Fault report | RViz - lidar_frame tf failure

Author: Nicolas Hammje

Title: RViz - lidar_frame tf failure

Problem Encountered:

When setting the fixed frame to anything other than lidar_frame, the tf would bug out.

Solution Implemented:

The time_increment on the raw_lidar_data was too big. There must be an issue in webots, but setting lidar_process.py to not carry over the time_increment but to instead set it to 0 arbitrarily solved the issue.

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