# NEWTON'S LAWS OF MOTION II

PHYS1112

Lecture 3

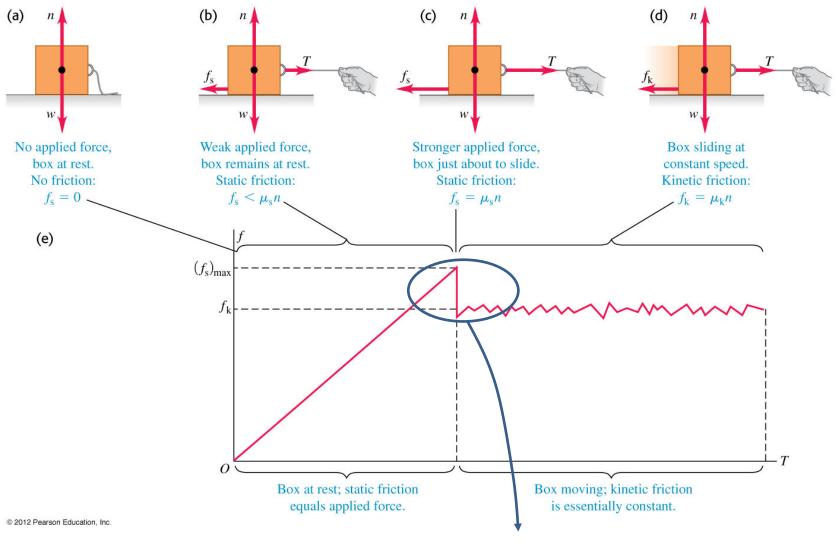
# Intended Learning Outcomes

- After this lecture you will learn:
  - 1. to describe friction in a macroscopic picture and solve problems involving it.
  - 2. to contrast fluid resistance to friction.
  - 3. uniform circular motion and centripetal acceleration
  - 4. to solve problems involving uniform circular motion

## **Frictional Forces**

- Microscopic: due to interactions between molecules of surfaces in contact
- Macroscopic (phenomenological): ignore microscopic level and look at the outcome only

#### Can be classified into two types: static friction, and dynamic (or kinetic) friction

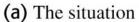


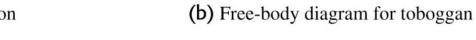
Interpretation: easier to keep the block moving than to start it moving

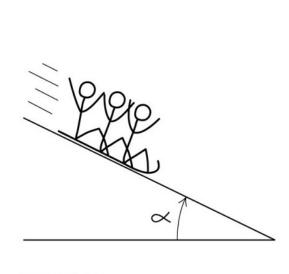
## Note

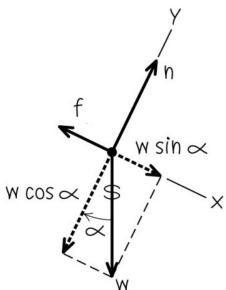
- the coefficients of static and kinetic friction  $\mu_{s}$  and  $\mu_{k}$  depends on the two surfaces in contact
- friction always along contact surface and therefore ⊥ to normal force
- static friction can be less than the maximum value

## Example: A block (or toboggan) sliding down an inclined plane





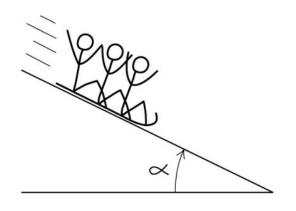




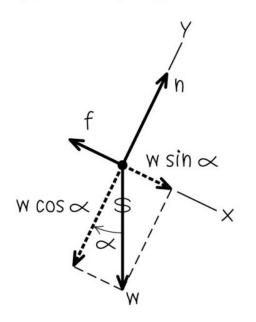
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Given:  $\mu_s$  and  $\mu_k$ , angle  $\alpha$  increases from zero Before the block starts to slide, friction is (static / kinetic), and equals \_\_\_\_\_

#### (a) The situation



**(b)** Free-body diagram for toboggan



If at a particular  $\alpha$ , the block <u>just</u> begins to slide, right before the block begins to slide, friction is (static / kinetic):

Resolving force ⊥ the plane:

$$\sum F_y = n - mg\cos\alpha = 0$$

along the plane:

$$\sum F_x = mg \sin \alpha - \mu_s n = 0 \implies \alpha = \tan^{-1} \mu_s$$

Right after the block begins to slide, friction is (static / kinetic) and the block slides with (constant speed / an acceleration):

$$\sum F_x = mg \sin \alpha - \mu_k n = ma$$

$$\implies a = g(\sin \alpha - \mu_k \cos \alpha) = g \frac{\mu_s - \mu_k}{\sqrt{1 + \mu_s^2}}$$

You are walking on a level floor. You are getting good traction, so the soles of your shoes don't slip on the floor.

Which of the following forces *should* be included in a free-body diagram for your body?

- A. the force of kinetic friction that the floor exerts on your shoes
- B. the force of static friction that the floor exerts on your shoes
- C. the force of kinetic friction that your shoes exert on the floor
- D. the force of static friction that your shoes exert on the floor
- E. more than one of these

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## Fluid Resistance



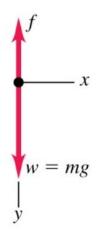
Fluid resistance depends on speed At high speed (or non-viscous fluid),  $f \propto v^2$ , or  $f = Dv^2$ e.g. air resistance

$$\sum F_y = mg - Dv^2 = ma$$

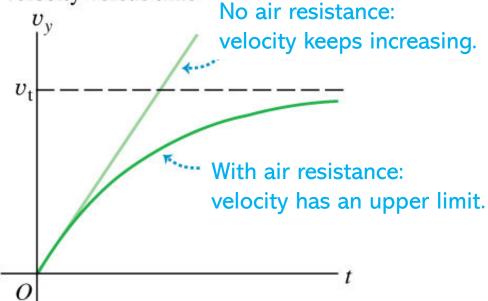
#### Note:

- 1) a decreases as  $\nu$  increases
- 2) there exists a terminal speed

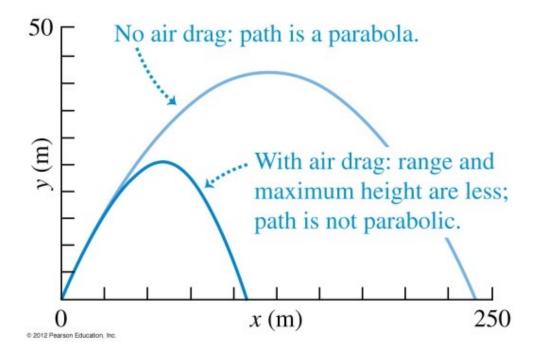
$$v_t = \sqrt{mg/D}$$
 when  $a = 0$ 



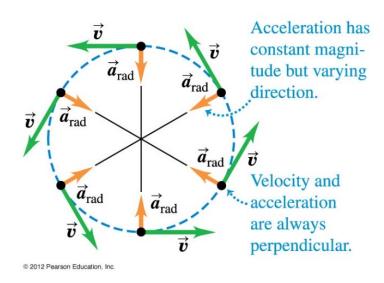
Velocity versus time



- riangle heavy bodies fall faster  $\because$  larger m
- ▲ a sheet of paper falls faster if crumpled into a ball∵ D smaller
- with air resistance, a projectile is no longer a parabola



## **Dynamics of Uniform Circular Motion**

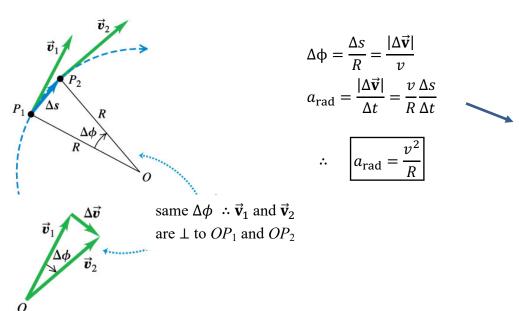


Speed (NOT velocity) constant

$$\Rightarrow a_{||} = 0$$

 $\Rightarrow \vec{a}$  along radial direction (inward / outward)

called centripetal acceleration

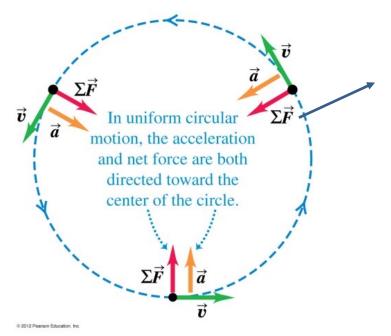


You drive a race car around a circular track of radius 100 m at a constant speed of 100 km/h. If you then drive the same car around a different circular track of radius 200 m at a constant speed of 200 km/h, your acceleration will be

- A. 8 times greater.
- B. 4 times greater.
- C. twice as great.
- D. the same.
- E. half as great.

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force providing the centripetal acceleration, sometimes called the "centripetal force".

$$F_{net} = ma = m\frac{v^2}{R}$$

Demonstration: vertical circular motion



A pendulum of length L with a bob of mass m swings back and forth. At the low point of its motion (point Q), the tension in the string is (3/2)mg. What is the speed of the bob at this point?

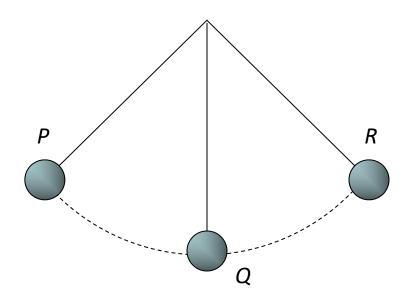
A. 
$$2\sqrt{gL}$$
B.  $\sqrt{2gL}$ 
C.  $\sqrt{gL}$ 

$$B.\sqrt{2gL}$$

$$C.\sqrt{gL}$$

$$D.\sqrt{\frac{gL}{2}}$$

$$E.\frac{\sqrt{gL}}{2}$$



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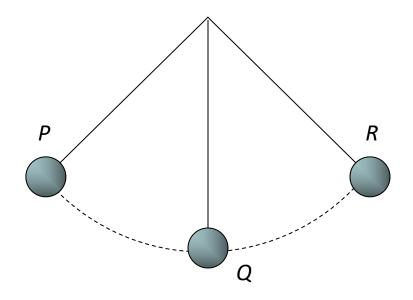
$$A.2\sqrt{gL}$$

$$B.\sqrt{2gL}$$

$$C.\sqrt{gL}$$



E. 
$$\frac{\sqrt{gL}}{2}$$

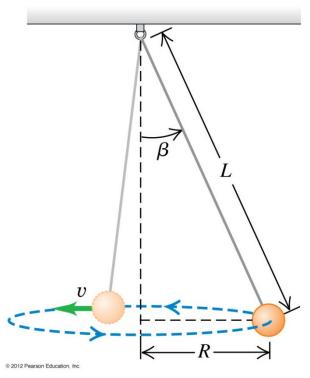




A pendulum bob of mass m is attached to the ceiling by a thin wire of length L. The bob moves at constant speed in a horizontal circle of radius R, with the wire making a constant angle  $\beta$  with the vertical. The tension in the wire

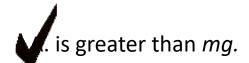


- B. is equal to mg.
- C. is less than mg.
- D. is any of the above, depending on the bob's speed v.

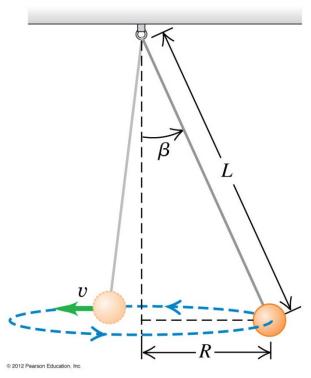


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A pendulum bob of mass m is attached to the ceiling by a thin wire of length L. The bob moves at constant speed in a horizontal circle of radius R, with the wire making a constant angle  $\beta$  with the vertical. The tension in the wire



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- C. is less than mg.
- D. is any of the above, depending on the bob's speed v.



## Example: A conical pendulum

#### horizontal uniform circular motion

$$\sum F_x = F \sin \beta = ma$$
  
$$\sum F_y = F \cos \beta - mg = 0$$

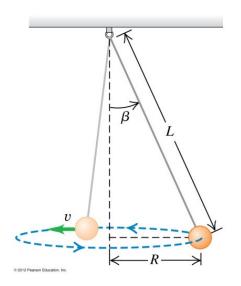
$$\Rightarrow$$
  $a = g \tan \beta$ 

### Period of the pendulum:

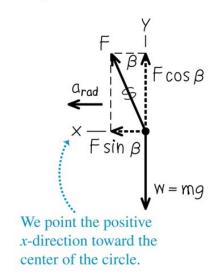
$$T = \frac{2\pi R}{v} = 2\pi \sqrt{\frac{R}{a}} = 2\pi \sqrt{\frac{L\cos\beta}{g}}$$

c.f. a planar pendulum

#### (a) The situation



**(b)** Free-body diagram for pendulum bob



## Observation: Why banked curves in a racing track help?

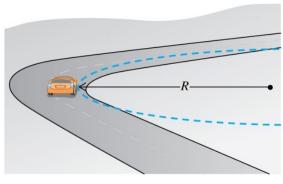
#### On a flat curve

Assume no skidding, what supplies the centripetal force? (Static / Kinetic) friction! Max. speed without skidding:

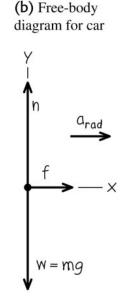
$$f = f_{max} = m \frac{v_{max}^2}{R} \implies v_{max} = \sqrt{\mu_s gR}$$

 $\mu_s n = \mu_s mg$ 

(a) Car rounding flat curve



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### If banked at angle $\theta$

## What supplies the centripetal force? n and f!

$$\sum F_x = n \sin \beta + f \cos \beta = mv^2/R$$

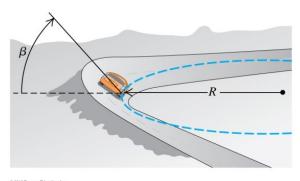
$$\sum F_y = n \cos \beta - f \sin \beta - mg = 0$$

$$\Rightarrow f = \frac{m \cos \beta}{R} (v^2 - gR \tan \beta),$$

$$n = \frac{m \cos \beta}{R} (v^2 \tan \beta + gR)$$

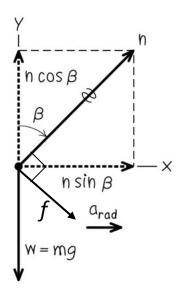
$$f \le \mu_{S} n \Rightarrow v \le v_{max} = \sqrt{\frac{\tan \beta + \mu_{S}}{1 - \mu_{S} \tan \beta}} gR$$
$$\ge \sqrt{\mu_{S} gR}$$

#### (a) Car rounding banked curve



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**(b)** Free-body diagram for car



# Challenging Question

• What happen to the friction f if  $v < \sqrt{gR \tan \beta}$ ?

How would you interpret this situation?