

# **PERIODIC MOTION I**

PHYS1112

Lecture 14

# Intended Learning Outcomes

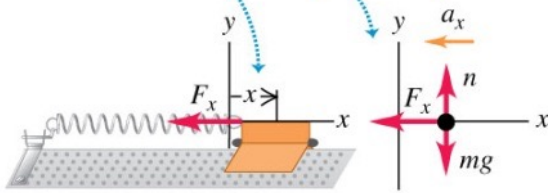
- After this lecture you will learn:
  - 1) definition of simple harmonic motion
  - 2) relation between uniform circular motion and simple harmonic motion
  - 3) description of simple harmonic motion in terms of phasor diagram
  - 4) kinetic, potential, and total energy in simple harmonic motion

# Simple Harmonic Motion (SHM)

Simplest example: a spring and mass system

(a)

$x > 0$ : glider displaced to the right from the equilibrium position.  $F_x < 0$ , so  $a_x < 0$ : stretched spring pulls glider toward equilibrium position.



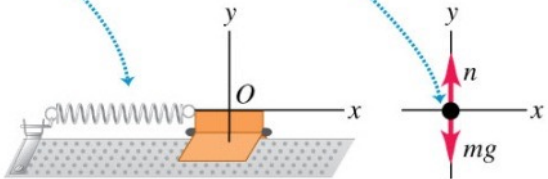
$$\text{Hooke's law: } F_x = -kx$$

restoring force

displacement (+/-)  
from equilibrium  
point

(b)

$x = 0$ : The relaxed spring exerts no force on the glider, so the glider has zero acceleration.



Newton's law

$$a_x = \frac{d^2x}{dt^2} = -\frac{k}{m}x$$

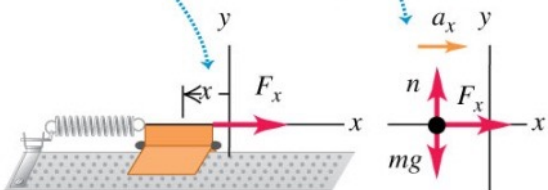
a differential equation of the form

$$\ddot{x} = -\alpha x, \alpha > 0,$$

called **simple harmonic motion (SHM)**

(c)

$x < 0$ : glider displaced to the left from the equilibrium position.  $F_x > 0$ , so  $a_x > 0$ : compressed spring pushes glider toward equilibrium position.



A system executing simple harmonic motion is called a **harmonic oscillator**

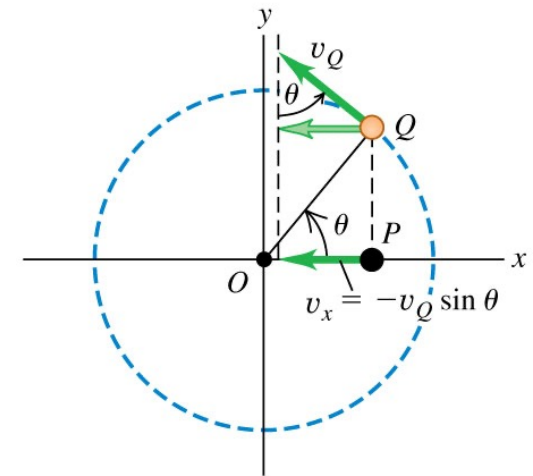
How to solve the differential equation? Consider a particle  $Q$  executing uniform circular motion with angular speed  $\omega$  and radius  $A$ .  $P$  is its projection along  $x$  axis.

position of  $P$ :  $x = A \cos \theta$

velocity of  $P$ :  $v_x = -v_Q \sin \theta$

acceleration of  $P$ :  $a_x = -a_Q \cos \theta$   
 $= -(\omega^2 A) \cos \theta$   
 $= -\omega^2 x$  *c.f.*  $a = -(k/m)x$

Conclusion: a harmonic oscillator is the same as a particle in uniform circular motion with  $\omega = \sqrt{k/m}$  projected along the  $x$  direction



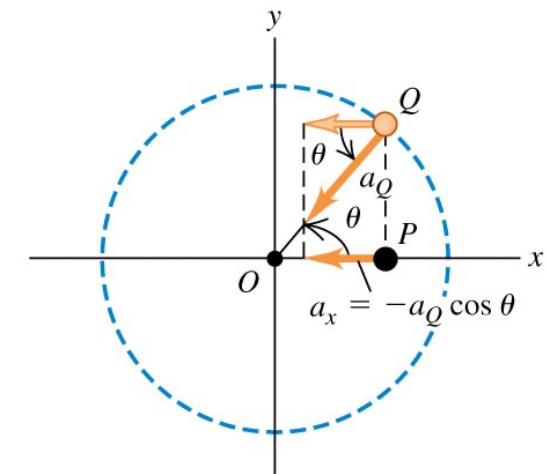
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**frequency**  $f$  = number of cycles per unit time

$$= \frac{\omega}{2\pi} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

**period**  $T$  = time for one complete cycle

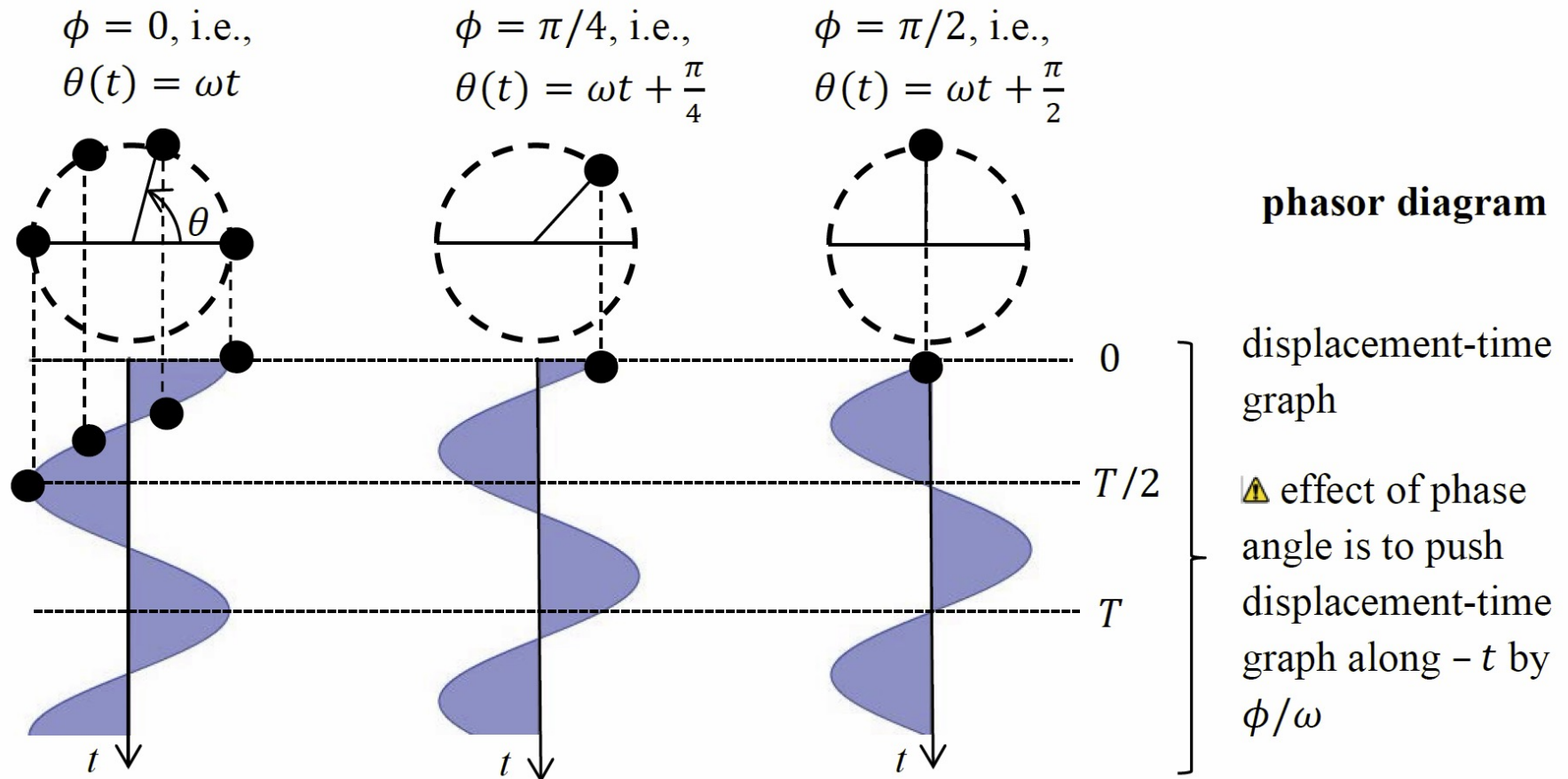
$$= \frac{1}{f} = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{m}{k}}$$



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**angular frequency**  $\omega$  = angle (in radian) per unit time  
 $= 2\pi f$

General solution:  $x = A \cos \theta(t) = A \cos(\omega t + \phi)$ , where the **phase angle**  $\phi = \theta(0)$   
 $A$  is the **amplitude** (maximum displacement) of the oscillation



velocity

$$v_x = \frac{dx}{dt} = -\omega A \sin(\omega t + \phi) = \omega A \cos\left(\omega t + \phi + \frac{\pi}{2}\right)$$

$$v_{max} = \omega A$$

acceleration

$$a_x = \frac{d^2x}{dt^2} = -\omega^2 A \cos(\omega t + \phi) = \omega^2 A \cos(\omega t + \phi + \pi)$$

$$a_{max} = \omega^2 A$$

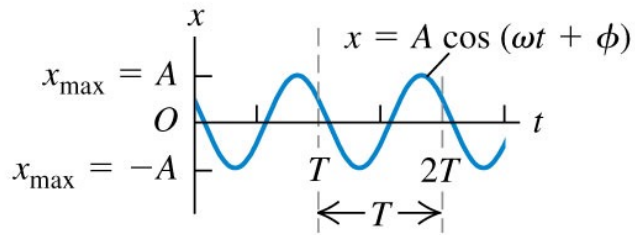
How to find  $A$  and  $\omega$ ? If given initial condition  $x(0) = x_0$ ,  $v(0) = v_{0x}$

$$\frac{v_{0x}}{x_0} = \frac{-\omega A \sin \phi}{A \cos \phi} = -\omega \tan \phi \Rightarrow \phi = \begin{cases} \tan^{-1} \left( -\frac{v_{0x}}{\omega x_0} \right), & \text{if } x_0 > 0 \\ \tan^{-1} \left( -\frac{v_{0x}}{\omega x_0} \right) + \pi, & \text{if } x_0 < 0 \end{cases}$$

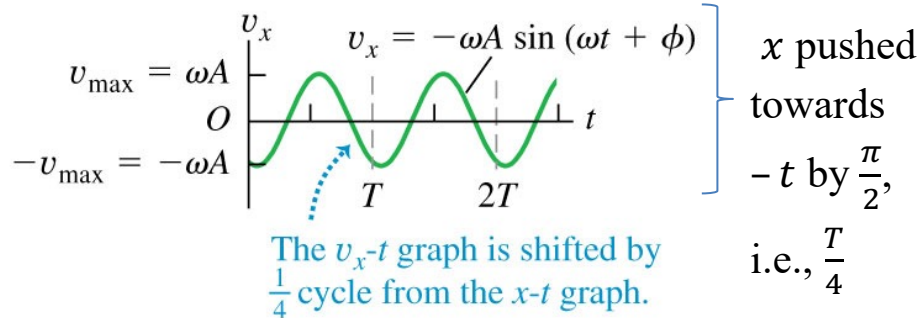
$$x_0^2 + \frac{v_{0x}^2}{\omega^2} = A^2(\cos^2 \phi + \sin^2 \phi) = A^2 \Rightarrow$$

$$A = \sqrt{x_0^2 + \frac{v_{0x}^2}{\omega^2}}$$

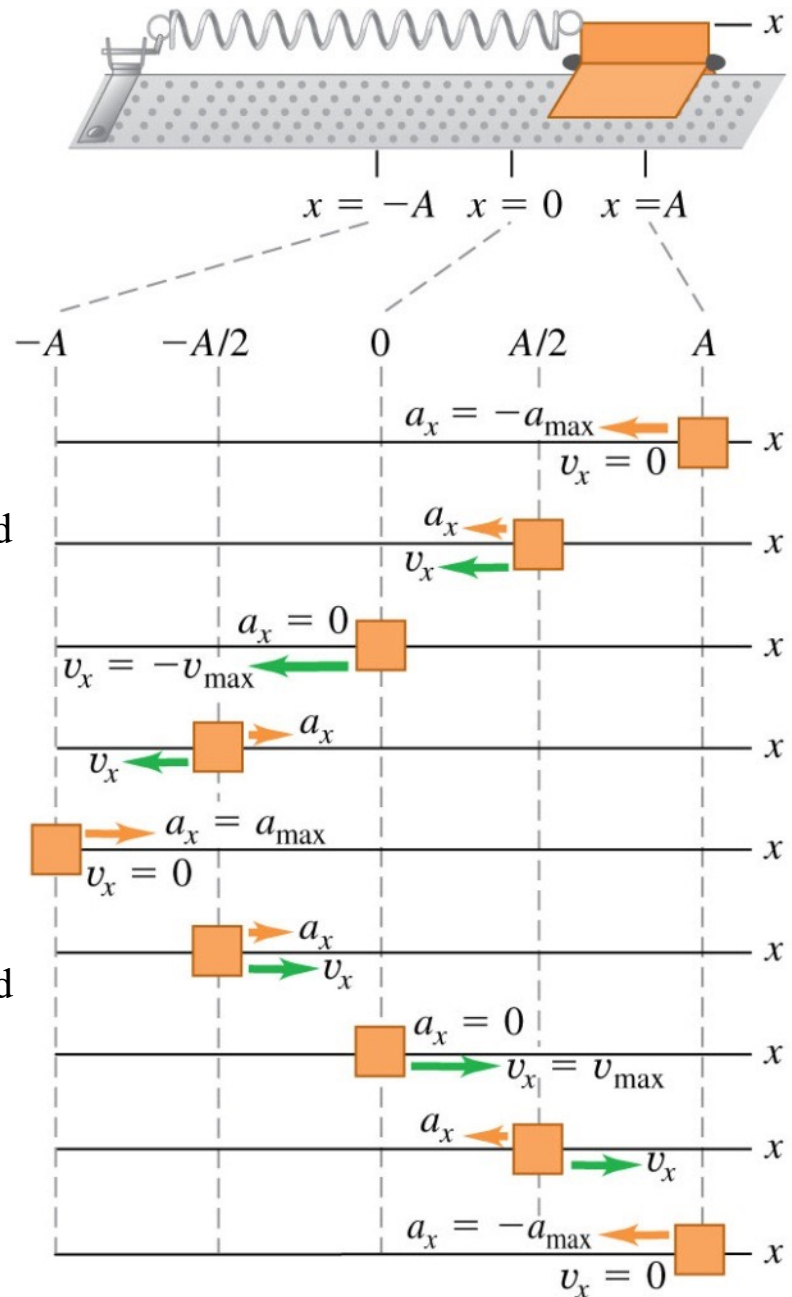
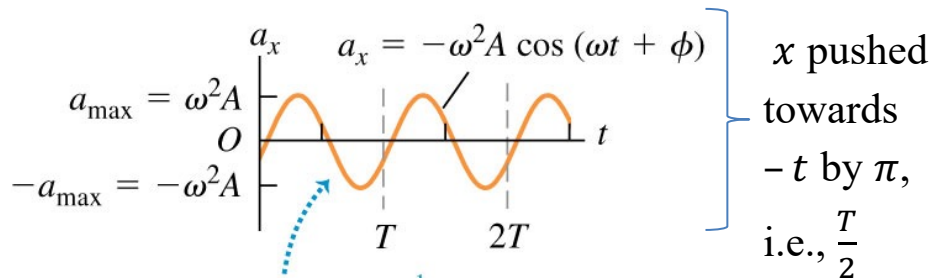
(a) Displacement  $x$  as a function of time  $t$



(b) Velocity  $v_x$  as a function of time  $t$



(c) Acceleration  $a_x$  as a function of time  $t$



### Question

Suppose the glider in the above diagram is moved to  $x = 0.10$  m and is released from rest at  $t = 0$ , then  $A = \underline{\hspace{1cm}}$  m and  $\phi = \underline{\hspace{1cm}}$  .

Suppose instead the glider in the above diagram at  $t = 0$  is at  $x = 0.10$  m and is moving to the right, then  $A$  is ( $> / < / =$ )  $0.10$  m and  $\phi$  is ( $> / < / =$ )  $0$ .



## Energy in Simple Harmonic Motion

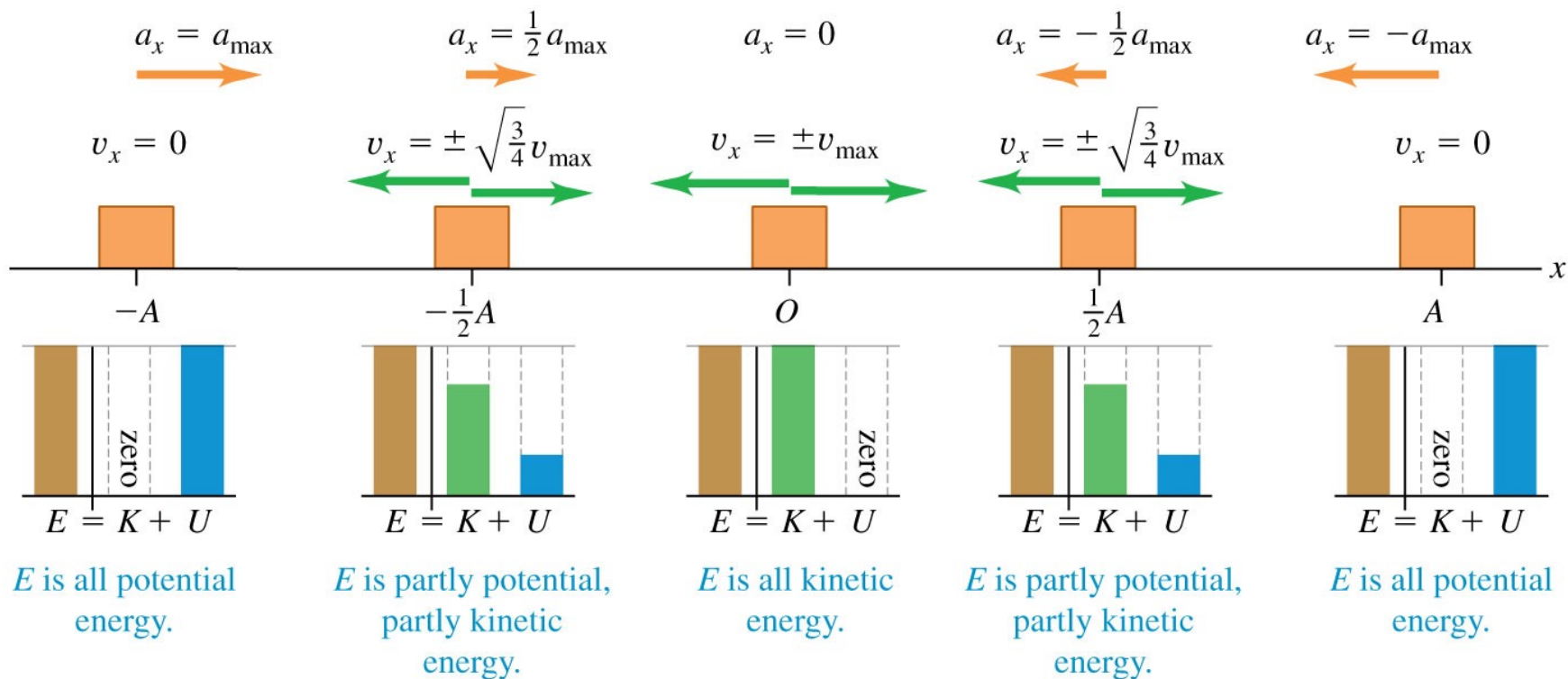
$$\begin{aligned} E &= \frac{1}{2}mv_x^2 + \frac{1}{2}kx^2 \\ &= \frac{1}{2}m\omega^2 A^2 \sin^2(\omega t + \phi) + \frac{1}{2}kA^2 \cos^2(\omega t + \phi) = \frac{1}{2}kA^2 \end{aligned}$$

## Conservation of energy!

To find velocity:

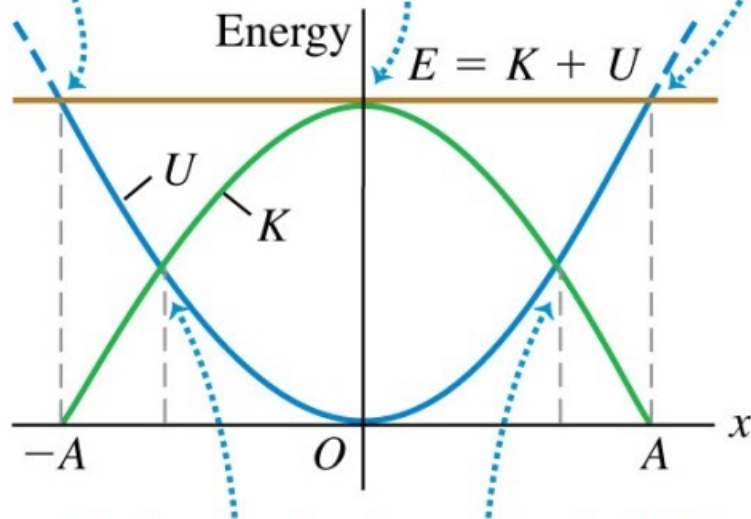
$$E = \frac{1}{2}mv_x^2 + \frac{1}{2}kx^2 = \frac{1}{2}kA^2 \quad \Rightarrow$$

$$v_x = \pm \sqrt{\frac{k}{m}} \sqrt{A^2 - x^2}$$



At  $x = \pm A$  the energy is all potential; the kinetic energy is zero.

At  $x = 0$  the energy is all kinetic; the potential energy is zero.



At these points the energy is half kinetic and half potential.

both  $U$  and  $K$  are quadratic (i.e., parabolic), and they add up to a constant

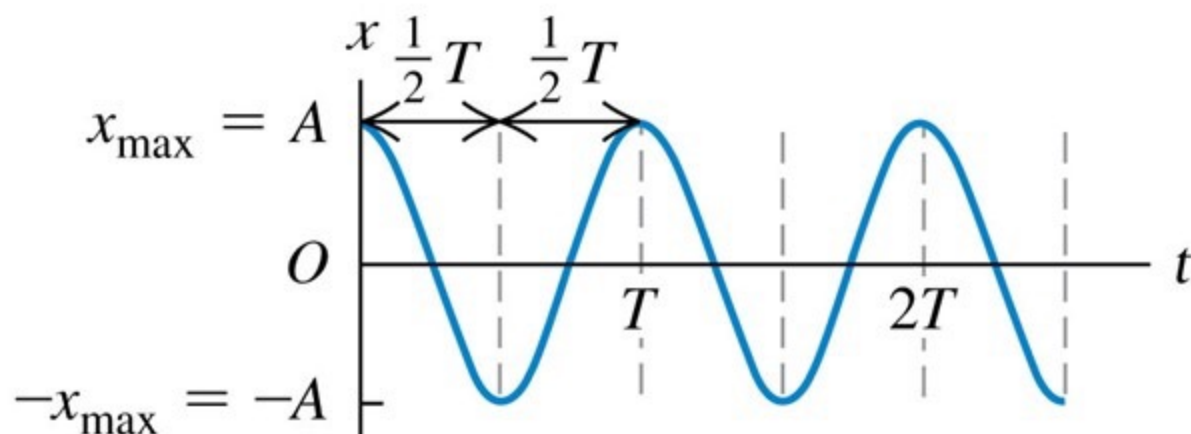
$$E = \frac{1}{2}kA^2$$

### Question

To double the total energy of a spring and mass system oscillating in SHM, one should increase the amplitude by a factor of \_\_\_\_\_. As a result of this amplitude change, the frequency of the oscillator will (be larger / be smaller / have no change).

## Q14.6

This is an  $x$ - $t$  graph for an object connected to a spring and moving in simple harmonic motion. At which of the following times is the *potential energy* of the spring the greatest?



A.  $t = T/8$

B.  $t = T/4$

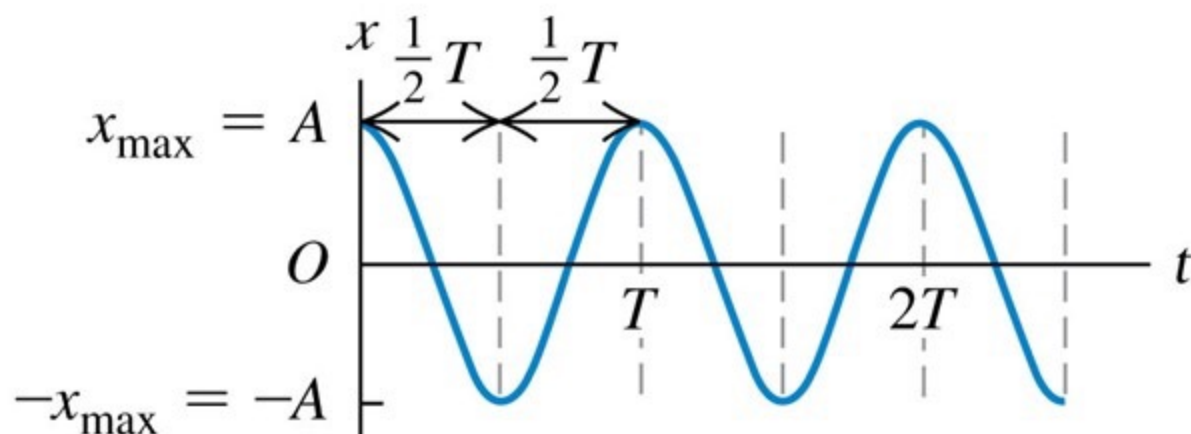
C.  $t = 3T/8$

D.  $t = T/2$

E. Two of the above are tied for greatest potential energy.

## A14.6

This is an  $x$ - $t$  graph for an object connected to a spring and moving in simple harmonic motion. At which of the following times is the *potential energy* of the spring the greatest?



A.  $t = T/8$

B.  $t = T/4$

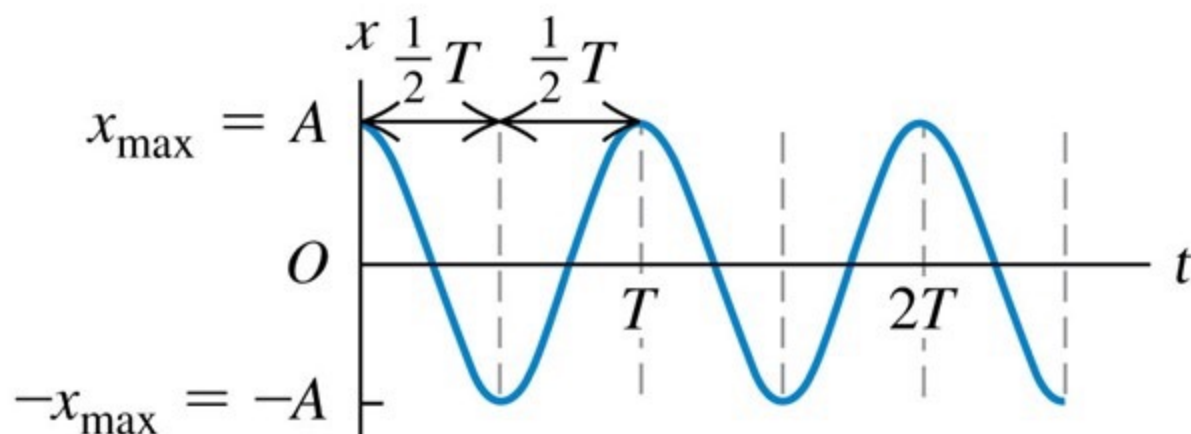
C.  $t = 3T/8$

☒ D.  $t = T/2$

E. Two of the above are tied for greatest potential energy.

## Q14.7

This is an  $x$ - $t$  graph for an object connected to a spring and moving in simple harmonic motion. At which of the following times is the *kinetic energy* of the object the greatest?



A.  $t = T/8$

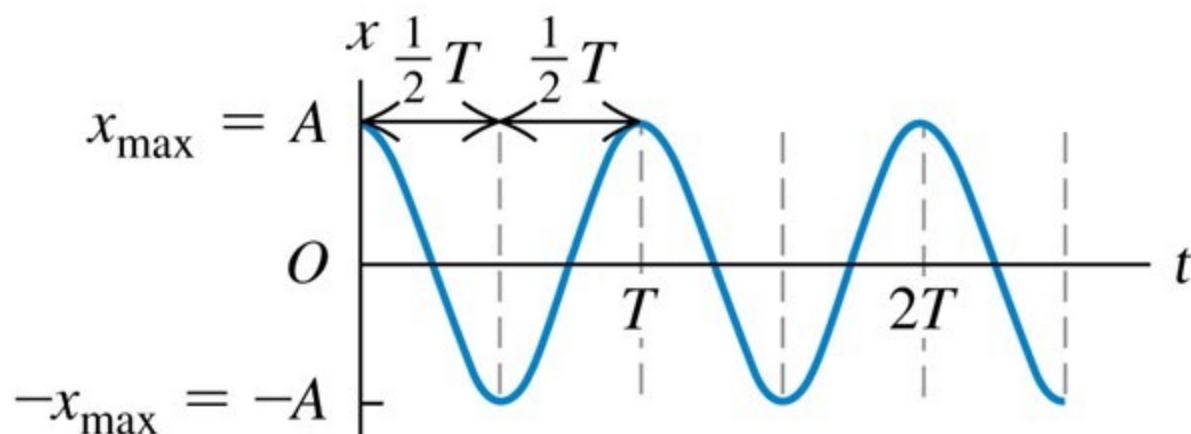
B.  $t = T/4$

C.  $t = 3T/8$

D.  $t = T/2$

E. Two of the above are tied for greatest kinetic energy.

This is an  $x$ - $t$  graph for an object connected to a spring and moving in simple harmonic motion. At which of the following times is the *kinetic energy* of the object the greatest?



A.  $t = T/8$

✓ B.  $t = T/4$

C.  $t = 3T/8$

D.  $t = T/2$

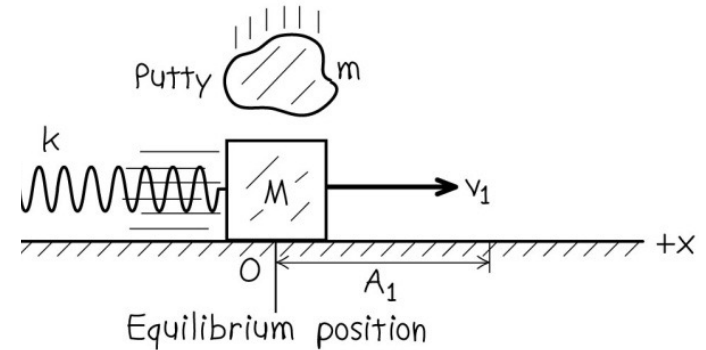
E. Two of the above are tied for greatest kinetic energy.



## Example Energy and momentum in SHM

Given: an oscillator with amplitude  $A_1$

When it is at  $x = 0$ , a putty of mass  $m$  hits, and then stays on the block after collision



During the collision:

y component of momentum (is / is not) conserved

x component of momentum (is / is not) conserved

New velocity at  $x = 0$ :

$$Mv_1 + 0 = Mv_2 + mv_2 \Rightarrow v_2 = \frac{M}{M+m}v_1$$

New amplitude:

$$\frac{1}{2}kA_2^2 = \frac{1}{2}(M+m)v_2^2 = \left(\frac{M}{M+m}\right)\frac{1}{2}Mv_1^2 = \left(\frac{M}{M+m}\right)\frac{1}{2}kA_1^2$$

$E$  in terms of amplitude after collision       $K$  right after collision       $\Rightarrow A_2 = A_1 \sqrt{\frac{M}{M+m}}$

Total energy of the oscillator (increase/decrease). Where does the energy go?

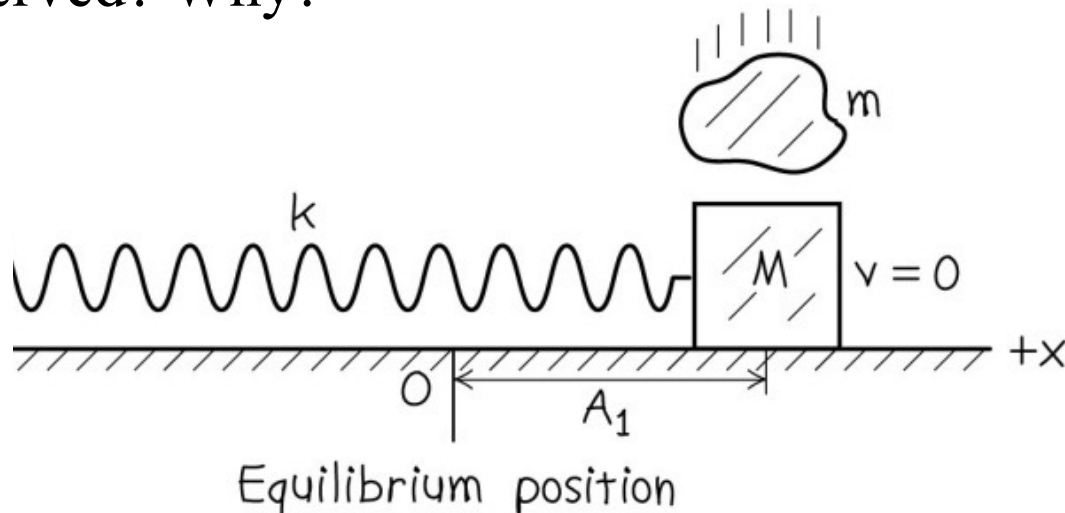
Suppose the putty hits when the block is at  $x = A_1$

No change in horizontal velocity (why?)

No change in  $K$  (why?)

Does the energy of the oscillator change? Why?

Is the energy of the system (oscillator + putty) conserved? Why?





For advanced students only. Others may ignore this part

## Appendix

The formula  $\phi = \tan^{-1}(-v_{0x}/\omega x_0)$  does not always give the correct answer. One needs to determine  $\phi$  in the correct quadrant through the conditions

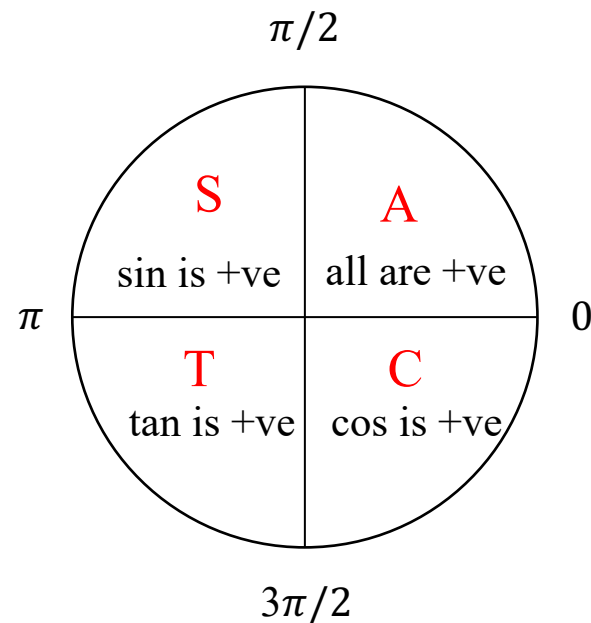
$$\sin \phi = -v_{0x}/\omega A$$

$$\cos \phi = x_0/A$$

But you can easily convince yourself that the general

$$\text{formula is } \phi = \begin{cases} \tan^{-1}\left(-\frac{v_{0x}}{\omega x_0}\right), & \text{if } x_0 > 0 \\ \tan^{-1}\left(-\frac{v_{0x}}{\omega x_0}\right) + \pi, & \text{if } x_0 < 0 \end{cases}$$

irrespective of whether  $v_{0x}$  is positive or negative, as illustrated in the following example:



## Example

Given  $v_{0x} = 0.40 \text{ m/s}$ ,  $x_0 = 0.015 \text{ m}$ ,  $\omega = 20 \text{ rad/s}$ ,  
then

$$\phi_1 = \tan^{-1} \left( -\frac{0.40 \text{ m/s}}{(20 \text{ rad/s})(0.015 \text{ m})} \right) = -0.93 \text{ rad}$$

But if  $v_{0x} = -0.40 \text{ m/s}$ ,  $x_0 = -0.015 \text{ m}$ , then  
 $\sin \phi_2 > 0$  and  $\cos \phi_2 < 0$ , i.e.,  $\phi_2$  in the second  
quadrant, and the correct phase angle is

$$\phi_2 = \pi - 0.93 \text{ rad} = 2.21 \text{ rad}$$

