



Master of Science in Informatics at Grenoble  
Master Mathématiques Informatique - spécialité Informatique  
option Graphics Vision and Robotics

# **Scalable image reconstruction methods for large data: Application to Synchrotron CT of biological samples**

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Under the supervision of:

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Defended before a jury composed of:

Head of the jury

Jury member 1

Jury member 2



### **Abstract**

Your abstract goes here...

### **Acknowledgement**

I would like to express my sincere gratitude to .. for his invaluable assistance and comments in reviewing this report... Good luck :)

### **Résumé**

Your abstract in French goes here...



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## Introduction

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## State-of-the-Art

intro about CT and importance for osteoporosis diagnosis + use of SR + low dose problem CS ([3, 1, 11])

### 2.1 Dose reduction in SR Micro-CT

Multiple CS algorithm were developed for Micro-CT allowing to generate different spacial resolutions. Alternative methods then FBP necessary to recover missing projections. Iterative algorithms are used.

#### 2.1.1 No SR

SART-L1 [18, 16] ASD-POCS TV [7]

#### 2.1.2 CS on SR micro-CT

multiple iterative methods using CGTV ([17]) ART with multiple denoising (TV [15]; L1 minimisation [9]; Discrete packet shrinkage [14]) SART ([12] with TV [13]) OS-SART [8]) EST [4, 19] PCCT [5] define resolution for each solution (maybe more details?)

### 2.2 SR Nano-CT

Nano-CT general ref: [2] (I can have other references but are mostly about the hardware side, new materials and acquisition methodology, or image post-processing without having used low dose)

less CS reconstruction experimented

Low dose nano OS-SART L1 norm TV [10]

### 2.3 Wrap-up

A lot of research these past few years of CSCT going toward a improvement of spacial resolution and dose reduction. Yet not so much has been done on Nano scale. In the context of osteoporosis nano scale is mandatory for a accurate diagnosis. Present our objective.



## Problem Statement

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## Proposed approach

We propose to use iterative reconstruction with the algorithm described by [6]. Split Bregman algorithm gives a solution to an L1-L2 constrained problem. We will here describe the bregman iteration and it's application to L2 minimisation reconstructions which will be used in our algorithm.

### 4.1 Split Bregman iterative reconstruction

#### 4.1.1 Split Bregman iteration

Using Split Bregman we wish to solve the constrained reconstruction optimization problem described in the section ??:

$$\min_u ||\nabla_u||_1 \text{ such that } Fu = f \quad (4.1)$$

Such constrained problem problems are difficult to solve directly. For this reason we need to define a new unconstrained problem. Luckily it is possible to approximate (4.1) as:

$$\min_u ||\nabla_u||_1 + \frac{\lambda}{2} ||Fu - f||_2^2 \quad (4.2)$$

The Bregman iteration allows us to reduce 4.1 in even shorter unconstrained problems using Bregman distances. These constrained problem can be resolved iteratively as follows:

$$\begin{aligned} u^{k+1} &= \min_u ||\nabla_u||_1 + \frac{\lambda}{2} ||Fu - f^k||_2^2 \\ f^{k+1} &= f^k + f - Fu^k \end{aligned} \quad (4.3)$$

#### 4.1.2 L1 regularization problem

Our compressed sensing reconstruction method is based on L1 regulation. A more faithful reconstruction problem must be formulated and we will see how to solve it iteratively with split Bregman.

The idea is to "de-couple" the L1 and L2 parts of our original problem. We wish to minimize the Total Variation  $\nabla_u$  of the image and a weight function  $H()$ . We write the problem as follows:

$$\min_{u,d} ||d||_1 + H(u) \text{ such that } d = \nabla_u \quad (4.4)$$

Which can be computed iteratively using Split Bregman iteration as:

$$\begin{aligned}(u^{k+1}, d^{k+1}) &= \min_{u, d} \|d\|_1 + H(u) + \frac{\lambda}{2} \|d - \nabla_u - b^k\|_2^2 \\ b^{k+1} &= b^k + \nabla_{u^{k+1}} - d^{k+1}\end{aligned}\tag{4.5}$$

## 4.2 SB-TV-2D reconstruction

isotropic TV denoising pbl:

$$\min_u \|\nabla_u\|_1 \text{ such that } \|Fu - f\|_2^2 < \delta^2\tag{4.6}$$

where  $\nabla_u = (\nabla_x, \nabla_y)u$

$$\begin{aligned}u &= \\d &=\end{aligned}\tag{4.7}$$

## 4.3 SB-TV-3D

pbl:  $\alpha \|(\nabla_x, \nabla_y, \nabla_z)u\|_1$  such that  $\|Fu - f\|_2^2 < \delta^2$

$$\begin{aligned}u &= \\d &=\end{aligned}\tag{4.8}$$

## Method evaluation

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## Conclusion

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# **— A —**

## **Appendix**

Appendix goes here...



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