

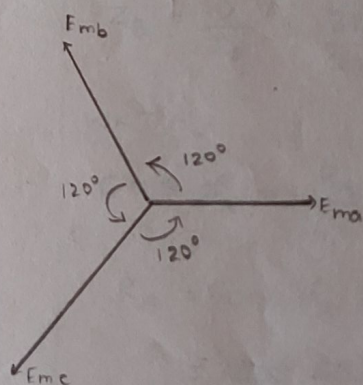
THREE-PHASE SYSTEM :

- * To reduce power loss
- * To increase the efficiency

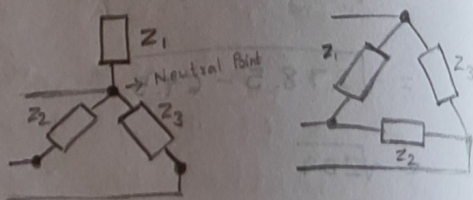
The phase difference between the phases will be generally 120°

Advantages of Three-Phase system :

- * Transmission lines require much less conductor material.
- * A three-phase machine gives a higher output.
- * A three-phase motor develops a uniform torque.
- * The three-phase induction motors are self-starting.
- * Voltage regulation is better.



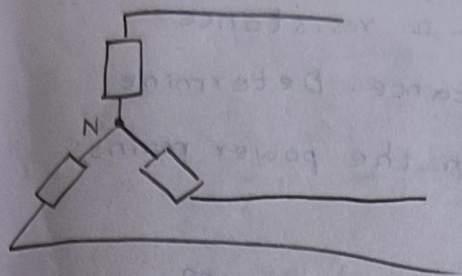
(Domestic) - Star (Industry) - Delta



- * If $Z_1 = Z_2 = Z_3$, it is known as a balanced system.
- * If the impedances are different, it is known as an unbalanced system.

- * Star connection gives high voltage, coil with less no.
- * Delta connection gives high current

STAR-CONNECTED SYSTEMS :



$$V_{RY} = V_{RN} - V_{YN}$$

$$V_{RY} = \sqrt{V_{RN}^2 + V_{YN}^2 + 2V_{RN}V_{YN}\cos 60^\circ}$$

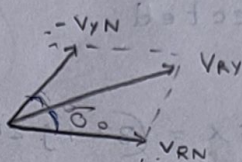
$$V_{RN} = V_{YN} = V_{BN} = V_{ph}$$

$$V_{RY} = \sqrt{3} (V_{RN} \cos 60^\circ)$$

$$V_L = \sqrt{3} V_{ph} \left(\frac{1}{2} \right)$$

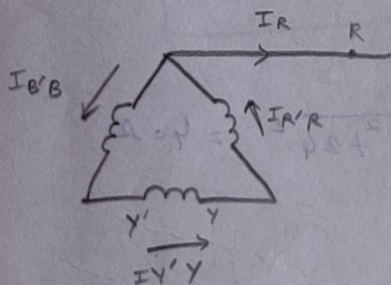
$$V_L = \sqrt{3} V_{ph}$$

$$I_L = I_{ph}$$



DELTA-CONNECTED SYSTEMS :

$$|I_{R'R}| = |I_{Y'Y}| = |I_{B'B}| = I_{ph}$$



$$I_R + I_{B'B} = I_{R'R}$$

$$I_R = I_{R'R} - I_{B'B}$$

$$I_R = \sqrt{I_{R'R}^2 + I_{B'B}^2 + 2I_{R'R}I_{B'B}\cos 60^\circ}$$

$$I_{R'R} = I_{B'B} = I_{ph}$$

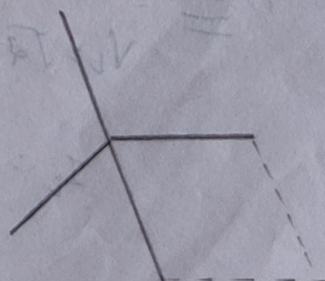
$$I_L = \sqrt{3} I_{ph} \left(\frac{1}{2} \right)$$

$$I_R = 2(I_{ph} \cos 30^\circ)$$

$$I_R = \sqrt{3} I_{ph}$$

$$I_L = \sqrt{3} I_{ph}$$

$$V_L = V_{ph}$$



Q) A 400-V, 3 ϕ supply is connected across a balanced load of three impedances each consisting of a 32- Ω resistance and 24- Ω inductive reactance. Determine the ~~power~~ current drawn from the power mains, if the impedances are ;

- a) Y-connected
b) Δ -connected

$$V_L = 400$$

A) $Z = R + jX = (32 + j24) \Omega$

$$Z = \sqrt{R^2 + X_L^2} = 40 \Omega$$

a) Y

$$V_{ph} = \frac{V_L}{\sqrt{3}} = \frac{400}{\sqrt{3}} V$$

$$I_{ph} = \frac{V_{ph}}{Z} = \frac{\frac{400}{\sqrt{3}}}{40} = \frac{10}{\sqrt{3}}$$

$$\therefore I_L = I_{ph} = \frac{10}{\sqrt{3}} = 5.78 A$$

b) Delta :

$$V_{ph} = V_L = 400 V ; I_{ph} = \frac{V_{ph}}{Z} = \frac{400}{40} = 10$$

$$I_L = \sqrt{3} I_{ph} = \sqrt{3} \times 10 = 17.32 A$$

$$Z = \sqrt{R^2 + X_L^2} = \sqrt{32^2 + 24^2} = 40 \Omega$$

$$\boxed{Z = 40 \Omega}$$

i) SC:

$$V_L = \sqrt{3} V_{ph} ; V_{ph} = \frac{400}{\sqrt{3}}$$

$$I_L = \frac{V_L}{Z} = \frac{400}{40}$$

Q) A $20\text{-}\Omega$ resistor is connected in series with an inductor.

$$\frac{1}{Z_1} = \frac{1}{R} + j \frac{1}{X_L}$$

$$\underline{Z} = \textcircled{R} + j \textcircled{X_L}$$

$$\underline{Z} = \underline{X + jY}$$

$$\underline{Z} = Z' + jZ''$$

$$|Z| = \sqrt{Z_1'^2 + Z_2'^2}$$

$$\tan \phi = \frac{Z_2}{Z_1} \quad \frac{Y}{X}$$

$$\frac{1}{Z} = \frac{1}{R} - \frac{1}{jX_C}$$

$$jX_C$$