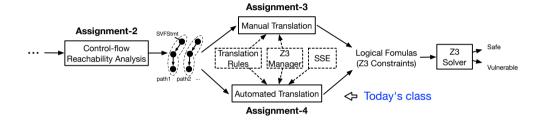
### **Assertion-based Verification Using Static Symbolic Execution**

Yulei Sui

University of Technology Sydney, Australia

### **Automated Assertion-based Verification**



### Static Symbolic Execution (SSE)

- An static interpreter follows the program, assuming symbolic values for inputs rather than obtaining actual inputs as normal execution of the program would.
- Automated testing technique that symbolically executes a program.
- Use symbolic execution to explore all program paths to find latent bugs.

### Static Symbolic Execution for Assertion-based Verification

- Given a Hoare triple P { prog } Q,
  - P represents program inputs.
  - prog is the actual source code,
  - Q is the assertion(s) to be verified.
- SSE translates SVFStmt of each program path (which ends with an assertion) into a Z3 logical formula.
  - In our project, the path of each loop is bounded once for verification.
- Prove satisfiability of the logic formulas of each program path from the program entry to each assertion on the ICFG.

# **Driver Program of SSE (What We Have From Assignment 2)**

```
Algorithm 1 Context sensitive control-flow reachability
  Input: src: ICFGNode dst: ICFGNode
         path: vector(ICFGNode) visited: set(ICFGNode):
  dfs(path.src.dst)
    visited.insert(src)
    path.push_back(src)
    if arc -- det then
     print path
    foreach edge ∈ src.getOutEdges() do
     if edge.dst ∉ visited then
         if edge.isIntraCFGEdge() then
             if handleIntra(edge) then
                dfs(path, edge.dst, dst)
         else if edge.isCallCFGEdge() then
11
             if handleCall(edge) then
12
                dfs(path, edge.dst, dst)
13
         else if edge.isRetCFGEdge() then
14
             if handleRet(edge) then
15
                dfs(path.edge.dst.dst)
    visited.erase(src)
    path.pop_back(src)
```

```
Algorithm 2 handleIntra(intraEdge) (Override in SSE)
 return true
Algorithm 3 handleCall(callEdge) (Override in SSE)
  callNode ← getSrcNode(callEdge)
  callstack.push_back(callNode)
  return true
Algorithm 4 handleRet(retEdge) (Override in SSE)
  retNode ← getDstNode(retEdge)
  if callstack \neq \emptyset then
   if callstack.back() == getCallICFGNode(retNode) then
       callstack.pop()
       return true
   else
      return false
  return true
```

# Driver Program of SSE (What We Have From Assignment 2)

```
Algorithm 1 Context sensitive control-flow reachability
                                                                     Algorithm 2 handleIntra(intraEdge) (Override in SSE)
  Input: src: ICFGNode dst: ICFGNode
                                                                      return true
        path: vector(ICFGNode) visited: set(ICFGNode):
  dfs(path.src.dst)
                                                                     Algorithm 3 handleCall(callEdge) (Override in SSE)
    visited.insert(src)
    path.push_back(src)
                                                                       callNode ← getSrcNode(callEdge)
    if arc -- det then
                                                                       callstack.push_back(callNode)
     print path
                                                                       return true
    foreach edge ∈ src.getOutEdges() do
     if edge.dst ∉ visited then
                                                                     Algorithm 4 handleRet(retEdge) (Override in SSE)
         if edge.isIntraCFGEdge() then
                                                                       retNode ← getDstNode(retEdge)
            if handleIntra(edge) then
                                                                       if callstack \neq \emptyset then
               dfs(path, edge.dst, dst)
                                                                        if callstack.back() == getCallICFGNode(retNode) then
        else if edge.isCallCFGEdge() then
11
                                                                            callstack.pop()
            if handleCall(edge) then
12
                                                                            return true
               dfs(path, edge.dst, dst)
13
                                                                        else
        else if edge.isRetCFGEdge() then
14
                                                                            return false
            if handleRet(edge) then
15
               dfs(path.edge.dst.dst)
                                                                       return true
    visited.erase(src)
    path.pop_back(src)
```

Override the above three methods in SSE implementation!

### Handle Intra-procedural CFG Edges (handleIntra)

```
Algorithm 2 handleIntra(intraEdge)
if intraEdge.getCondition() && !handleBranch(intraEdge)
  then
     return false
3 else
     handleNonBranch(edge)
                                                               10
  handleBranch(intraEdge)
                                                               11
    cond = intraEdge.getCondition()
                                                               12
                                                               13
    successorVal = intraEdge.getSuccessorCondValue()
                                                               14
    res = getEvalExpr(cond == suc)
4 if res.is_false() then
                                                               15
      addToSolver(cond! = suc)
                                                               16
     return false
                                                               17
                                                               18
  else if res.is_true() then
                                                               19
     addToSolver(cond == suc)
                                                               20
     return true
                                                               21
10 else
                                                               22
     return true
                                                               23
                                                               24
```

```
HandleNonBranch(intraEdge)
  dst ← intraEdge.getDstNode(): src ← intraEdge.getSrcNode()
  foreach stmt ∈ dst.getSVFStmts() do
   if addr ← dvn cast/AddrStmt\(stmt) then
      obj ← getMemObjAddress(addr.getRHSVarID())
      lhs ← getZ3Expr(addr.getLHSVarID())
      addToSolver(obi == lhs)
   else if copy ← dyn_cast(CopyStmt)(stmt) then
       lhs ← getZ3Expr(copy.getLHSVarID())
       rhs ← getZ3Expr(copv.getRHSVarID())
      addToSolver(rhs == lhs)
   else if load ← dyn_cast(LoadStmt)(stmt) then
       lhs ← getZ3Expr(load.getLHSVarID())
      rhs ← getZ3Expr(load.getRHSVarID())
       addToSolver(lhs == z3Mgr.loadValue(rhs))
   else if store \leftarrow dvn_cast(StoreStmt)(stmt) then
       lhs ← getZ3Expr(store.getLHSVarID())
       rhs ← getZ3Expr(store.getRHSVarID())
      z3Mgr.storeValue(lhs.rhs)
   else if gep ← dvn_cast(GepStmt)(stmt) then
       lhs ← getZ3Expr(gep.getLHSVarID())
       rhs ← getZ3Expr(gep.getRHSVarID())
       offset ← z3Mgr.getGepOffset(gep)
       gepAddress \( \sim z \) 3Mgr.getGepObjAddress(rhs, offset)
       addToSolver(lhs == gepAddress)
```

### Handle Call (handleCall) and Return (handleRet) CFG Edges

### Algorithm 3 handleCall(callEdge) callNode ← callEdge.getSrcNode(): FunEntryNode ← callEdge.getDstNode(); callstack.push\_back(callNode); getSolver().push(); 5 foreach callPE ∈ calledge.getCallPEs() do lhs ← getZ3Expr(callPE.getLHSVarID()); rhs ← getZ3Expr(callPE.getRHSVarID()): addToSolver(lhs == rhs); 9 return true:

```
Algorithm 4 handleRet(retEdge)
    retNode ← retEdge.getDstNode();
    rhs(getCtx()):
    lhs(getCtx());
    if retPE ← retEdge.getRetPE() then
      rhs ← getEvalExpr(getZ3Expr(retPE.getRHSVarID()));
      lhs ← getZ3Expr(retPE.getLHSVarID()):
    if callstack \neq \emptyset then
      if callstack.back() == getCallICFGNode(retNode) then
         callstack.pop_back():
         getSolver().pop():
      else
11
12
         return false:
    if retEdge.getRetPE() then
13
      addToSolver(lhs == rhs):
    return true:
```

### **Scalar Example**

Comparison between the concrete and symbolic states before the assertion.

```
t void foo(unsigned x){
   if(x > 10) {
      y = x + 1;
}
else {
      y = 10;
}
assert(y >= x + 1);
}
```

### **Scalar Example**

Comparison between the concrete and symbolic states before the assertion.

```
void foo(unsigned x){
if(x > 10) {
    y = x + 1;
}
else {
    y = 10;
}
assert(y >= x + 1);
}
```

```
Concrete Execution
(Concrete states of x, y)

One execution:
    x : 20
    y : 21

Another execution:
    x : 8
    y : 9
```

### Scalar Example

### Comparison between the concrete and symbolic states before the assertion.

```
void foo(unsigned x){
    if(x > 10) {
        v = x + 1:
    else {
        v = 10:
assert(v >= x + 1):
```

```
Concrete Execution
                                        Symbolic Execution
(Concrete states of x, y)
                           (getZ3Expr(x) represents x's symbolic state)
   One execution:
                       If branch:
       x : 20
                       x: getZ3Expr(x) > 10 \land getZ3Expr(x) < UINT_MAX)
                       v: getZ3Expr(x) + 1
        v : 21
  Another execution:
                       Else branch:
        x:8
                       x: getZ3Expr(x) > 0 \land getZ3Expr(x) < 10
        v:9
                       v: 10
```

### **Memory Operation Example**

```
void foo(unsigned x) {
int* p;
int y;

p = malloc(..);
*p = x + 5;
y = *p;
assert(y>5);
}
```

### **Memory Operation Example**

# void foo(unsigned x) { int\* p; int y; p = malloc(..); \*p = x + 5; y = \*p; assert(y>5); }

```
Concrete Execution (Concrete states)
```

```
One execution:
    x : 10
    p : 0x1234
0x1234 : 15
    y : 15
```

### Another execution:

```
x : 0
p : 0x1234
0x1234 : 5
```

### **Memory Operation Example**

### void foo(unsigned x) { int\* p; int v: p = malloc(..): \*p = x + 5: g = g = gassert(v>5):

```
Concrete Execution
 (Concrete states)
```

```
One execution:
            10
         0x1234
0x1234:
            15
            15
Another execution:
            0
         0x1234
0x1234:
```

```
Symbolic Execution
 (Symbolic states)
```

```
: getZ3Expr(x)
    x
           : 0x7f000001
    р
            virtual address from
            getMemObjAddress("malloc")
0x7f000001 : getZ3Expr(x) + 5
```

: getZ3Expr(x) + 5

## **Field Access for Struct and Array Example**

```
1 struct st{
2    int a;
3    int b;
4 }
5 void foo(unsigned x) {
6    struct st* p = malloc(..);
7    q = &(p->b);
8    *q = x;
9    assert(*(&p->b) == x);
10 }
```

# **Field Access for Struct and Array Example**

```
struct st{
   int a;
   int b;
}

void foo(unsigned x) {
   struct st* p = malloc(..);
   q = &(p->b);
   *q = x;
   assert(*(&p->b) == x);
}
```

```
(Concrete states)
  One execution:
              10
            0x1234
&(p→b)
         : 0x1238
           0x1238
0x1238
            10
 Another execution:
              20
            0x1234
\&(p\rightarrow b)
            0x1238
```

0x1238

0x1238

20

Concrete Execution

# Field Access for Struct and Array Example

&(p→b)

```
struct st{
      int a:
3
      int b;
4 }
  void foo(unsigned x) {
   struct st* p = malloc(..);
   q = &(p->b);
   *a = x:
   assert(*(\&p->b) == x);
10 }
```

```
Concrete Execution
 (Concrete states)
                                      Symbolic Execution
  One execution:
                                       (Symbolic states)
              10
           0x1234
                                      getZ3Expr(x)
                           x
           0x1238
                                      0x7f000001
```

0x1238 virtual address from

0x1238 10 getMemObjAddress("malloc") 0x7f000002

**&**(p→b) Another execution: 0x7f000002

20 field virtual address from 0x1234 getGepObiAddress(base, offset)

 $\&(p\rightarrow b)$ 0x1238 0x7f000002 getZ3Expr(x)

0x1238 0x1238 20

The virtual address for modeling a field is based on the index of the field offset from the base pointer of a struct (nested struct will be flattened to allow each field to have a unique index)

### **Call and Return Example**

```
1 int foo(int z) {
2          k = z;
3          return k;
4 }
5 int main(unsigned z) {
6          int x;
7          int y;
8          x = foo(3);
9          y = foo(z);
10          assert(x == 3);
11 }
```

# Concrete Execution (Concrete states)

### One execution:

z : 10 stack push (calling foo at line 8)

k : 3

stack pop (returning from foo at line 4)

x : 3

stack push (calling foo at line 9)

k : 10

stack pop (returning from foo line 4)

y : 10

# Symbolic Execution (Symbolic states)

#### One execution:

z : getZ3Expr(z) stack push (calling foo at line 8)

k : 3

stack pop (returning from foo at line 4)

x : 3

stack push (calling foo at line 9)

k : getZ3Expr(z)

stack pop (returning from foo line 4)

y : getZ3Expr(z)

### What's next?

- (1) Understand SSE algorithms in the slides
- (2) Read through Assignment-4.pdf on Canvas to understand some examples for automated code verification.
- (3) Finish the guizzes of Assignment 4 on Canvas
- (4) Implement a automated translation from code to Z3 formulas using SSE and Z3Mgr i.e., coding task in Assignment 3