

Motor::getPWM



```
graph LR; A[lcd_implementation_control_status_motor] --> B[Motor::getPWM];
```

The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'Motor::getPWM'. The box on the right is white and contains the text 'lcd_implementation_control_status_motor'. A dark blue arrow points from the right side of the white box to the left side of the gray box.

lcd_implementation
_control_status_motor