### SUPPORT VECTOR MACHINES 2

-STATISTICAL LEARNING AND DATA MINING-

Lecturer: Darren Homrighausen, PhD

#### OPTIMAL SEPARATING HYPERPLANE

REMINDER: The optimal separating hyperplane is produced by maximizing

$$\sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i=1}^{n} \sum_{k=1}^{n} \alpha_{i} \alpha_{k} Y_{i} Y_{k} X_{i}^{\top} X_{k}$$

subject to  $\alpha_i \geq 0$ 

A similar result holds after the introduction of slack variables (e.g. support vector classifiers. In fact, the only difference is  $\alpha_i \leq \lambda$  for each i)

IMPORTANT: The features only enter via

$$X^{\top}X' = \langle X, X' \rangle$$

### (Kernel) ridge regression

REMINDER: Suppose we want to predict at X, then

$$\hat{f}(X) = X^{\top} \hat{\beta}_{\text{ridge}}(\lambda) = X^{\top} \mathbb{X}^{\top} (\mathbb{X} \mathbb{X}^{\top} + \lambda I)^{-1} Y$$

Also,

$$\mathbb{X}\mathbb{X}^{\top} = \begin{bmatrix} \langle X_1, X_1 \rangle & \langle X_1, X_2 \rangle & \cdots & \langle X_1, X_n \rangle \\ & \vdots & & \\ \langle X_n, X_1 \rangle & \langle X_n, X_2 \rangle & \cdots & \langle X_n, X_n \rangle \end{bmatrix}$$

and

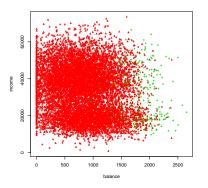
$$X^{\top}X^{\top} = [\langle X, X_1 \rangle, \langle X, X_2 \rangle, \cdots, \langle X, X_n \rangle]$$

Again, we have the features enter only as

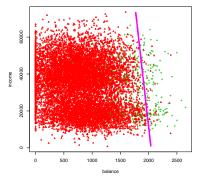
$$\langle X, X' \rangle = X^{\top} X'$$

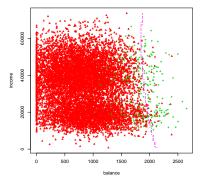
Let's look at the default data in ISL

In particular, we will look at default status as a function of balance and income



out.glm = glm(default~balance + income,family='binomial')





CONCLUSION: Linear rules in a transformed space can have nonlinear decisions in original features

REMINDER: The logistic model: untransformed

$$\begin{aligned} \operatorname{logit}(\mathbb{P}(Y=1|X)) &= \beta_0 + \beta^\top X \\ &= \beta_0 + \beta_1 \operatorname{balance} + \beta_2 \operatorname{income} \end{aligned}$$

The decision boundary is the hyperplane  $\{X: \beta_0 + \beta^\top X = 0\}$ 

This is linear in the feature space

Adding the polynomial transformation:

$$\Phi(X) = (\phi_1(X), \phi_2(X), \phi_3(X)) = (x_1, x_2, x_2^2)$$

$$\begin{aligned} \operatorname{logit}(\mathbb{P}(Y=1|X)) &= \beta_0 + \beta^{\top} \Phi(X) \\ &= \beta_0 + \beta_1 \operatorname{balance} + \beta_2 \operatorname{income} + \beta_3 \operatorname{income}^2 \end{aligned}$$

Decision boundary is still a hyperplane  $\{X : \beta_0 + \beta^\top \Phi(X) = 0\}$ 

This is nonlinear in the original  $x_1, x_2$  feature space, but is linear in terms of  $\Phi(X)$ !

Of course, as we include more transformations,

- We need to choose the transformations manually
- Computations can become difficult if we aren't careful
- We need to regularize to prevent overfitting

Can we form them in an automated fashion?

## Kernel Methods

#### KERNEL: EXAMPLE

Back to polynomial terms/interactions  $\Phi(X) = (x_1, x_2, x_2^2)$ :

What if instead we could form a (kernel) function that produces these polynomial terms automatically?

#### WE CAN!

$$\rightarrow$$
 Form  $k(X, X') = (X^{\top}X' + 1)^d$ 

This kernel implicitly forms all polynomials/interactions up to degree  $\emph{d}$ 

#### KERNEL: EXAMPLE

EXAMPLE: Let d = p = 2

$$k(u, v) = 1 + 2u_1v_1 + 2u_2v_2 + u_1^2v_1^2 + u_2^2v_2^2 + 2u_1u_2v_1v_2$$

$$= \sum_{k=1}^{M} \Phi_k(u)\Phi_k(v) \qquad (M = 6)$$

$$= \Phi(u)^{\top}\Phi(v)$$

$$= \langle \Phi(u), \Phi(v) \rangle$$

where

$$\Phi(\nu)^\top = [1, \sqrt{2}\nu_1, \sqrt{2}\nu_2, \nu_1^2, \nu_2^2, \sqrt{2}\nu_1\nu_2]$$

IMPORTANT: These equalities are everything that makes kernelization work!

#### Kernel: Conclusion

Let's recap:

$$k(u, v) = 1 + 2u_1v_1 + 2u_2v_2 + u_1^2v_1^2 + u_2^2v_2^2 + 2u_1u_2v_1v_2$$
  
=  $\langle \Phi(u), \Phi(v) \rangle = \Phi(u)^{\top} \Phi(v)$ 

where

$$\Phi(v)^{\top} = [1, \sqrt{2}v_1, \sqrt{2}v_2, v_1^2, v_2^2, \sqrt{2}v_1v_2]$$

• Some methods only involve features via inner products  $X^{\top}X' = \langle X, X' \rangle$ 

(We've explicitly seen two: ridge regression and support vector classifiers)

- If we make transformations of X to  $\Phi(X)$ , the procedure depends on  $\Phi(X)^{\top}\Phi(X') = \langle \Phi(X), \Phi(X') \rangle$
- CRUCIAL: We can compute this inner product via the kernel:

$$k(X,X') = \langle \Phi(X), \Phi(X') \rangle$$

#### Kernel: Conclusion

Instead of creating a very high dimensional object via transformations, choose a kernel k

Now, the only thing left to do is form the outer product of kernel evaluations

$$\mathbb{K} = [k(X_i, X_{i'})]_{1 \leq i, i' \leq n}$$

# (Kernel) SVMs

#### KERNEL SVM

RECALL:

$$\frac{1}{2} ||\beta||_2^2 - \sum_{i=1}^n \alpha_i [Y_i(X_i^\top \beta + \beta_0) - 1]$$

Derivatives with respect to  $\beta$  and  $\beta_0$  imply:

- $\beta = \sum_{i=1}^{n} \alpha_i Y_i X_i$
- $0 = \sum_{i=1}^n \alpha_i Y_i$

Write the solution function

$$f(X) = \beta_0 + \beta^\top X = \beta_0 + \sum_{i=1}^n \alpha_i Y_i X_i^\top X$$

Kernelize the SVC  $\Rightarrow$  support vector machine (SVM):

$$f(X) = \beta_0 + \sum_{i=1}^n \alpha_i Y_i k(X_i, X)$$

#### GENERAL KERNEL MACHINES

We can write the eigenvalue expansion of k as

$$k(x, y) = \sum_{j=1}^{\infty} \theta_j \phi_j(x) \phi_j(y)$$

(This is called Mercer's theorem, and such a k is called a Mercer kernel)

Replacing inner products with kernel evaluations is equivalent to performing the unkernelized method in the space given by the eigenfunctions of k with feature map  $\Phi = [\phi_1, \dots, \phi_p, \dots]$ 

#### POLYNOMIAL EXAMPLE:

$$k(u, v) = 1 + 2u_1v_1 + 2u_2v_2 + u_1^2v_1^2 + u_2^2v_2^2 + 2u_1u_2v_1v_2$$
  
=  $\sum_{k=0}^{M} \Phi_k(u)\Phi_k(v)$ ,

where: 
$$\Phi(v)^{\top} = [1, \sqrt{2}v_1, \sqrt{2}v_2, v_1^2, v_2^2, \sqrt[3]{2}v_1v_2]^{-\frac{1}{2}}$$

#### KERNEL SVMS

Hence (and luckily) specifying  $\Phi$  itself unnecessary,

We need only define the kernel that is symmetric, positive definite

Some common choices for SVMs:

- POLYNOMIAL:  $k(X, X') = (1 + X^{T}X')^{d}$
- RADIAL BASIS:  $k(X, X') = e^{-\tau ||X X'||_b^b}$ (For example, b = 2 and  $\tau = \sigma^{-2}/2$  is (proportional to) the Gaussian density)

#### KERNEL SVMs: SUMMARY

Reminder: the solution form for SVM is

$$\beta = \sum_{i=1}^{n} \alpha_i Y_i X_i$$

Kernelized, this is

$$\beta = \sum_{i=1}^{n} \alpha_i Y_i \Phi(X_i)$$

Therefore, the induced hyperplane is:

$$f(X) = \Phi(X)^{\top} \beta + \beta_0 = \sum_{i=1}^{n} \alpha_i Y_i \langle \Phi(X), \Phi(X_i) \rangle + \beta_0$$
$$= \sum_{i=1}^{n} \alpha_i Y_i k(X, X_i) + \beta_0$$

The final classification is still  $\hat{g}(X) = \operatorname{sgn}(\hat{f}(X))$ 

# SVMs via penalization

#### SVMs via penalization

NOTE: SVMs can be derived from penalized loss methods

The support vector classifier optimization problem:

$$\min_{\beta_0,\beta,\xi} \frac{1}{2} ||\beta||_2^2 + \lambda \sum_{i} \xi_i \text{ subject to}$$

$$Y_i f(X_i) \ge 1 - \xi_i, \xi_i \ge 0,$$
, for each  $i$ 

Consider the alternative optimization problem:

$$\min_{\beta,\beta_0} \sum_{i=1}^n [1 - Y_i f(X_i)]_+ + \tau ||\beta||_2^2$$

These optimization problems are the same!

(With the relation:  $2\lambda = 1/\tau$ )



#### SVMs via penalization

The loss part is the hinge loss function

$$\ell(f(X), Y) = [1 - Yf(X)]_+$$

The hinge loss approximates the zero-one loss function underlying classification

It has one major advantage, however: convexity

### Surrogate losses

Looking at

$$\min_{\beta,\beta_0} \sum_{i=1}^n [1 - Y_i f(X_i)]_+ + \tau ||\beta||_2^2$$

It is tempting to minimize (analogous to linear regression)

$$\sum_{i=1}^{n} \mathbf{1}(Y_i \neq \hat{g}(X_i)) + \tau ||\beta||_2^2$$

However, this is nonconvex

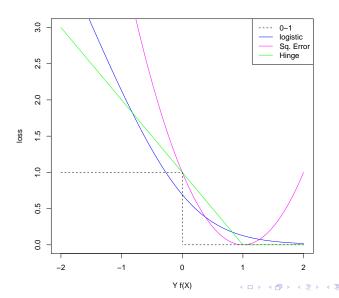
#### Surrogate losses

IDEA: We can use a surrogate loss that mimics this function while still being convex

It turns out we have already done that! (twice times)

- HINGE:  $[1 Yf(X)]_+$
- LOGISTIC:  $\log(1 + e^{-Yf(X)})$

#### Comparing loss functions



#### SVMs in practice

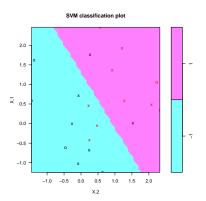
GENERAL FUNCTIONS: The basic SVM functions are in the C++ library libsym

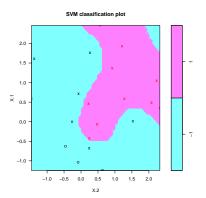
R PACKAGE: The R package e1071 calls libsvm

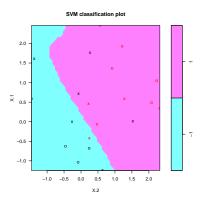
PATH ALGORITHM: sympath

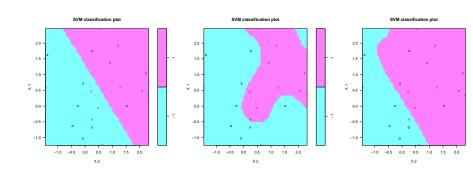
For a nice comparison of these approaches, see "Support vector machines in R"

(http://www.jstatsoft.org/v15/i09/paper)









## Multiclass SVMs

#### Multiclass SVMs

Sometimes, it becomes necessary to do multiclass classification

There are two main approaches:

- One-versus-one
- One-vesus-all

#### Multiclass SVMs: One-versus-one

Here, for G possible classes, we run G(G-1)/2 possible pairwise classifications

For a given test point X, we find  $\hat{f}_k(X)$  for  $k = 1, \dots, G(G - 1)/2$  fits

The result is a vector  $\hat{G} \in \mathbb{R}^G$  with the total number of times X was assigned to each class

We report  $\hat{f}(X) = \operatorname{arg\,max}_g \hat{G}$ 

This approach leverages all the class information, but can be REALLY slow

(It does have the advantage of only using at any one time the training observations i such that  $Y_i$  has either of two classes we are considering)

#### Multiclass SVMs: One-vesus-all

Here, we fit only G SVMs by respectively collapsing over all size G-1 subsets of  $\{1,\ldots,G\}$ 

Take all  $\hat{h}_g(X)$  for  $g=1,\ldots,G$ , where class g is coded 1 and "the rest" is coded -1

Assign 
$$\hat{f}(X) = \operatorname{arg\,max}_g \hat{h}_g(X)$$