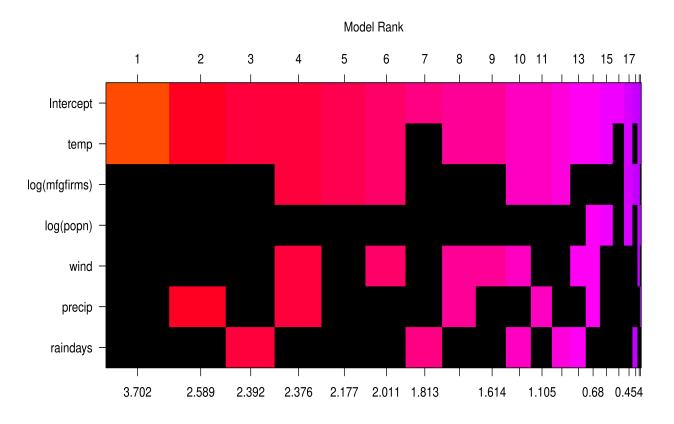






Posterior Distribution with Uniform Prior on Model Space

1 image(poll.bma, rotate=FALSE)



Log Posterior Odds



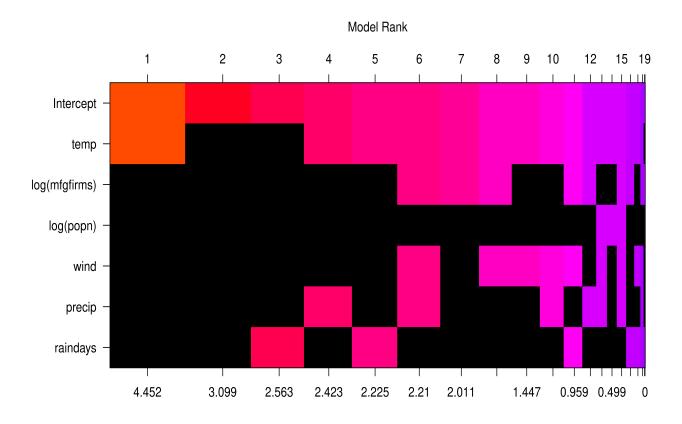


Posterior Distribution with BB(1,1) Prior on Model Space



Posterior Distribution with BB(1,1) Prior on Model Space

1 image(poll.bb.bma, rotate=FALSE)



Log Posterior Odds





Summary

- Choice of prior on $oldsymbol{eta}_{\gamma}$
- \bullet g-priors or mixtures of g (sensitivity)
- priors on the models (sensitivity)
- posterior summaries select a model or "average" over all models

