Control-Dependence and Control-Flow Reachability

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What are control- and data-dependence?

Control-dependence

- Execution order between two program statements/instructions.
- Can program point B be reached from point A in the control-flow graph of a program?
- Obtained through traversing the ICFG of a program

Data-dependence

- Definition-use relation between two program variables.
- Will the definition of a variable X be used and passed to another variable Y?
- Obtained through analyzing the SVFIR of a program
- Combining SVFIR with ICFG to conduct symbolic execution (mimic the runtime path-based execution) of a program.

Why learn control- and data-dependence?

A program dependence relation by its nature is the reachability property on a graph, particularly useful in program understanding, optimizations and bug detection.

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- Applications of control-dependence
 - Dead code elimination: If a subgraph of an ICFG is not connected from the entry block of a program, that subgraph is possibly dead code.

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Applications of control-dependence

- Dead code elimination: If a subgraph of an ICFG is not connected from the entry block of a program, that subgraph is possibly dead code.
- Identifying infinite loops: If the exit block is unreachable from the entry block, an infinite loop may exist.

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Applications of data-dependence

Pointer alias analysis: statically determine possible runtime values of a pointer to detect memory errors, such as null pointer dereferences and use-after-frees.

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Applications of data-dependence

- Pointer alias analysis: statically determine possible runtime values of a pointer to detect memory errors, such as null pointer dereferences and use-after-frees.
- Taint analysis: if two program variables v1 and v2 are aliases (e.g., representing the same memory location), if v1 is tainted by user inputs, then v2 is also tainted.
- . . .

We say that a program statement (ICFG node) snk is control-flow dependent on src if src can reach snk on the ICFG.

- Context-insensitive control-dependence
 - control-flow traversal without matching calls and returns.
 - fast but imprecise

We say that a program statement (ICFG node) snk is control-flow dependent on src if src can reach snk on the ICFG.

- Context-insensitive control-dependence
 - control-flow traversal without matching calls and returns.
 - fast but imprecise
- Context-sensitive control-dependence
 - control-flow traversal by matching calls and returns.
 - precise but maintains an extra abstract call stack (storing a sequence of callsite ID information) to mimic the runtime call stack.

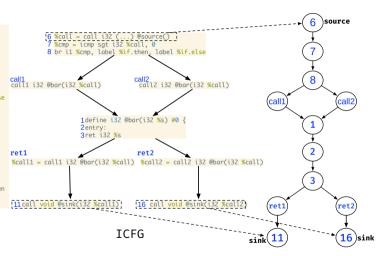
```
int bar(int s){
    return s;
}
int main(){
    int a = source();
    if (a > 0){
        int p = bar(a);
        sink(p);
}else{
        int q = bar(a);
        sink(q);
}
```

```
define i32 @bar(i32 %s) #0 {
1 entry:
2 ret i32 %s
3 }
  define i32 @main() #0 {
4 entry:
5 %call = call i32 (...) @source()
6 %cmp = icmp sqt i32 %call, 0
7 br i1 %cmp, label %if.then, label %if.else
  if.then:
                   : preds = %entry
9 %call1 = call i32 @bar(i32 %call)
10 call void @sink(i32 %call1)
11 br label %if.end
12
  if.else:
                    : preds = %entry
13 %call2 = call i32 @bar(i32 %call)
14 call void @sink(i32 %call2)
15 br label %if.end
16
  if.end:
                 : preds = %if.else. %if.then
17 ret i32 0
18 1
```

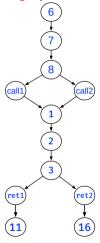
```
define i32 @bar(i32 %s) #0 {
1 entry:
                                                         6 %call = call i32 (...) @source()
2 ret i32 %s
                                                         7 %cmp = icmp sat i32 %call. 0
3 }
                                                         8 br i1 %cmp, label %if.then, label %if.else
  define i32 @main() #0 {
4 entry:
                                                                                 call2 i32 @bar(i32 %call)
                                              call1 i32 @bar(i32 %call)
5 %call = call i32 (...) @source()
6 %cmp = icmp sqt i32 %call, 0
7 br i1 %cmp, label %if.then, label %if.else
   if then:
                   : preds = %entry
9 %call1 = call i32 @bar(i32 %call)
                                                                  1define i32 @bar(i32 %s) #0
10 call void @sink(i32 %call1)
                                                                  2entry:
                                                                  3ret i32 %s
11 br label %if.end
12
   if.else:
                     : preds = %entry
                                                                                  ret2
                                              ret1
13 %call2 = call i32 @bar(i32 %call)
                                               %call1 = call1 i32 @bar(i32 %call) %call2 = call2 i32 @bar(i32 %call)
14 call void @sink(i32 %call2)
15 br label %if.end
16
  if.end:
                 : preds = %if.else. %if.then
17 ret i32 0
18 1
                                               11 call void @sink(i32 %call1)
                                                                                  16 call void @sink(i32 %call2)
```

TCFG

```
define i32 @bar(i32 %s) #0 {
1 entry:
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  define i32 @main() #0 {
4 entry:
5 %call = call i32 (...) @source()
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10 call void @sink(i32 %call1)
11 br label %if.end
12
   if.else:
                     : preds = %entry
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14 call void @sink(i32 %call2)
15 br label %if.end
16
  if.end:
                 : preds = %if.else. %if.then
17 ret i32 0
18 1
```



Obtaining a path from source to sink on ICFG

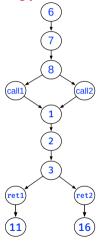


```
Basic DFS on ICFG: source → sink
```

```
visited: set<NodeID>
path: vector<NodeID>

DFS(visited, path, src, dst)
   visited.insert(src);
   path.push_back(src);
   if src == dst then
        Print path;
   foreach edge e ∈ outEdges(src) do
        if (e.dst ∉ visited)
            DFS(visited, path, e.dst, dst);
   visited.erase(src);
   path.pop_back();
```

Obtaining paths from node 6 to node 11 on the ICFG



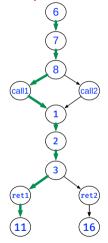
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Basic DFS on ICFG: source → sink
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        if (e.dst ∉ visited)
            DFS(visited, path, e.dst, dst);
    visited.erase(src);
    path.pop_back();
```

```
ICFG paths: node 6 \rightarrow node 11
Path 1: 6 \rightarrow 7 \rightarrow 8 \rightarrow \mathbf{call1} \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow \mathbf{ret1} \rightarrow 11
Path 2: 6 \rightarrow 7 \rightarrow 8 \rightarrow \mathbf{call2} \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow \mathbf{ret1} \rightarrow 11
```

Feasible paths from node 6 to node 11



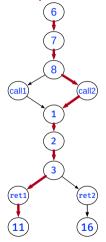
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    Print path;
  foreach edge e ∈ outEdges(src) do
    if (e.dst ∉ visited)
        DFS(visited, path, e.dst, dst);
  visited.erase(src);
  path.pop_back();
```

```
ICFG paths: node 6 \rightarrow node 11

Path 1: feasible path
6 \rightarrow 7 \rightarrow 8 \rightarrow \mathbf{call1} \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow \mathbf{ret1} \rightarrow 11
Path 2:
6 \rightarrow 7 \rightarrow 8 \rightarrow \mathbf{call2} \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow \mathbf{ret1} \rightarrow 11
```

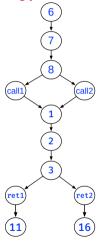
Infeasible path from node 6 to node 11



```
visited: set<NodeID>
path: vector<NodeID>
DFS(visited, path, src, dst)
   visited.insert(src):
   path.push back(src):
   if src == dst then
     Print path:
   foreach edge e ∈ outEdges(src) do
      if (e.dst ∉ visited)
          DFS(visited, path, e.dst, dst);
   visited.erase(src);
   path.pop_back();
```

```
ICFG paths: node 6 → node 11
Path 1:
         6 \rightarrow 7 \rightarrow 8 \rightarrow call1 \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow ret1 \rightarrow 11
Path 2:
         6 \rightarrow 7 \rightarrow 8 \rightarrow call2 \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow ret1 \rightarrow 11
                           spurious path
```

Obtaining paths from node 6 to node 16 on ICFG



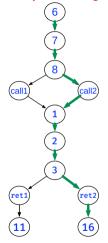
```
visited: set<NodeID>
path: vector<NodeID>

DFS(visited, path, src, dst)
  visited.insert(src);
  path.push_back(src);
  if src == dst then
    Print path;
  foreach edge e ∈ outEdges(src) do
    if (e.dst ∉ visited)
        DFS(visited, path, e.dst, dst);
  visited.erase(src);
  path.pop_back();
```

```
ICFG paths: node 6 \rightarrow node 16

Path 3:
6 \rightarrow 7 \rightarrow 8 \rightarrow \mathbf{call2} \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow \mathbf{ret2} \rightarrow 16
Path 4:
6 \rightarrow 7 \rightarrow 8 \rightarrow \mathbf{call1} \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow \mathbf{ret2} \rightarrow 16
```

Feasible paths using from node 6 to node 16 on the ICFG



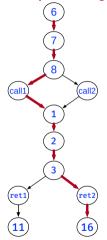
```
visited: set<NodeID>
path: vector<NodeID>

DFS(visited, path, src, dst)
  visited.insert(src);
  path.push_back(src);
  if src == dst then
    Print path;
  foreach edge e ∈ outEdges(src) do
    if (e.dst ∉ visited)
        DFS(visited, path, e.dst, dst);
  visited.erase(src);
  path.pop_back();
```

```
ICFG paths: node 6 \rightarrow node 16

Path 3: feasible path
6 \rightarrow 7 \rightarrow 8 \rightarrow \mathbf{call2} \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow \mathbf{ret2} \rightarrow 16
Path 4:
6 \rightarrow 7 \rightarrow 8 \rightarrow \mathbf{call1} \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow \mathbf{ret2} \rightarrow 16
```

Infeasible paths using from node 6 to node 16 on the ICFG



```
visited: set<NodeID>
path: vector<NodeID>

DFS(visited, path, src, dst)
   visited.insert(src);
   path.push_back(src);
   if src == dst then
        Print path;
   foreach edge e ∈ outEdges(src) do
        if (e.dst ∉ visited)
        DFS(visited, path, e.dst, dst);
   visited.erase(src);
   path.pop_back();
```

```
ICFG paths: node 6 \rightarrow node 16

Path 3:
6 \rightarrow 7 \rightarrow 8 \rightarrow \mathbf{call2} \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow \mathbf{ret2} \rightarrow 16

Path 4:
6 \rightarrow 7 \rightarrow 8 \rightarrow \mathbf{call1} \rightarrow 1 \rightarrow 2 \rightarrow 3 \rightarrow \mathbf{ret2} \rightarrow 16

spurious path
```

An extension of the context-insensitive algorithm by matching calls and returns.

- Get only feasible interprocedural paths and exclude infeasible ones
- Requires an extra callstack to store and mimic the runtime calling relations.

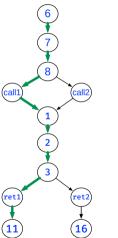
Context-Sensitive Control-Dependence (Algorithm)

Algorithm 1 Context sensitive control-flow reachability

```
Input: curEdge : ICFGEdge dst : ICFGNode path : vector(ICFGEdge) visited : set(ICFGEdge, callstack);
1 dfs(path, curEdge, dst)
    curItem \leftarrow \langle curEdge, callstack \rangle
    visited.insert(curItem)
    path.push_back(curEdge)
    if arc == dat then
     printICFGPath(path)
    foreach edge ∈ curEdge.dst.getOutEdges() do
     if edge.dst ∉ visited then
         if edge.isIntraCFGEdge() then
             dfs(path, edge, dst)
10
         else if edge.isCallCFGEdge() then
             callNode ← getSrcNode(edge)
             callstack.push_back(callNode)
             dfs(path.edge.dst)
14
         else if edge.isRetCFGEdge() then
15
             if callstack ≠ Ø && callstack.back() == edge.getCallSite() then
                 callstack.pop()
17
                 dfs(path, edge, dst)
18
             else if callstack == Ø then
                 dfs(path, edge, dst)
20
    visited.erase(curItem)
    path.pop_back()
```

Context-Sensitive Control-Dependence (Example)

call1 matches with ret1



```
Algorithm 1 Context sensitive control-flow reachability
```

```
1 dfs(curEdge.dst)
    curItem ← ⟨curEdge.callstack⟩
    visited.insert(curItem)
    path.push_back(curEdge)
    if src == dst then
    printICFGPath(path)
    foreach edge ∈ curEdge.dst.getOutEdges() do
     if edge.dst ∉ visited then
        if edge.isIntraCFGEdge() then
           dfs(path, edge, dst)
10
        else if edge.isCallCFGEdge() then
           callNode ← getSrcNode(edge)
           callstack.push_back(callNode)
           dfs(path, edge, dst)
        else if edge.isRetCFGEdge() then
15
           if callstack ≠ Ø && callstack.back() == edge.getCallSite() then
              callstack.pop()
17
              dfs(path.edge.dst)
           else if callstack == Ø then
19
              dfs(path.edge.dst)
20
    visited.erase(curItem)
21
    path.pop_back()
```

Context-Sensitive Control-Dependence (Example)

call2 does not match with ret1

call1 ret2 16

```
Algorithm 1 Context sensitive control-flow reachability
```

```
1 dfs(curEdge.dst)
    curItem ← ⟨curEdge.callstack⟩
    visited.insert(curItem)
    path.push_back(curEdge)
   if src == dst then
    printICFGPath(path)
    foreach edge ∈ curEdge.dst.getOutEdges() do
     if edge.dst ∉ visited then
        if edge.isIntraCFGEdge() then
           dfs(path, edge, dst)
10
        else if edge.isCallCFGEdge() then
           callNode ← getSrcNode(edge)
           callstack.push_back(callNode)
           dfs(path, edge, dst)
        else if edge.isRetCFGEdge() then
15
           if callstack ≠ Ø && callstack.back() == edge.getCallSite() then
              callstack.pop()
17
              dfs(path.edge.dst)
           else if callstack == Ø then
19
              dfs(path.edge.dst)
20
    visited.erase(curItem)
21
    path.pop_back()
```

What's next?

- (1) Understand control-flow reachability in this slides
- (2) Finish the quizzes of Assignment 2 on Canvas
- (3) Implement a context-sensitive ICFG traversal, i.e., coding task in Assignment 2
 - Refer to 'Assignment-2.pdf' on Canvas to know more.