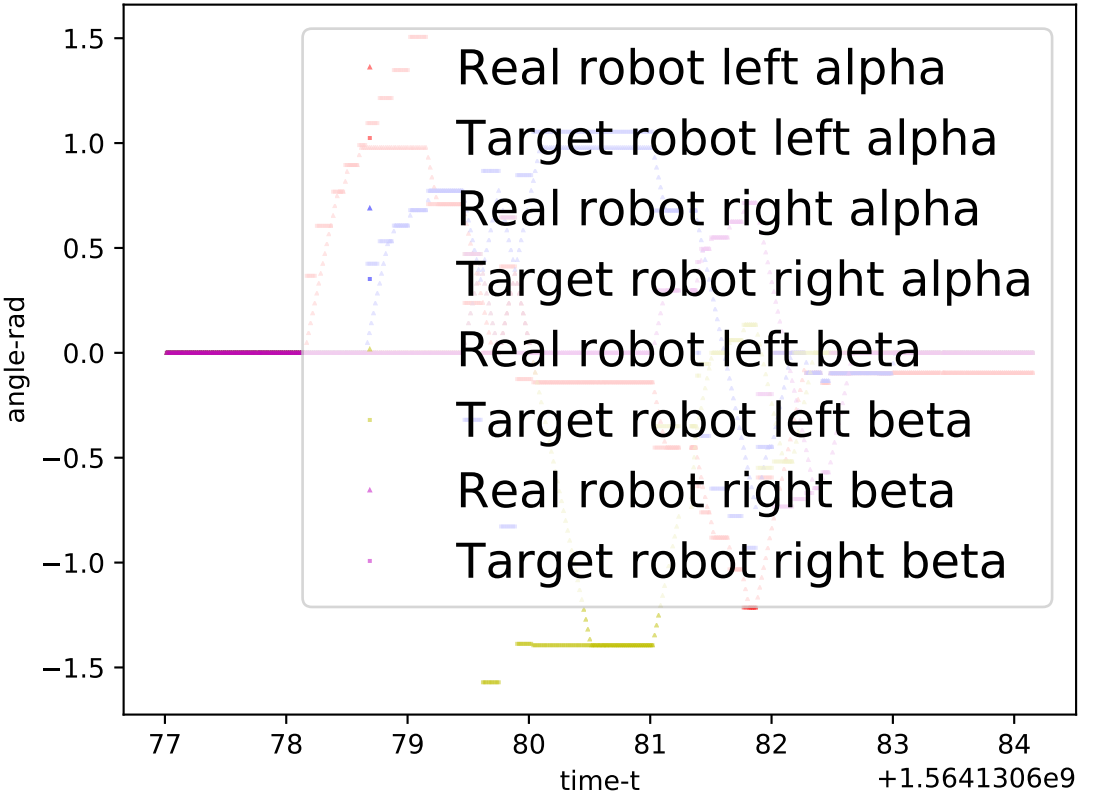
Real robot left alpha
Target robot left alpha
Real robot right alpha
Target robot right alpha
Real robot left beta
Target robot left beta
Real robot right beta
Target robot right beta
angle-rad
1.5
1.0
0.5
0.0
−0.5
−1.0
−1.5
77
78
79
80
81
82
83
84
time-t
+1.5641306e9