

Final phase



ITU AI/ML in 5G Challenge Smart Transportation

AGENDA

- 1 Description of the project
- 2 Requirements analysis & methodology
- 3 Evaluation setup& timeline
- 4 Demonstration
- 5 Team dynamic
- 6 Relevance with automotive industry

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WE ARE





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REGION INSIGHT

2nd

8

Various type of transportation methods, lead to different challenges.

Bicycle, Motor Cycle, Car, Tempo, Bus, Train, etc.

largest road network in The World with length around 4,320,000 kilometers.



4.3_M

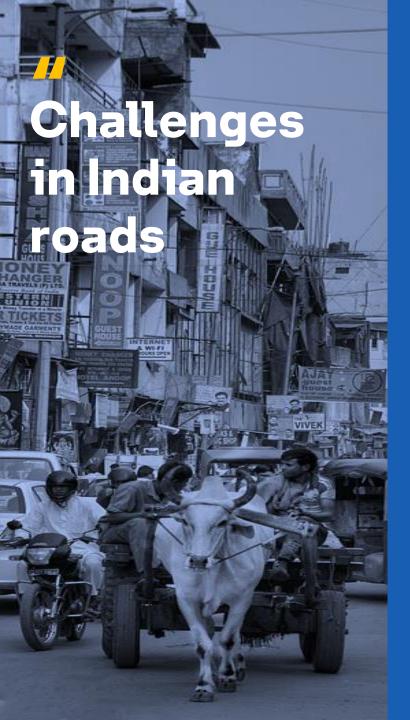
4.3 m road accidents recorded across India in 2019. where the major cause of road accidents (driver behavior, road condition, distraction, etc.)

PROBLEM STATMENT



Road condition one of the main causes of road.

one of the main causes of road safety level around all around the world. This project seeks to improve road condition by address an new techniques for road quality inspection process and instance fixing through emerging technologies.





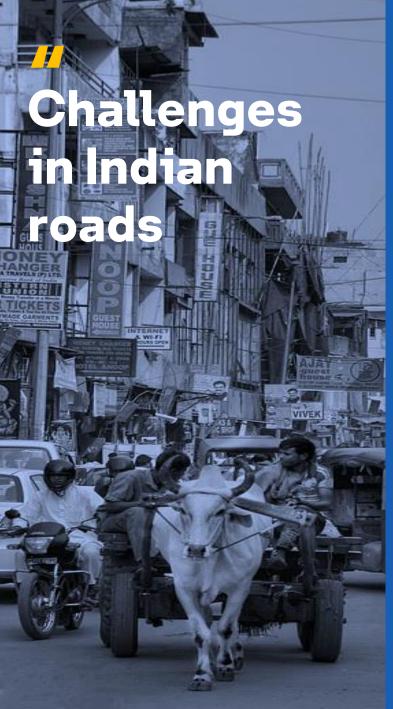
India has one of the most pothole stricken road networks. In 2017, potholes killed 3,597 people in India.

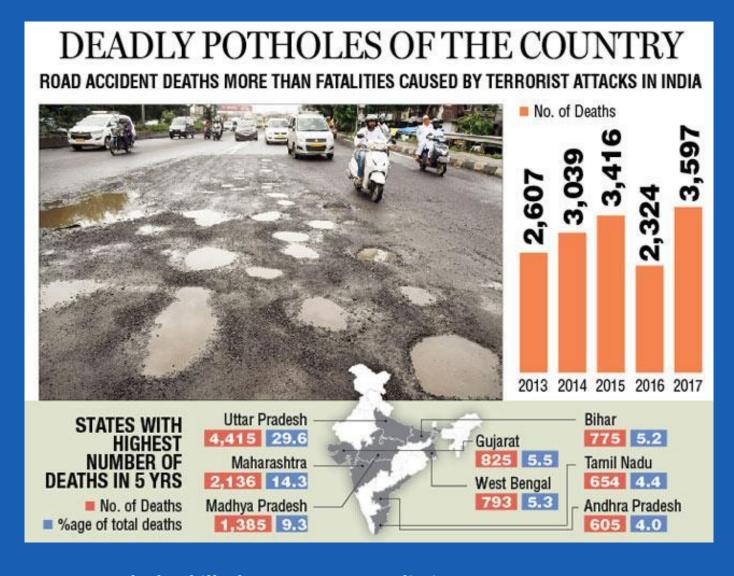


Newly surfaced roads with no lane markings are often seen by motorists as a green pass to speed and cut lanes. But most of roads have little or no markings and uneven signage.

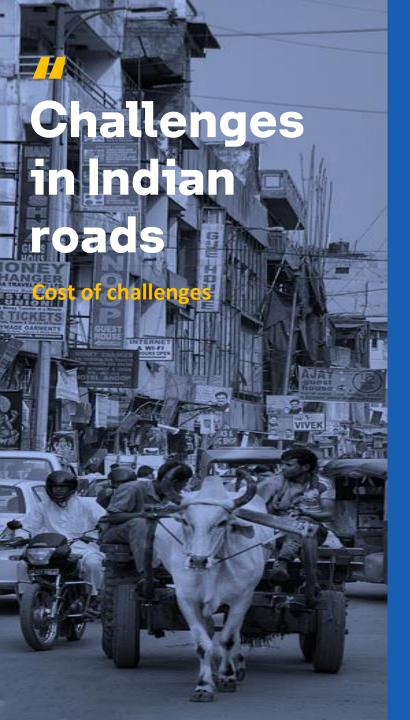
Due to hitting a pothole - or taking the wrong measures to avoid one - can also lead to a crash resulting in injuries or worse. A blown tire or broken suspension part can cause you to lose control of your vehicle, as can a split-second decision to stomp on the brakes or suddenly swerve out of your lane to avoid a pothole.

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Potholes killed 3,597 across India in 2017, terror 803





2.8
M Rs

Potholes are a major factor in causing axle & suspension failure, which counts for a third of mechanical issues on Mumbai roads and costs motorists an estimated Rs.2.8 million every year.



Authorities currently pay out more than Rs.50 million in compensation claims due to poor roads.

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NEW METHODS & TECHNOLGY

Project aims

The project involves the AI to identify road condition and using 5G to enable the remote repair of roads with the goal of reducing manpower and the expertise needed to fix potholes and road lane painting.

ARCHITECTURE





defects in real time

Data analytics Through Al



Remote vehicle control Center owned/authorized by Gov **5G**

Videoframes are the output

Road lab captures

Final report of road status is sent to the client

Operators start manual digitization

Construction vehicle

With GPS and communication model

Send construction vehicle for identifies places

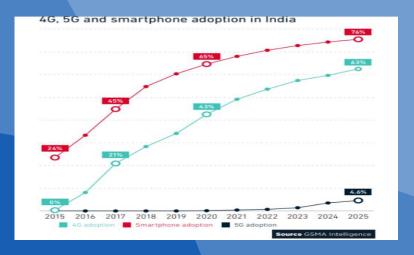
Image/ video Data sources by different of users **Previous collaboration**

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Usability/Motivation



Over than 1 million trip per day leads to real time monitoring



India 5G coverage plan

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Challenges

01

New machines & vehicle support 5G network.

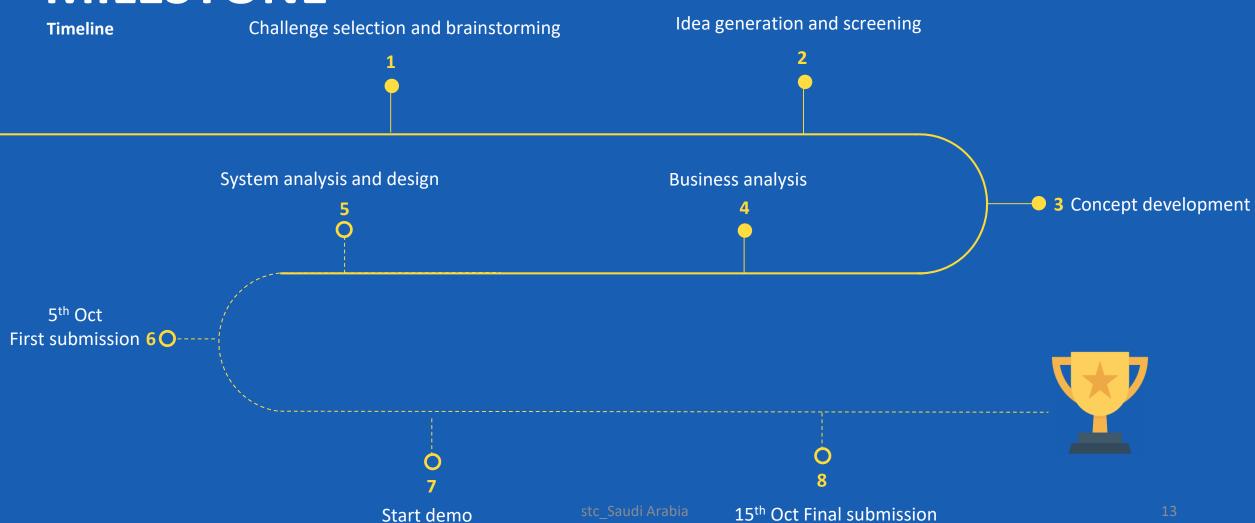
02

Real data availability to train the Al model.

03

New regulations for remote driving.

PROJECT MILESTONE



HOW 5G AND ALLIS BEING USED IN SOLUTION



5G



- I. High-definition video feeds from trucks can be sent back and distributed to the local control center via the 5G network and MEC for remote monitoring.
- II. Control the vehicle remotely as a result the 5G network's low latency.



Al



. To automate manual work of operators who search and select road defects from road laboratories video footage, like cracks, holes and patches.

END USER DETAILS







Road condition report to report road defects in real time



Vehicle control center
Remote driving machine for road fixing

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GOALS TO BE ACHIEVED

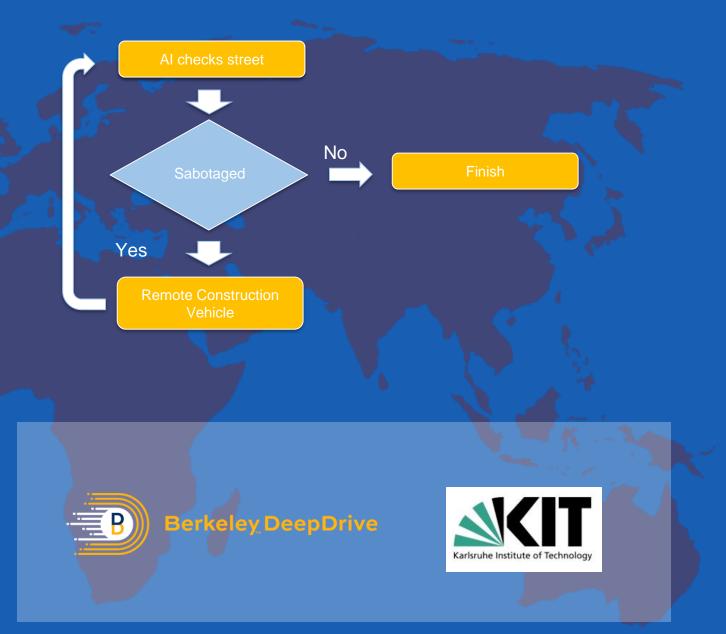
Project aims

- 1 Work efficiency
- Visible road lane and good road condition
- 3 Low car accidences
- 4 Decrease human risk

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Use case diagram/Flow chart

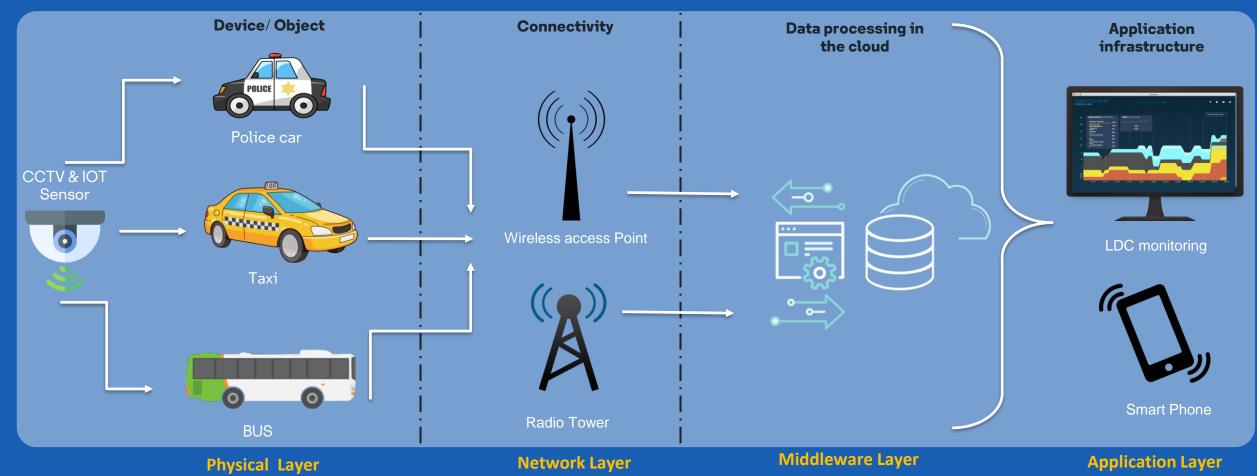
System Design and Data set



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ARCHITECTURE



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Evaluation Setup & Timeline

Metrics to be used (Quantitative and Qualitative)

Quantitative

of covered roads

To measure the roads covering by setting the covering baseline and target

% of defects repaired

To measure the percentage of repairing the identified defects

of vehicles detect road defects in real time To measure the efficiency of vehicles which will detect the defects and their ability to do the work

% of time consumed in defects repairing

To measure the real time per defect repairing

Qualitative

Road color/slop after repairing

To measure the overall work done in repairing defects and compare it with the ideal work

Customer satisfaction survey

To see what customers think of the work done and the solution impact

Focus groups

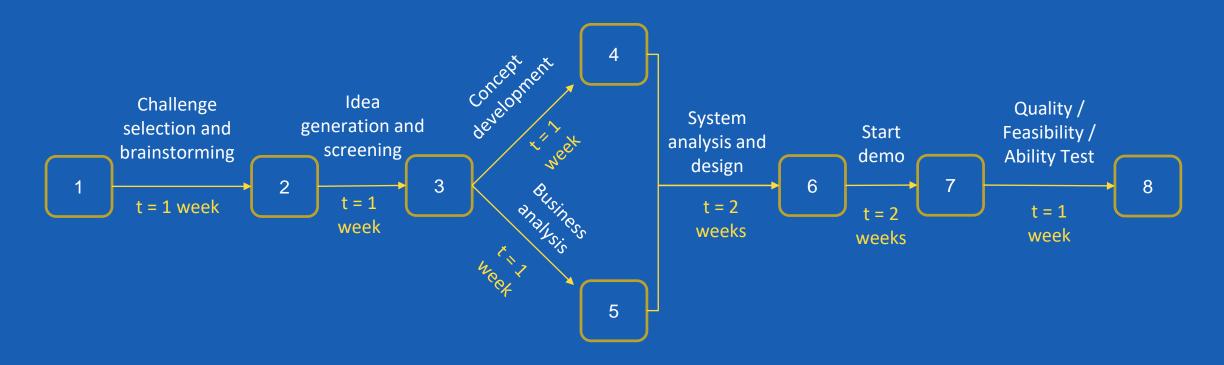
To see what customers think of the work done and the solution impact

Individual Interview

To see what customers think of the work done and the solution impact

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Pert Chart



Solution Developed Type

The solution development type is an algorithm to use 5G and AI in repairing road defects while using control centers, remote driving vehicles, and cams using mobile app

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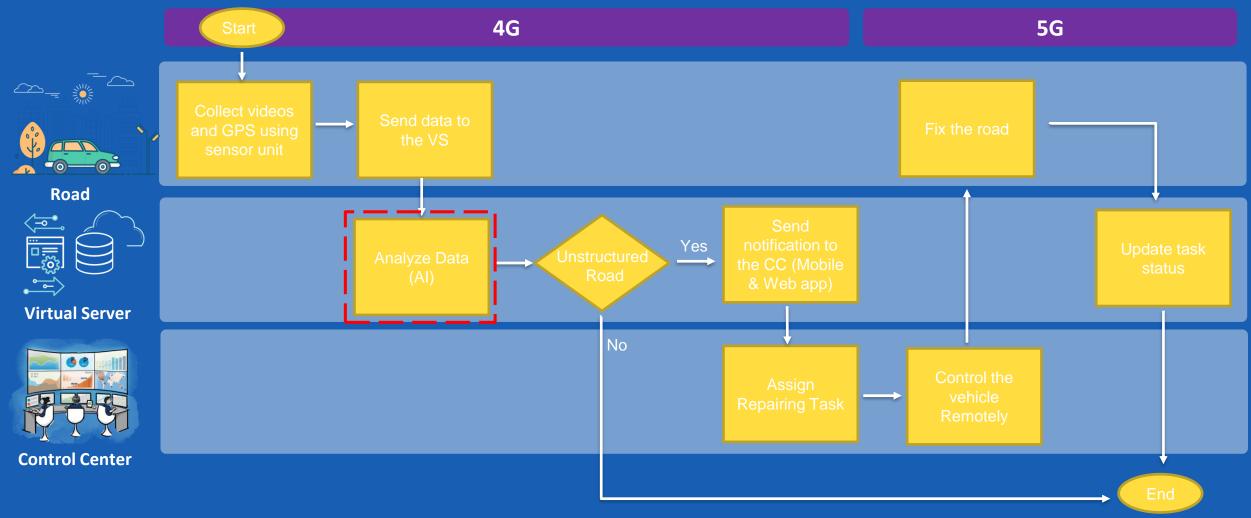
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SOLUTION

Flowchart



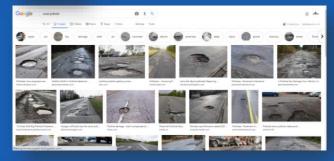


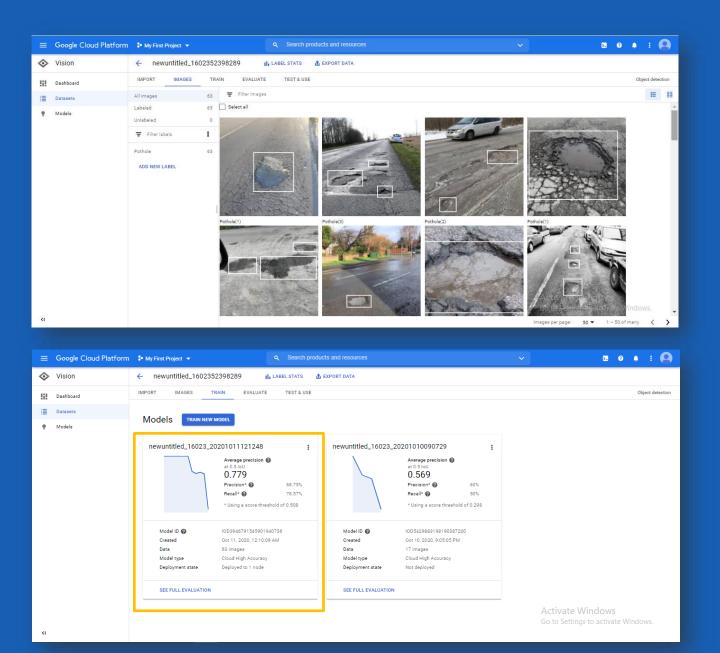


Cloud AutoML



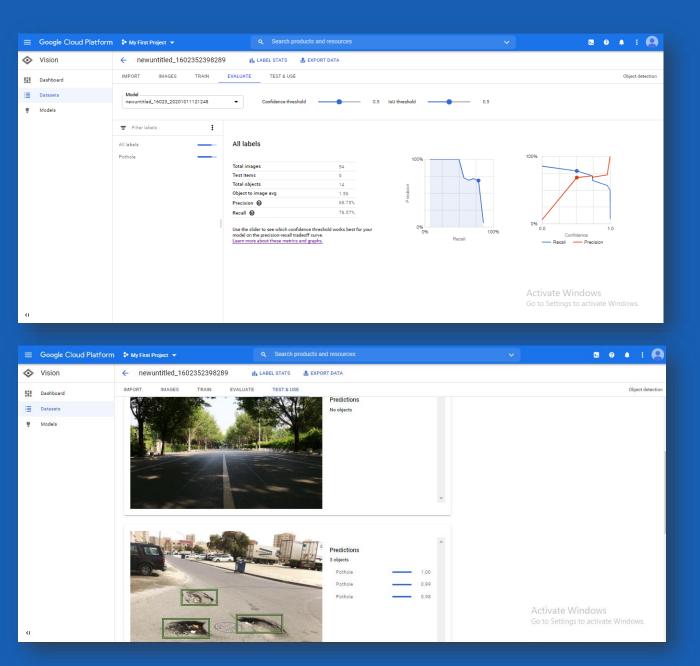
Batch Image Download Full Screen Capture





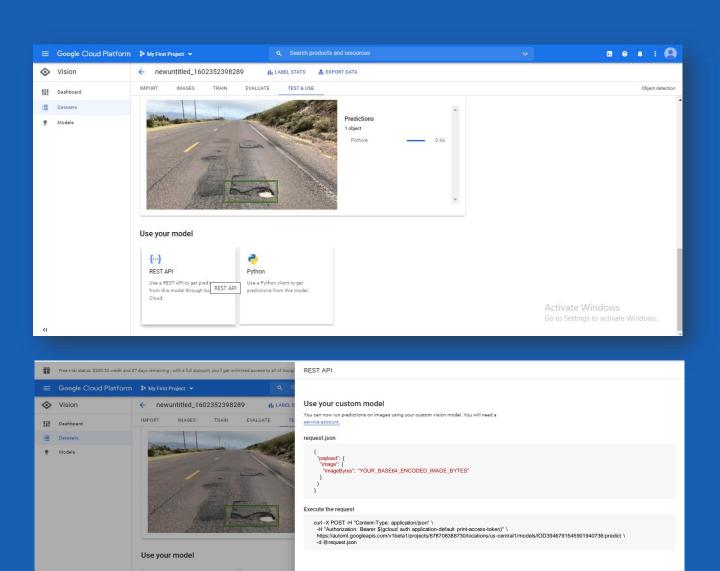
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Use a REST API to get predictions

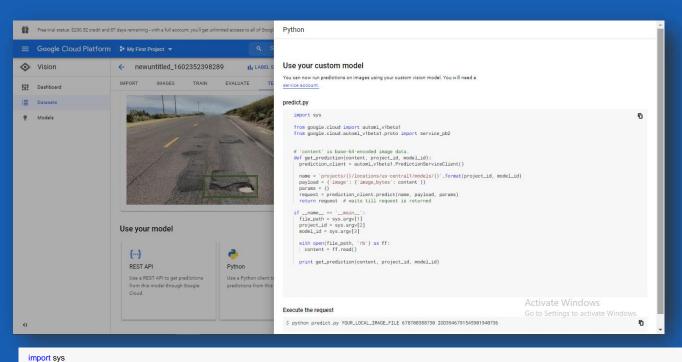
from this model through Google

Use a Python clien

predictions from th

(AI)

Analyze Data

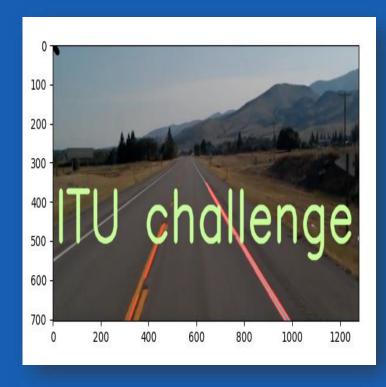


```
from google.cloud import automl_v1beta1
from google.cloud.automl_v1beta1.proto import service_pb2
# 'content' is base-64-encoded image data.
def get_prediction(content, project_id, model_id):
prediction_client = automl_v1beta1.PredictionServiceClient()
name = 'projects/{}/locations/us-central1/models/{}'.format(project_id, model_id)
payload = {'image': {'image_bytes': content }}
request = prediction_client.predict(name, payload, params)
 return request # waits till request is returned
if __name__ == '__main__':
file_path = sys.argv[1]
project_id = sys.argv[2]
model_id = sys.argv[3]
 with open(file_path, 'rb') as ff:
 content = ff.read()
 print get_prediction(content, project_id, model_id)
```

python predict.py YOUR_LOCAL_IMAGE_FILE 678708388730 IOD3946791545901940736

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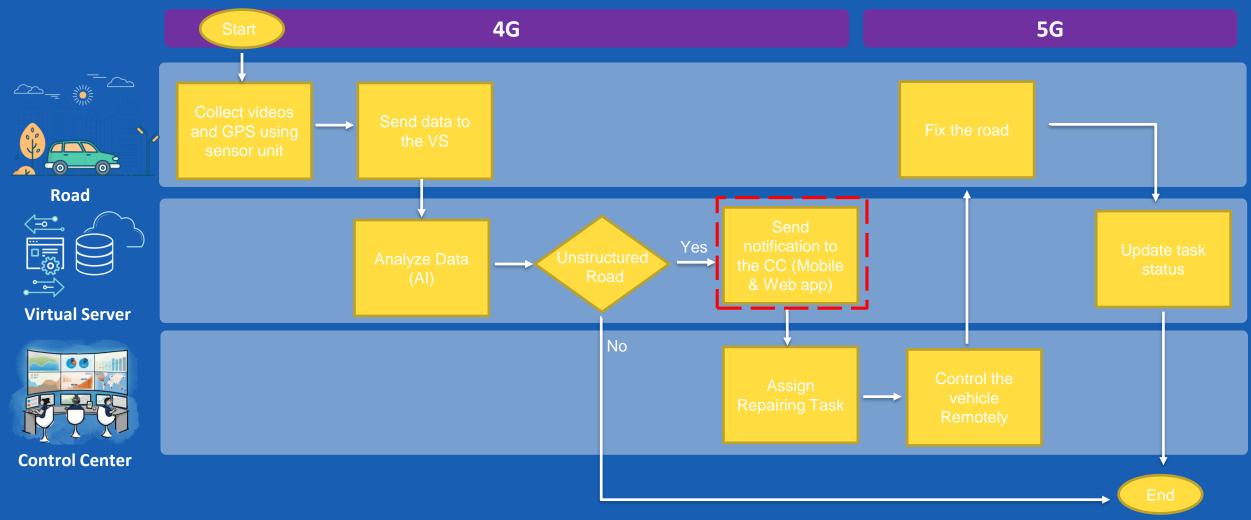


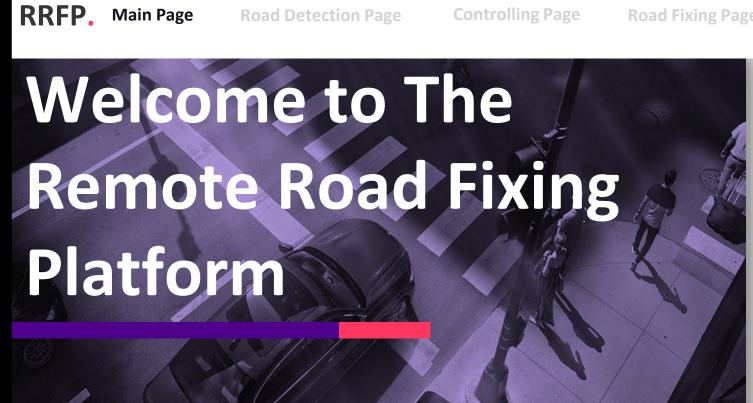
```
# Hello World program in Python
import matplotlib.pylab as plt
import cv2
import numpy as np
def region_of_interest(img, vertices):
  mask = np.zeros_like(img)
  #channel_count = img.shape[2]
  match mask color = 255
  cv2.fillPoly(mask, vertices, match_mask_color)
  masked_image = cv2.bitwise_and(img, mask)
  return masked image
def drow_the_lines(img, lines):
  blank_image = np.zeros((img.shape[0], img.shape[1], 3), dtype=np.uint8)
    for x1, v1, x2, v2 in line:
      cv2.line(blank_image, (x1, y1), (x2, y2), (255, 0, 0), thickness=5)
  img = cv2.addWeighted(img, 0.8, blank_image, 1, 0.0)
  return img
image = cv2.imread('Road.png')
image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
print(image.shape)
height = image.shape[0]
width = image.shape[1]
 region_of_interest_vertices = [
  (width / 2, height / 2).
  (width, height)
gray_image = cv2.cvtColor(image, cv2.COLOR_RGB2GRAY)
canny_image = cv2.Canny(gray_image, 100, 200)
cropped_image = region_of_interest(canny image,
                    np.array([region_of_interest_vertices], np.int32), )
lines = cv2.HoughLinesP(cropped_image,
              rho=6.
              theta=np.pi/60,
              threshold=160.
              lines=np.array([]),
              minLineLength=40,
              maxLineGap=25)
image_with_lines = drow_the_lines(image, lines)
cv2.line(image with lines, (0.0), (20.20), (0.0.0), 15)
font = cv2.FONT HERSHEY SIMPLEX
cv2.putText(image_with_lines, 'ITU challenge!',(10,500), font, 6, (200,255,155), 13, cv2.LINE_AA)
plt.imshow(image_with_lines)
plt.show()
print("Good jop")
```

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SOLUTION

Flowchart





Click Here To Start As a **Road Detector**

Click Here To Start As a Controller

Click Here To Start As a **Road Fixer**





Automatically activate the sensor unit

Manually activate the sensor & send the date

Review the collected data of sensor unit

It will be available as an application to detect defects from cameras and sensor units







Notification Center

Data Review & Analytics

Road Fixing Assignment





Road Detection Page

Past Notifications

- Road X99 has 3 defects reported by sensor unit 5
- Road Fixer XY has been assigned to fix road AW12
- Road N15 has been fixed
-

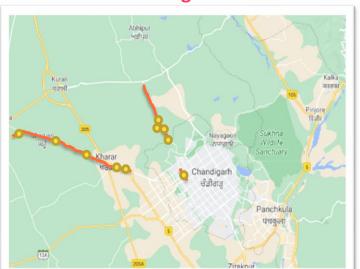
Today

- Road AB has 7 defects reported by sensor unit 2
- Road M99F has 4 defects reported by sensor unit 7
- Road 100 needs to fixer assignment
-

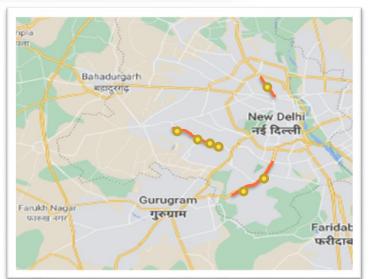
Future Notifications

- · Road YYM needs to be checked
-

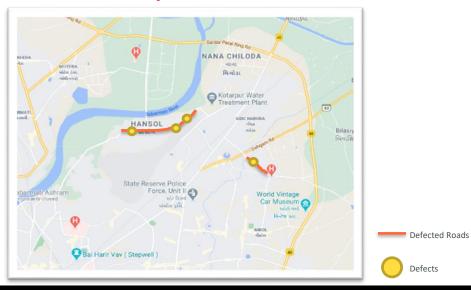
Chandigarh



New Delhi



Hyderabad



RRFP.



Data Review & Analytics

Road Name	Sensor Unit Number	Number of Defects	Controller Name	Fixer Name
X1	1	12	АВ	XX
Y1	2	4	MN	YY
Z1	1	7	ВА	ZZ
M1	4	2	NA	MM



Occupied Road Fixers



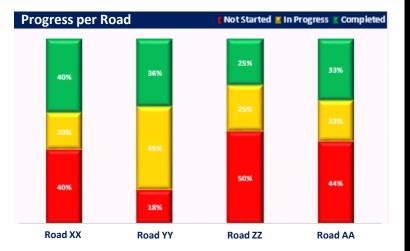
Total Reported Defects



Occupied Sensor Units







Main Page

Road Detection Page



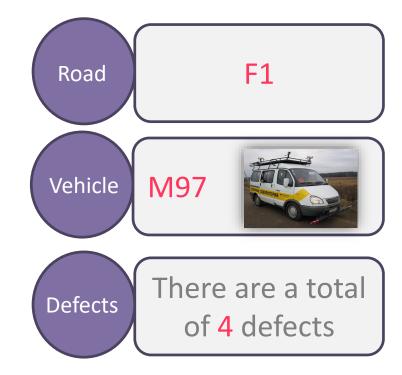
Road Name	Sensor Unit Number	Number of Defects	Controller Name	Fixer Name
F1	1	5	AB	Click to Assign
G1	5	2	AB	Click to Assign
L1	3	9	AB	Click to Assign

- Norah
- Abdullah
- Abdulrahman
- Atheer

Main Page







Start to drive the remote fixing vehicle

Activate Vehicle

Start Virtual Driving

Report Issue



Activate Alarms

Emergency Stop

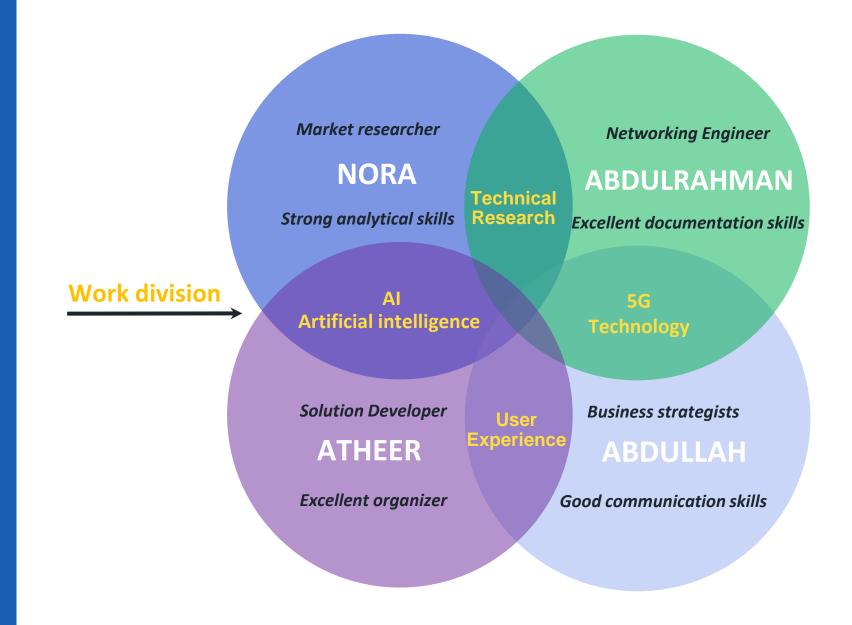
Repair

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TEAM DYNAMIC



NAME
Work division
Key strengths of team member

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Relevance with Indian automotive industry

How the solution can benefit in a large scale automotive Industry?







Map depicting wildfires in India

Fire points from 23 May -3 Jun2 2020



Remote-control and monitor

Fire Engine Truck

Commercial truck

