Title of the project

Subtitle

Project Report
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Abstract:

This is the best abstract ever written

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Abbreviations

Terms and abbreviations used in the report:

Chapter 1

Introduction

1.1 Project idea

The idea for this project is to create a team building game using augmented reality (AR). Two teams will compete against each other to score the most goals using a ball. Each player will be equipped with a Google Cardboard, and these will display the playing field from a top-down 2D view. To achieve this, each player's position needs to be tracked as well as where the ball is located on the field. In the top down view each player needs to see the positions of the other players and the ball. They also need to see their own position on the playing field and where the goalposts are. The players should be able to set an amount of goals they need to score to win before beginning the game.
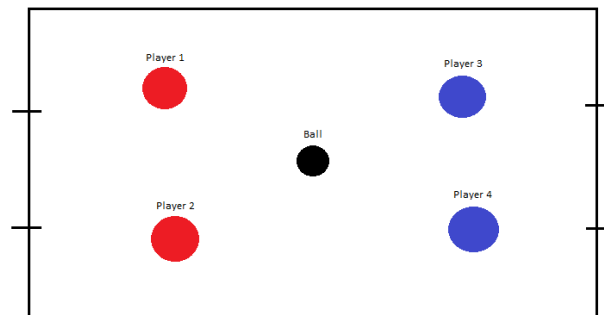

Figure 1.1: An illustration of the playing field

In Figure 1.1, an illustration of the playing field for the game is shown. There are goalposts in each end of the field, and the teams score goals by getting the ball between the goalposts. There could also be another version of the game where, instead of goalposts, there would be goal zones into which the teams need to bring the ball. These zones could even change locations as the game progressed.

1.1.1   Problems to consider

The project idea proposes some problems that will need to be solved for the game to work. We will need to consider which technologies to use for development of the visual aspect of the game which shows the top-down view for each player. As it is something we do not have experience with, it would be preferable if we do not have to build it from scratch. We will also need hardware that is able to track the positions of players and the ball. This must be accurate and update quickly such that the players do not run into each other, otherwise the game will not work. Another problem to consider is how the ball should be displayed in a 2D view. For the players to be able to find the ball on the field, it either has to be quite large to make it easier to find from the top-down view, or the game will need some metric to display how far the ball is from the ground. The game will also need to be able to track when the ball has crossed the goalline and then give feedback to the players. Another problem to solve is how to keep the positional data synchronized across all the players' devices, as it will be difficult to play the game without accurate data.

Chapter 2

Sprint 1

2.1 Pozyx

Pozyx is a hardware/software solution that is used to provide positioning with an accuracy of down to 10 cm [1]. It makes use of ultra-wideband in combination with machine learning for positioning, which according to their documentation is more precise and efficient than traditional positioning systems such as WiFi, Bluetooth, RFID, and GPS.

Since the two major requirements for positioning in this project are precision and a high update rate in order to ensure that the players can have reliable data available, the Pozyx system seems like a good place to start.

The Pozyx tags support update rates of up to 125 Hz for a single tag [1]. The Creator system from Pozyx is sold with 4 anchors and 5 locatable tags. An anchor is a stationary sensor used by the moveable tags to get their exact position.

2.1.1 Finding the location of anchors

A trilateration method is used for finding the position of a given tag using the anchors. This method uses basic geometry to estimate the position by measuring the distance to the anchors of which we know the position. With this data, it is possible to draw a circle with a given radius. If we use two anchors, we will have two intersection points which are the possible positions of the tag. This means that to find a two-dimensional location, we will need at least three anchors, which will lead to only a single point where all three circles intersect, as seen on Figure 2.1
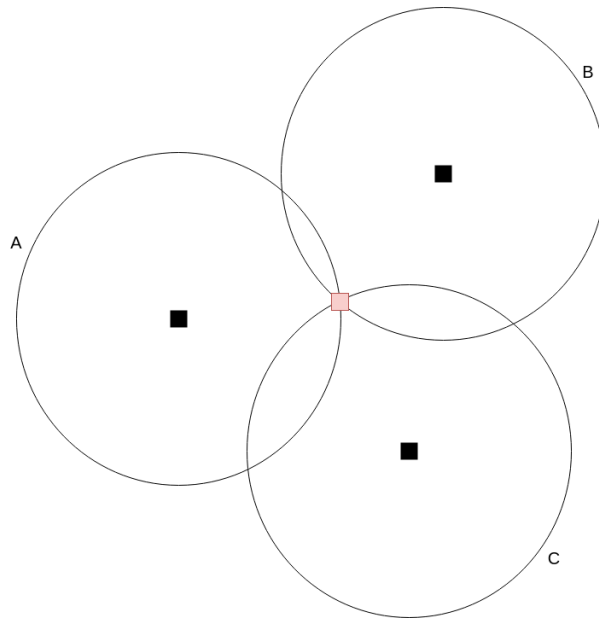
Figure 2.1: An example of trilateration using three anchors

The issue with this approach is that the measurements are not perfect, which might cause the circles to not intersect at exactly one point which will make the positional data seem to jitter.

2.1.2 Using UWB

To find the position of the tags Pozyx makes use of radio waves. Radio waves travel at the speed of light, so by dividing the time of travel between anchors with the speed of light, the distance between them can be found. Because the speed of light is so fast the time measure needs to be very accurate to get the correct distance. To achieve this the anchors make use of ultra-wide bandwidth (UWB) [2]. The ultra-wideband signals that the Pozyx devices utilize has a bandwidth of 500 MHz. This makes the wavelength very short and by detecting the peak of a narrow "pulse", an accurate time can be found. High bandwidth means faster data transfer, which most people would prefer, but if everyone were to use the same frequency the signals would interfere with each other, therefore the use of high-frequency signals is tightly regulated. Pozyx can use 500 MHz because it transmits at very low power.

2.1.3 Two-way-ranging

We are using the Pozyx Creator Kit Lite which uses the Two-way-ranging (TWR) protocol for positioning [3]. A tag calculates its position by communicating with the anchors one by one, getting the distance from the anchor to itself. Once it has the distance from 3 anchors it can compute its position utilizing trilateration.
If multiple tags are being used at once, one tag is made the master tag and the other

tags become the slave tags. The master tag instructs the slave tags to report their position to the master tag one by one. The master tag is then usually connected to a computer that can use the position data. This technique does not scale well as all the slave tags have to be within the radio range of the master tag so spreading them across huge areas is not possible. Instead of a tag being the master it is possible to use an anchor. This makes it easier to have a computer attached, as the anchors are stationary, unlike the tags.

2.2 Unity introduction

As defined in FUK, this project aims to create a team-building augmented reality game. This means the project has to have a game component - an application to display the objectives of the game, the play area and the players. To create this, a game engine can be used, such as `Unity`. A game engine is a piece of software that provides creators with the necessary set of features to build games quickly and efficiently[6]. This means that a game engine is a collection of reusable components, abstracted away from the game developer. This can include tools to help with, for example, graphics, physics, networking or audio. These tools would expose certain functionality to a developer to make use of, and hide the specific implementation details for that functionality, ensuring the developer can focus on more pressing issues. Unity supports the C# language for development[4].

Add ref to project idea section

The Unity game engine supports development for different game platforms. Of particular interest to this project is the support for both `Android` and `iOS` devices, as well as `Google Cardboard`[5]. We chose to use Unity for the development of the game aspect of this project. This facilitates that a greater amount of time can be spent on the other aspects of the project rather than the low-level details of game development, and it allows for easier inclusion of multiple platforms.

Chapter 3

Sprint 2

Chapter 4

Sprint 3

Chapter 5

Sprint 4

Chapter 6

Appendix

Bibliography

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[5]   Unity Technologies. URL: https://unity3d.com/unity/features/multiplatform (visited on 02/13/2019).

[6]   Unity Technologies. *Game engines - how do they work?* URL: https://unity3d.com/what-is-a-game-engine (visited on 02/13/2019).

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