

Digital Signal Processing Course Laboratory 7

Digital Filter Design (December 2023)

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Abstract—This lab report will cover some basic examples of FIR and IIR filters, and then introduces the concepts of FIR filter design.

Index Terms—Digital Filter, FIR Filter, IIR Filter, MATLAB

I. Introduction

THE objective of this lab is to explore the fundamental concepts of FIR and IIR filters, their design principles, and their effects on signals (sound signals). We will derive analytical transfer function, difference equation, system diagram and then use MATLAB to implement the designed filters and analyze their performance. Then we will discuss how the filter's size affects the frequency characteristics of it.

II. Experimental Contents

A. Design of a Simple FIR Filter

Analytical transfer function:

$$\begin{aligned} H_f(z) &= (1 - z_1 z^{-1})(1 - z_2 z^{-1}) \\ &= (1 - e^{j\theta} z^{-1})(1 - e^{-j\theta} z^{-1}) = 1 - 2z^{-1} \cos \theta + z^{-2} \end{aligned}$$

Impulse response:

$$h_f[n] = \delta[n] - 2\delta[n-1] \cos \theta + \delta[n-2]$$

Difference equation:

$$y[n] = x[n] - 2x[n-1] \cos \theta + x[n-2]$$

The system diagram:

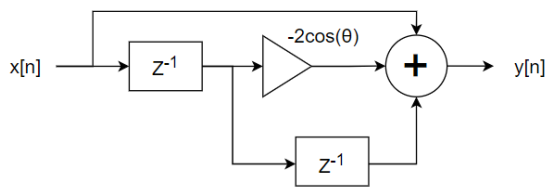


Fig. 1: The System Diagram of FIR Filter H_f

Using MATLAB to research how θ affects the magnitude response of H_f :

```
1 w=-pi:0.01:pi;
2 z=exp(1i*w);
3 H1=1-2*cos(pi/6)*z.^(-1)+z.^(-2);
4 H2=1-2*cos(pi/3)*z.^(-1)+z.^(-2);
5 H3=1-2*cos(pi/2)*z.^(-1)+z.^(-2);
```

Magnitude of H_f with different θ 12110405 Zhewei Chen

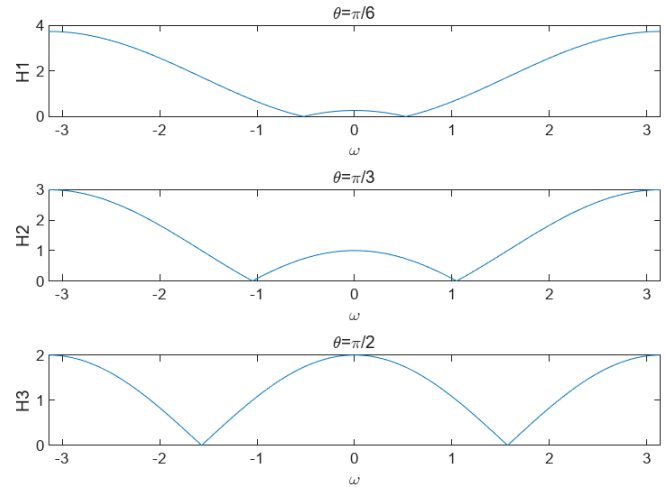


Fig. 2: Plot of $|H_f|$ with different θ

Analysis:

-The frequency response shows that it is a bandstop filter.

-When $\omega = \theta$, $|H_f(e^{j\omega})| = 0$, which shows $\omega = \theta$ is the center frequency of this bandstop filter. When θ decreases(increases), the center frequency of the bandstop filter decreases(increases).

Then we write a Matlab function **FIRfilter(x)** that implements the filter $H_f(z)$ with the measured value of θ and outputs the filtered signal.

FIRfilter.m

```
1 function y = FIRfilter(x)
2 [X,w]=DTFT(x,0);
3 [~,Imax]=max(abs(X));
4 h=[1 -2*cos(w(Imax)) 1];
5 y=conv(x,h);
6 end
```

And applying the **nspeech1** vector to attenuate the sinusoidal interference.

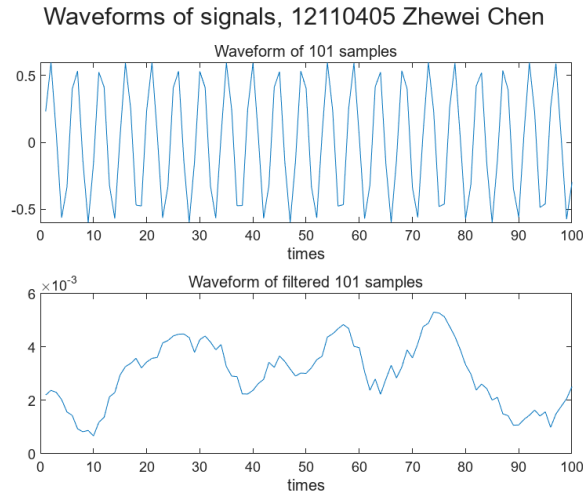


Fig. 3: Plot of Waveforms of 101 Samples of Signal and Filtered Signal

Analysis:

- The original signal approximates a sine wave.
- The filtered signal has a lower volume than the original signal.

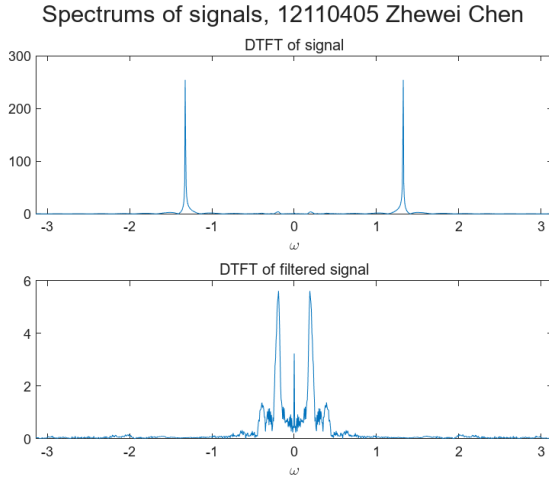


Fig. 4: Spectrums of DTFTs of Signal and Filtered Signal

Analysis:

- This is a bandstop filter.
- The noise of the original signal has been filtered, we can hear the voice more clearly.

B. Design of a Simple IIR Filter

Analytical transfer function:

$$H_i(z) = \frac{1-r}{1-2r\cos\theta z^{-1}+r^2 z^{-2}}$$

Impulse response:

$$h_i[n] = \frac{(1-r)\delta[n]}{\delta[n] - 2r\delta[n-1]\cos\theta + r^2\delta[n-2]}$$

Difference equation:

$$y[n] - 2r\cos\theta y[n-1] + r^2 y[n-2] = (1-r)x[n]$$

The system diagram:

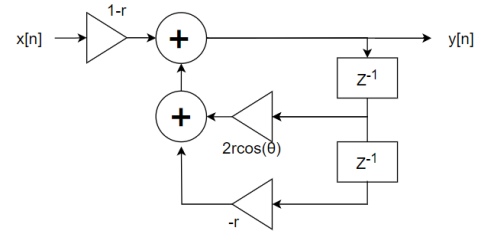


Fig. 5: The System Diagram of IIR Filter H_i

Using MATLAB to research how r affects the magnitude response of H_i :

```
1 w1=-pi:0.01:pi;
2 z=exp(1i*w1);
3 r1=0.99;
4 r2=0.9;
5 r3=0.7;
6 H1=(1-r1)./(1-2*r1*cos(pi/3).*z.^(-1)+
7   r1.^2.*z.^(-2));
8 H2=(1-r2)./(1-2*r2*cos(pi/3).*z.^(-1)+
9   r2.^2.*z.^(-2));
10 H3=(1-r3)./(1-2*r3*cos(pi/3).*z.^(-1)+
11   r3.^2.*z.^(-2));
```

Magnitude of H_i with different r , 12110405 Zhewei Chen

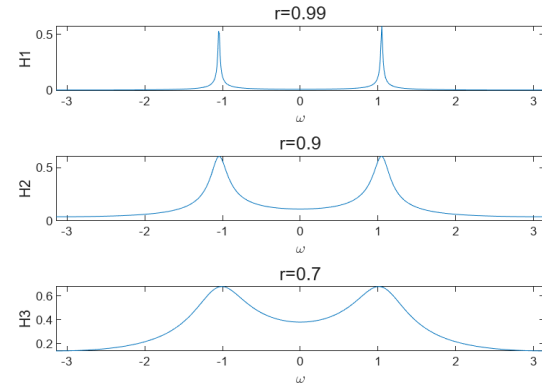


Fig. 6: Plot of $|H_i|$ with different r

Analysis:

As r increases, the magnitude responses will be more sharp, and similar to a bandpass filter.

Write a Matlab function **IIRfilter.m** that implements the filter $H_i(z)$.

IIRfilter.m

```
1 function y = IIRfilter(x)
2 theta=(3146/8000)*2*pi;
3 r=0.995;
4 N=length(x);
5 y=zeros(1,N);
6 y(1)=(1-r)*x(1);
7 y(2)=(1-r)*x(2)+2*r*cos(theta)*y(1);
```

```

8 for k=3:N
9     y(k)=(1-r)*x(k)+2*r*cos(theta)*y(k-1)-r^2*y(k-2);
10 end
11 end

```

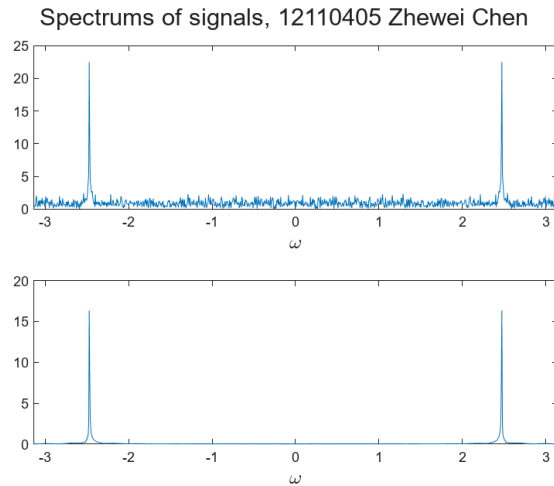
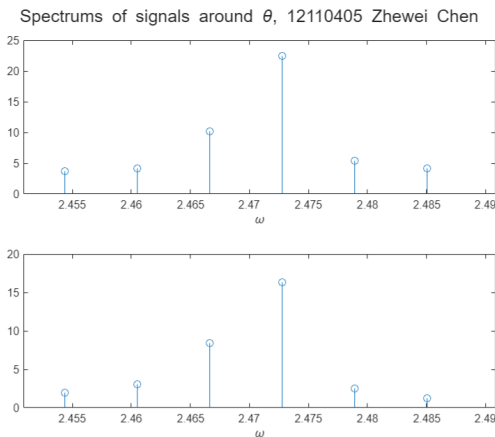


Fig. 7: Plot of Spectrums of Signals and Filtered Signals

Fig. 8: Plot of Spectrums of Signals Around θ

Waveforms of signals of 101 samples, 12110405 Zhewei Chen

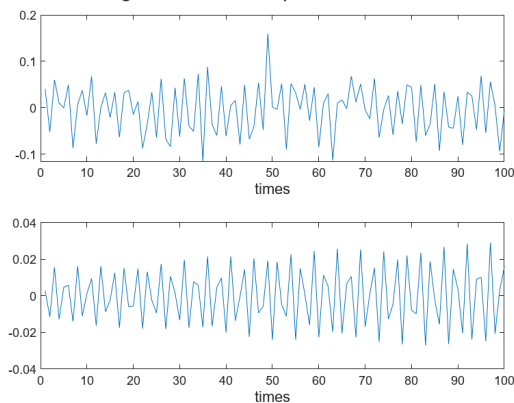
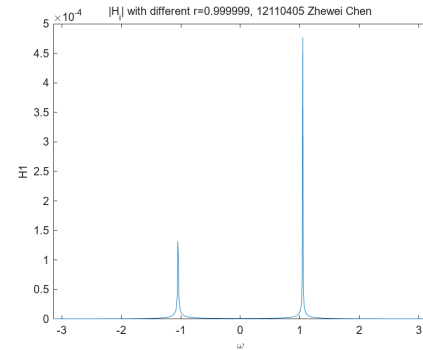


Fig. 9: Plot of Waveforms of 101 Samples

Analysis:

- The magnitude of frequency that is not around θ in the frequency domain decreases a lot after filtering.
- The spectrums show that the magnitude of DTFT of signal decreases a bit after filtering around θ
- The volume decreases a bit after filtering but we can hear more clearly.

Fig. 10: Plot of $|H_i|$ with $r=0.999999$ **Analysis:**

- When $r=0.999999$ (very close to 1), we can hear nothing. Because the magnitude response shows that the volume of the signal decrease to much. Though it is still a bandpass filter.

C. Filter Design Using Truncation

To examine the effect of filter size on the frequency characteristics of the filter, write a Matlab function **LPFtrunc.m** that computes the truncated and shifted impulse response of size N for a lowpass filter with a cutoff frequency of $\omega_c = 2.0$.

LPFtrunc.m

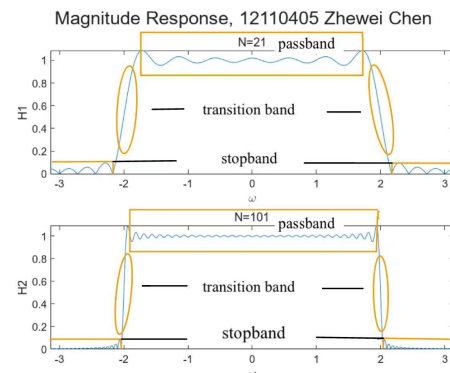
```

1 function h = LPFtrunc(N)
2 n=0:N-1;
3 h = 2/pi * sinc(2/pi * (n - (N-1)/2));
4 end

```

Analysis:

- We can use matrix multiplication to avoid the for loop.

Fig. 11: Plot of Magnitude Response $N = 101$ and $N = 21$

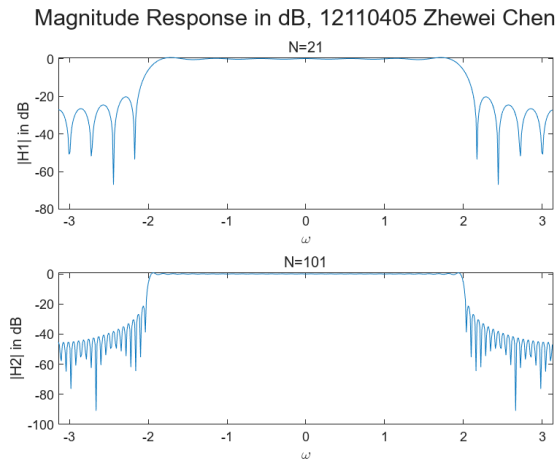


Fig. 12: Plot of Magnitude Response in dB $N = 101$ and $N = 21$

Analysis:

- Clearly we can observe the Gibbs Phenomenon. When N increases, the influence of Gibbs Phenomenon decreases and the filtering becomes more similar to a ideal lowpass filter because of the more sampling points.

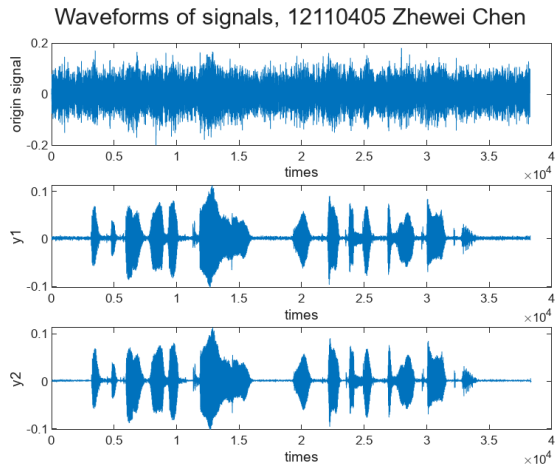


Fig. 13: Plot of Waveforms of Signal and Filtered Signals

Analysis:

-After hear and observing the waveforms of sound and filtered sound. We observe that y_2 , which is filtered by the truncated impulse response of size 101, contains **less noise** than y_1 , which is filtered by the truncated impulse response of size 21.

III. Conclusion

Through this experiment, we attempted to derive the theoretical forms of filter design, including difference equations and system diagrams, using mathematical methods. We then implemented these designs using MATLAB. By observing the spectrum, waveform, and listening to the filtered signals, we studied the characteristics of the signals before and after filtering. Constantly adjusting parameters allowed for comprehensive and detailed exploration of the results.

During the experiment, we also discovered the limitations of simple filters. When the filtering effect was significant, there was often a considerable loss in volume. This highlighted the need for alternative methods to compensate for the volume loss and overcome the limitations of simple filters.