

# MATH2111 Tutorial 5

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## 1 Linear Transformation

### 1. Definition (Linear Transformation):

A transformation (or mapping)  $T$  is linear if:

- (a)  $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$  for all  $\mathbf{u}, \mathbf{v}$  in the domain of  $T$ .
- (b)  $T(c\mathbf{u}) = cT(\mathbf{u})$  for all scalars  $c$  and all  $\mathbf{u}$  in the domain of  $T$ .

### 2. Theorem 4 (Properties of Linear Transformation):

If  $T$  is a linear transformation, then

- (a)  $T(\mathbf{0}) = \mathbf{0}$
- (b)  $T(c\mathbf{u} + d\mathbf{v}) = cT(\mathbf{u}) + dT(\mathbf{v})$  for all vectors  $\mathbf{u}, \mathbf{v}$  in the domain of  $T$  and all scalars  $c, d$
- (c)  $T(c_1\mathbf{v}_1 + \dots + c_p\mathbf{v}_p) = c_1T(\mathbf{v}_1) + \dots + c_pT(\mathbf{v}_p)$  for all vectors  $\mathbf{v}_1, \dots, \mathbf{v}_p$  in the domain of  $T$  and all scalars  $c_1, \dots, c_p$ .

## 2 The Matrix of a Linear Transformation

### 1. Theorem:

Let  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear transformation. Then there exists a unique matrix  $A$  such that

$$T(\mathbf{x}) = A\mathbf{x} \text{ for all } \mathbf{x} \text{ in } \mathbb{R}^n$$

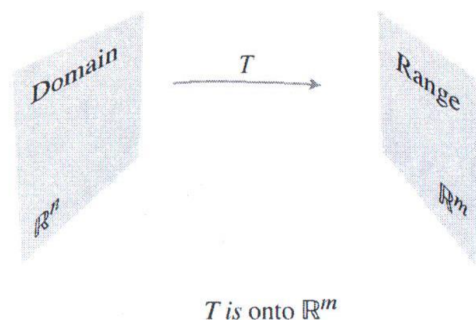
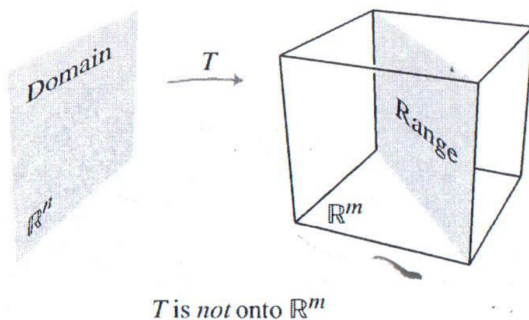
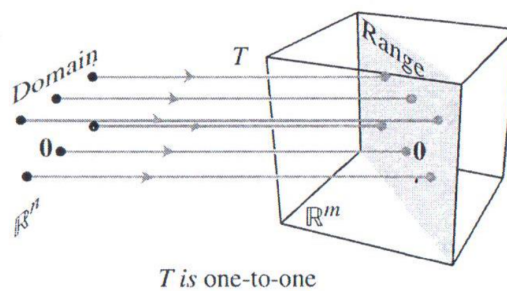
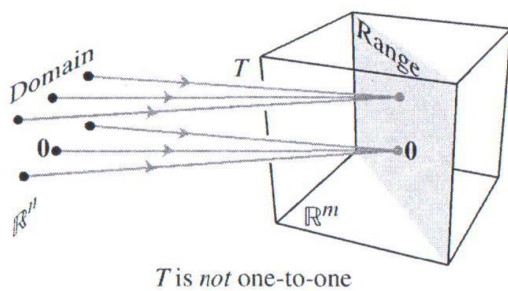
$A$  is the  $m \times n$  matrix whose  $j$ th column is the vector  $T(\mathbf{e}_j)$ , where  $\mathbf{e}_j$  is the  $j$ th column of the identity matrix in  $\mathbb{R}^n$ :

$$A = [T(\mathbf{e}_1) \cdots T(\mathbf{e}_n)]$$

This matrix  $A$  is called the **standard matrix** for the linear transformation  $T$ .

### 2. Definition (One-To-One):

A mapping  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is said to be one-to-one if each  $\mathbf{b}$  in  $\mathbb{R}^m$  is the image of at most one  $\mathbf{x}$  in  $\mathbb{R}^n$ .



### 3. Definition (Onto):

A mapping  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is said to be onto if each  $\mathbf{b}$  in  $\mathbb{R}^m$  is the image of at least one  $\mathbf{x}$  in  $\mathbb{R}^n$ .

### 4. Theorem:

Let  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear transformation. Then  $T$  is one-to-one if and only if the equation  $T(\mathbf{x}) = \mathbf{0}$  has only the trivial solution.

### 5. Theorem:

Let  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  be a linear transformation and let  $A$  be the standard matrix for  $T$ . Then:

- (a)  $T$  maps  $\mathbb{R}^n$  onto  $\mathbb{R}^m$  if and only if the columns of  $A$  span  $\mathbb{R}^m$ ;
- (b)  $T$  is one-to-one if and only if the columns of  $A$  are linearly independent.

## 3 Matrix Operations

### 1. Theorem (Property of Matrix):

Let  $A, B$  and  $C$  be matrices of the same size, and let  $r$  and  $s$  be scalars. Then

- (a)  $A + B = B + A$
- (b)  $(A + B) + C = A + (B + C)$
- (c)  $A + 0 = A$
- (d)  $r(A + B) = rA + rB$
- (e)  $(r + s)A = rA + sA$
- (f)  $r(sA) = (rs)A$

**2. Definition (Matrix Multiplication):**

If  $A$  is an  $m \times n$  matrix, and if  $B$  is an  $n \times p$  matrix, then the product  $AB$  is the  $m \times p$  matrix with entry

$$(AB)_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \cdots + a_{in}b_{nj}$$

**3. Theorem (Properties of Matrix Multiplication):**

Let  $A$  be an  $m \times n$  matrix, and let  $B$  and  $C$  have sizes for which the indicated sums and products are defined. Then

- (a)  $A(BC) = (AB)C$  (associative law of multiplication)
- (b)  $A(B + C) = AB + AC$  (left distributive law)
- (c)  $(B + C)A = BA + CA$  (right distributive law)
- (d)  $r(AB) = (rA)B = A(rB)$  for any scalar  $r$
- (e)  $I_m A = A = A I_n$  (identity for matrix multiplication)

**WARNINGS:**

- 1. In general,  $AB \neq BA$ .
- 2. The cancellation laws do not hold for matrix multiplication. That is, if  $AB = AC$ , then it is not true in general that  $B = C$ .
- 3. If a product  $AB$  is the zero matrix, you cannot conclude in general that either  $A = 0$  or  $B = 0$ .

**4. Definition (Powers of a Matrix):**

If  $A$  is an  $n \times n$  matrix,  $k$  is a positive integer,

$$A^k = \underbrace{A \cdots A}_{k \text{ times}}, \quad A^0 = I_n$$

**5. Definition (Transpose of a Matrix):**

Given an  $m \times n$  matrix  $A$ , the transpose of  $A$  is the  $n \times m$  matrix, denoted by  $A^\top$ , whose columns are formed from the corresponding rows of  $A$ .

**6. Theorem (Properties of Transpose of a Matrix):**

Let  $A$  and  $B$  denote matrices whose sizes are appropriate for the following sums and products. Then

- (a)  $(A^\top)^\top = A$
- (b)  $(A + B)^\top = A^\top + B^\top$
- (c) For any scalar  $r$ ,  $(rA)^\top = rA^\top$
- (d)  $(AB)^\top = B^\top A^\top$

## 4 Exercises

1. Given transformation  $T(x_1, x_2, x_3) = (x_2 + 1, x_3 + 1)$ .

(1) What is  $T(1, 2, 1)$  ?

(2) Is  $T(\cdot)$  a linear transformation?

2. (1) Find the standard matrix of the following linear transformation

$$T(x_1, x_2, x_3, x_4) = (5x_1 - x_2, 5x_2 - x_3, 5x_3 - x_4, 5x_4 - x_1) .$$

(2) Find the linear transformation of the following standard matrix

$$A = \begin{pmatrix} 5 & 1 & 1 \\ 1 & 5 & 1 \\ 1 & 1 & 5 \end{pmatrix}$$

3. Given linear transformation  $T(x_1, x_2, x_3) = (x_1 + x_2, x_2 + x_3, x_1 + x_3)$ , determine whether
- (1)  $T$  is a one-to-one map,
  - (2)  $T$  maps  $\mathbb{R}^3$  onto  $\mathbb{R}^3$ .

4. Suppose  $\alpha$  is an angle. Given linear transformation  $T(x_1, x_2) = (\cos \alpha \cdot x_1 + \sin \alpha \cdot x_2, -\sin \alpha \cdot x_1 + \cos \alpha \cdot x_2)$ . Determine whether
- (1)  $T$  is a one-to-one map,
  - (2)  $T$  maps  $\mathbb{R}^2$  onto  $\mathbb{R}^2$ .

5. Given  $A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$  and  $B = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$ .

(1) Compute  $AB$ .

(2) Compute  $A^2, A^3$ .

(3) Compute  $A^\top B$ .