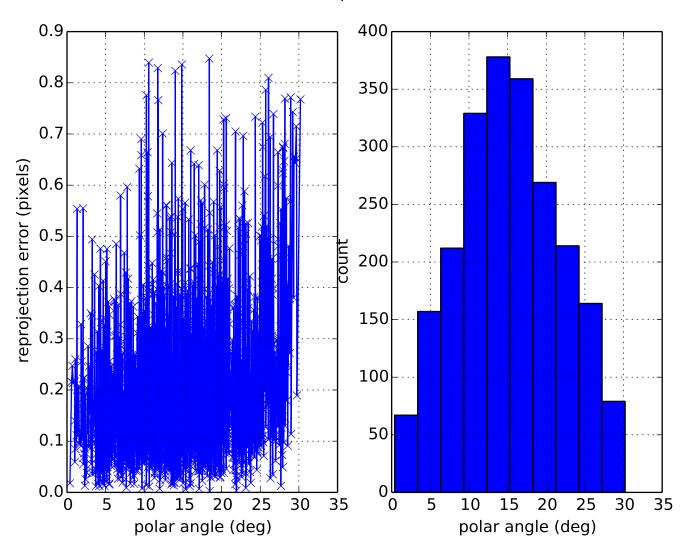
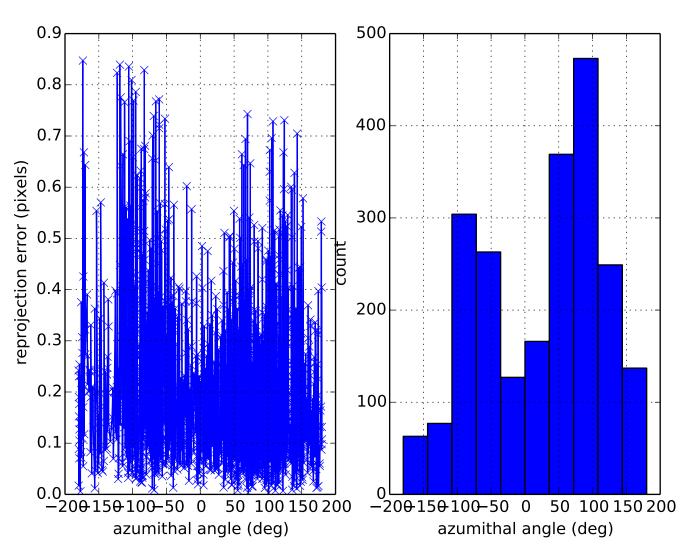
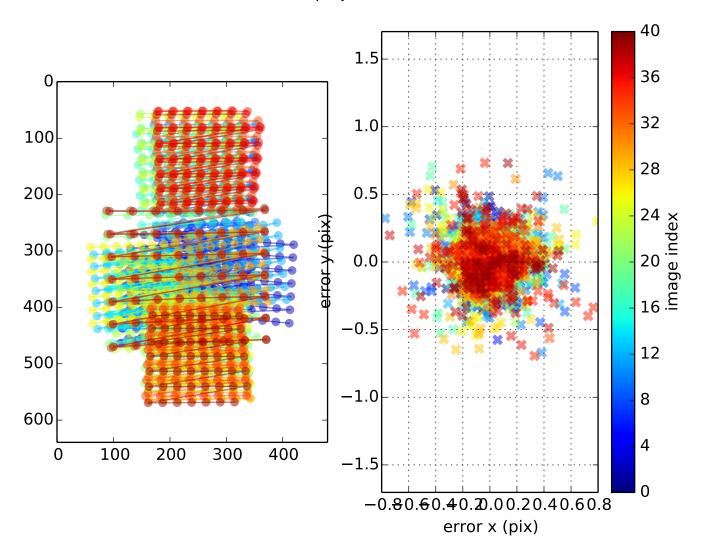
cam0: polar error



cam0: azimutal error



cam0: reprojection errors



Location of removed outlier corners cam0 0 $\times^{\!\!\!\times}$ \times \times \times \times 100 \times \times \times \times \times \times X

