Code Verification Using Symbolic Execution

(Week 5)

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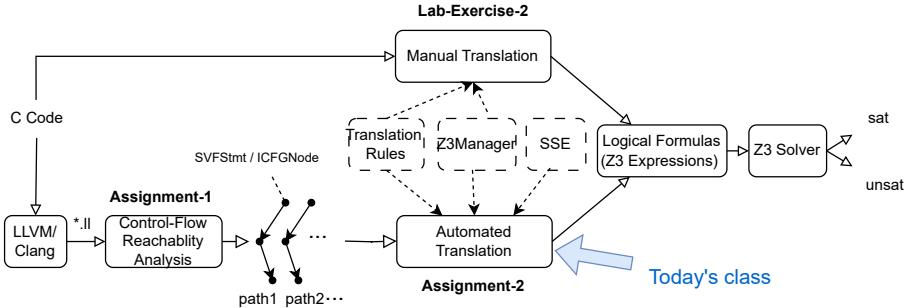
Revisit Lab-Exercise-2 Cases

- Lab-Exercise-2 Validation Code
  - `test0()` has an example for validating your translation. Given a program `prog` and an assert `Q`, you are expected to (1) use `checkNegateAssert` to translate the negation of `Q` and check **unsat** of *prog* $\wedge \neg Q$; `checkNegateAssert` returns true means the non-existence of counterexamples, and (2) also **evaluate individual variables' values** (e.g., `a`) if you know `a`'s value is 3. For example, `z3Mgr->getEvalExpr("a") == 3`.
  - Closed-world programs, checking **sat** of *prog* $\wedge$ *Q* $\equiv$ checking **unsat** *prog* $\wedge \neg Q$
- `addToSolver(e1)` vs `getEvalExpr(e2)`
  - `e1` is added as a constraint to the solver, while `e2` is not added to the solver hence its truth depends on a particular model (one solution).
- Memory allocations: p = &a;
  - `a` is address-taken by `p`, hence an object `&a` needs to be created via `a_addr = getMemObjAddress("&a");`
- Interprocedural (call and return)
  - Bookkeeping the calling context to distinguish local variables.

Code Verification Using Static Symbolic Execution



Static Symbolic Execution (SSE)

- Automated analysis and testing technique that symbolically analyzes a program without runtime execution.
- Use symbolic execution to explore all program paths to find bugs and assertion validations.
- A static interpreter follows the program, assuming symbolic values for variables and inputs rather than obtaining actual inputs as normal program execution would.
- International Competition on Software Verification (SV-COMP): `https://sv-comp.sosy-lab.org/`

SSE for Assertion-based Verification

- Given a Hoare triple $P\ \{prog\}\ Q$,
  - P represents pre-condition,
  - *prog* is the program,
  - Q is the post-condition i.e., assertion(s) specifications.

```
// no-precondition
assume(true);        // P
    if(x > 10) {
        y = x + 1;
    }
    else {
        y = 10;
    }
assert(y >= x + 1);  //Q
```

translate

$$\Longrightarrow \underbrace{\exists \mathrm{x}\ \exists \mathrm{y}\ \ P \wedge S_{prog}(\mathrm{x},\mathrm{y})) \wedge \neg Q(\mathrm{x},\mathrm{y})}_{\text{logical formula } \psi}$$

feed into

$\Longrightarrow$ SMT Solver

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translate ⟹ $\underbrace{\exists x\ \exists y\ \ P \wedge S_{prog}(x, y)) \wedge \neg Q(x, y)}_{\text{logical formula } \psi}$ feed into ⟹ SMT Solver

Check **unsat** of ψ (non-existence of counterexamples)!

SSE for Assertion-based Verification

- Translate each $\forall path \in prog$ consisting of a sequence of ICFGNodes $path = [N_1, N_2, \ldots, N_i, Q]$, from the entry node N_1 to an assertion Q on ICFG.
  - In `Assignment-2`, the node on each path appears at most once for verification.

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  - In `Assignment-2`, the node on each path appears at most once for verification.
- SSE translates `SVFStmts` of each ICFGNode (except the last one) on each *path* into Z3 expressions and validate whether they conform to the assertion Q by proving non-existence of counterexamples (Week 4).
  - $\forall path \in prog : \psi_{path} = \psi(N_1) \wedge \psi(N_2) \wedge \ldots \psi(N_i) \wedge \neg\psi(Q)$
  - Checking **unsat** of each ψ_{path}. A **sat** of ψ_{path} indicates that there exists at least one counterexample from the **model** from the z3 solver.

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  - Checking **unsat** of each ψ_{path}. A **sat** of ψ_{path} indicates that there exists at least one counterexample from the **model** from the z3 solver.

```
void main(int x){
  assume(true);
    if(x > 10)
        y = x + 1;
    else
        y = 10;
  assert(y >= x + 1);
}
```

ψ_{path_1}: $\exists x\ true \wedge \big((x > 10) \wedge (y \equiv x + 1)\big) \wedge \neg(y \geq x + 1)$ (`if` branch)
unsat (no counterexample found!)

ψ_{path_2}: $\exists x\ true \wedge \big((x \leq 10) \wedge (y \equiv 10)\big) \wedge \neg(y \geq x + 1)$ (`else` branch)
sat (a counterexample $x = 10$ found!)

Closed-World Programs and Assertion Checking

- If the program operates in a **closed-world** (value initializations are fixed and there are no inputs from externals and always has a single execution path), there is no need to find the existence of invalid inputs or counterexamples.
- For closed-world programs, only **logical errors** are verified against assertions, rather than finding the **counterexamples**. Simply checking satisfiability is **the same** as checking the non-existence of counterexamples.
  - Checking **unsat** of the $\psi(N_1) \wedge \psi(N_2) \wedge \ldots \psi(N_i) \wedge \neg\psi(Q)$.
  - Checking **sat** of the $\psi(N_1) \wedge \psi(N_2) \wedge \ldots \psi(N_i) \wedge \psi(Q)$.

```
void main(int x){
  x = 5;
    if(x > 10)
        y = x + 1;
    else
        y = 10;
  assert(y >= x + 1);
}
```

ψ_{path_1}: (`if` branch)
checking **unsat** of $x \equiv 5 \wedge \big((\mathtt{x} > 10) \wedge (\mathtt{y} \equiv \mathtt{x} + 1)\big) \wedge \neg(\mathtt{y} \geq \mathtt{x} + 1)$
checking **sat** of $\mathtt{x}\ x \equiv 5 \wedge \big((\mathtt{x} > 10) \wedge (\mathtt{y} \equiv \mathtt{x} + 1)\big) \wedge (\mathtt{y} \geq \mathtt{x} + 1)$

ψ_{path_2}: (`else` branch)
checking **unsat** of $x \equiv 5 \wedge \big((\mathtt{x} \leq 10) \wedge (\mathtt{y} \equiv 10)\big) \wedge \neg(\mathtt{y} \geq \mathtt{x} + 1)$
checking **sat** of $x \equiv 5 \wedge \big((\mathtt{x} \leq 10) \wedge (\mathtt{y} \equiv 10)\big) \wedge (\mathtt{y} \geq \mathtt{x} + 1)$

Reachability Paths (Recall Assignment-1)

Algorithm 1: Context sensitive control-flow reachability

Input : `curNode : ICFGNode  snk : ICFGNode  path : vector⟨ICFGNode⟩  callstack : vector⟨SVFInstruction⟩`
`visited : set⟨ICFGNode, callstack⟩;`

```
1  dfs(curNode, snk)                    // Argument curNode becomes to curEdge in Assignment-2
2    pair = ⟨curNode, callstack⟩;
3    if pair ∈ visited then
4        return;
5    visited.insert(pair);
6    path.push_back(curNode);
7    if src == snk then
8        collectICFGPath(path);          // collectAndTranslatePath in Assignment-2
9    foreach edge ∈ curNode.getOutEdges() do
10       if edge.isIntraCFGEdge() then
11           dfs(edge.dst, snk);
12       else if edge.isCallCFGEdge() then
13           callstack.push_back(edge.getCallSite());
14           dfs(edge.dst, snk);
15           callstack.pop_back();
16       else if edge.isRetCFGEdge() then
17           if callstack ≠ ∅ && callstack.back() == edge.getCallSite() then
18               callstack.pop_back();
19               dfs(edge.dst, snk);
20               callstack.push_back(edge.getCallSite());
21           else if callstack == ∅ then
22               dfs(edge.dst, snk);
23   visited.erase(pair);
24   path.pop_back();
```

Rhs/LhS/Operators of a Statement

SVFStmt	C-Like	PAG Edge	Lhs/Rhs/Operator
AddrStmt	`p = &o`	$p \xleftarrow{Addr} o$	`p`: lhs var, `o`: rhs var
CopyStmt	`p = q`	$p \xleftarrow{Copy} q$	`p`: lhs var, `q`: rhs var
StoreStmt	`*p = q`	$p \xleftarrow{Store} q$	`p`: lhs var, `q`: rhs var
LoadStmt	`p = *q`	$p \xleftarrow{Load} q$	`p`: lhs var, `q`: rhs var
GepStmt	`p = &q->fld`	$p \xleftarrow{Gep,fld} q$	`p`: lhs var, `q`: rhs var
CallPE	`p = q` (caller arg to callee arg)	$p \xleftarrow{Copy} q$	`p`: lhs var (callee), `q`: rhs var (caller)
RetPE	`p = q` (callee ret to caller rev)	$p \xleftarrow{Copy} q$	`p`: lhs var (caller), `q`: rhs var (callee)
CmpStmt	`r = op(p, q)`	r: result, `p`: operand 0, `q`: operand 1	
BinaryOPStmt	`r = op(p, q)`	r: result, `p`: operand 0, `q`: operand 1	
SelectStmt	`r = sel(c,tval,fval)`	`r`: result, condition `c`: 0 or 1 `r` is `tval` when c≡1, `r` is `fval` when c≡0	

`lhs` and `rhs` When Handling Calls/Returns

Let us see the example of `lhs` and `rhs` varaiables for call and parameter passings (i.e., `CallPE` and `RetPE`)

```
1 int foo(int x){ // CallPE: x = m;  lhs: x, rhs: m
2     int y = x;
3     return y;
4 }
5
6 main(){
7     int m = 0;
8     n = foo(m); // RetPE: n = y;   lhs: n, rhs : y
9 }
```

Parameters passing from actual parameter `m` at the callsite (Line 8) to formal parameter `n` at the entry of `foo`. Return parameter passing from return variable `y` in `foo` to `n` at the callsite (Line 8).

Context-Sensitive `getZ3Expr(NodeID)`

- `callingCtx`: current calling context stack as a sequence of callsites (`ICFGNode`s) during your traversal
- `pushCallingCtx(ICFGNode*)` add a callsite on to the current calling context stack
- `popCallingCtx()` pop the top callsite from the current calling context stack
- `getZ3Expr(NodeID)` in Assignment-2 is context-sensitive, i.e., retrieving an z3 expr based on **variable's ID + current calling context**.

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- `pushCallingCtx(ICFGNode*)` add a callsite on to the current calling context stack
- `popCallingCtx()` pop the top callsite from the current calling context stack
- `getZ3Expr(NodeID)` in Assignment-2 is context-sensitive, i.e., retrieving an z3 expr based on **variable's ID + current calling context**.
- Interprocedural context-sensitive variable copies:
  - $\mathtt{r} = \mathtt{call\_f}(\ldots, \mathtt{q}, \ldots) \quad \mathtt{f}(\ldots, \mathtt{p}, \ldots)\{\ldots \ \mathtt{return\ z}\}$
  - Context-insensitive z3 formula $\mathtt{p} \equiv \mathtt{q}, \quad \mathtt{r} \equiv \mathtt{z}$
  - Context-sensitive z3 formula (each expr corresponds to a pair) $\langle[\mathtt{c}'], \mathtt{p}\rangle \equiv \langle[\mathtt{c}], \mathtt{q}\rangle$ $\langle[\mathtt{c}], \mathtt{r}\rangle \equiv \langle[\mathtt{c}'], \mathtt{z}\rangle$, where $\mathtt{c}' \equiv \mathtt{c} + \mathtt{ICFGNode}_{\mathtt{call\_f}}$ (Assignment-2)
  - Use `pushCallingCtx` and `popCallingCtx` before retrieving an z3 expression.

Overview of SSE Algorithms: Translate Paths into Z3 Formulas

Algorithm 2: `translatePath(path)`

```
1 foreach edge ∈ path do
2     if intra ← dyn_cast⟨Intra⟩(edge) then
3         if handleIntra(intra) == false then
4             return false
5     else if call ← dyn_cast⟨CallEdge⟩(edge) then
6         handleCall(call)
7     else if ret ← dyn_cast⟨RetEdge⟩(edge) then
8         handleRet(ret)
9     return true
```

Algorithm 3: `handleIntra(intraEdge)`

```
1 if intraEdge.getCondition() then
2     if !handleBranch(intraEdge) then
3         return false;
4     else
5         return handleNonBranch(intraEdge);
6 else
7     return handleNonBranch(intraEdge);
```

Algorithm 4: `handleCall(callEdge)`

```
1 Declare a z3 expression vector : preCtxExprs; // rhs
    of call edges
2 callPEs ← get all callPEs of callEdge;
3 foreach callPE ∈ callPEs do
4     push rhs in preCtxExprs; //rhs under the context
        before entering callee
5 push current calling context;
6 for i = 0; i < callPEs.size(); ++i do
7     lhs ← get z3 expression of lhs var; //lhs under the
        context after entering callee
8     add lhs == preCtxExprs[i] to z3 solver;
```

Algorithm 5: `handleRet(retEdge)`

```
1 if retPE ← get returnPE from retEdge then
2     rhs ← get z3 expression of rhsvar; //rhs under the
        context before returning to caller
3 popCallingCtx();
4 if retPE ← get returnPE from retEdge then
5     lhs ← get z3 expression of lhsvar; //lhs under the
        context after returning to caller
6     add lhs == rhs to z3 solver;
```

Handle Intra-procedural CFG Edges (`handleIntra`)

Algorithm 6: `handleIntra(intraEdge)`

```
1  if intraEdge.getCondition() then
2      if !handleBranch(intraEdge) then
3          return false;
4      else
5          return handleNonBranch(intraEdge);
6  else
7      return handleNonBranch(intraEdge);
```

Algorithm 7: `handleBranch(intraEdge)`

```
1  cond = intraEdge.getCondition();
2  succ = intraEdge.getSuccessorCondValue();
3  getSolver().push();
4  addToSolver(cond == succ);
5  res = getSolver().check();
6  getSolver().pop();
7  if res == unsat then
8      return false;
9  else
10     addToSolver(cond == succ);
11     return true;
```

Algorithm 8: `HandleNonBranch(intraEdge)`

```
1   dst ← intraEdge.getDstNode();
    src ← intraEdge.getSrcNode();
2   foreach stmt ∈ dst.getSVFStmts() do
3       if addr ← dyn_cast⟨AddrStmt⟩(stmt) then
4           // handle AddrStmt
5       else if copy ← dyn_cast⟨CopyStmt⟩(stmt) then
6           // handle CopyStmt
7       else if load ← dyn_cast⟨LoadStmt⟩(stmt) then
8           // handle LoadStmt
9       else if store ← dyn_cast⟨StoreStmt⟩(stmt) then
10          // handle StoreStmt
11      else if gep ← dyn_cast⟨GepStmt⟩(stmt) then
12          // handle GepStmt
13      else if binary ← dyn_cast⟨BinaryStmt⟩(stmt) then
14          // handle BinaryStmt
15      else if cmp ← dyn_cast⟨CmpStmt⟩(stmt) then
16          // handle CmpStmt
17      else if phi ← dyn_cast⟨PhiStmt⟩(stmt) then
18          // handle PhiStmt
19      else if select ← dyn_cast⟨SelectStmt⟩(stmt) then
20          // handle SelectStmt
21      ...
```

Example 1: CmpStmt and BinaryOPStmt

```
1 void main(int x) {
2  int y, z, b;
3  y = x;
4  // C-like CmpStmt
5  b = (x == y);
6  // C-like BinaryOPStmt
7  z = x + y;
8  assert(z == 2 * x)
9 }
```

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```

Concrete Execution
(Concrete states)

One execution:

x :	5
y :	5
b :	1
z :	10

Another execution:

x :	10
y :	10
b :	1
z :	20

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Symbolic Execution
(`getZ3Expr(x)` **represents** `x`'s **symbolic state**)

x : `getZ3Expr(x)`
y : `getZ3Expr(x)`
b : `ite(getZ3Expr(x)≡getZ3Expr(y), 1, 0)`
z : `getZ3Expr(x) + getZ3Expr(y)`

Checking satisfiability using "`getSolver().check()`".

Checking non-existence of counterexamples: $\psi(N_1) \wedge \psi(N_2) \wedge \ldots \psi(N_i) \wedge \neg\psi(Q)$	Satisfiability
$\mathtt{y} \equiv \mathtt{x} \wedge \mathtt{b} \equiv \mathtt{ite}(\mathtt{x} \equiv \mathtt{y}, 1, 0) \wedge \mathtt{z} \equiv \mathtt{x} + \mathtt{y} \wedge \mathtt{z} \neq 2 * \mathtt{x}$	unsat

Example 1: CmpStmt and BinaryOPStmt

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2   int y, z, b;
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8   assert(z == 2 * x)
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Symbolic Execution
(`getZ3Expr(x)` **represents** `x`'s **symbolic state**)

```
x : getZ3Expr(x)
y : getZ3Expr(x)
b : ite(getZ3Expr(x)≡getZ3Expr(y), 1, 0)
z : getZ3Expr(x) + getZ3Expr(y)
```

In `Assignment-2`, we **only handle signed integers** including both positive and negative numbers and the assume that the program is **integer-overflow-free** in this assignment.

Handling CmpStmt

Algorithm 9: Handle CmpStmt

```
op0 ← get z3 expression of operand 0;
op1 ← get z3 expression of operand 1;
res ← get z3 expression of result;
switch predicate of cmp do
    case CmpInst :: ICMP_EQ do
        Use the ite (if − then − else) API to return 1
          if operands are equal, 0 otherwise
          then add to z3 solver
    case CmpInst :: ICMP_NE do
        addToSolver(res == ite(op0! = op1,
          getCtx().int_val(1), getCtx().int_val(0)));
    case CmpInst :: ICMP_UGT do
        addToSolver(res == ite(op0 > op1,
          getCtx().int_val(1), getCtx().int_val(0)));
    case CmpInst :: ICMP_SGT do
        addToSolver(res == ite(op0 > op1,
          getCtx().int_val(1), getCtx().int_val(0)));
    case CmpInst :: ICMP_UGE do
        addToSolver(res == ite(op0 >= op1,
          getCtx().int_val(1), getCtx().int_val(0)));
    ...
```

Algorithm 10: Handling CmpStmt

```
case CmpInst :: ICMP_SGE do
    addToSolver(res == ite(op0 >= op1,
      getCtx().int_val(1), getCtx().int_val(0)));
case CmpInst :: ICMP_ULT do
    addToSolver(res == ite(op0 < op1,
      getCtx().int_val(1), getCtx().int_val(0)));
case CmpInst :: ICMP_SLT do
    addToSolver(res == ite(op0 < op1,
      getCtx().int_val(1), getCtx().int_val(0)));
case CmpInst :: ICMP_ULE do
    addToSolver(res == ite(op0 <= op1,
      getCtx().int_val(1), getCtx().int_val(0)));
case CmpInst :: ICMP_SLE do
    addToSolver(res == ite(op0 <= op1,
      getCtx().int_val(1), getCtx().int_val(0)));
```

Handle BinaryOPStmt

Algorithm 10: Handle BinaryOpStmt

```
1  op0 ← getZ3Expr(binary.getOpVarID(0));
2  op1 ← getZ3Expr(binary.getOpVarID(1));
3  res ← getZ3Expr(binary.getResID());
4  switch binary.getOpcode() do
5      case BinaryOperator :: Add do
6          addToSolver(res == op0 + op1);
7      case BinaryOperator :: Sub do
8          addToSolver(res == op0 − op1);
9      case BinaryOperator :: Mul do
10         addToSolver(res == op0 × op1);
11     case BinaryOperator :: SDiv do
12         addToSolver(res == op0/op1);
13     case BinaryOperator :: SRem do
14         addToSolver(res == op0%op1);
15     case BinaryOperator :: Xor do
16         addToSolver(res ==
17             bv2int(int2bv(32, op0) ⊕ int2bv(32, op1), 1)));
18     case BinaryOperator :: And do
19         addToSolver(res ==
20             bv2int(int2bv(32, op0)&int2bv(32, op1), 1)));
21     ...
```

Algorithm 10: Handle BinaryOpStmt

```
1  case BinaryOperator :: Or do
2      addToSolver(res ==
3          bv2int(int2bv(32, op0)|int2bv(32, op1), 1)));
4  case BinaryOperator :: AShr do
5      addToSolver(res ==
6          bv2int(ashr(int2bv(32, op0), int2bv(32, op1)), 1)));
7  case BinaryOperator :: Shl do
8      addToSolver(res ==
9          bv2int(shl(int2bv(32, op0), int2bv(32, op1)), 1)));
```

Example 2: Memory Operation

```
1 void main(int x) {
2  int* p;
3  int y;
4
5  p = malloc(..);
6  *p = x + 5;
7  y = *p;
8  assert(y==x+5);
9 }
```

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8   assert(y==x+5);
9 }
```

Concrete Execution
(Concrete states)

One execution:

x	:	10
p	:	0x1234
0x1234	:	15
y	:	15

Another execution:

x	:	0
p	:	0x1234
0x1234	:	5
y	:	5

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0x1234	:	5
y	:	5

Symbolic Execution
(Symbolic states)

x	:	getZ3Expr(x)
p	:	0x7f000001
		virtual address from
		getMemObjAddress(ObjVarID)
0x7f000001	:	getZ3Expr(x) + 5
y	:	getZ3Expr(x) + 5

Checking non-existence of counterexamples:

$\psi(N_1) \wedge \psi(N_2) \wedge \ldots \psi(N_i) \wedge \neg\psi(Q)$	Satisfiability
$\mathtt{p} \equiv \mathtt{0x7f000001} \wedge \mathtt{y} \equiv \mathtt{x} + 5 \wedge \mathtt{y} \neq \mathtt{x} + 5$	unsat

Handling Memory Operation

Algorithm 11: Handle AddrStmt

```
1 obj ← getMemObjAddress(addr.getRHSVarID());
2 lhs ← getZ3Expr(addr.getLHSVarID());
3 addToSolver(obj == lhs);
```

Algorithm 12: Handle LoadStmt

```
1 lhs ← getZ3Expr(load.getLHSVarID());
2 rhs ← getZ3Expr(load.getRHSVarID());
3 addToSolver(lhs == z3Mgr.loadValue(rhs));
```

Algorithm 13: Handle StoreStmt

```
1 lhs ← getZ3Expr(store.getLHSVarID());
2 rhs ← getZ3Expr(store.getRHSVarID());
3 z3Mgr.storeValue(lhs, rhs);
```

Example 3: Field Access for Struct and Array

```
1  struct st{
2      int a;
3      int b;
4  }
5  void main(int x) {
6   struct st* p = malloc(..);
7   q = &(p->b);
8   *q = x;
9   int k = p->b;
10  assert(k == x);
11 }
```

Example 3: Field Access for Struct and Array

```
1  struct st{
2      int a;
3      int b;
4  }
5  void main(int x) {
6   struct st* p = malloc(..);
7   q = &(p->b);
8   *q = x;
9   int k = p->b;
10  assert(k == x);
11 }
```

Concrete Execution
(Concrete states)

One execution:

x	:	10
p	:	0x1234
&(p→b)	:	0x1238
q	:	0x1238
0x1238	:	10
k	:	10

Another execution:

x	:	20
p	:	0x1234
&(p→b)	:	0x1238
q	:	0x1238
0x1238	:	20
k	:	20

Example 3: Field Access for Struct and Array

```
1  struct st{
2      int a;
3      int b;
4  }
5  void main(int x) {
6   struct st* p = malloc(..);
7   q = &(p->b);
8   *q = x;
9   int k = p->b;
10  assert(k == x);
11 }
```

Concrete Execution
(Concrete states)
One execution:

x	:	10
p	:	0x1234
&(p→b)	:	0x1238
q	:	0x1238
0x1238	:	10
k	:	10

Another execution:

x	:	20
p	:	0x1234
&(p→b)	:	0x1238
q	:	0x1238
0x1238	:	20
k	:	20

Symbolic Execution
(Symbolic states)

x	:	getZ3Expr(x)
p	:	0x7f000001
		virtual address from
		getMemObjAddress(ObjVarID)
&(p→b)	:	0x7f000002
q	:	0x7f000002
		field virtual address from
		getGepObjAddress(base, offset)
0x7f000002	:	getZ3Expr(x)
k	:	getZ3Expr(x)

The virtual address for modeling a field is based on the index of the field offset from the base pointer of a struct (nested struct will be flattened to allow each field to have a unique index)

Example 3: Field Access for Struct and Array

```
1  struct st{
2      int a;
3      int b;
4  }
5  void main(int x) {
6   struct st* p = malloc(..);
7   q = &(p->b);
8   *q = x;
9   int k = p->b;
10  assert(k == x);
11 }
```

Concrete Execution
(Concrete states)

One execution:

x	:	10
p	:	0x1234
&(p→b)	:	0x1238
q	:	0x1238
0x1238	:	10
k	:	10

Another execution:

x	:	20
p	:	0x1234
&(p→b)	:	0x1238
q	:	0x1238
0x1238	:	20
k	:	20

Symbolic Execution
(Symbolic states)

x	:	getZ3Expr(x)
p	:	0x7f000001
		virtual address from
		getMemObjAddress(ObjVarID)
&(p→b)	:	0x7f000002
q	:	0x7f000002
		field virtual address from
		getGepObjAddress(base, offset)
0x7f000002	:	getZ3Expr(x)
k	:	getZ3Expr(x)

Checking non-existence of counterexamples:

$\psi(N_1) \wedge \psi(N_2) \wedge \ldots \psi(N_i) \wedge \neg\psi(Q)$	Satisfiability
$\mathtt{p} \equiv \mathtt{0x7f000001} \wedge \mathtt{q} \equiv \mathtt{0x7f000002} \wedge \mathtt{k} \equiv \mathtt{x} \wedge \mathtt{k} \neq \mathtt{x}$	unsat

Handling Field and Array Access (GepStmt)

Algorithm 13: `Handle GepStmt`

```
1 lhs ← getZ3Expr(gep.getLHSVarID());
2 rhs ← getZ3Expr(gep.getRHSVarID());
3 offset ← z3Mgr.getGepOffset(gep, curCallCtx);
4 gepAddress ← z3Mgr.getGepObjAddress(rhs, offset);
5 addToSolver(lhs == gepAddress);
```

Method `getGepObjAddress` supports both `struct` and `array` accesses using a base pointer and element index.

In `Assignment-2`, **we don't consider object byte sizes** and low-level incompatible type casting in `Assignment-2`.

```
z3::expr Z3SSEMgr::getGepObjAddress(z3::expr pointer, u32_t offset) {
    NodeID obj = getInternalID(z3Expr2NumValue(pointer));
    // Find the baseObj and return the field object.
    // The indices of sub-elements of a nested aggregate object has been flattened
    NodeID gepObj = svfir->getGepObjVar(obj, offset);
    if (obj == gepObj)
        return getZ3Expr(obj);
    else
        return createExprForObjVar(SVFUtil::cast<GepObjVar>(svfir->getGNode(gepObj)));
}
```

Example 4: Branches

```
1 void main(int x){
2     if(x > 10) {
3         y = x + 1;
4     }
5     else {
6         y = 10;
7     }
8 assert(y >= x + 1);
9 }
```

Example 4: Branches

```
1 void main(int x){
2     if(x > 10) {
3         y = x + 1;
4     }
5     else {
6         y = 10;
7     }
8 assert(y >= x + 1);
9 }
```

Concrete Execution
(concrete states)

One execution:
x : 20
y : 21

Another execution:
x : 8
y : 10

Example 4: Branches

```
1 void main(int x){
2     if(x > 10) {
3         y = x + 1;
4     }
5     else {
6         y = 10;
7     }
8 assert(y >= x + 1);
9 }
```

Concrete Execution (concrete states)	Symbolic Execution (Symbolic states)
One execution:	If branch:
x : 20	x : getZ3Expr(x) $>$ 10
y : 21	y : getZ3Expr(x) + 1
Another execution:	Else branch:
x : 8	x : getZ3Expr(x) $\leq$ 10
y : 10	y : 10

Checking non-existence of counterexamples:

Path	$\psi(N_1) \wedge \psi(N_2) \wedge \ldots \psi(N_i) \wedge \neg\psi(Q)$	Satisfiability	Counterexample
$\ell_1 \rightarrow \ell_2 \rightarrow \ell_3 \rightarrow \ell_8$ (if.then branch)	$x > 10 \wedge y \equiv x + 1 \wedge y < x + 1$	unsat	$\varnothing$
$\ell_1 \rightarrow \ell_2 \rightarrow \ell_6 \rightarrow \ell_8$ (if.else branch)	$x \leq 10 \wedge y \equiv 10 \wedge y < x + 1$	sat	$\{x : 10, y : 10\}$

Getting the potential counterexample via "`getSolver().get_model()`" after "`getSolver().check()`".

What's next?

- (1) Understand SSE algorithms and examples in the slides
- (2) Finish the Quiz-2 and Lab-2 on WebCMS
- (3) Start implementing the automated translation from code to Z3 formulas using `SSE` and `Z3SSEMgr` in Assignment 2