

25/10/24

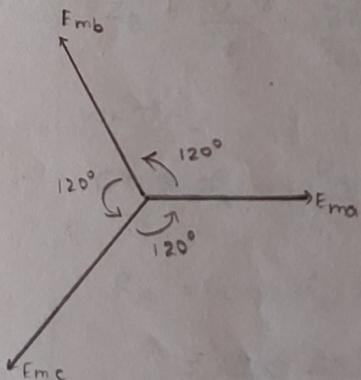
## THREE-PHASE SYSTEM :

- \* To reduce power loss
- \* To increase the efficiency

The phase difference between the phases will be generally  $120^\circ$

### Advantages of Three-Phase System:

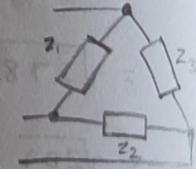
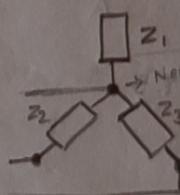
- \* Transmission lines require much less conductor material.
- \* A three-phase machine gives a higher output.
- \* A three-phase motor develops a uniform torque.
- \* The three-phase induction motors are self-starting.
- \* Voltage regulation is better.



(Domestic) -  $\frac{440}{\sqrt{3}}$  (Industry)

Star

Delta

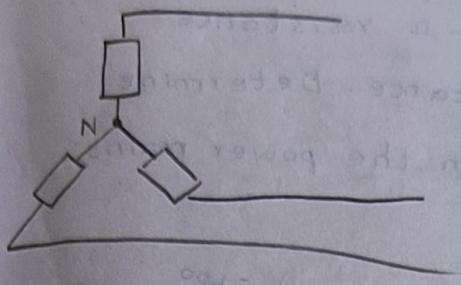


\* If  $Z_1 = Z_2 = Z_3$ , it is known as balanced system.

\* If the impedances are different, it is known as unbalanced systems.

- \* Star connection gives high voltage, coil with less no.
- \* Delta connection gives high current

## STAR-CONNECTED SYSTEMS :



$$V_{RY} = V_{RN} - V_{YN}$$

$$V_{RY} = \sqrt{V_{RN}^2 + V_{YN}^2 + 2 V_{RN} V_{YN} \cos 60^\circ}$$

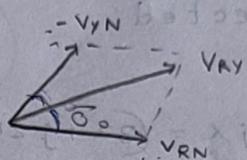
$$V_{RN} = V_{YN} = V_{BN} = V_{ph}$$

$$V_{RY} = \sqrt{3} (V_{RN} \cos 60^\circ)$$

$$V_L = \sqrt{3} V_{ph} \left(\frac{1}{2}\right)$$

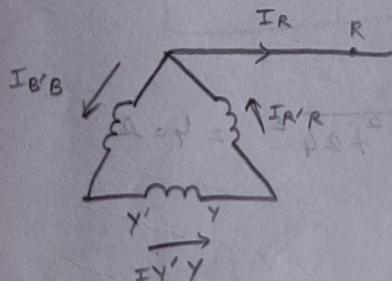
$$\boxed{V_L = \sqrt{3} V_{ph}}$$

$$\boxed{I_L = I_{ph}}$$



## DELTA-CONNECTED SYSTEMS :

$$|I_{R'R}| = |I_{Y'Y}| = |I_{B'B}| = I_{ph}$$



$$I_R + I_{B'B} = I_{R'R}$$

$$I_R = I_{R'R} - I_{B'B}$$

$$I_R = \sqrt{I_{R'R}^2 + I_{B'B}^2 + 2 I_{R'R} I_{B'B} \cos 60^\circ}$$

$$I_{R'R} = I_{B'B} = I_{ph}$$

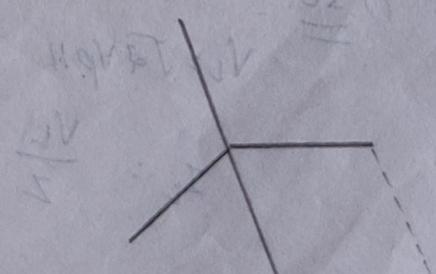
$$I_L = \sqrt{3} I_{ph} \left(\frac{1}{2}\right)$$

$$I_R = 2 (I_{ph} \cos 30^\circ)$$

$$I_R = \sqrt{3} I_{ph}$$

$$\boxed{I_L = \sqrt{3} I_{ph}}$$

$$\boxed{V_L = V_{ph}}$$



Q) A 400-V, 3 $\phi$  supply is connected across a balanced load of three impedances each consisting of a 32- $\Omega$  resistance and 24- $\Omega$  inductive reactance. Determine the power current drawn from the power mains, if the impedances are;

- a) Y-connected
- b)  $\Delta$ -connected

$$V_L = 400$$

A)  $Z = R + jX = (32 + j24) \Omega$

$$Z = \sqrt{R^2 + X^2} = 40 \Omega$$

a) Y

$$V_{ph} = \frac{V_L}{\sqrt{3}} = \frac{400}{\sqrt{3}} V$$

$$I_{ph} = \frac{V_{ph}}{Z} = \frac{\frac{400}{\sqrt{3}}}{40} = \frac{10}{\sqrt{3}}$$

$$\therefore I_L = I_{ph} = \frac{10}{\sqrt{3}} = 5.78 A$$

b) Delta:

$$V_{ph} = V_L = 400 V ; I_{ph} = \frac{V_{ph}}{Z} = \frac{400}{40} = 10$$

$$I_L = \sqrt{3} I_{ph} = \sqrt{3} \times 10 = 17.32 A$$

$$Z = \sqrt{R^2 + X^2} = \sqrt{32^2 + 24^2} = 40 \Omega$$

$Z = 40 \Omega$

i)  $\underline{SC}$ :  $V_L = \sqrt{2} V_{ph} ; V_{ph} = \frac{400}{\sqrt{3}}$

$$I_L : \frac{V_L}{Z} = \frac{400}{40}$$

Q2) A  $20\Omega$  resistor is connected in series with an inductor.

$$\frac{1}{Z_1} = \frac{1}{R} + j \frac{1}{X_C}$$

$$Z = R + j X_C$$

$$Z = X + j Y$$

$$Z = Z^1 + j Z^2$$

$$|Z| = \sqrt{Z_1^1 + Z_2^2}$$

$$\tan \phi = \frac{Z_2}{Z_1}$$

$$\frac{1}{Z} = \frac{1}{R} - j \frac{1}{X_C}$$