Chapter 7

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Quick review of OLS

- OLS stands for "ordinary least-squares".
- Essentially, it means "solve the least-squares problem"

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \sum_{i=1}^{n} (x_i^{\top} \beta - y_i)^2 = (X^{\top} X)^{-1} X^{\top} Y$$

• The hat matrix is

$$\hat{Y} = X\hat{\beta} = X(X^{\top}X)^{-1}X^{\top}Y = HY$$

- The Gauss-Markov theorem says if:

 - 1. $Y_i = x_i^{\top} \beta + \epsilon_i$ 2. $\mathbb{E} [\epsilon_i] = 0$ 3. $\mathbb{V} [\epsilon_i] = \sigma^2 < \infty$ 4. $\operatorname{Cov} [\epsilon_i, \ \epsilon_j] = 0$

Then $\hat{\beta}$ has the smallest variance of all possible unbiased estimators for β .

What is WLS and why use it?

• Weighted least-squares (WLS) is simply

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \sum_{i=1}^{n} w_i (x_i^{\top} \beta - y_i)^2 = (X^{\top} W X)^{-1} X^{\top} W Y$$

- If some of those assumptions for G-M are violated, in particular, if $\mathbb{V}[\epsilon_i]$ depends on x_i (notated like $\sigma^2(x_i)$), then we lose the optimality.
- Aside: Gauss-Markov is a commonly used justification for OLS in applied work. The logic goes like this: (1) unbiased is good, (2) G-M says OLS is the best linear model which is unbiased. The problem is that (1) is wrong. Unbiased may be good, but often a little bias is better.
- So what does WLS do?
 - 1. It **is** optimal, in the sense of G-M, if $\mathbb{V}\left[\epsilon_i\right] = \sigma^2(x_i)$.
 - 2. You've already used it (see next slide).
 - 3. What if you want to predict Y_i which have other structures like $y_i \in \{0,1\}$? The new estimators (often called GLS for generalized least squares) are special cases of WLS (logistic regression is one example we are building to).

You already used WLS

- I said you already did this. It is convenient that Kernel regression is WLS.
- In particular Kernel regression looks like

$$\hat{c} = \underset{c}{\operatorname{argmin}} \sum_{i=1}^{n} \sum_{i=1}^{n} w_{ij} (c_j - y_i)^2 \quad w_{ij} = \frac{K((x_i - x_j)/h)}{\sum_{i=1}^{n} K((x_i - x_j)/h)}$$

This is locally constant regression.

• You don't need to understand this formula, but it can be useful, and it provides some justification for WLS based on previous ideas.

What goes wrong with heteroskedasticity?

- So suppose $\mathbb{V}[\epsilon_i] = \sigma^2(x_i)$. That is our "homoskedasticity" assumption is violated. Should we care?
- What if we just use OLS (that is 1m) anyway?
- Some things don't change.
 - 1. We still have that $\mathbb{E}\left[\hat{\beta}\right] = \beta$. That is OLS **is** still unbiased.
 - 2. We still have that \overrightarrow{OLS} minimizes the sum of squared residuals: among all lines, OLS makes $\sum_{i=1}^{n} (x_i^{\top} \hat{\beta} y_i)^2$ as small as possible.
- Some things do change.
 - 1. OLS no longer has the best variance of all unbiased estimators (WLS does).
 - 2. The standard errors that R produces are wrong. They make it seem "more certain" than is correct (could use the bootstrap to fix it though).
 - 3. So are the F-tests and p-values (again, the bootstrap).

Log squared residuals

- So WLS is fairly general. But for now, let's focus on how to use it for heteroskedasticity.
- Suppose you **know** the following:
 - 1. $y_i = \beta_0 + \beta_1 x_i + \epsilon_i$.
 - 2. You know $\beta_0 = 3$ and $\beta_1 = 2$.
 - 3. $\mathbb{E}\left[\epsilon_{i}\right]=0$
 - 4. $\mathbb{V}\left[\epsilon_i\right] = \sigma^2(x_i)$ ($\sigma^2(\cdot)$ is a function).
- You don't know $\sigma^2(\cdot)$
- How would you estimate $\sigma^2(x)$?
- You can use nonparametric regression of course!
 - Just look at $e_i = y_i 3 + 2x_i$.
 - We already know that e_i has mean zero, so no use estimating it's mean
 - Therefore $\mathbb{E}\left[e_i^2\right] = \sigma^2(x_i)$.
 - Now this is easy: rewrite the model as $e_i^2 = \sigma^2(x_i) + \eta_i$
 - It's just nonparametric regression (since you know e_i^2 and x_i).

So why not?

- There's one problem with the above line of reasoning: $e_i^2 > 0$ so there are some constraints on η_i .
- Imagine if, say, at x = 1, $\sigma^2(1) = .001$, then it's pretty likely that η is large and positive there, so there's heteroskedasticity in our model for heteroskedasticity...
- If the original ϵ_i were $N(0, \sigma^2(x_i))$, then the new η_i are distributed as χ_1^2 , so these are right skewed, everywhere.
- A remedy is to look at $\log e_i^2 = \log \sigma^2(x_i) + \tau_i$.
- You could try both and look at qq-plots of the residuals. I tend to prefer the second set-up. It's just more satisfying.
- This is just a transformation: just like when you looked at qq-plots and decided to model log Y rather than Y.

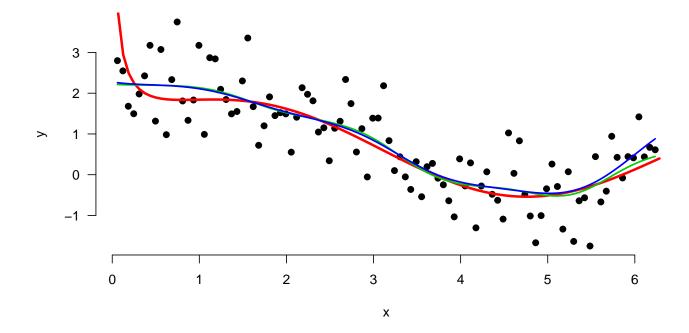
Local linear vs. Kernels

- People often wonder whether to use local linear regression or Kernels.
- Like with many things, there isn't really a cut-and-dried answer.
- Some practitioners prefer local linear regression.
- It's main benefit is to correct "boundary bias".
- Otherwise, not much different.

Repeat of Ch. 4

• We can estimate this easily with both a kernel and local linear regression

```
set.seed(1234)
trueFunction <- function(x) sin(x) + 1/sqrt(x)
x = runif(100, 0, 2*pi)
x = seq(min(x), max(x), length.out=100)
y = trueFunction(x) + rnorm(100, 0, .75)
par(mar=c(5,4,0,0))
plot(x, y, pch=19, bty='n', las=1, cex.lab=1, cex.axis=1)
curve(trueFunction(x), 0, 2*pi, col=2, lwd=3, add=TRUE)
library(np)
kern = npreg(y~x)
loclin = npreg(y~x, regtype='ll')
lines(x, fitted(kern), col=3, lwd=2)
lines(x, fitted(loclin), col=4, lwd=2)</pre>
```



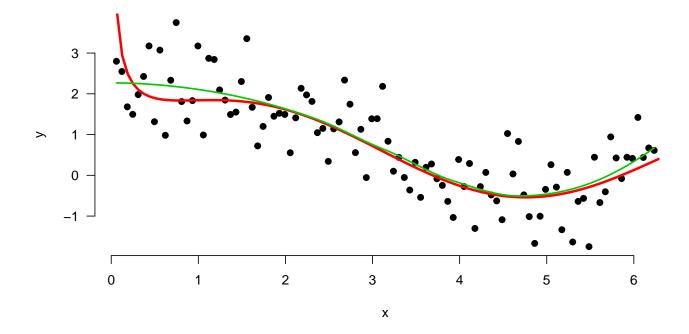
What's the Oracle?

- So back to WLS.
- I had that example where I wanted to estimate the variance function
- In that case I knew the mean: 3+2x
- I knew because the Oracle told me. The Oracle is a wise woman who lives at Delphi according to the ancient Greeks, and speaks the thoughts of Apollo.
- In other words, she tells me things no one could possibly know, like the mean function.
- In statistics, we talk about Oracles a lot, usually as a way of comparing a procedure we cook up for estimating something to the answers the Oracle would have told us (the best possible, but unobtainable estimator).

What is Loess?

- So kernel regressions are local constants, we then saw local linear regression which is quite similar.
- Why stop there? The next term is squared things, then cubics, then...
- Loess uses local polynomials (of some order) in a particular way (combining k-nearest neighbor regression with subsampling).
- It is actually quite cool, but it's complexity makes it hard to deal with.
- Theoretically, one can show that Kernels are optimal, so it's not really worth worrying too much about, but it can work well, and it doesn't require installing a package.
- Here it is on my previous example

```
ls = loess(y~x)
lines(x, predict(ls), col=3, lwd=2)
```



A big example (as promised)

- This is a (slightly modified) portion of a real job interview.
- It is a very simple application of heterosked asticity.
- Heteroskedasticity appears frequently with financial data, so those companies like to see if you can handle it.

The set up

- The dataset jobInt contains data from a simple linear model with heteroskedastic noise.
- In other words, for $i = 1, \ldots, 250$,

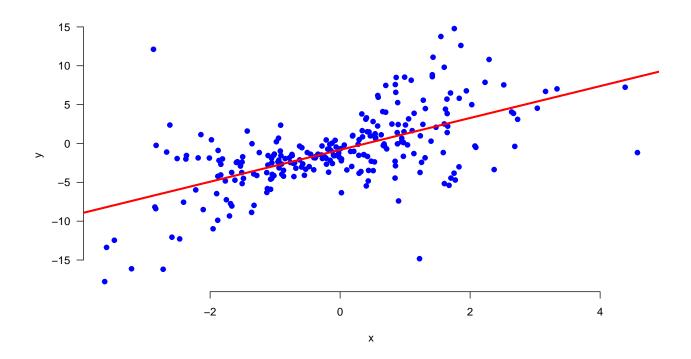
$$y_i = \beta_0 + \beta_1 x_i + \sigma(x_i) \epsilon_i$$
 $\epsilon_i \sim N(0, 1).$

- You know nothing about (the function) $\sigma(\cdot)$.
- Your goal is to estimate (β_0, β_1) as well as possible, and provide a CI.

How do I do this?

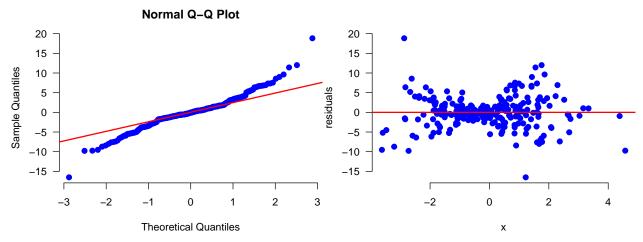
• First things first, EDA.

```
plot(jobInt, pch=19, col=4, bty='n', las=1)
basicMod = lm(y~x)
abline(basicMod, col=2, lwd=3)
```



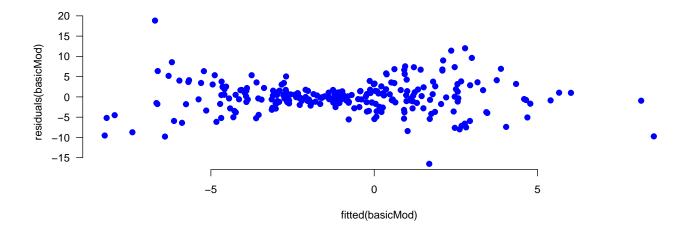
qq-plot and residuals against x

```
par(mfrow=c(1,2), las=1, bty='n', mar=c(5,4,3,0), lwd=2, pch=19)
qqnorm(residuals(basicMod), col=4)
qqline(residuals(basicMod), col=2)
plot(jobInt$x, residuals(basicMod), col=4, xlab='x', ylab='residuals')
abline(h=0, col=2)
```



residuals vs. fitted values

```
par(las=1, bty='n', mar=c(5,4,3,0), lwd=2, pch=19)
plot(fitted(basicMod), residuals(basicMod), col=4)
```



So now what?

- We know that $\mathbb{E}[Y \mid X = x] = \beta_0 + \beta_1 x$.
- We know that $\mathbb{E}\left[\hat{e} \mid X=x\right]=0$.
- We know that $\mathbb{E}\left[\hat{e}^2 \mid X = x\right] = \sigma^2(x)$.
- So we want to try to estimate $\sigma^2(x)$ and β_0 and β_1 all at the same time.

Oracle information

- If we knew β_0 and β_1 , then we could use npreg to estimate $\sigma^2(x)$.
- If we knew $\sigma^2(x)$, then we could use WLS to estimate β_0 and β_1 (and all the SEs would be right!)
- But we don't know either.

Procedure

- 1. Use 1m to estimate β_0 and β_1 .
- 2. Now pretend that you "know" them, calculate $\log(\hat{e}^2)$ and use npreg to estimate $\log \sigma^2(x)$.
- 3. Now pretend that you "know" $\sigma^2(x)$ (take exp of your estimate from 2.) and use WLS (with $lm(y\sim x, weights=1/sig2)$)
- 4. You could stop here. But since you now have "better" estimates of β_1 and β_0 , it's better to iterate 2 and 3 until some convergence.
- 5. Ok. Something converged, so you return the last estimates of β_0 and β_1 . But the SEs are not right (because you "know" $\sigma^2(x)$ but you don't **know** it).
- 6. To get SEs, use the bootstrap:
 - a. Non-parametric: repeat 1-5 ${\cal B}$ times on resampled data.
 - b. Model-based: this is actually pretty hard here, better not to do it.

Some code

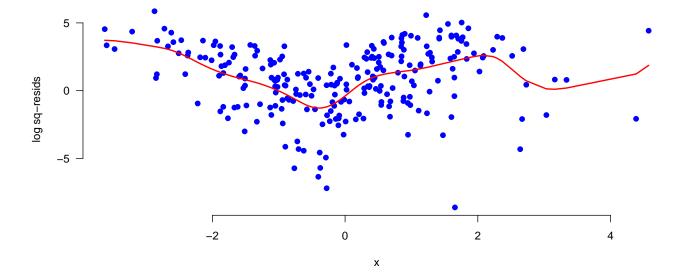
• This code takes in data and does steps 1-5. It is **not** optimized for speed, but for readability, so run with care.

```
heteroWLS <- function(dataFrame, tol = 1e-4, maxit = 100, track=FALSE){
  # inputs: a data object, optional: tolerance, max.iterations, and progress tracker (prints)
  # outputs: estimated betas and weights
  require(np)
  ols = lm(y~x, data=dataFrame)
  b = coefficients(ols)
  conv = FALSE
  for(iter in 1:maxit){ # don't let this run forever
    if(conv) break # if the b's stop moving, get out of the loop
   logSqResids = log(residuals(ols)^2)
   winv = exp(predict(npreg(logSqResids~x, data=dataFrame, tol=1e-2, ftol=1e-2)))
   winv[winv < tol] = tol # zero inverse weights are bad, make them small
   ols = lm(y~x, weights = 1/winv, data=dataFrame) #weights are 1 / estim.variance
   newb = coefficients(ols)
    conv.crit = sum((b-newb)^2) # calculate how much b moved
   if(track) cat('\n', iter, '/', maxit, 'conv.crit = ', conv.crit) # print progress
    conv = (conv.crit < tol) # check if the b's changed much</pre>
   b = newb # update the coefficient estimates
  }
  return(list(betas=b, weights = winv, log2resids = log(residuals(ols)^2)))
```

Do it! (takes a little while...)

```
resampWLS <- function(dataFrame,...) { # ... means options passed on
  rowSamp = sample(1:nrow(dataFrame), size=nrow(dataFrame), replace=TRUE)
  return(heteroWLS(dataFrame[rowSamp,],...)$betas) # passed things on if desired
}
B = 100 #
alp = .05
origBetas = heteroWLS(jobInt)
ptm = proc.time()
bootBetas = replicate(B, resampWLS(jobInt, maxit=20))
ptm = proc.time()-ptm
qq = apply(bootBetas, 1, quantile, probs=c(1-alp/2, alp/2))
CI = cbind(origBetas$betas, 2*origBetas$betas - t(qq))
colnames(CI) = c('coef', rev(colnames(CI)[2:3]))
CI
##
                                        97.5%
                    coef
                              2.5%
## (Intercept) -1.002996 -1.521497 -0.7480195
                1.959554 1.374641 2.4224998
## x
ptm
      user system elapsed
            0.299 50.922
    49.929
```

Some plots



Some caveats

- If we care about estimating $\sigma(\cdot)$, then what we did is ok.
- But we don't.
- We only care about estimating β_0 and β_1 .
- So better to use CV with leaving out (y_i, x_i) , instead of using CV to estimate $\sigma(\cdot)$ (which is what npreg is doing; it know's nothing about y_i)
- This takes a bit more work to code up (Try it!)

Brief intro to Ch. 8

- This chapter is another way of fitting "smooth" curves for regression: splines.
- Splines are very nice, and they turn out to be linear smoothers: we can write

$$\hat{Y} = WY$$
.

• Splines are given by solving

$$\hat{\mu}_{\lambda} = \underset{m}{\operatorname{argmin}} \sum_{i=1}^{n} (y_i - m(x_i))^2 + \lambda \int dx (m''(x))^2.$$

- The first half you know: it's the MSE
- The second half **penalizes** the second derivative of m.
- Second derivatives measure the curvature of a function, the smaller, the smoother.
- With Kernels, we used the bandwidth to control the smoothness, here λ controls it directly.

Some notes

• Of course we choose λ with CV (or GCV)

- Sorry, there is not a good reason (that I know) to prefer splines over Kernels or vice-versa.
- Skip 8.6 (or read it very lightly, and don't ask me questions about it)