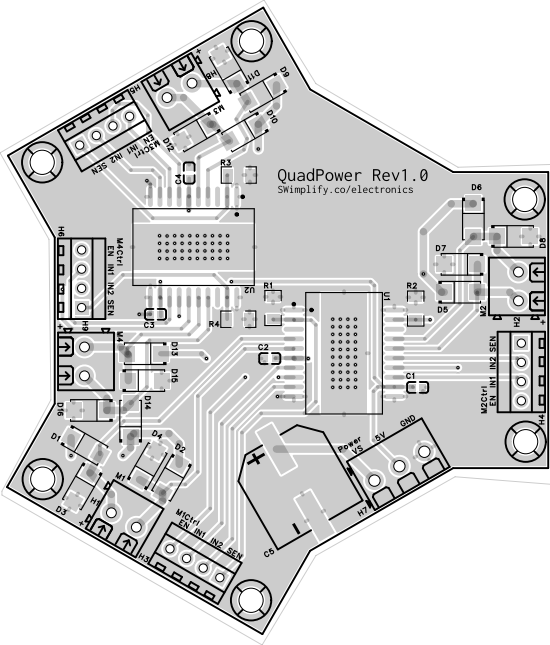
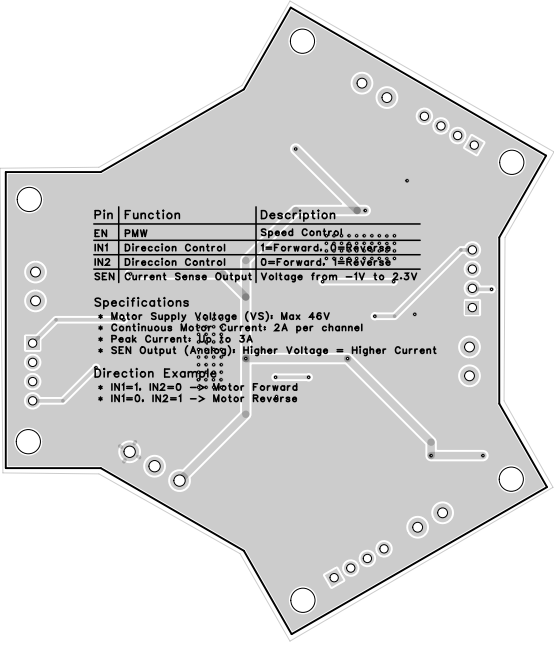


QuadPower Rev1.0

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Pin	Function	Description
EN	PMW	Speed Control
IN1	Direction Control	1=Forward, 0=Reverse
IN2	Direction Control	0=Forward, 1=Reverse
SEN	Current Sense Output	Voltage from -1V to 2.3V

Specifications

- * Motor Supply Voltage (VS): Max 46V
- * Continuous Motor Current: 2A per channel
- * Peak Current: 16 to 3A
- * SEN Output (Analog): Higher Voltage = Higher Current

Direction Example:

- * IN1=1, IN2=0 -> Motor Forward
- * IN1=0, IN2=1 -> Motor Reverse

