MATH2111 Tutorial 2

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1 Procedures to solve a system of linear equations

- 1. Write the system as augmented matrix $[M \mid b]$;
- 2. Use EROs to reduce $[M \mid b]$ into RREF $[M' \mid b']$;
- 3. Locate the pivot columns of [M' | b'];
- 4. If b' is a pivot column, the system is inconsistent (has 0 solution); otherwise, the system is consistent, locate the free columns of M'.
 - (a) If there is a free column, then the system has infinitely many solutions;
 - (b) otherwise the system has a unique solution.

2 Vectors

1. A **column vector** is a matrix with one column. We add and subtract vectors of the same size by doing operations component-wise:

$$\begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \pm \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} u_1 \pm v_1 \\ u_2 \pm v_2 \\ \vdots \\ u_n \pm v_n \end{bmatrix}, \text{ and } c \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} cv_1 \\ cv_2 \\ \vdots \\ cv_n \end{bmatrix} \text{ for } c \in \mathbb{R}.$$

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- 2. Let *n* be a positive integer and define \mathbb{R}^n to be the set of vectors with *n* rows.
- 3. Algebraic Properties of Vectors in \mathbb{R}^n :

For all \mathbf{u} , \mathbf{v} , \mathbf{w} in \mathbb{R}^n and all scalars c and d:

- (1). u + v = v + u
- (2). $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$
- (3). $\mathbf{u} + \mathbf{0} = \mathbf{0} + \mathbf{u} = \mathbf{u}$
- (4). $\mathbf{u} + (-\mathbf{u}) = (-\mathbf{u}) + \mathbf{u} = \mathbf{0}$ where $-\mathbf{u}$ denotes $(-1)\mathbf{u}$
- (5). $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$
- (6). $(c+d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$
- (7). $c(d\mathbf{u}) = (cd)\mathbf{u}$
- (8). $1\mathbf{u} = \mathbf{u}$

4. Linear Combination and Span

Let $S = \{u_1, u_2 \cdots, u_k\}$ be a collection of vectors in \mathbb{R}^n .

(a) Another vector $v \in \mathbb{R}^n$ is a linear combination of S if

$$\mathbf{v} = c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \cdots + c_k \mathbf{u}_k$$

for some scalars $c_1, c_2, \cdots, c_k \in \mathbb{R}$.

(b) The **span** of S, Span(S), is the collection of all vectors of the form $c_1 u_1 + c_2 u_2 + \cdots + c_k u_k$, i.e.

$$Span(S) := \{c_1 u_1 + c_2 u_2 + \dots + c_k u_k \mid c_1, c_2, \dots, c_k \in \mathbb{R}\}\$$

So Span(S) contains all possible linear combinations of S.

5. **Theorem** A vector \boldsymbol{b} is a linear combination of $\boldsymbol{a}_1, \boldsymbol{a}_2, \cdots, \boldsymbol{a}_k$ if and only if there exists a solution to the corresponding linear system with the augmented matrix $[\boldsymbol{a}_1 \ \boldsymbol{a}_2 \ \cdots \ \boldsymbol{a}_k \ | \ \boldsymbol{b}]$.

Exercises

- 1. Suppose $\begin{pmatrix} 1 & 1 & 1 & 0 \\ 2 & 2 & a & 3 \\ 1 & 1 & b & 4 \end{pmatrix}$ is an augmented matrix. Determine a and b such that the linear system
- (1) is inconsistent,
- (2) has a unique solution,
- (3) has infinite many solutions.

$$\begin{bmatrix} 1 & 1 & 1 & 0 \\ 2 & 2 & a & 3 \\ 1 & 1 & b & 4 \end{bmatrix} \xrightarrow{R_2 - 2R_1 \rightarrow R_2} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 0 & a-2 & 3 \\ 0 & 0 & b-1 & 4 \end{bmatrix}$$

- D When a = 2 or b=1, inconsistent
- 1 When a-2 =0, b-1 = 0 i.e. a=2 , b=6

$$\begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 0 & a-2 & 3 \\ 0 & 0 & b-1 & 4 \end{bmatrix} \xrightarrow{R_3 - \frac{b-1}{a-2} R_2 \rightarrow R_3} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 0 & a-2 & 3 \\ 0 & 0 & 0 & 4 - \frac{b-1}{a-2} 3 \end{bmatrix}$$

if
$$4 - \frac{b-1}{a-2} \cdot 3 \neq 0$$
, i.e. $4(a-2) \neq 3(b-1)$ in consistent

if
$$\psi - \frac{b-1}{a-2} \cdot 3 \neq 0$$
, i.e. $\psi(a-2) \neq 3(b-1)$, in consistent if $\psi - \frac{b-1}{a-2} \cdot 3 = 0$, i.e. $\psi(a-2) = 3(b-1)$, infinitely many solutions.

2. Suppose
$$\begin{pmatrix} 1 & 1 & 1 & 0 \\ 2 & a & 3 & 3 \\ 1 & 2 & b & 4 \end{pmatrix}$$
 is an augmented matrix. Determine a and b such that the linear system

- (1) is inconsistent.
- (2) has a unique solution,
- (3) has infinite many solutions.

$$\begin{bmatrix} 1 & 1 & 1 & 0 \\ 2 & a & 3 & 3 \\ 1 & 2 & b & 4 \end{bmatrix} \xrightarrow{R_2 - 2R_1 \to R_2} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & a-2 & 1 & 3 \\ 0 & 1 & b-1 & 4 \end{bmatrix}$$

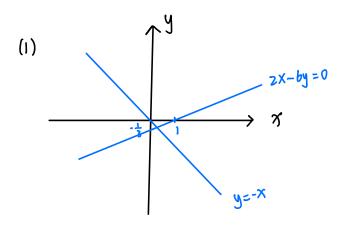
① if
$$1-(a-2)(b-1)=0$$
 and $3-4(a-2)\neq0$,
i.e. $a+\frac{1}{4}$, $b\neq\frac{7}{3}$, it's inconsistent

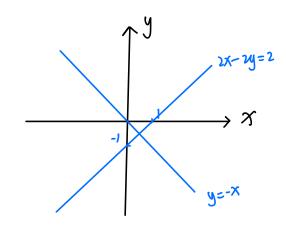
② if
$$1-(a-2)(b-1)\neq 0$$
, i.e. $(a-2)(b-1)\neq 1$, unique solution

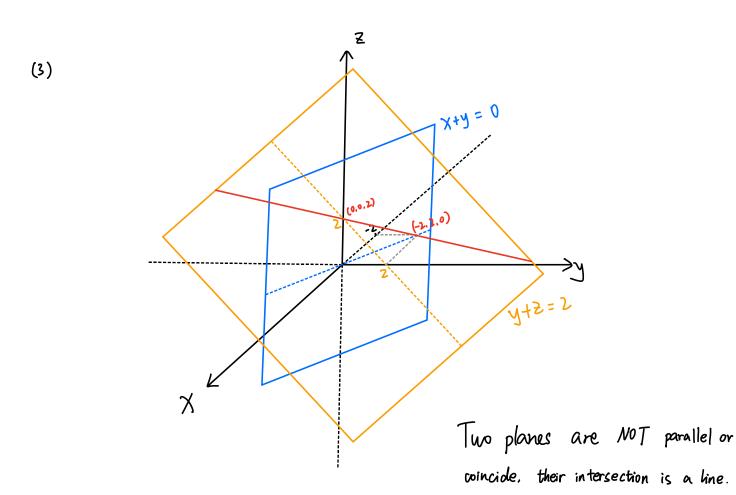
② if
$$1-(a-2)(b-1)=0$$
 and $2-4(a-2)=0$,
 $\therefore (a-2)(b-1)=1$, and $a=\frac{11}{4}$,
 $\therefore e. \ a=\frac{11}{4}, \ b=\frac{7}{3}$, infinitely many solutions.

3. Plot the following linear systems:

- (1) Two variables: $\begin{cases} x + y = 0, \\ 2x 6y = 2 \end{cases}$
- (2) Two variables: $\begin{cases} x + y = 0, \\ 2x 2y = 2. \end{cases}$
- (3) Three variables: $\begin{cases} x + y = 0 \\ y + z = 2 \end{cases}$







(2)

4. Let
$$\boldsymbol{u} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$
, $\boldsymbol{v} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$

- (1) Write down the subset of \mathbb{R}^3 spanned by \boldsymbol{u} and \boldsymbol{v} .
- (2) Determine whether vector $\mathbf{w} = \begin{pmatrix} 2 \\ 2 \\ 2 \end{pmatrix}$ could be spanned by \mathbf{u} and \mathbf{v} .
- (1) Set: $\{\vec{x} \mid \vec{x} = c_1\vec{u} + c_2\vec{v} \text{ for all } c_1, c_2 \in \mathbb{R}\}$
- (2) If \vec{w} is spanned by \vec{u} and \vec{v} , then there exists C_1 , $C_2 \in \mathbb{R}$ such that $C_1\vec{u} + C_2\vec{v} = \vec{w}$

$$\begin{bmatrix} 1 & -1 & | & 2 \\ 1 & 0 & | & 2 \\ 0 & 1 & | & 2 \end{bmatrix} \xrightarrow{R_2 - R_1 \to R_2} \begin{bmatrix} 1 & -1 & | & 2 \\ 0 & 1 & | & 0 \\ 0 & 1 & | & 2 \end{bmatrix} \xrightarrow{R_3 - R_2 \to R_3} \begin{bmatrix} 1 & -1 & | & 2 \\ 0 & 1 & | & 0 \\ 0 & 0 & | & 2 \end{bmatrix}$$

The system has no solution

- .. The vector equation $C_1\vec{u} + C_2\vec{V} = \vec{w}$ has no solution
- : w is NOT in span {v. v)

5. Let
$$\mathbf{u} = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$$
, $\mathbf{v} = \begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix}$

- (1) Write down the subset of \mathbb{R}^3 spanned by \boldsymbol{u} and \boldsymbol{v} .
- (2) Determine h such that vector $\mathbf{w} = \begin{pmatrix} 2 \\ 2 \\ h \end{pmatrix}$ could be spanned by \mathbf{u} and \mathbf{v} .
- (1) Set: $\{\vec{x} \mid \vec{x} = c_1\vec{u} + c_2\vec{v}, \text{ for all } c_1, c_2 \in \mathbb{R}\}$
- (2) If \vec{w} is spanned by \vec{u} and \vec{v} , then there exists C_1 , $C_2 \in \mathbb{R}$ such that

$$C_1\vec{u} + C_2\vec{V} = \vec{w}$$

$$\begin{bmatrix} 3 & -2 & 2 \\ 1 & 0 & 2 \\ 0 & 1 & h \end{bmatrix} \xrightarrow{R_2 - \frac{1}{3}R_1 \to R_2} \begin{bmatrix} 3 & -2 & 2 \\ 0 & \frac{2}{3} & \frac{4}{3} \\ 0 & 1 & h \end{bmatrix} \xrightarrow{R_3 - \frac{3}{2}R_2 \to R_3} \begin{bmatrix} 3 & -2 & 2 \\ 0 & \frac{2}{3} & \frac{4}{3} \\ 0 & 0 & \frac{1}{3} \end{bmatrix}$$

when h=2, \vec{w} is spanned by \vec{u} and \vec{v}

6. Let
$$\mathbf{u} = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$$
, $\mathbf{v} = \begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix}$, $\mathbf{w} = \begin{pmatrix} 2 \\ 2 \\ 2 \end{pmatrix}$.

- (1) Write down the subset of \mathbb{R}^3 spanned by u, v, w.
- (2) Determine h such that vector $\mathbf{x} = \begin{pmatrix} 1 \\ 3 \\ h \end{pmatrix}$ could be spanned by \mathbf{u} and \mathbf{v} .

 (3) Determine h such that vector $\mathbf{x} = \begin{pmatrix} 1 \\ 3 \\ h \end{pmatrix}$ could be spanned by \mathbf{u} and \mathbf{v} , \mathbf{w} .
- (1) Set: | | x = c, \vec{u} + c, \vec{v} + c, \vec{w} for all C, C, C, C, EP
- (2) If \vec{x} is spanned by \vec{u} and \vec{v} , then there exists C, Cz ER Such that

$$C_1\vec{u} + C_2\vec{V} = \vec{x}$$

$$\begin{bmatrix} 3 & -2 & | & 1 \\ 1 & 0 & | & 3 \\ 0 & 1 & | & h \end{bmatrix} \xrightarrow{R_2 - \frac{1}{3}R_1 \Rightarrow R_2} \begin{bmatrix} 2 & -2 & | & 1 \\ 0 & \frac{2}{3} & | & \frac{8}{3} \\ 0 & 1 & | & h \end{bmatrix} \xrightarrow{R_3 - \frac{3}{2}R_2 \Rightarrow R_3} \begin{bmatrix} 2 & -2 & | & 1 \\ 0 & \frac{2}{3} & | & \frac{8}{3} \\ 0 & 0 & | & h-4 \end{bmatrix}$$

when h=4, it's consistent

(3) Similarly, if \$\times\$ is spanned by \$\tau\$, \$\tilde{v}\$, \$\tilde{v}\$, \$\tilde{v}\$, then. = C1, C2 C3 GP S.t. C1 12 + C2 12 + C3 12 = 7

when h=4, it's consistent.

R: Think about why (2) and (3) have same solution?

A: Set of vectors $\{\vec{u}, \vec{v}, \vec{w}\}$ is linearly dependent. $\vec{W} = 2\vec{u} + 2\vec{v}$