## **Models Used**

## **ARIMA (Autoregressive Integrated Moving Average)**

- Uses 3 parameters p, d, and q to parametrize the 3 major aspects of a time series seasonality, trend, and noise.
- P is the number of autoregressive terms.
- D is the number of nonseasonal differences needed for stationarity.
- Q is the number of lagged forecast errors.

### **SARIMA (Seasonal ARIMA)**

 Uses an additional parameter m in the parametrization to take into consideration the number of time steps for a single period

#### **SARIMAX**

• SARIMA with an additional argument X, which allows exogenous variables to be added.

# **Understanding the Models:**

- Time series are simply stochastic processes where the index set T in  $\{X_t:t\in T\}$  is time.
- An **autoregressive process** of order 1 is an i.i.d.  $N\left(0,\tau^2\right)$  process with  $\{Z_n:n\in\mathbb{Z}\}$  and  $X_n=\alpha X_{n-1}+Z_n$  where  $X_{n-1}$  is independent of  $Z_n$

## **Stationarity:**

- ullet For  $T\subset \mathbb{R}^k$ , a stochastic process is said to be **weakly stationary** if
  - 1. its mean function  $\mu(t)$  is constant in t and
  - 2. its autocovariance function  $\sigma(s,t)=\kappa(s-t)$  for some  $\kappa:\mathbb{R}^k o \mathbb{R}^1$ .

**Note**:  $\kappa$  is a positive semidefinite function, i.e. it must satisfy  $\kappa(0) \geq 0$ ,  $\kappa(t) = \kappa(-t)$ , and  $\sum_{i=1}^{n} \sum_{t=1}^{n} x_i x_i \kappa_i(t) = t \geq 0 \text{ for all } \{t_1, \dots, t_n\} \subset T_n x_n = (x_1, \dots, x_n)^T \in \mathbb{R}^n$ 

$$\sum_{i=1}^n\sum_{i=1}^nx_ix_j\kappa\left(t_i-t_j
ight)\geq 0$$
 for all  $\{t_1,\ldots,t_n\}\subset T$  ,  $x=\left(x_1,\ldots,x_n
ight)^T\in\mathbb{R}^n$ 

• A **strictly stationary** process has the property that  $(X_{t_1+h},\ldots,X_{t_n+h})\sim (X_{t_1},\ldots,X_{t_n})$  where h is such that  $\{t_1+h,\ldots,t_n+h\}\subset T$ 

**Note**: A weakly stationary Gaussian process is always strictly stationary, since  $\sigma(t_i+h,t_j+h)=\kappa(t_i-t_j)=\sigma(t_i,t_j)$  (similar to how covariance = 0 implies statistical independence with joint normality)

### **Autocorrelation:**

- Suppose  $\{(t,X_t):t\in T\}$  is a stochastic process such that  $E\left(X_t^2\right)<\infty$  for all  $t\in T$ . Then provided  $\sigma(t,t)>0\ \forall t\in T$ , the **autocorrelation function**  $\rho:T\times T\to\mathbb{R}^1$  is defined as  $\rho(s,t)=\dfrac{\sigma(s,t)}{\sqrt{\sigma(s,s)}\sqrt{\sigma(t,t)}}$
- In words, autocorrelation is the correlation of a signal with a delayed copy of itself as a function of delay (Wikipedia definition). Informally, it is the similarity between observations as a function of the time lag between them.