

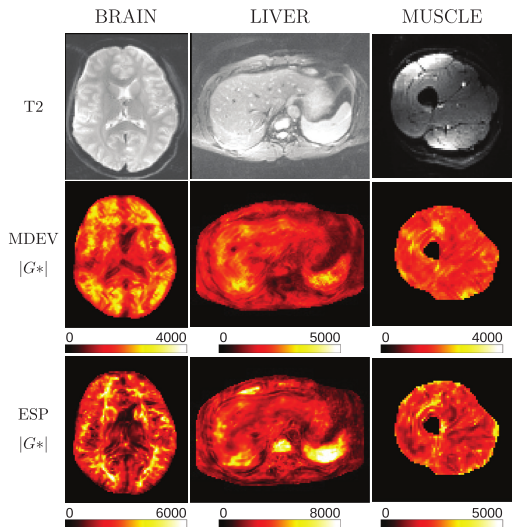
# MRE Reconstruction: Inverting the wave equation

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- 1 Why we need MRE
- 2 Data Reconstruction and current Problems



**Fig. 9.** Comparison of  $|G^*|$  and  $\varphi$  maps using the MDEV and ESP pipelines. All values are in Pascals.

- ▶ diseased tissue changes mechanical

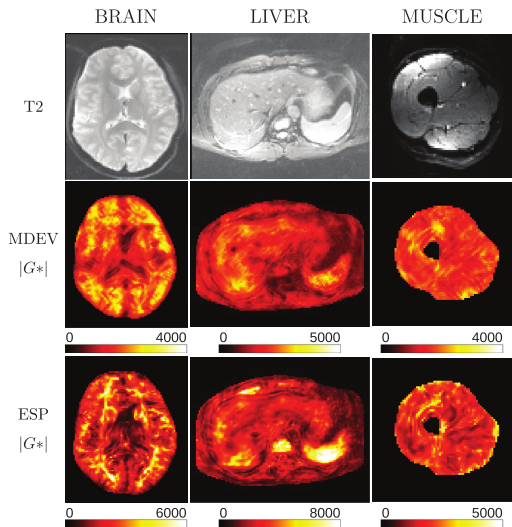


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- ▶ diseased tissue changes mechanical
- ▶ low tech: palpation

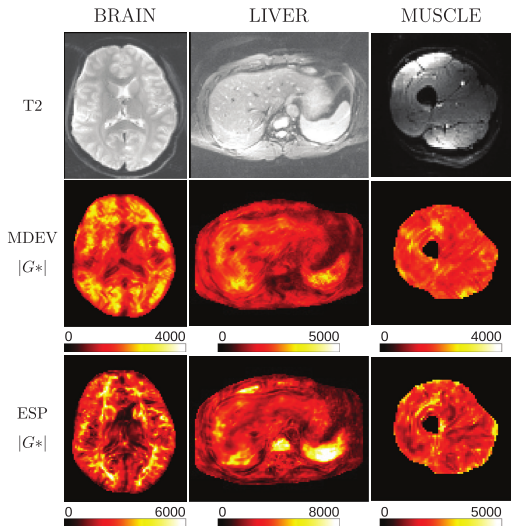


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# Why do we need MRE?

E. Barnhill et al./Medical Image Analysis 35 (2017) 133–145

- ▶ diseased tissue changes mechanical
- ▶ low tech: palpation
- ▶ higher tech: ultrasound

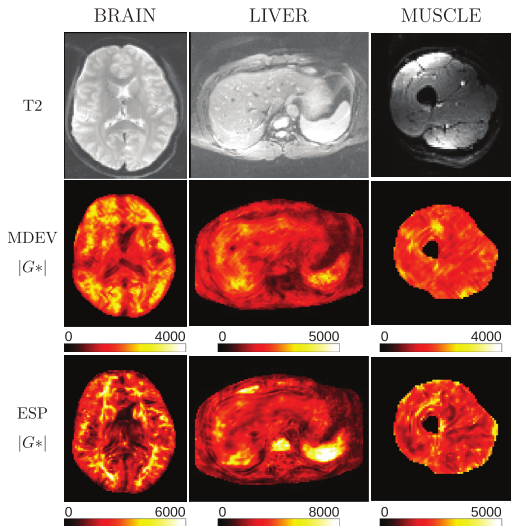


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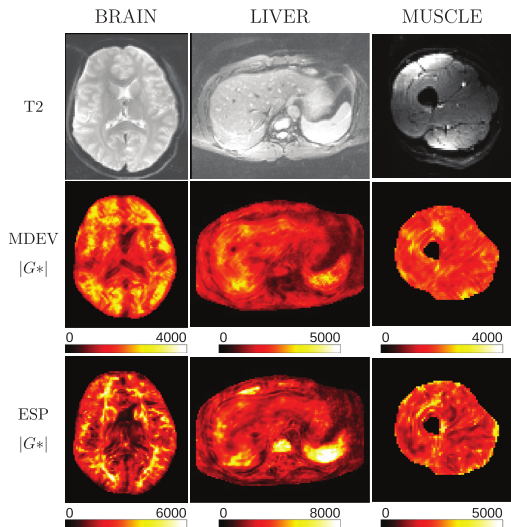


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# Why do we need MRE?

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- ▶ diseased tissue changes mechanical
- ▶ low tech: palpation
- ▶ higher tech: ultrasound
- ▶ highest tech: MRE
- ▶ for deep tissue and brains, but non-invasive

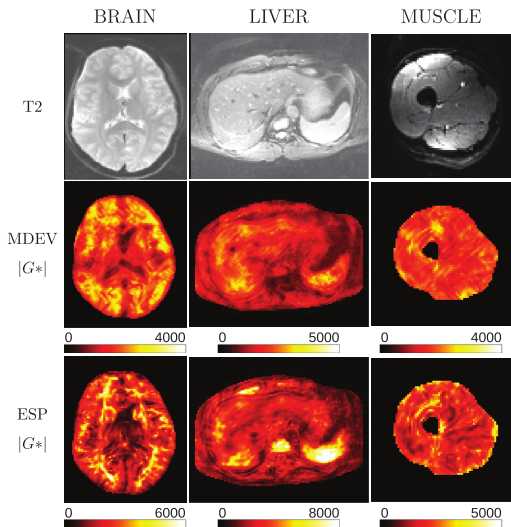
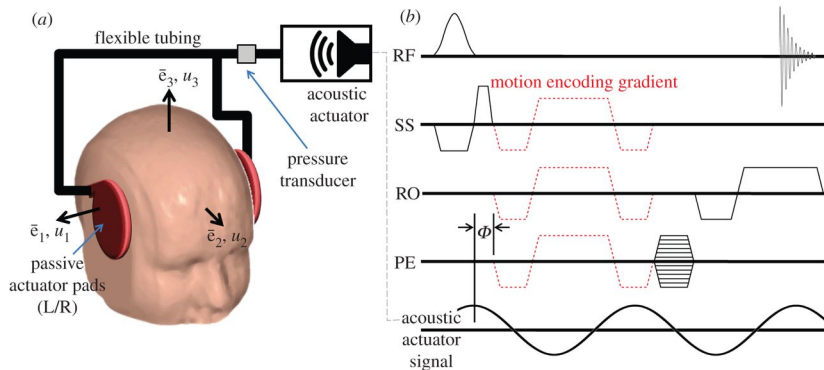


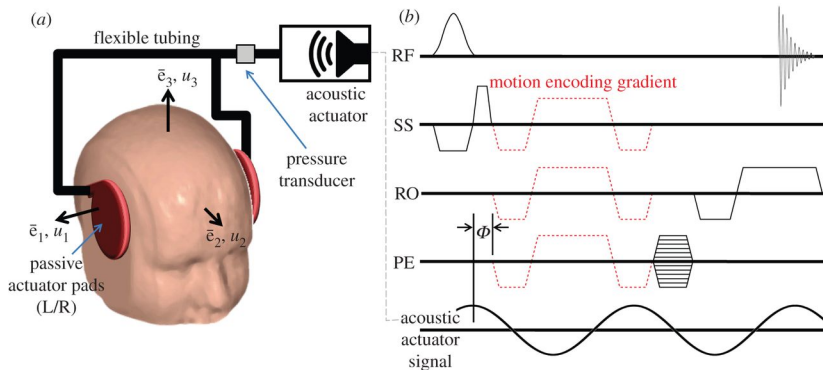
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# How does the measuring process work

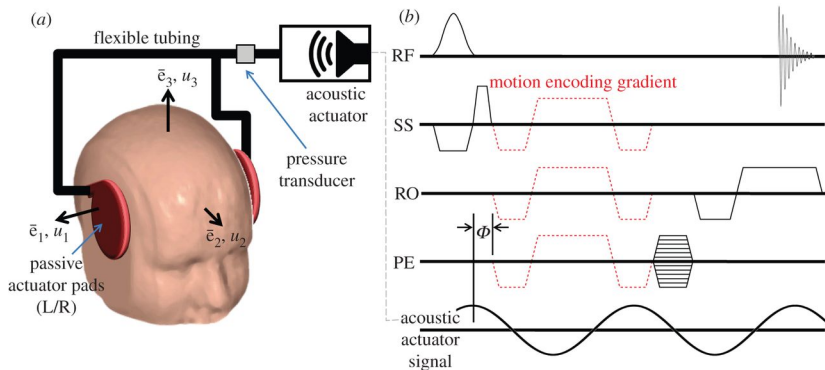


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- ▶ 3 spatial directions  $\times$  8 time steps  $\times$  3 frequencies
- ▶ 72 times longer per pixel than MRI

$$\mathbf{u} = \mathbf{u}(\mathbf{x}t)$$

$$\mu =$$

$$\sum_j \partial_j (\mu (\partial_j u_i + \partial_i u_j)) + \partial_i (\lambda \partial_j u_j) = \rho \ddot{u}_i$$

- ▶ differential equation  $\rightarrow$  inverse problem
- ▶ Problem underdetermined, we need boundary values
- ▶ Problem: some regions are close to nodes  $\rightarrow$  no movement
- ▶ Solution: Multi frequency inversion
- ▶ Problem: Need to reconstruct the derivatives
- ▶ motion encoding gradient
- ▶ MRI measurement in 3 spatial directions and 8 time steps
- ▶ MRI measurement in 3 spatial directions and 8 time steps and 3 frequencies  $\rightarrow$  72 times MRI overhead
- ▶  $\rightarrow$  reduced resolution
- ▶ Problem: Need to reconstruct the derivatives
- ▶ slight noise can lead to totally wrong derivatives  $\rightarrow$  inversion is useless
- ▶ MRI measurement in 3 spatial directions and 8 time steps

- ▶ Do simulations in 1d: wavelets
- ▶ Do simulations in 2d: wavelets, shearlets
- ▶
- ▶ Problem: Need to reconstruct the derivatives
- ▶ slight noise can lead to totally wrong derivatives  $-i$  inversion is useless
- ▶ MRI measurement in 3 spatial directions and 8 time steps  $-i$

- ▶ Have better resolution of the stiffness map
- ▶ Have clinically useful values, at the moment to varying
- ▶ Have shorter acquisition times per pixel
- ▶ Problem: Need to reconstruct the derivatives
- ▶ slight noise can lead to totally wrong derivatives  $-\dot{\chi}$  inversion is useless
- ▶ MRI measurement in 3 spatial directions and 8 time steps  $-\dot{\chi}$