

# Topics to be Discussed

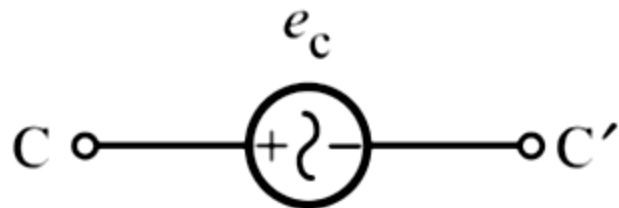
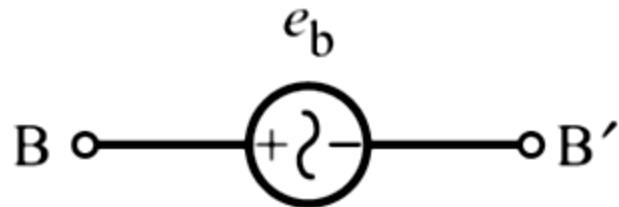
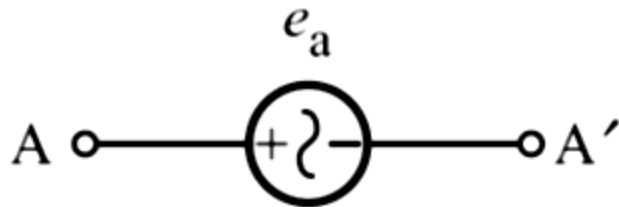
- **Three-Phase System.**
  - Advantages.
  - Concept.
  - Generation.
- **Unbalanced Three-Phase System.**
- **Voltages And Currents Relations.**
  - (1) Star-Connected System.
  - (2) Delta-Connected System
- **Power In Three-phase System.**
- **Power Measurement.**
  - Two-Wattmeter Method.
- **Power Factor Measurement.**
  - Important Points.

# Advantages of Three-Phase System

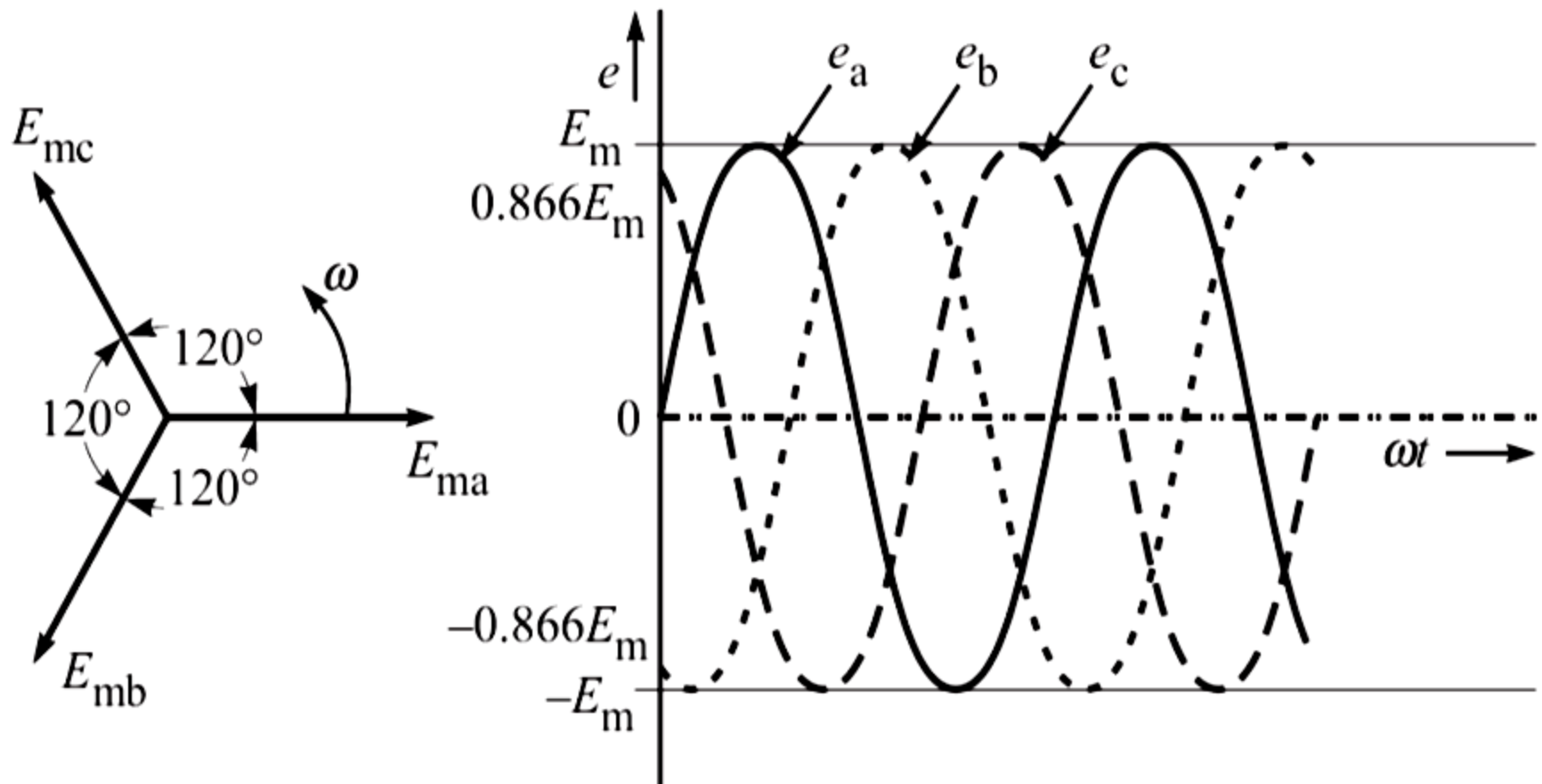
- Transmission lines require much less conductor material.
- A three-phase machine gives a higher output.
- A three-phase motor develops a uniform (not a pulsating) torque.
- The three-phase induction motors are self-starting.
- Can be used to supply domestic as well as industrial (or commercial) power.
- The voltage regulation is better.



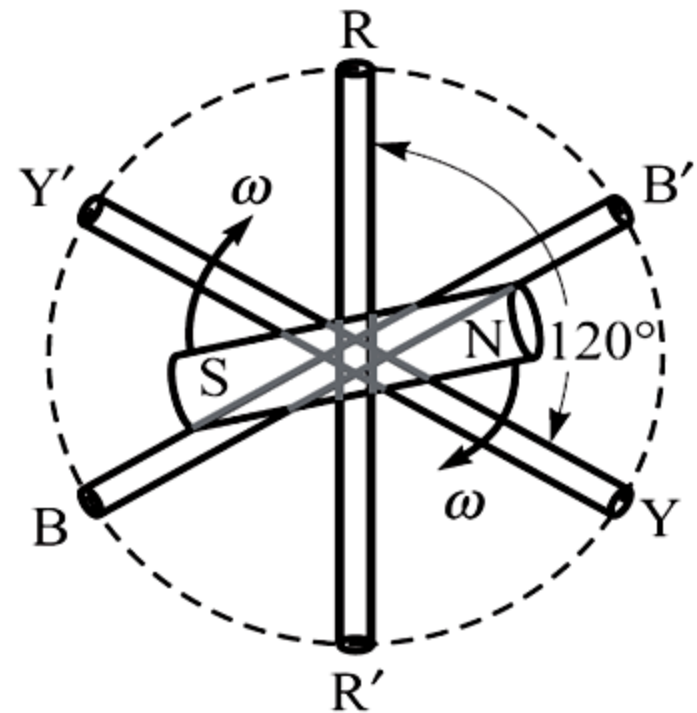
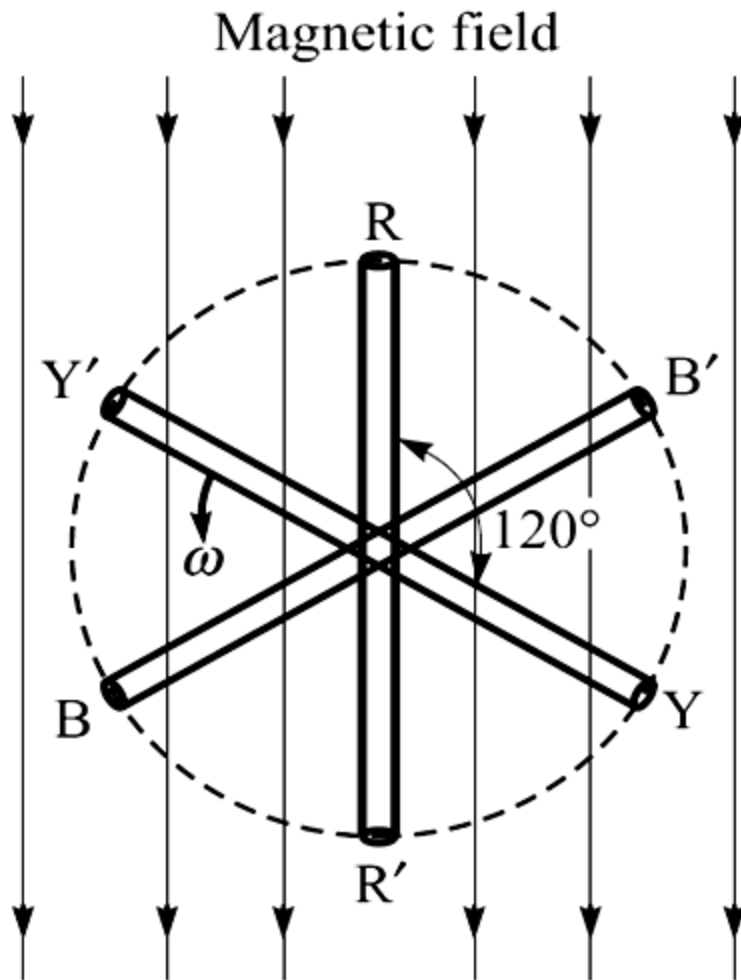
# Concept of Three-phase Voltages



- The *phase order* or *phase sequence* or *phase rotation* is *abc*.



# Generation of Three-phase Voltages



- Whether the coils rotate anti-clockwise or the magnet on the rotor rotates clockwise, the effect is the same.
- But the latter is safer and easier to make external connections to stationary coils.





## Three windings connected to three loads using six line conductors

- Thus, the terminals on the periphery appear in the order : R, B', Y, R', B, Y'.
- The three emfs generated  $e_R$ ,  $e_Y$  and  $e_B$  connected to three respective loads  $L_1$ ,  $L_2$  and  $L_3$ .
- This necessitates the use of six line conductors.
- Obviously, it is cumbersome and expensive.
- Let us now consider how it may be simplified.



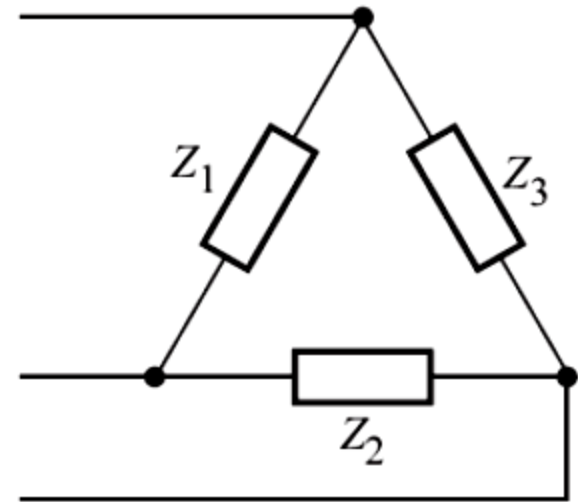
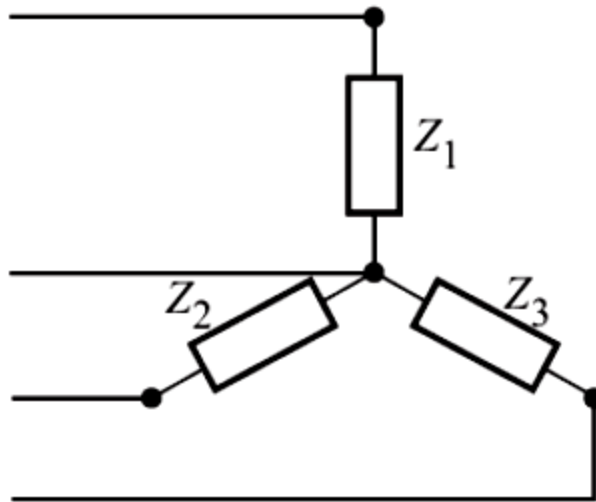


# Three-phase Loads

There are *two* kinds of three-phase systems :

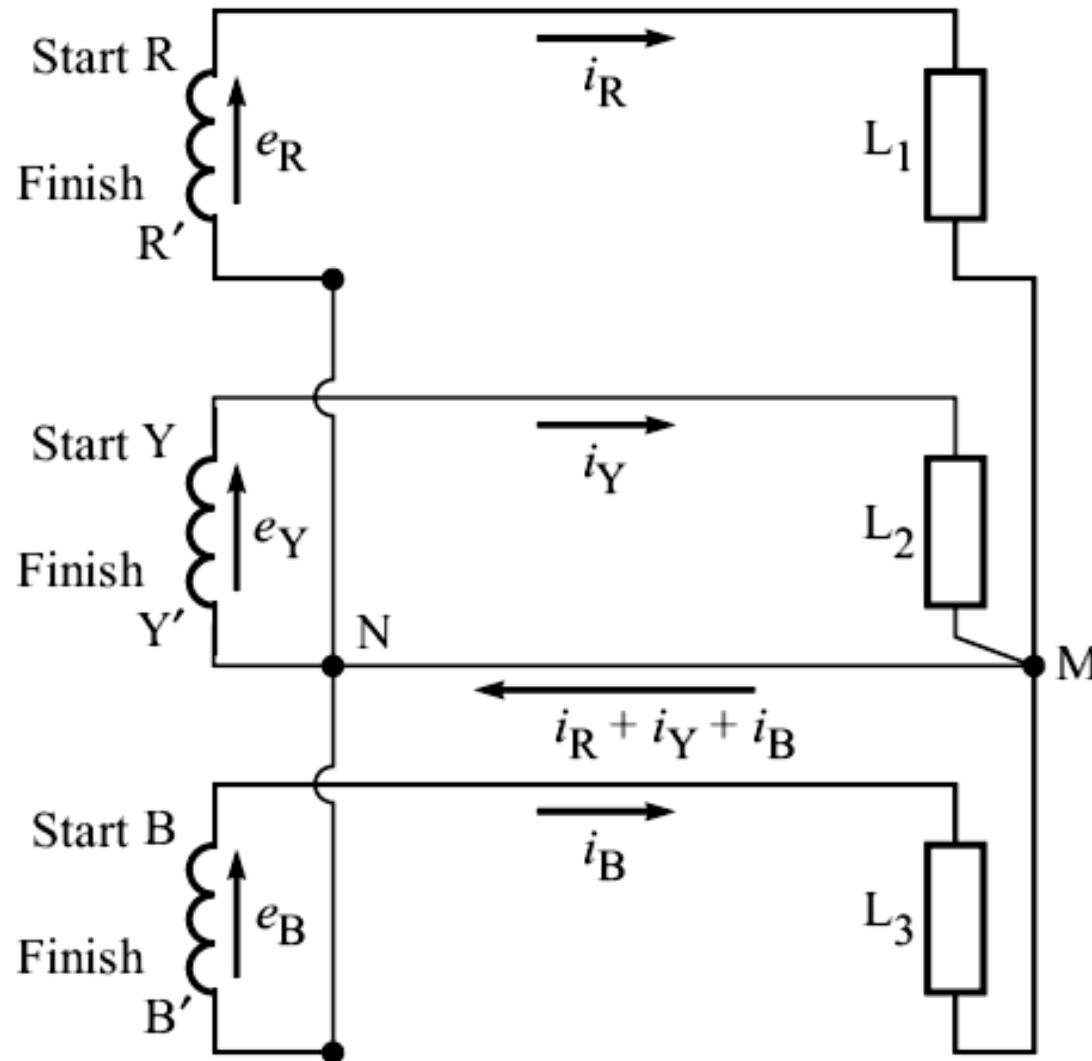
(i) **Star** or wye (Y) connection, and

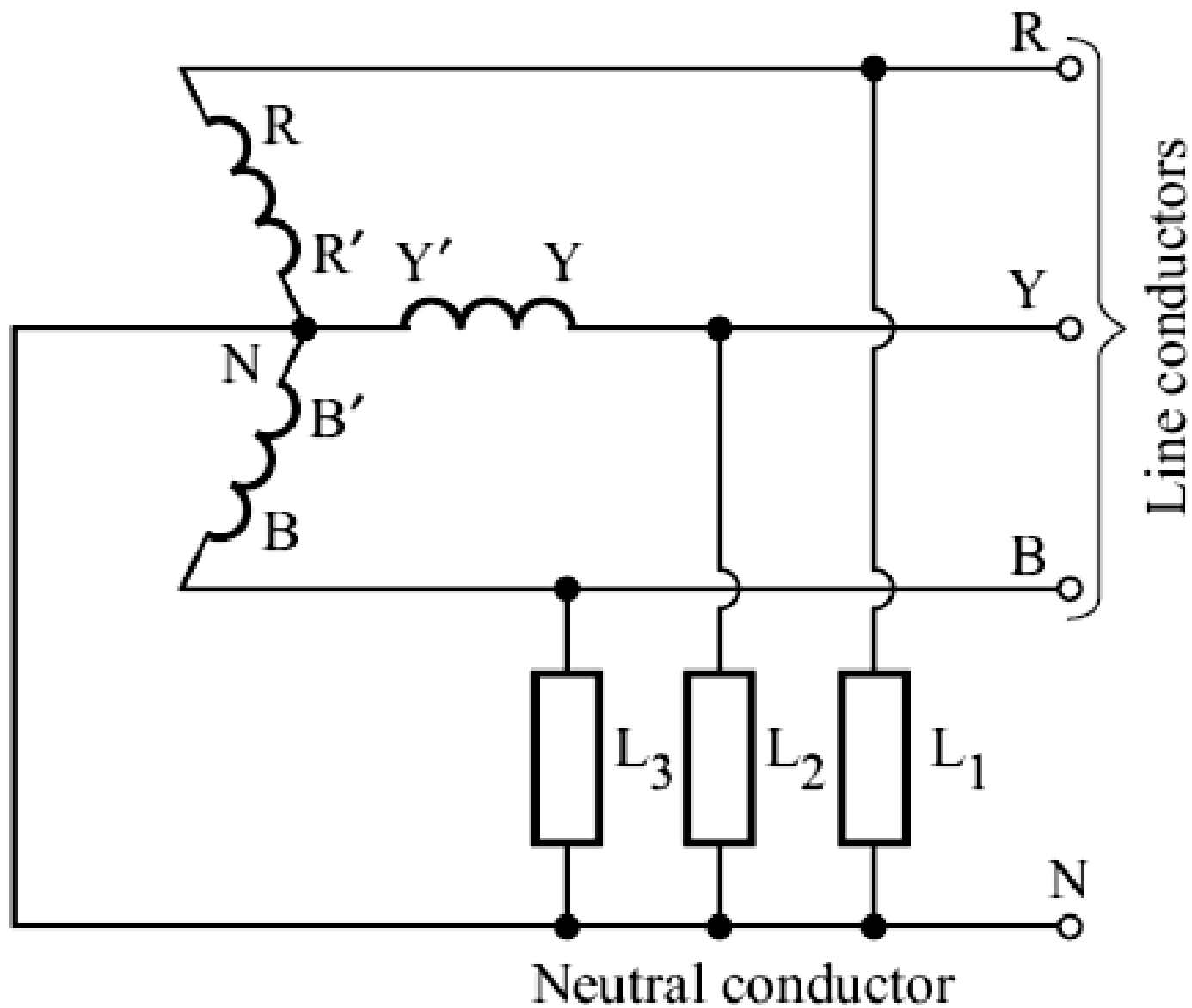
(ii) **Delta** ( $\Delta$ ) or mesh connection



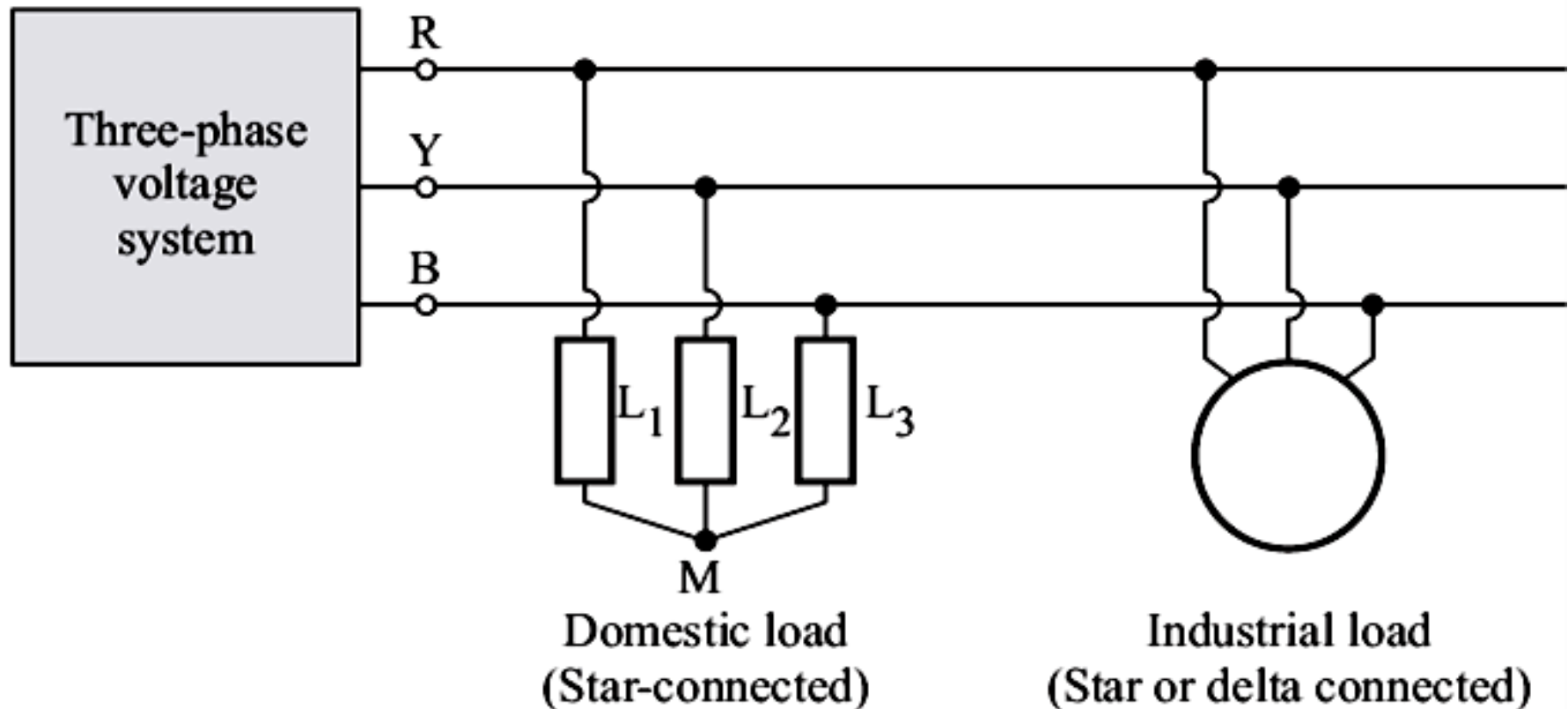
If all the three impedances are equal, the load is said to be a *balanced load*.

# Star (Y) Connected Three-phase System





# Unbalanced Three-Phase System

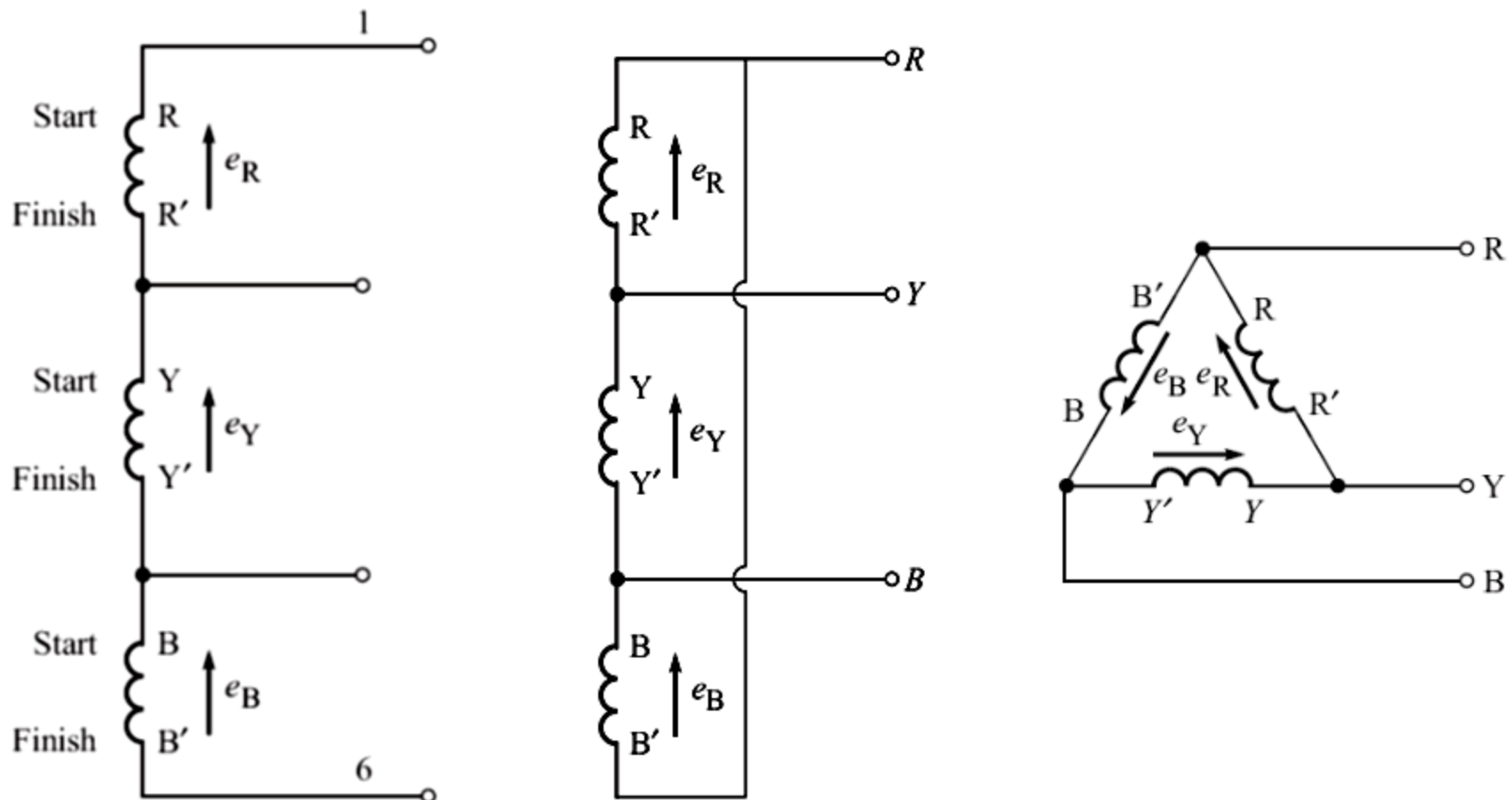


The common point M is called *local neutral point*.

- Practically, it may not be possible always to make this star-connected domestic load balanced.
- However, as per KCL, the sum of the three line currents must still be zero.
- Hence, the voltages across the three loads get adjusted, resulting in *neutral shift* or *floating neutral*.
- This situation is definitely undesirable.
- Therefore, we use *Four-Wire Three-Phase Voltage System*.



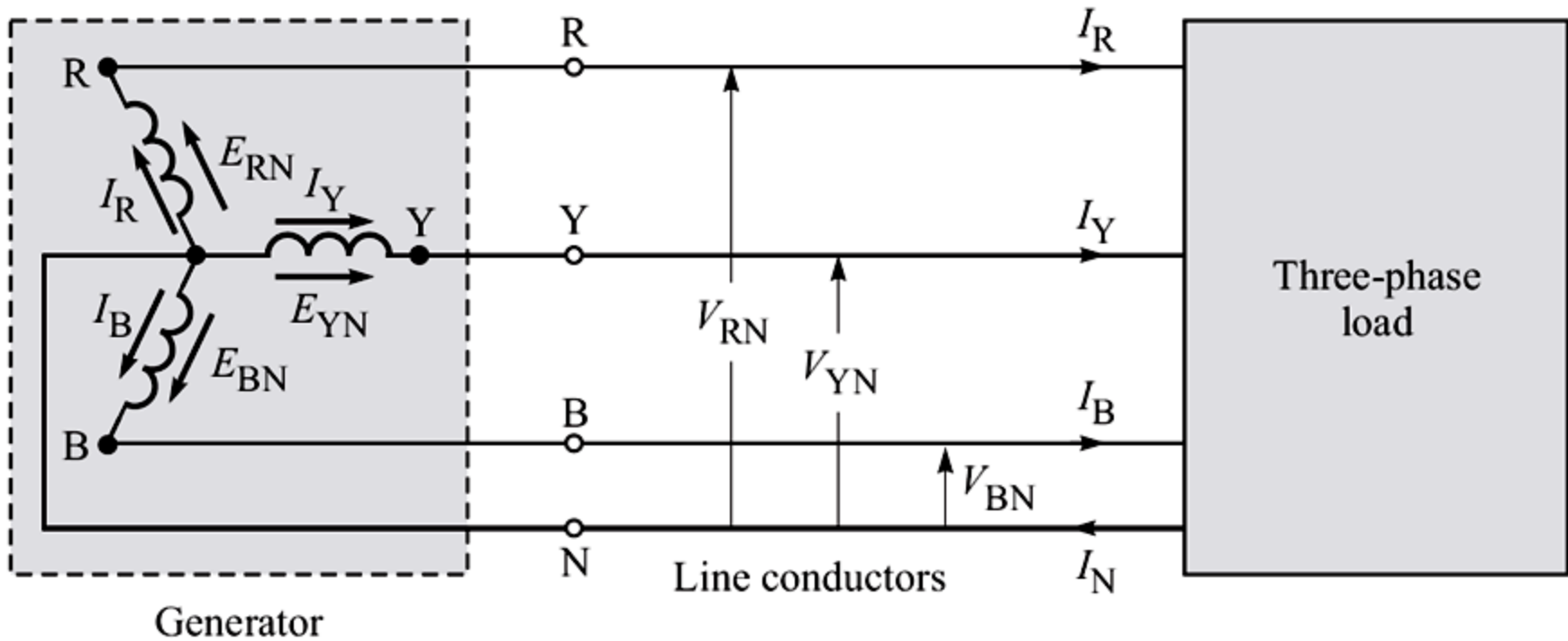
# Delta ( $\Delta$ ) Connected Three-phase System



**Note** that the 'finish' of one phase is connected to the 'start' of another phase.

# Voltages And Currents Relations in 3- $\phi$ Systems

## (1) Star-Connected System



- In a three-phase system, there are two sets of voltages :
  - the set of *phase voltages*, and
  - the other is the set of *line voltages*.
- $V_{RN}$ ,  $V_{YN}$  and  $V_{BN}$  denote the set of three *phase voltages*.
- The term ‘line voltage’ is used to denote the voltage between two lines.
- $V_{RY}$  represents line voltage between the lines R and Y.



$$\begin{aligned} \mathbf{V}_{RY} &= \mathbf{V}_{RNY} = \mathbf{V}_{RN} + \mathbf{V}_{NY} \\ &= \mathbf{V}_{RN} - \mathbf{V}_{YN} = \mathbf{V}_{RN} + (-\mathbf{V}_{YN}) \end{aligned}$$

$$V_{RY} = 2(V_{RN} \cos 30^\circ)$$

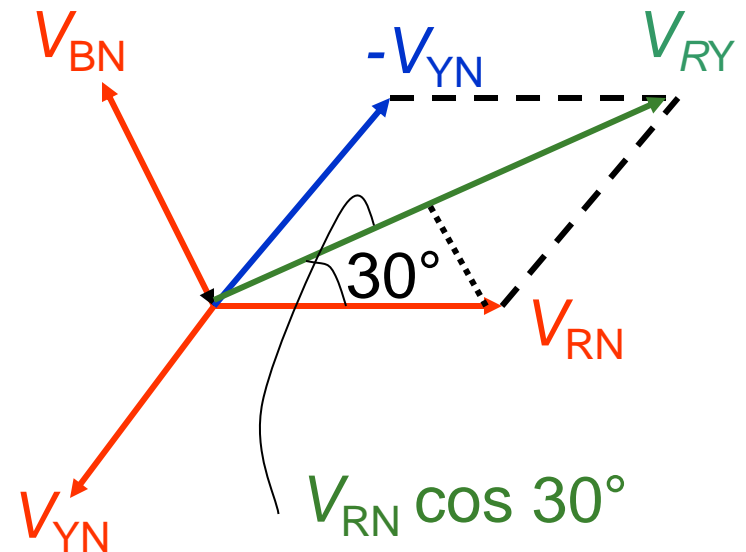
or

$$V_L = 2V_{ph} \left( \sqrt{3} / 2 \right) = \sqrt{3}V_{ph}$$

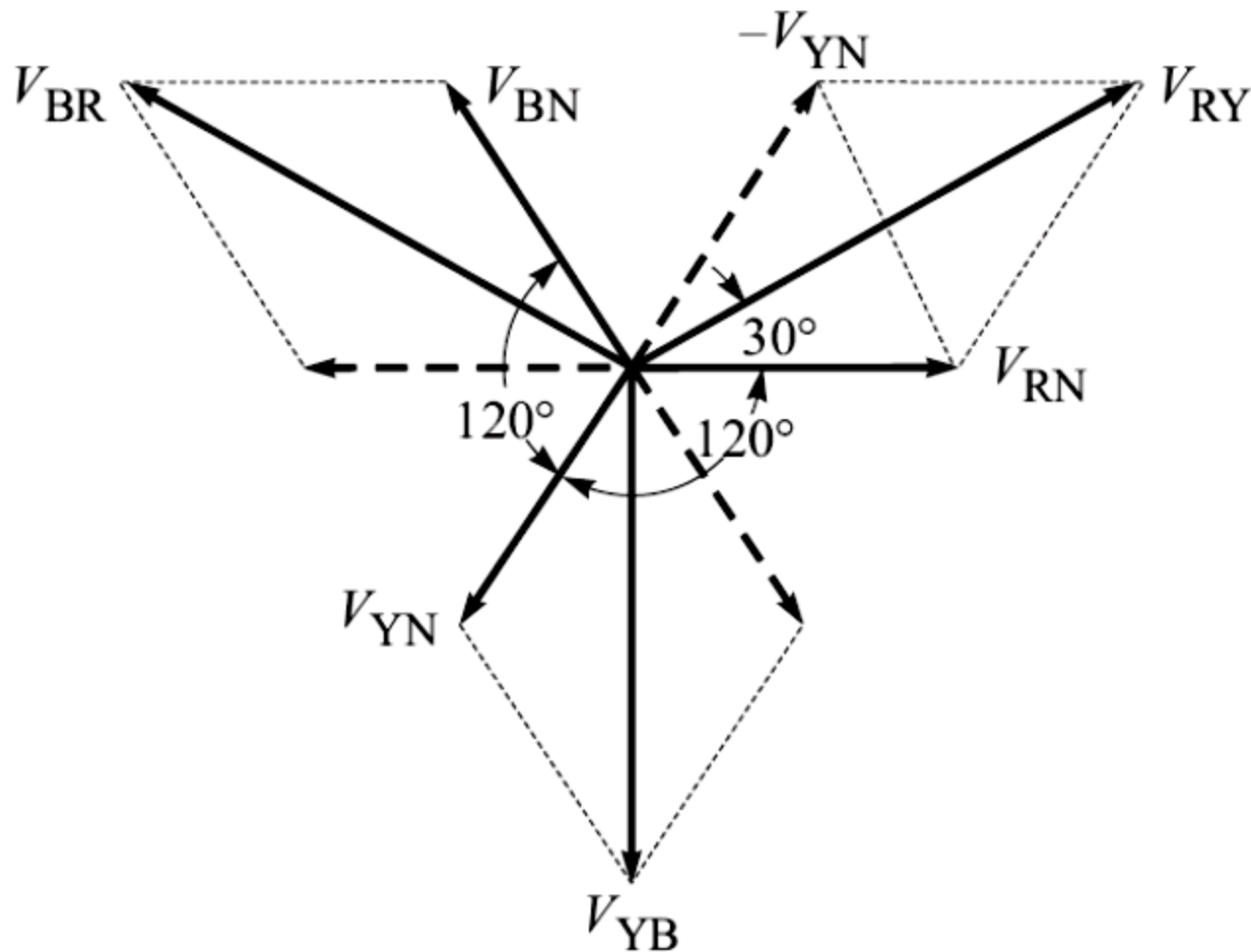
$$V_L = \sqrt{3}V_{ph}$$

and

$$I_L = I_{ph}$$

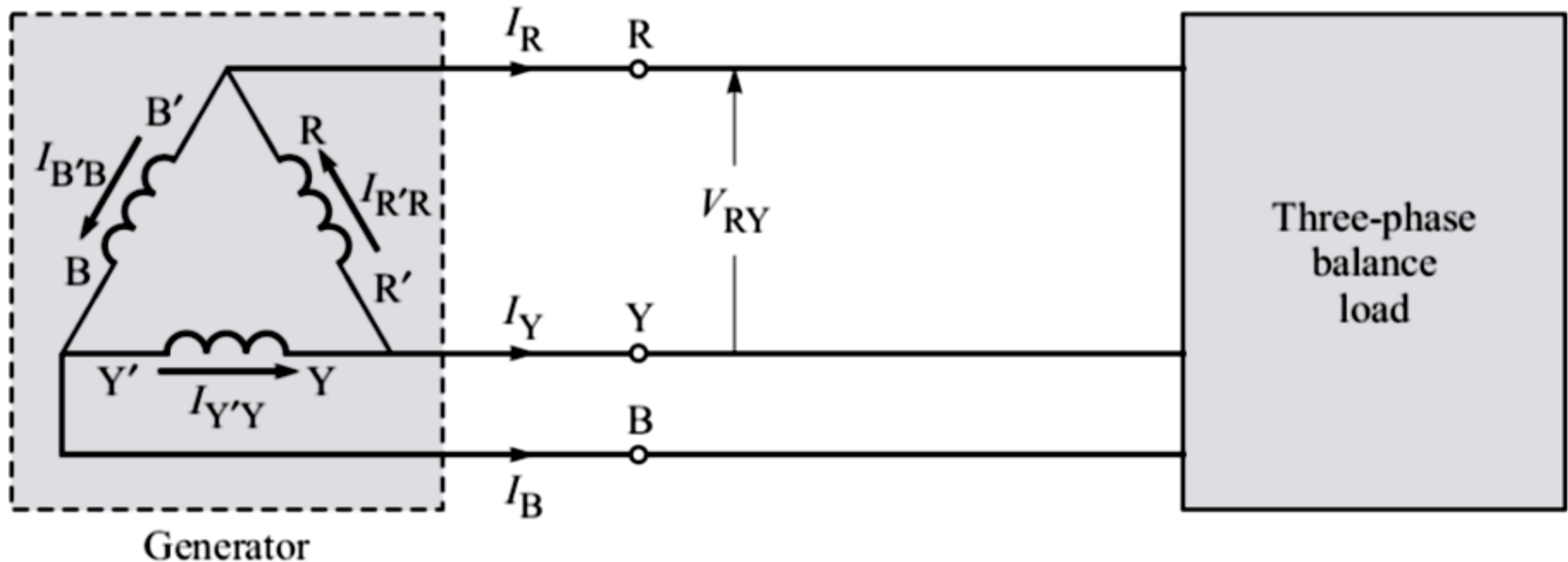


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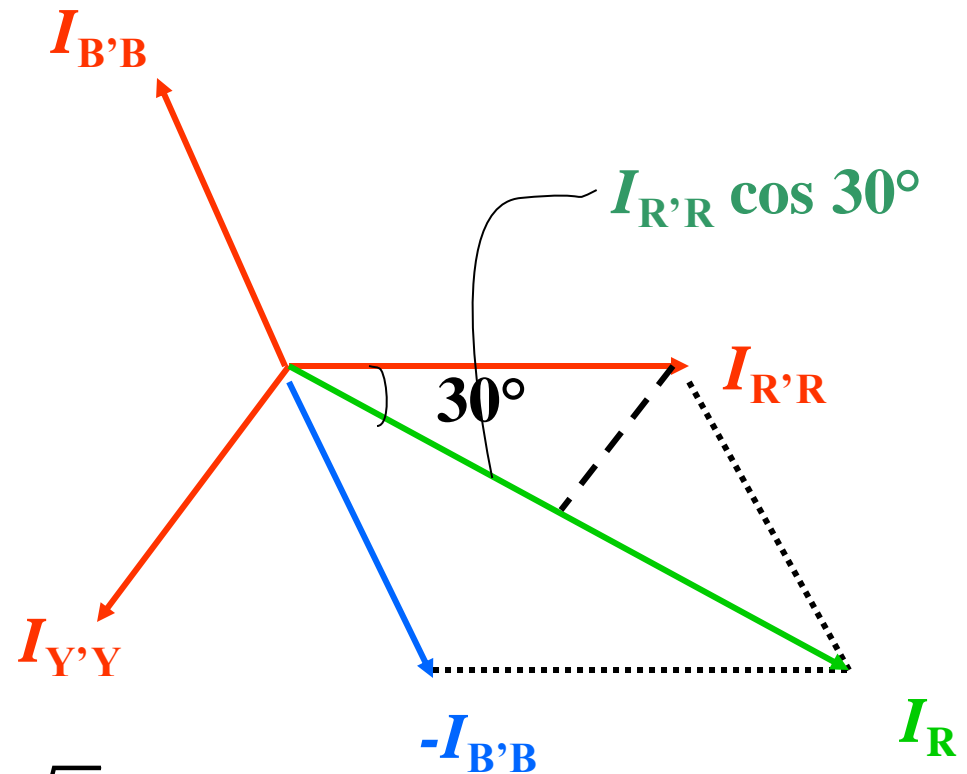
## Star-connected System

## (2) Delta-Connected System



$$|\mathbf{I}_{R'R}| = |\mathbf{I}_{Y'Y}| = |\mathbf{I}_{B'B}| = I_{ph} \text{ (say)}$$

$$\mathbf{I}_R = \mathbf{I}_{R'R} - \mathbf{I}_{B'B}$$



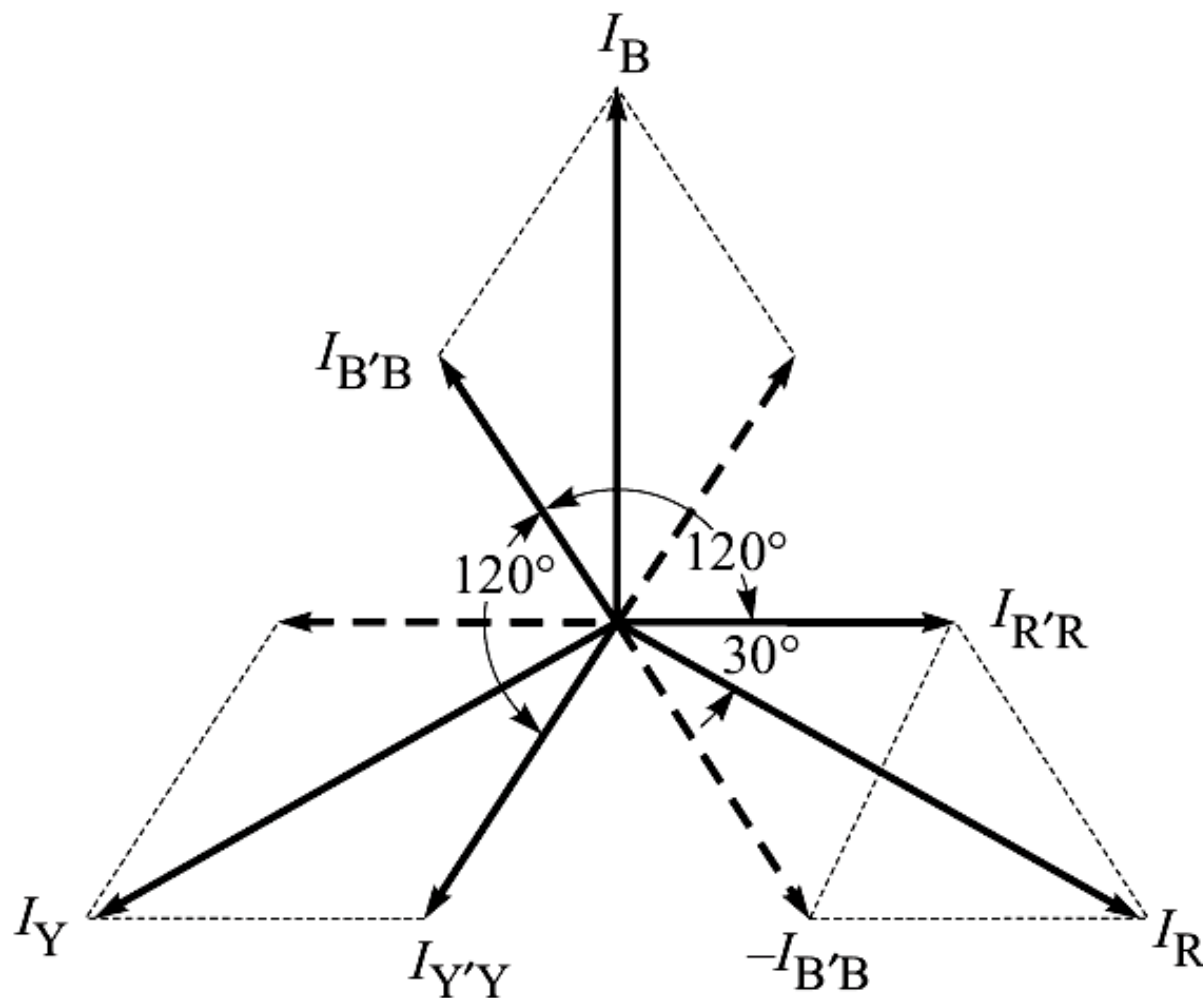
$$I_R = 2(I_{ph} \cos 30^\circ) = \sqrt{3}I_{ph}$$

$$I_L = \sqrt{3}I_{ph}$$

and

$$V_L = V_{ph}$$

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## Delta-connected System

# Important Points about Three-Phase Systems

1. It is normal practice to specify the values of the line voltages and line currents.
2. The current in any phase can be determined by dividing the phase voltage by its impedance.

# Example 1

- A 400-V, 3- $\phi$  supply is connected across a balanced load of three impedances each consisting of a 32- $\Omega$  resistance and 24- $\Omega$  inductive reactance. Determine the current drawn from the power mains, if the three impedances are
  - (a) Y-connected, and
  - (b)  $\Delta$ -connected.



**Solution :**  $\mathbf{Z} = R + jX = (32 + j24) \Omega.$

$$\therefore Z = \sqrt{R^2 + X^2} = \sqrt{32^2 + 24^2} = 40 \Omega$$

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**(a) Y-connection :**

$$V_{\text{ph}} = \frac{V_L}{\sqrt{3}} = \frac{400}{\sqrt{3}} \text{ V} \quad \Rightarrow \quad I_{\text{ph}} = \frac{V_{\text{ph}}}{Z} = \frac{400 / \sqrt{3}}{40} = \frac{10}{\sqrt{3}} \text{ A}$$

$$\therefore I_L = I_{\text{ph}} = \frac{10}{\sqrt{3}} = \mathbf{5.78 \text{ A}}$$

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**(b) For  $\Delta$ -connection :**

$$V_{\text{ph}} = V_L = 400 \text{ V} \quad \Rightarrow \quad I_{\text{ph}} = \frac{V_{\text{ph}}}{Z} = \frac{400}{40} = 10 \text{ A}$$

$$\therefore I_L = \sqrt{3} I_{\text{ph}} = \sqrt{3} \times 10 = \mathbf{17.32 \text{ A}}$$



# Power In Three-phase System With A Balanced Load

Consider one phase only,  $P_1 = V_{\text{ph}} I_{\text{ph}} \cos \phi$

Hence, the total power consumed,

$$P = 3P_1 = 3V_{\text{ph}} I_{\text{ph}} \cos \phi$$

For a *star-connected system*,  $V_L = \sqrt{3} V_{\text{ph}}$  and  $I_L = I_{\text{ph}}$

$$P = 3(V_L / \sqrt{3}) I_L \cos \phi = \sqrt{3} V_L I_L \cos \phi$$

For a *delta-connected system*,  $V_L = V_{\text{ph}}$  and  $I_L = \sqrt{3} I_{\text{ph}}$

$$P = 3V_L (I_L / \sqrt{3}) \cos \phi = \sqrt{3} V_L I_L \cos \phi$$

Thus, for *any balanced load*,

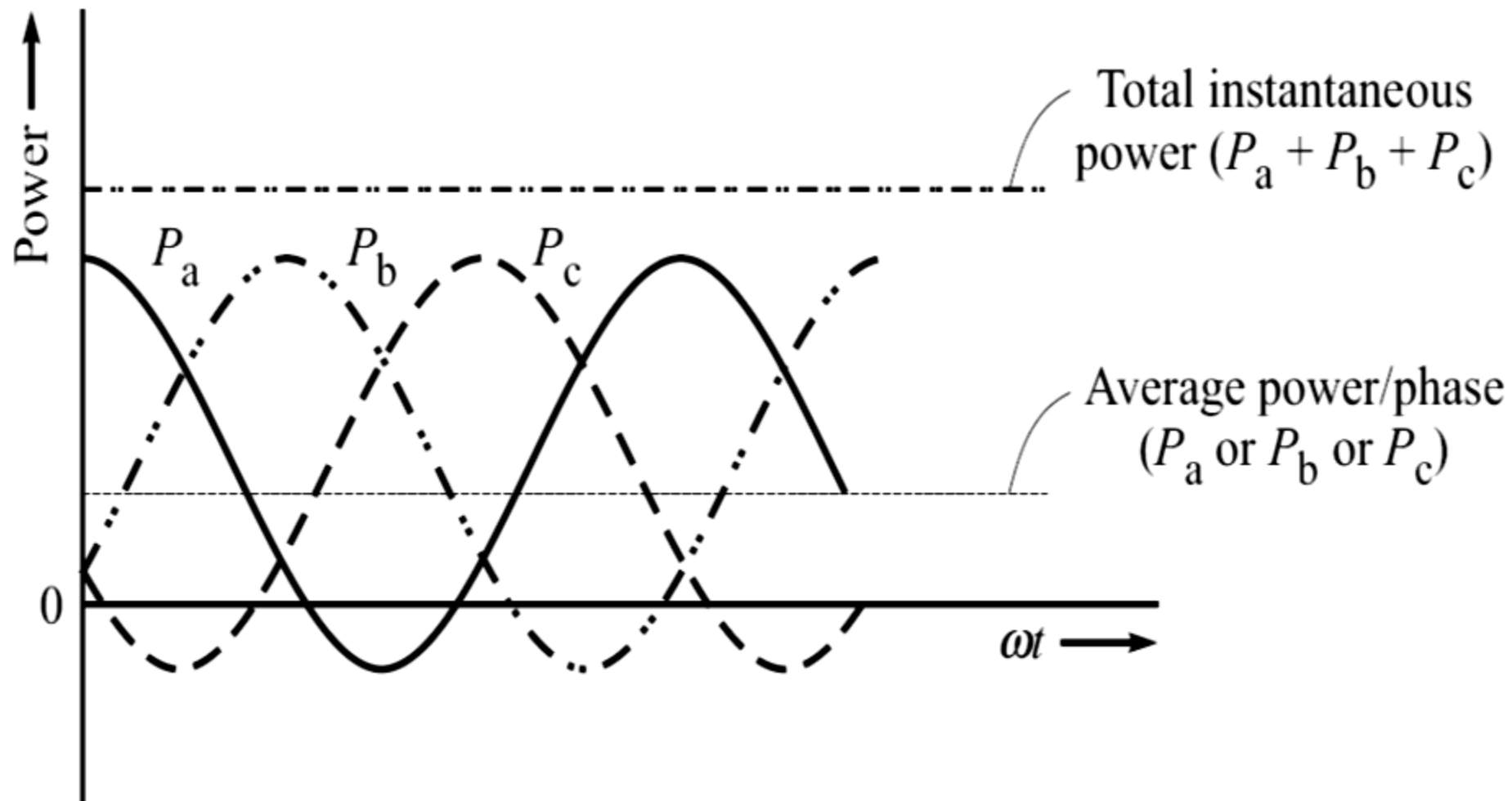
$$P = \sqrt{3} V_L I_L \cos \phi$$

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- In three-phase system with balanced load (such as a three-phase motor), **there is no variation of power at all.**
- This is the reason why for driving heavy mechanical loads we prefer a three-phase motor rather than a single-phase motor.

## Example 2

- A 400-V, 3- $\phi$  supply is connected to a balanced network of three impedances each consisting of a 20- $\Omega$  resistance and a 15- $\Omega$  inductive reactance.
- If the three impedances are (*a*) star-connected, and (*b*) delta-connected, in each case determine
  - (*i*) the line current,
  - (*ii*) the power factor, and
  - (*iii*) the total power in kW.



(a) For *star-connected load* :  $V_L = \sqrt{3} V_{ph}$  and  $I_L = I_{ph}$

$$V_{ph} = \frac{V_L}{\sqrt{3}} = \frac{400}{\sqrt{3}} = 231 \text{ V}$$

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and  $Z_{ph} = \sqrt{20^2 + 15^2} = 25 \Omega$

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(i)  $I_L = I_{ph} = \frac{V_{ph}}{Z_{ph}} = \frac{231}{25} = \mathbf{9.24 \text{ A}}$

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(ii)  $\cos \phi = \frac{R_{ph}}{Z_{ph}} = \frac{20}{25} = \mathbf{0.8 \text{ (lagging)}}$

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(iii)  $P = \sqrt{3} V_L I_L \cos \phi = \sqrt{3} \times 400 \times 9.24 \times 0.8 = \mathbf{5.12 \text{ kW}}$

(b) For *delta-connected load* :  $V_L = V_{ph}$  and  $I_L = \sqrt{3} I_{ph}$

$$\therefore V_L = V_{ph} = 400 \text{ V}$$

$$(i) \quad I_{ph} = \frac{V_{ph}}{Z_{ph}} = \frac{400}{25} = 16 \text{ A}$$

$$\therefore I_L = \sqrt{3} I_{ph} = \sqrt{3} \times 16 = \mathbf{27.71 \text{ A}}$$

(ii) The power factor is same as above,

$$pf = \mathbf{0.8 \text{ (lagging)}}$$

$$(iii) \quad P = \sqrt{3} V_L I_L \cos \phi = \sqrt{3} \times 400 \times 27.71 \times 0.8 = \mathbf{15.36 \text{ kW}}$$

**Note** that power consumed has become 3 times.

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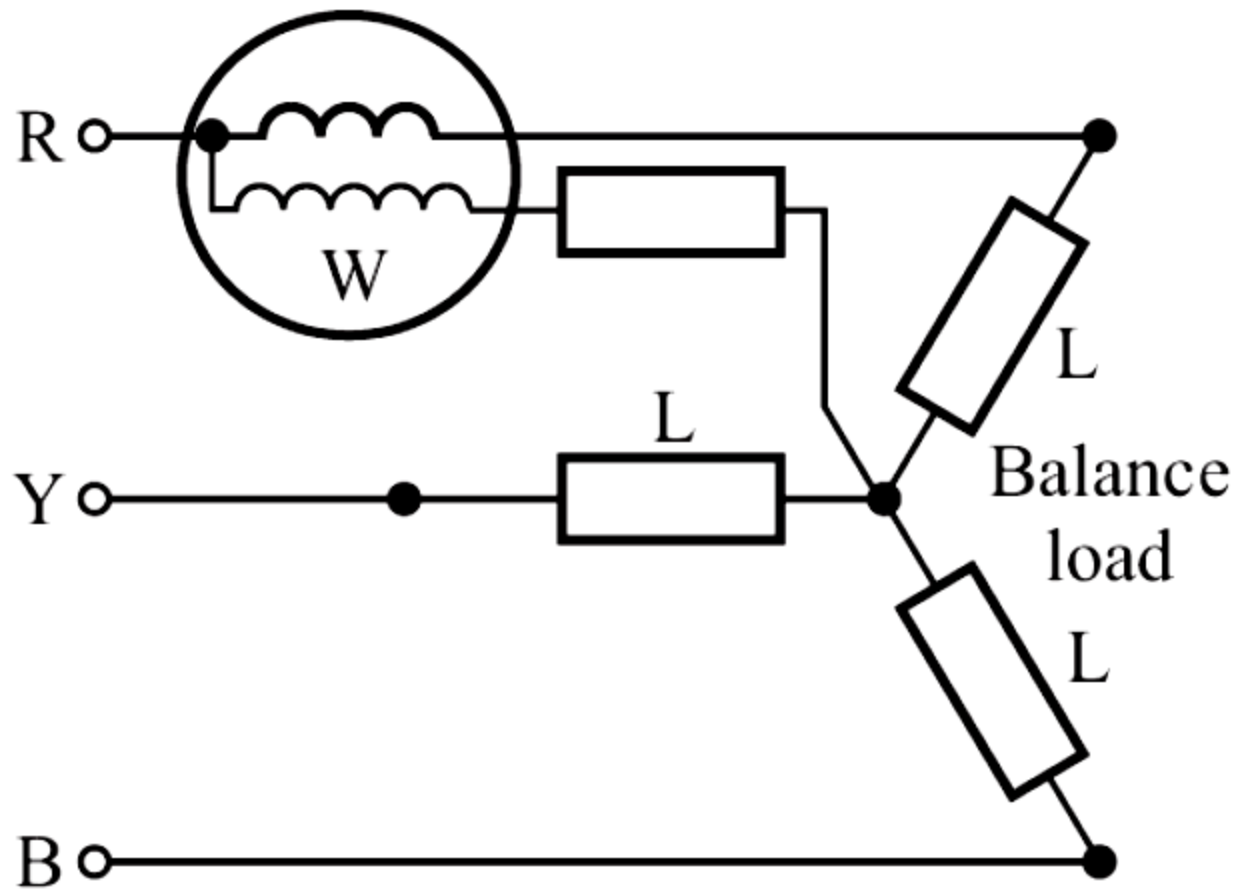
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<i>No.</i>	<i>Star-Connected System</i>	<i>Delta-Connected System</i>
1.	Similar ends are joined together.	Dissimilar ends are joined.
2.	$V_L = \sqrt{3} V_{ph}$ and $I_L = I_{ph}$	$V_L = V_{ph}$ and $I_L = \sqrt{3} I_{ph}$
3.	Neutral wire available.	Neutral wire not available.
4.	4-wire, 3- $\phi$ system possible.	4-wire, 3- $\phi$ system not possible.
5.	Both domestic and industrial loads can be handled.	Only industrial loads can be handled.
6.	By earthing the neutral wire, relays and protective devices can be provided in alternators for safety.	Due to absence of neutral wire, it is not possible.

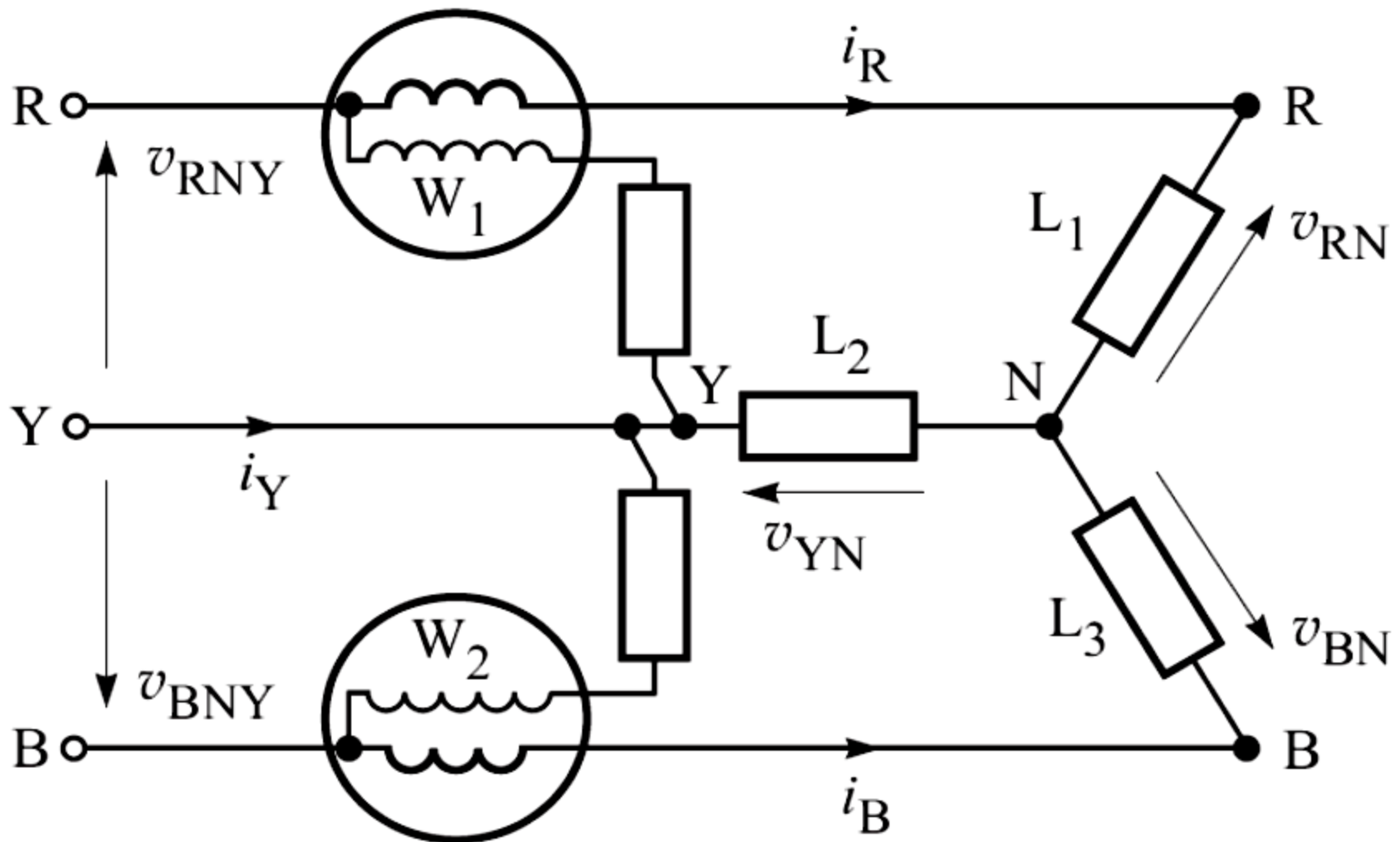
# Measurement of Power

- (i) Three-Wattmeter Method :** This is simplest and straight forward method.
- (ii) Two-Wattmeter Method :** This can be used for any balanced or unbalanced load, star- or delta-connected.
- (iii) One-Wattmeter Method :** This can be used only for a star-connected **balanced** load.





# Two-Wattmeter Method



The sum of the wattmeter readings gives the average value of the total power absorbed by the three phases

**Proof :** Total instantaneous power

$$= i_R v_{RN} + i_Y v_{YN} + i_B v_{BN}.$$

The instantaneous power measured by  $W_1$ ,

$$p_1 = i_R (v_{RN} - v_{YN})$$

The instantaneous power measured by  $W_2$ ,

$$p_2 = i_B (v_{BN} - v_{YN})$$

$$\begin{aligned}\therefore p_1 + p_2 &= i_R (v_{RN} - v_{YN}) + i_B (v_{BN} - v_{YN}) \\ &= i_R v_{RN} + i_B v_{BN} - (i_R + i_B) v_{YN}\end{aligned}$$

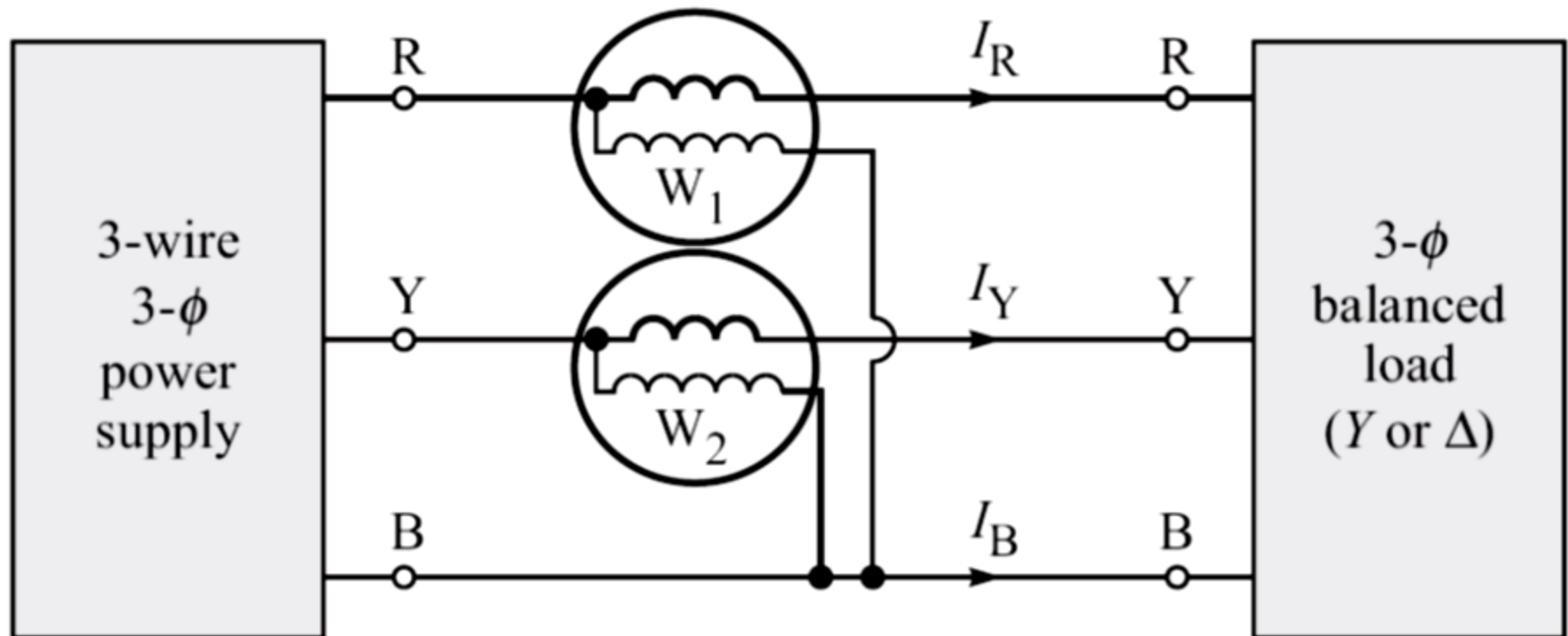
By KCL,  $i_R + i_Y + i_B = 0 \Rightarrow (i_R + i_B) = -i_Y$

$$\begin{aligned}\therefore p_1 + p_2 &= i_R v_{RN} + i_B v_{BN} + i_Y v_{YN} \\ &= \text{total instantaneous power}\end{aligned}$$

Since we did **not** assume a **balanced load** or a **sinusoidal waveform**, it follows that **the sum of the two wattmeter readings gives the total power under all conditions.**

# Power Factor Measurement by Two-Wattmeter Method

Concept of ‘**power factor**’ is meaningful only if the load is **balanced**.



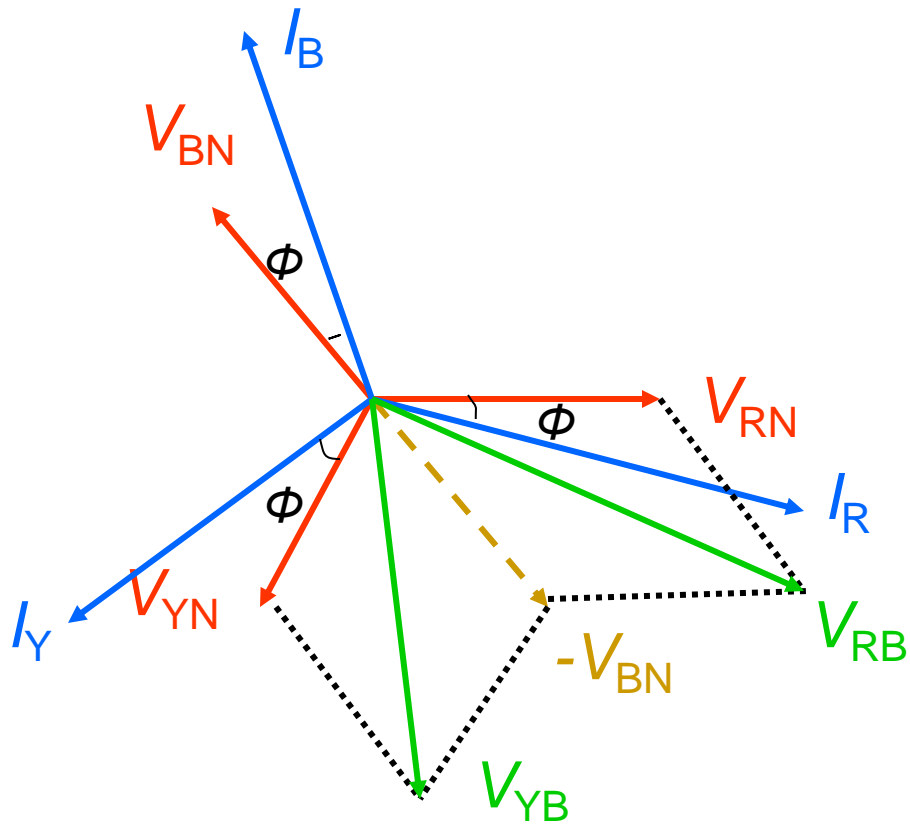
Since the load is balanced,

$$I_R = I_Y = I_B = I_L \text{ (say)}$$

$$\text{and } V_{RN} = V_{YN} = V_{BN} = V_{ph} \text{ (say)}$$

Since  $V_{RB} = V_{RN} - V_{BN}$ , and  $V_{YB} = V_{YN} - V_{BN}$ , we can determine the line voltages  $V_{RB}$  and  $V_{YB}$  by phasor method,





- It is seen that the line voltage  $V_{RB}$  lags the phase voltage  $V_{RN}$  by  $30^\circ$  and  $V_{YB}$  leads  $V_{YN}$  by  $30^\circ$ .
- Thus, the phase angle between  $V_{RB}$  and  $I_R$  is  $(30^\circ - \phi)$ .
- Similarly, the phase angle between  $V_{YB}$  and  $I_Y$  is  $(30^\circ + \phi)$ .
- Therefore, the readings of the two wattmeters are





$$P_1 = V_{RB} I_R \cos(30^\circ - \phi) = V_L I_L \cos(30^\circ - \phi)$$

[Click](#)  


$$P_2 = V_{YB} I_Y \cos(30^\circ + \phi) = V_L I_L \cos(30^\circ + \phi)$$

[Click](#)  


$$\therefore \frac{P_1}{P_2} = \frac{\cos(30^\circ - \phi)}{\cos(30^\circ + \phi)}$$

By applying componendo and dividendo,

$$\begin{aligned}\frac{P_1 - P_2}{P_1 + P_2} &= \frac{\cos(30^\circ - \phi) - \cos(30^\circ + \phi)}{\cos(30^\circ - \phi) + \cos(30^\circ + \phi)} \\ &= \frac{2 \sin 30^\circ \sin \phi}{2 \cos 30^\circ \cos \phi} = \tan 30^\circ \tan \phi\end{aligned}$$

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$$\therefore \boxed{\tan \phi = \sqrt{3} \left[ \frac{P_1 - P_2}{P_1 + P_2} \right]}$$

Calculate the phase angle  $\phi$ , and then determine the power factor.

# Important Points :

- If  $\Phi = 0^\circ$ ,  $P_1 = P_2$ .
- If  $\Phi < 60^\circ$ , both  $P_1$  and  $P_2$  are positive; and
$$P = P_1 + P_2$$
- If  $\Phi = 60^\circ$ ,  $P_2$  is zero.
- If  $\Phi > 60^\circ$ , (i.e., if  $pf < 0.5$ ),  $P_2$  is negative.

In such case, the connection of either the current coil or the potential coil has to be reversed to make positive deflection.

The value  $P_2$  should then be taken as negative while calculating the power factor or the total power.



## Example 3

- Two-wattmeter method was used to determine the input power to a three-phase motor. The readings were 5.2 kW and -1.7 kW, and the line voltage was 415 V. Calculate
  - (a) the total power,
  - (b) the power factor, and
  - (c) the line current.



## Solution :

(a) The total power,

$$P = P_1 + P_2 = 5.2 \text{ kW} - 1.7 \text{ kW} = \mathbf{3.5 \text{ kW}}$$

$$(b) \tan \phi = \sqrt{3} \left[ \frac{P_1 - P_2}{P_1 + P_2} \right] = \sqrt{3} \left[ \frac{5.2 - (-1.7)}{5.2 + (-1.7)} \right] = 3.41$$

$$\therefore \phi = \tan^{-1} 3.41 = 73^\circ 39'$$

$$\therefore pf = \cos \phi = \cos 73^\circ 39' = \mathbf{0.281}$$

$$(c) \quad 3500 = \sqrt{3} \times 415 \times I_L \times 0.281$$

$$\Rightarrow \quad I_L = \mathbf{17.3 \text{ A}}$$

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# Review

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