Quest 3 – Checklist



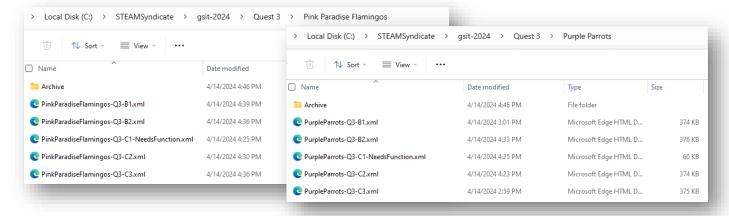
Watch video about Challenge 1
Update code for Challenge 1
Complete Challenge 2
Add lights/sounds to Challenge 3 [Optional but Recommended]
Complete Bonus 2
Record Intro
Record Quest 3 Challenge 1
Record Quest 3 Challenge 2
Record Quest 3 Challenge 3
Record Quest 3 Bonus 1
Record Quest 3 Bonus 2
Record "Thank You"

Snap! File Management



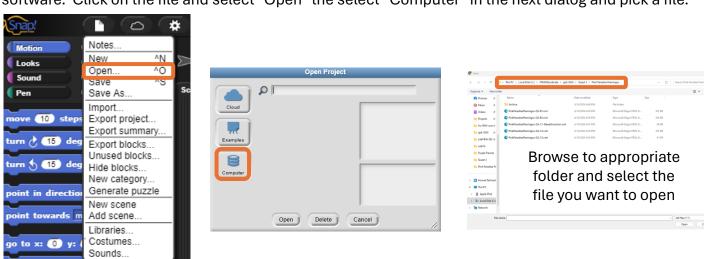
All Girls Solve IT files are saved locally on disk and backed up to the STEAM Syndicate GitHub. You can find all of your team's quest 3 files in the following disk location:

C:\STEAMSyndicate\gsit-2024\Quest 3\<team name>



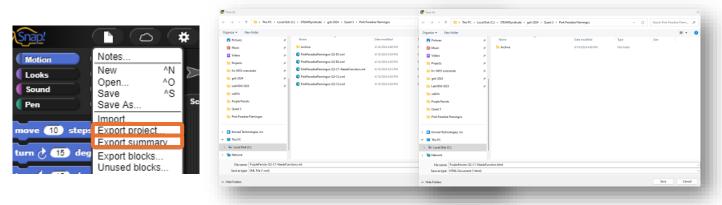
Open Files

Navigate to https://snap.berkeley.edu/snap/snap.html# -or- launch from the Bluebird Connector software. Click on the file and select "Open" the select "Computer" in the next dialog and pick a file.



Export Project / Summary

Click on the file icon and select "Export project...". A windows prompt will appear allowing you to save the project to disk. You need to repeat this action except select "Export summary..." to generate a file that has images of your project. The files generated are different (*.xml vs. *.html).



Quest 3 - Challenge 1



```
when 💌 clicked
Finch A Beak R 0 % G 0 % B 0 %
                                                  Initialize (turn off colors, reset sensors)
Finch A Tail all R 0 % G 0 % B 0 %
Finch A Reset Encoders
set miles ▼ to 214
                  VARIABLE – Given value, 214 miles to travel
set fullGasTank to (miles) / 2) VARIABLE – Given value, 107 miles in full gas tank
set circumference ▼ to (3.142) x (5) (1) VARIABLE – Given wheel diameter calculate circumference
set cmMilesConversionFactor ▼ to 10 VARIABLE – Pick a conversion factor (how many miles = 1 cm)
set currentDistanceTraveled ▼ to 🚺 VARIABLE – Calculated; keeps track of distance traveled on current gas tank
set numGasTankFilled ▼ to 0 VARIABLE – Counter; keeps track of how many times we fill gas tank
set totalDistanceTraveled ▼ to 0  VARIABLE – Calculated; keeps track of total distance traveled
repeat until ( totalDistanceTraveled ) > (miles ) ( )
 set currentDistanceTraveled v to
                                                              Our current distance traveled is our encoder
  Finch A ▼ Right ▼ Encoder (rotations) × (circumference)
                                                              count * circumference * conversion factor
  cmMilesConversionFactor
                                                    Check status of gas tank
 if ( currentDistanceTraveled ) < (fullGasTank ) 🕪 🕽
 Finch A Move Forward 1 cm at 50 % Move Finch!
  if \langle \text{currentDistanceTraveled} \rangle > (0.8) \times \text{fullGasTank} \langle 0.8 \rangle
   Finch A Beak R 100 % G 0 % B 0 %
   Finch A Tail all R 100 % G 0 % B 0 %
                                                                          Set Finch lights based
  else if ( currentDistanceTraveled ) > (0.2) × (fullGasTank) ( ) ( )
                                                                          on gas tank - this is
                                                                          the part they really
   Finch A Beak R 75 % G 40 % B 0 %
                                                                          want you to put into
   Finch A Tail all R 75 % G 40 % B 0 %
                                                                          the function!
  else if 🕡
   Finch A Beak R 0 % G 100 % B 0 %
   Finch A Tail all R 0 % G 100 % B 0 %
 else
                                  It is very important we increment our gas tank filling before next step
  change numGasTankFilled by 1
  set totalDistanceTraveled * to
                                                        Our total distance traveled is the number of
  (numGasTankFilled) × (currentDistanceTraveled)
                                                        gas tanks filled * current distance traveled
  set currentDistanceTraveled v to 0
                                 Reset current Distance variable and
                                 encoders so we can keep going
  Finch A ▼ Reset Encoders
```

Ideally you add some sort of notification (Microbit Lights, sound, etc.) in the "else" case to indicate that Finch is filling up her gas tank!

Quest 3 – Challenge 2



- Program Finch to follow the black line path set for the trolly tour using the line tracking sensors
- Traverse the entire path of the tour.
- Add sounds / lights/ or anything else to convey Finch's excitement while sightseeing

```
when space key pressed

forever

repeat until (Finch Distance (cm) < 25 (*)

say (Finch Left Line)

if (Finch Left Line) < 90 (*)

Finch Wheels L 0 % R 20 %

else

Finch Wheels L 20 % R 0 %
```

This is a great start to challenge 2 but you are missing the last requirement – "Add sounds/lights/anything else to convey Finch's excitement while sightseeing"

Quest 3 – Challenge 3



- Place ping pong ball on the paper cup
- Tape the plastic fork to the straw to make a jousting stick.
- Tape the jousting stick to your Finch robot.
- Place Finch about 60 cm (2 feet) back and 30 cm (1 feet) over from the paper cup
- Program Finch to move forward 60 cm (2 feet) and 30 cm (1 feet) to the right, towards the paper cup
- Program Finch to spin around when near the cup to knock the ping pong ball of the cup using the jousting stick

```
when 3 key pressed

Finch Move Forward 60 cm at 50 %

Finch Turn Right 90 o at 50 %

Finch Move Forward 28 cm at 50 %

Finch Turn Left 380 o at 50 %
```

This meets the minimum requirements (provided you setup the ping pong ball and distances appropriately. For bonus points consider adding lights/sounds!

Quest 3 - Bonus 1



- Paste the images of the obstacles onto the cups and place the cups along the path at the marked positions.
- Program Finch to follow the black line path set for the trolly tour using the line tracking sensors
- Program finch to use the distance sensors to look out for any obstacles along the path
- Program a function that gets called every time Finch is near an obstacle.
 This function should have Finch
 - Move around the obstacle
 - Come back to the designated black line path
- Finch should continue to traverse forward through the tour each time she returns to the path after overtaking the obstacle
- Traverse the entire tour without crashing into any obstacle

```
when space key pressed

forever

repeat until (Finch Distance (cm) < 25 (i)

say (Finch Left Line)

if (Finch Left Line)

Finch Wheels L (0) % R (20) %

else

Finch Wheels L (20) % R (0) %

Finch Turn Right (80) ° at (50) %

Finch Turn Left (90) ° at (50) %

Finch Move Forward (9) × (2.54) (i) cm at (50) %

Finch Turn Left (90) ° at (50) %

Finch Turn Left (90) ° at (50) %

Finch Move Forward (10) cm at (50) %

Finch Move Forward (10) cm at (50) %
```

Good job! One minor change – put the code that moves Finch "around" the object in a single function. Also if you have time add lights/sounds for Finch. She should be mad if something is in her way and happy if she gets around!

Quest 3 – Bonus 2



- <u>Use Finch Encoders block to calculate the total distance travelled along the entire tour</u>
- Program Finch to display the calculated total distance

```
when space ▼ key pressed
                                       Reset encoders and calculate circumference
Finch Reset Encoders
set circumference ▼ to (3.142 × 5)
 repeat until (Finch Distance (cm)) < 25 (>)
  say (Finch Left Line
  if (Finch Left ▼ Line < 90 ♦)
  Finch Wheels L 0 % R 20 %
  Finch Wheels L 20 % R 0 %
   set distanceTraveled v to
    circumference ×
      Finch Left ▼ Encoder (rotations) + Finch Right ▼ Encoder (rotations) ◆
   say distanceTraveled
                                                Calculate distance traveled...
   micro:bit Print distanceTraveled
                                                Average of Encoders * Circumference
```

Show result to user somehow (microbit, etc)

Script Template



Intro

EVERYONE: "Hi! We are the Purple Parrots and this is our solution to guest 3!"

Challenge 1

NARRATOR: Finch is loving this road trip! Before getting back on the road, Finch checks her gas gauge and decides to setup a quick alert to let her know when she's running low on gas. Finch's road trip is 214 miles long, and the gas tank allows her to travel 107 miles. <Add more details of challenge/fun comments while Finch is moving> <Explain code>

Challenge 2

FINCH: "Ah great, now my tank is all filled up for some sightseeing!".

NARRATOR: Finch had read up on a lot of fun stuff to see in Atlanta and was really looking forward to this pitstop! She decides to take a trolly tour around the city so that she can cover multiple locations in a short time. Her tour will cover:

- Centennial Olympic Park
- Martin Luther King Jr. National Historic Site
- The Woodruff Arts Center
- Georgia State Capitol
- <Add more details of challenge/fun comments while Finch is moving>
- <Explain code>

Challenge 3

FINCH "Ah finally my tank is all filled up and it's time to head off straight to Florida!! Next stop- the amusement park!"

NARRATOR: Finch hummed along with the crickets in the night sky, merrily continuing her journey. She halted to a stop as she noticed a humongous boulder blocking her path! It was too wide to go around it. Finch could of course fly over it, but she knew that humans coming this way would get stuck. Her second nature to help others prevented her from going her own way. She notices a big log a wood by the side of the road. She decides to use the log of wood as a jousting stick to knock the boulder.

<Add more details of challenge/fun comments while Finch is moving><Explain code>

Bonus 1

<Add more details of challenge/fun comments while Finch is moving><Explain code>

Bonus 2

<Add more details of challenge/fun comments while Finch is moving>
<Explain code>

Thank You

EVERYONE: "Thank you"