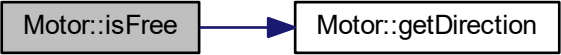


Motor::isFree



```
graph LR; A[Motor::isFree] --> B[Motor::getDirection]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'Motor::isFree'. The right box is white and contains the text 'Motor::getDirection'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

Motor::getDirection