

MATH2111 Tutorial 6

T1A&T1B QUAN Xueyang
T1C&T2A SHEN Yinan
T2B&T2C ZHANG Fa

1 The Inverse of a Matrix

1. Definition (Inverse of a Matrix)

An $n \times n$ matrix A is said to be invertible if there is an $n \times n$ matrix C such that

$$CA = I_n \text{ and } AC = I_n$$

where I_n denote the $n \times n$ identity matrix. In this case, C is the inverse of A , and is denoted by A^{-1} . A matrix that is not invertible is called a singular matrix, and an invertible matrix is called a nonsingular matrix.

2. **Theorem.** Let $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$.

If $ad - bc \neq 0$, then A is invertible and

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

If $ad - bc = 0$, then A is not invertible.

Note: The quantity $ad - bc$ is called the determinant of A , and we write

$$\det A = ad - bc$$

3. **Theorem.** If A is an invertible $n \times n$ matrix, then for each \mathbf{b} in \mathbb{R}^n , the equation $A\mathbf{x} = \mathbf{b}$ has the unique solution $\mathbf{x} = A^{-1}\mathbf{b}$.

4. Theorem.

(a) If A is an invertible matrix, then A^{-1} is invertible and

$$\left(A^{-1}\right)^{-1} = A$$

(b) If A and B are $n \times n$ invertible matrices, then so is AB , and the inverse of AB is the product of the inverses of A and B in the reverse order. i.e.

$$(AB)^{-1} = B^{-1}A^{-1}$$

(c) If A is an invertible matrix, then so is A^T , and the inverse of A^T is the transpose of A^{-1} . i.e.

$$\left(A^T\right)^{-1} = \left(A^{-1}\right)^T$$

5. **Theorem.** An $n \times n$ matrix A is invertible if and only if A is row equivalent to I_n , and in this case, any sequence of elementary row operations that reduces A to I_n also transforms I_n into A^{-1} .
6. **Algorithm for Finding A^{-1}**
 - (a) Row reduce the augmented matrix $\left[A \mid I \right]$.
 - (b) If A is row equivalent to I , then $\left[A \mid I \right]$ is row equivalent to $\left[I \mid A^{-1} \right]$. Otherwise, A does not have an inverse.

2 Characterizations of Invetible Matrices

1. Theorem (The Invertible Matrix Theorem)

Let A be a square $n \times n$ matrix. Then the following statements are equivalent.

- (a) A is an invertible matrix.
 - (b) A is row equivalent to the $n \times n$ identity matrix.
 - (c) A has n pivot positions.
 - (d) The equation $A\mathbf{x} = \mathbf{0}$ has only the trivial solution.
 - (e) The columns of A form a linearly independent set.
 - (f) The linear transformation $\mathbf{x} \rightarrow A\mathbf{x}$ is one-to-one.
 - (g) The equation $A\mathbf{x} = \mathbf{b}$ has at least one solution for each \mathbf{b} in \mathbb{R}^n .
 - (h) The columns of A span \mathbb{R}^n .
 - (i) The linear transformation $\mathbf{x} \rightarrow A\mathbf{x}$ maps \mathbb{R}^n onto \mathbb{R}^n .
 - (j) There is an $n \times n$ matrix C such that $CA = I$.
 - (k) There is an $n \times n$ matrix D such that $AD = I$.
 - (l) A^T is an invertible matrix.
2. **Definition.** A linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is said to be invertible if there exists a function $S : \mathbb{R}^n \rightarrow \mathbb{R}^n$ such that

$$S(T(\mathbf{x})) = \mathbf{x} \text{ for all } \mathbf{x} \text{ in } \mathbb{R}^n, \text{ and } T(S(\mathbf{x})) = \mathbf{x} \text{ for all } \mathbf{x} \text{ in } \mathbb{R}^n$$

3. **Theorem.** Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear transformation and let A be the standard matrix for T . Then T is invertible if and only if A is an invertible matrix. In that case, the linear transformation S given by $S(\mathbf{x}) = A^{-1}\mathbf{x}$ is the unique function satisfying the definition.

3 Determinants

3.1 Calculate Determinants

1. Notation.

- (1) A_{ij} is the submatrix got from matrix A by deleting the i th row and j th column of A .
- (2) $C_{ij} = (-1)^{i+j} \det A_{ij}$ is called the (i, j) -**cofactor** of A .

2. Definition.

For $n \geq 2$, the determinant of an $n \times n$ matrix $A = [a_{ij}]$ is given by

$$\begin{aligned} \det A &= a_{11} \det A_{11} - a_{12} \det A_{12} + \cdots + (-1)^{1+n} a_{1n} \det A_{1n} \\ &= \sum_{j=1}^n (-1)^{1+j} a_{1j} \det A_{1j} \end{aligned}$$

3. Theorem.

The determinant of an $n \times n$ matrix A can be computed by a cofactor expansion across any row or down any column:

$$\begin{aligned}\det A &= (-1)^{i+1}a_{i1} \det A_{i1} + (-1)^{i+2}a_{i2} \det A_{i2} + \cdots + (-1)^{i+n}a_{in} \det A_{in} \\ &= \sum_{j=1}^n (-1)^{i+j}a_{ij} \det A_{ij} \quad (\text{expansion across row } i)\end{aligned}$$

$$\begin{aligned}\det A &= (-1)^{1+j}a_{1j} \det A_{1j} + (-1)^{2+j}a_{2j} \det A_{2j} + \cdots + (-1)^{n+j}a_{nj} \det A_{nj} \\ &= \sum_{i=1}^n (-1)^{i+j}a_{ij} \det A_{ij} \quad (\text{expansion down column } j)\end{aligned}$$

Note: Use a matrix of signs to determine $(-1)^{i+j}$

$$\begin{bmatrix} + & - & + & \cdots \\ - & + & - & \cdots \\ + & - & + & \cdots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

3.2 Properties of Determinants

1. **Theorem (Row Operations).** Let A be a square matrix.

- (a) If a multiple of one row of A is added to another row to produce a matrix B , then $\det B = \det A$.
- (b) If two rows of A are interchanged to produce B , then $\det B = -\det A$.
- (c) If one row of A is multiplied by k to produce B , then $\det B = k \cdot \det A$.

2. **Theorem.** A square matrix A is invertible if and only if $\det A \neq 0$.

3. **Corollary.** $\det A = 0$ if the rows of A are linearly dependent.

4. **Theorem.** If A is an $n \times n$ matrix, then $\det A^T = \det A$.

5. **Theorem.** If A and B are $n \times n$ matrices, then $\det AB = (\det A)(\det B)$.

4 Exercises

1. Find the inverses of the matrices below, if they exist.

(a) $\begin{bmatrix} 1 & 0 & -2 \\ -3 & 1 & 4 \\ 2 & -3 & 4 \end{bmatrix}$ (b) $\begin{bmatrix} 1 & -2 & 1 \\ 4 & -7 & 3 \\ -2 & 6 & -4 \end{bmatrix}$

Q1.

$$\begin{aligned}
 \textcircled{1} \left[\begin{array}{ccc|ccc} 1 & 0 & -2 & 1 & 0 & 0 \\ -3 & 1 & 4 & 0 & 1 & 0 \\ 2 & -3 & 4 & 0 & 0 & 1 \end{array} \right] & \xrightarrow[\substack{R_2 + 3R_1 \rightarrow R_2 \\ R_3 - 2R_1 \rightarrow R_3}]{} \left[\begin{array}{ccc|ccc} 1 & 0 & -2 & 1 & 0 & 0 \\ 0 & 1 & -2 & 3 & 1 & 0 \\ 0 & -3 & 8 & -2 & 0 & 1 \end{array} \right] \\
 & \xrightarrow{R_3 + 3R_1 \rightarrow R_3} \left[\begin{array}{ccc|ccc} 1 & 0 & -2 & 1 & 0 & 0 \\ 0 & 1 & -2 & 3 & 1 & 0 \\ 0 & 0 & 2 & 7 & 3 & 1 \end{array} \right] \\
 & \xrightarrow{\frac{1}{2}R_3 \rightarrow R_3} \left[\begin{array}{ccc|ccc} 1 & 0 & -2 & 1 & 0 & 0 \\ 0 & 1 & -2 & 3 & 1 & 0 \\ 0 & 0 & 1 & \frac{7}{2} & \frac{3}{2} & \frac{1}{2} \end{array} \right] \\
 & \xrightarrow[\substack{R_2 + 2R_3 \rightarrow R_2 \\ R_1 + 2R_3 \rightarrow R_1}]{} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 8 & 3 & 1 \\ 0 & 1 & 0 & 10 & 4 & 1 \\ 0 & 0 & 1 & \frac{7}{2} & \frac{3}{2} & \frac{1}{2} \end{array} \right] = [I | A^{-1}]
 \end{aligned}$$

$$\begin{aligned}
 \textcircled{2} \left[\begin{array}{ccc|ccc} 1 & -2 & 1 & 1 & 0 & 0 \\ 4 & -7 & 3 & 0 & 1 & 0 \\ -2 & 6 & -4 & 0 & 0 & 1 \end{array} \right] & \xrightarrow[\substack{R_2 - 4R_1 \rightarrow R_2 \\ R_3 + 2R_1 \rightarrow R_3}]{} \left[\begin{array}{ccc|ccc} 1 & -2 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -4 & 1 & 0 \\ 0 & 2 & -2 & 2 & 0 & 1 \end{array} \right] \\
 & \xrightarrow{R_3 - 2R_2 \rightarrow R_3} \left[\begin{array}{ccc|ccc} 1 & -2 & 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -4 & 1 & 0 \\ 0 & 0 & 0 & 10 & -2 & 1 \end{array} \right]
 \end{aligned}$$

A^{-1} doesn't exist.

2. Suppose T and U are linear transformations from \mathbb{R}^n to \mathbb{R}^n such that $T(U\mathbf{x}) = \mathbf{x}$ for all \mathbf{x} in \mathbb{R}^n . Is it true that $U(T\mathbf{x}) = \mathbf{x}$ for all \mathbf{x} in \mathbb{R}^n ? Why or why not?

Q2. Let A, B be standard matrices of T, U .

Then standard matrix of $T(U\vec{x})$ is AB .

$$\because T(U\vec{x}) = \vec{x} \text{ for all } \vec{x} \in \mathbb{R}^n$$

$$\therefore \text{we have } AB = I_n$$

For $A, B \in \mathbb{R}^{n \times n}$, by invertible matrix theorem,

$$A, B \text{ are invertible, } B = A^{-1}, BA = I$$

And BA is standard matrix of $U(T\vec{x})$,

$$\text{so we have } U(T\vec{x}) = \vec{x} \text{ for all } \vec{x} \in \mathbb{R}^n.$$

3. Compute the determinants by cofactor expansions.

$$(a) \begin{vmatrix} 4 & 0 & -7 & 3 & -5 \\ 0 & 0 & 2 & 0 & 0 \\ 7 & 3 & -6 & 4 & -8 \\ 5 & 0 & 5 & 2 & -3 \\ 0 & 0 & 9 & -1 & 2 \end{vmatrix} \quad (b) \begin{vmatrix} 6 & 3 & 2 & 4 & 0 \\ 9 & 0 & -4 & 1 & 0 \\ 8 & -5 & 6 & 7 & 1 \\ 2 & 0 & 0 & 0 & 0 \\ 4 & 2 & 3 & 2 & 0 \end{vmatrix}$$

Q3. (a)

$$\det(A) = \begin{vmatrix} 4 & 0 & -7 & 3 & -5 \\ 0 & 0 & 2 & 0 & 0 \\ 7 & 3 & -6 & 4 & -8 \\ 5 & 0 & 5 & 2 & -3 \\ 0 & 0 & 9 & -1 & 2 \end{vmatrix} = (-3) \begin{vmatrix} 4 & -7 & 3 & -5 \\ 0 & 2 & 0 & 0 \\ 5 & 5 & 2 & -3 \\ 0 & 9 & -1 & 2 \end{vmatrix}$$

$$= (-3) \cdot (2) \begin{vmatrix} 4 & 3 & -5 \\ 5 & 2 & -3 \\ 0 & -1 & 2 \end{vmatrix}$$

$$= (-3) \cdot (2) \cdot \left(4 \begin{vmatrix} 2 & -3 \\ -1 & 2 \end{vmatrix} + 5 \begin{vmatrix} 3 & -5 \\ -1 & 2 \end{vmatrix} \right)$$

$$= -6 \cdot \left[4(2 \times 2 - (-3) \times (-1)) - 5(3 \times 2 - (-1) \times (-5)) \right]$$

$$= -6(4 \times 1 - 5 \times 1) = 6$$

(b)

$$\det(B) = \begin{vmatrix} 6 & 3 & 2 & 4 & 0 \\ 9 & 0 & -4 & 1 & 0 \\ 8 & -5 & 6 & 7 & 1 \\ 2 & 0 & 0 & 0 & 0 \\ 4 & 2 & 3 & 2 & 0 \end{vmatrix} = (-2) \begin{vmatrix} 3 & 2 & 4 & 0 \\ 0 & -4 & 1 & 0 \\ -5 & 6 & 7 & 1 \\ 2 & 3 & 2 & 0 \end{vmatrix}$$

$$= (-2)(-1) \begin{vmatrix} 3 & 2 & 4 \\ 0 & -4 & 1 \\ 2 & 3 & 2 \end{vmatrix}$$

$$= 2 \left[3 \times \begin{vmatrix} -4 & 1 \\ 3 & 2 \end{vmatrix} + 2 \times \begin{vmatrix} 2 & 4 \\ -4 & 1 \end{vmatrix} \right]$$

$$= 2 \cdot \left[3 \times (-4 \times 2 - 3 \times 1) + 2 \times (2 \times 1 - 4 \times (-4)) \right] = 6$$

4. Find the determinant by row reduction to echelon form.

$$\begin{vmatrix} 1 & 3 & -1 & 0 & -2 \\ 0 & 2 & -4 & -2 & -6 \\ -2 & -6 & 2 & 3 & 10 \\ 1 & 5 & -6 & 2 & -3 \\ 0 & 2 & -4 & 5 & 9 \end{vmatrix}$$

R_4 .

$$\det(A) = \begin{vmatrix} 1 & 3 & -1 & 0 & -2 \\ 0 & 2 & -4 & -2 & -6 \\ -2 & -6 & 2 & 3 & 10 \\ 1 & 5 & -6 & 2 & -3 \\ 0 & 2 & -4 & 5 & 9 \end{vmatrix} \xrightarrow[\begin{smallmatrix} R_4 - R_1 \rightarrow R_4 \end{smallmatrix}]{\begin{smallmatrix} R_3 + 2R_1 \rightarrow R_3 \end{smallmatrix}} \begin{vmatrix} 1 & 3 & -1 & 0 & -2 \\ 0 & 2 & -4 & -2 & -6 \\ 0 & 0 & 0 & 3 & 6 \\ 0 & 2 & -5 & 2 & -1 \\ 0 & 2 & -4 & 5 & 9 \end{vmatrix}$$

$$\xrightarrow[\begin{smallmatrix} R_5 - R_2 \rightarrow R_5 \end{smallmatrix}]{\begin{smallmatrix} R_4 - R_2 \rightarrow R_4 \end{smallmatrix}} \begin{vmatrix} 1 & 3 & -1 & 0 & -2 \\ 0 & 2 & -4 & -2 & -6 \\ 0 & 0 & 0 & 3 & 6 \\ 0 & 0 & -1 & 4 & 5 \\ 0 & 0 & 0 & 7 & 15 \end{vmatrix}$$

$$\xrightarrow[\begin{smallmatrix} (-1) \end{smallmatrix}]{\begin{smallmatrix} R_3 \leftrightarrow R_4 \end{smallmatrix}} \begin{vmatrix} 1 & 3 & -1 & 0 & -2 \\ 0 & 2 & -4 & -2 & -6 \\ 0 & 0 & -1 & 4 & 5 \\ 0 & 0 & 0 & 3 & 6 \\ 0 & 0 & 0 & 7 & 15 \end{vmatrix}$$

$$\xrightarrow[\begin{smallmatrix} (-1) \end{smallmatrix}]{\begin{smallmatrix} R_5 - \frac{7}{3}R_4 \rightarrow R_5 \end{smallmatrix}} \begin{vmatrix} 1 & 3 & -1 & 0 & -2 \\ 0 & 2 & -4 & -2 & -6 \\ 0 & 0 & -1 & 4 & 5 \\ 0 & 0 & 0 & 3 & 6 \\ 0 & 0 & 0 & 0 & 1 \end{vmatrix}$$

$$= (-1) \cdot 1 \cdot 2 \cdot (-1) \cdot 3 \cdot 1 = 6$$

5. Let $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$. Show that $\det(A+B) = \det A + \det B$ if and only if $a+d=0$.

$$\begin{aligned} \text{Q5. } \det(A+B) &= \begin{vmatrix} 1+a & b \\ c & 1+d \end{vmatrix} = (1+a)(1+d) - bc \\ &= 1 + ad + a + d - bc \end{aligned}$$

$$\det(A) + \det(B) = \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} + \begin{vmatrix} a & b \\ c & d \end{vmatrix} = 1 + ad - bc$$

$$\begin{aligned} \text{Thus } \det(A+B) = \det(A) + \det(B) &\iff 1 + ad + a + d - bc = 1 + ad - bc \\ &\iff a + d = 0 \end{aligned}$$