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% Authors ~
    % Suyash Sardar

% Function Calculates the following ~
    % 1.Pressure Distribution across theta and radius
    % 2.Load Carrying Capacity of the bearing

% Inputs ~
    %[n ~ Attitude Ratio]
    %[x_nodes ~ Number of Nodes in X direction]
    %[z_nodes ~ Number of Nodes in Z direction]
    %[L_B ~ Length to Width Ratio]

% Outputs ~
    %[ h_bar ~ Height at various nodes]
    %[ p_bar ~ Pressure at various nodes]
    %[ Load_capacity ~ Load carrying capacity of the bearing]

% Trial run for function
% [h_bar,p_bar,Load_capacity] = two_de_polar(2,20,20,1);

function [h_bar,p_bar,Load_capacity] =
    two_de_polar(n,theta_nodes,r_nodes,L_B)

flag =0;
iter =0;
theta_t = 60 * (pi/180);

B_L = 1/ L_B;
dtheta = 1/ (theta_nodes-1);
dr = 1/ (r_nodes-1);

% Creating Mesh
theta=0:dtheta:1;
r=0:dr:1;
[Theta,R] = meshgrid(theta,r);

p_bar = zeros(theta_nodes,r_nodes);
%h_bar = n + n * (1 - Theta);
h_bar = n - (n-1) * Theta;

while flag ~=1

    p_bar_prev=p_bar;
    iter = iter + 1;

    for i=2:r_nodes-1
        for j=2:theta_nodes-1

            % Updating Pressure Matrix

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        A=(-1.5 * (1-n) / h_bar(i,j) * R(i,j)^2 * thetha_t^2) *
        (p_bar(i+1,j)-p_bar(i-1,j))) / dthetha;
        B=(1/ (R(i,j)^2 * thetha_t^2) * (p_bar(i+1,j) +
        p_bar(i-1,j)) / (dthetha^2));
        C=(p_bar(i,j+1) - p_bar(i,j-1)) / (2 * dr * R(i,j));
        D=(p_bar(i,j+1) + p_bar(i,j-1)) / (dr^2);
        E=((n-1)/ (h_bar(i,j)^3));
        F=2*((1/(dthetha^2 * R(i,j)^2 * thetha_t^2))+((1/dr^2)));
        p_bar(i,j)=(A+B+D+E)/F;
        p_bar(i,j)=p_bar_prev(i,j)+(p_bar(i,j)-
        p_bar_prev(i,j))*0.9;

    end
end

% Checking For Convergence
convergence= (sum(sum(p_bar - p_bar_prev))/sum(sum(p_bar)));
sprintf("iter: %d conv: %f",iter, convergence)
if convergence<=1e-4
    flag=1;
end

% Plotting pressure distribution
drawnow
surf(Thetha,R,p_bar);
title(['PRESSURE DISTRIBUTION' ' ' 'for' ' ' 'Attitude
Ratio:' ' ' num2str(n)])
xlabel('Non-dimentional Thetha');
ylabel('Non-dimentional Radius');
zlabel('Non-dimentional Pressure');

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% Calculating Load Carrying Capacity

% Trapezoidal 2D Rule

% Four Corner Points of the Meshgrid
Load_capacity = (p_bar(1,1) + p_bar(thetha_nodes,1) +
p_bar(1,r_nodes) + p_bar(thetha_nodes,r_nodes)) ...
    * (dthetha * dr) / 4 ;

% Four Sides Except Corner Points of the Meshgrid
Load_capacity = Load_capacity + (sum(p_bar(2:thetha_nodes-1,1)) +
sum(p_bar(2:thetha_nodes-1,r_nodes)) ...
    + sum(p_bar(1,2:r_nodes-1)) +
sum(p_bar(thetha_nodes,2:r_nodes-1))) * (dthetha * dr / 2) ;

% Central Points (i.e : All points except the 4 sides of the
Meshgrid)
Load_capacity = Load_capacity + (sum(sum(p_bar(2:thetha_nodes-1,
2:r_nodes-1)))) * (dthetha * dr);

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%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% Displaying Results
end
disp(' ')
t_time=clock;
disp(['===== ',date,'
====='])
disp(['===== Steady State Analysis of Hydrodynamic Slider
Bearings ====='])
disp(['===== Time
',num2str(t_time(4)),':',num2str(t_time(5)), '
====='])
disp('*****')
sprintf("Load Carrying Capacity (Non-Dimensionalized Value) : %f",
Load_capacity)
disp('*****')

ans =

    "iter: 1 conv: 1.000000"

ans =

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===== 05-May-2018

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===== Steady State Analysis of Hydrodynamic Slider Bearings

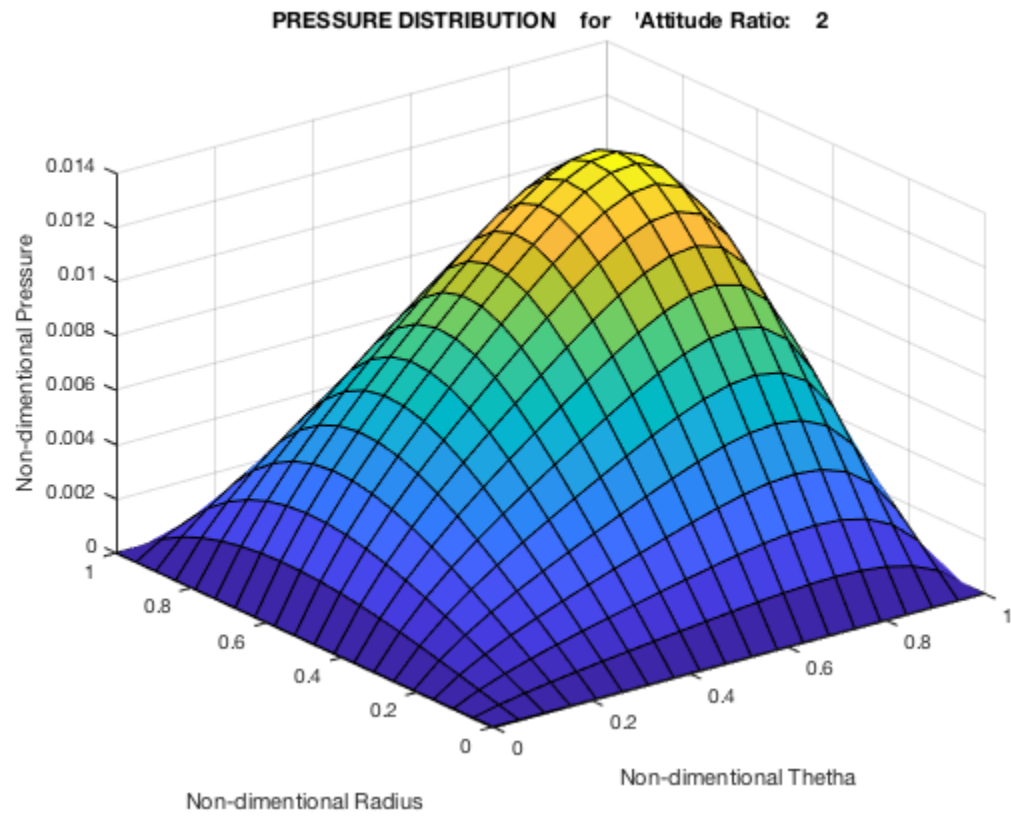
=====

===== Time 1:23

=====

ans =

"Load Carrying Capacity (Non-Dimensionalized Value) : 0.005519"



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