

# Module Interface Specification for Software Engineering

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# 1 Revision History

Date	Version	Notes
11/13/2025	1.0	Draft Rev Minus 1
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## 2 Symbols, Abbreviations and Acronyms

See SRS Documentation at <https://github.com/SY3141/RLCatan>.

# Contents

### 3 Introduction

The following document details the Module Interface Specifications for our project RLCatan. This project aims to create a competent reinforcement learning AI agent designed to master the board game Settlers of Catan through autonomous self-play training. The AI will use deep reinforcement learning algorithms to learn optimal decision-making strategies across several game states including resource management, territory expansion and adaptive responses to opponent actions.

Complementary documents include the System Requirement Specifications and Module Guide. The full documentation and implementation can be found at <https://github.com/SY3141/RLCatan>.

### 4 Notation

The structure of the MIS for modules comes from ?, with the addition that template modules have been adapted from ?. The mathematical notation comes from Chapter 3 of ?. For instance, the symbol  $::=$  is used for a multiple assignment statement and conditional rules follow the form  $(c_1 \Rightarrow r_1 | c_2 \Rightarrow r_2 | \dots | c_n \Rightarrow r_n)$ .

The following table summarizes the primitive data types used by Software Engineering.

Type/Symbol	Notation	Annotations
boolean	$\mathbb{B}$	
character	char	
integer	$\mathbb{Z}$	
natural number	$\mathbb{N}$	
real	$\mathbb{R}$	
string	$\Sigma^*$	
sequence	seq of T	
tuple	$(T_1, T_2, \dots)$	a finite, ordered collection of elements
dictionary	dict	a collection of key-value pairs
function	$T_1 \rightarrow T_2$	a function mapping inputs to outputs
true	$\top$	
false / null	$\perp$	the boolean value for false, or null

In addition, Software Engineering uses abstract data types (e.g., `FrameData`, `GameStateData`, `AIMove`) which are defined by their use in the modules that hide their implementation details. Local functions are described by giving their type signature followed by their specification.

## 5 Module Decomposition

The following table is taken directly from the Module Guide document for this project.

Level 1
Hardware-Hiding Module
Behaviour-Hiding Module
Software Decision Module



## 6 MIS of Hardware-Hiding Module

### 6.1 Module

Hardware-Hiding Module (M1)

### 6.2 Uses

- **FrameData (Data Type):** Represents the raw image data captured from the camera or a simulated source.
- **HardwareInitError, CaptureError, HardwareShutdownError (Exception Types):** Indicate errors that may occur during hardware initialization, frame capture, or shutdown processes.

### 6.3 Syntax

#### 6.3.1 Exported Constants

- **CAMERA\_RESOLUTION:** tuple of  $(\mathbb{Z}, \mathbb{Z})$  - width and height of captured frames
- **FRAME\_RATE:**  $\mathbb{R}$  - frames per second captured by the hardware layer

#### 6.3.2 Exported Access Programs

Name	In	Out
initializeHardware	-	$\mathbb{B}$
captureFrame	-	FrameData
shutdownHardware	-	$\mathbb{B}$
isInitialized	-	$\mathbb{B}$

### 6.4 Semantics

#### 6.4.1 State Variables

- **hardwareStatus:**  $\mathbb{B}$   
Indicates whether the hardware subsystem has been successfully initialized.
- **frameBuffer:** FrameData  
Stores the most recent frame captured from the camera.

#### 6.4.2 Environment Variables

- **CameraDevice:** external hardware input for image capture
- **DisplayInterface:** external interface for visualization

### 6.4.3 Assumptions

- The CameraDevice is available and functional within the operating environment.
- Calling modules will invoke `isInitialized()` before executing `captureFrame()` or `shutdownHardware()`.

### 6.4.4 Access Routine Semantics

`initializeHardware()`:

- transition: Attempts connection to CameraDevice. If successful: `hardwareStatus` :=  $\top$ .
- output: Returns initialization success status:  $\mathbb{B}$
- exception: raises `HardwareInitError` if initialization fails.

`captureFrame()`:

- transition: Reads a new frame from CameraDevice into `frameBuffer`.
- output: Returns the current `frameBuffer` of type FrameData.
- exception: raises `CaptureError` if `hardwareStatus` =  $\perp$  or frame capture fails.

`shutdownHardware()`:

- transition: Releases device resources and sets `hardwareStatus` :=  $\perp$ .
- output: Returns shutdown success status:  $\mathbb{B}$
- exception: raises `HardwareShutdownError` if hardware cleanup fails.

`isInitialized()`:

- transition: -
- output: returns `hardwareStatus`:  $\mathbb{B}$
- exception: -

### 6.4.5 Local Functions

- `checkDeviceConnection()`: verifies device presence
- `allocateBufferMemory()`: allocates buffer for captured frames
- `releaseResources()`: frees hardware-related resources

# 7 MIS of Computer Vision Module

## 7.1 Module

Computer Vision Module (M2)

## 7.2 Uses

- **M1.captureFrame()**: Provides a single frame of image data from the hardware or simulated camera.
- **FrameData (Data Type)**: Represents the raw image frame used for analysis.
- **GameStateData (Data Type)**: Abstract representation of detected game state.
- **ProcessingError, DetectionError (Exception Types)**: Raised during processing or detection failures.
- **seq of Elements, dict (Derived Data Types)**: Sequences and mappings used to store detected features and confidence metrics.

## 7.3 Syntax

### 7.3.1 Exported Constants

- DETECTION\_THRESHOLD:  $\mathbb{R}$  - minimum required confidence for object recognition
- MODEL\_PATH:  $\Sigma^*$  - file system path to trained CV model

### 7.3.2 Exported Access Programs

Name	In
processFrame	frame:FrameData
detectBoardElements	frame:FrameData
getConfidenceMetrics	-

## 7.4 Semantics

### 7.4.1 State Variables

- **lastFrame**: FrameData  
Stores the most recent processed frame.
- **lastConfidence**: dict  
A mapping from element identifiers ( $\Sigma^*$ ) to confidence scores ( $\mathbb{R}$ ).

#### 7.4.2 Environment Variables

None.

#### 7.4.3 Assumptions

- All `FrameData` inputs are valid and camera-calibrated.
- The model at `MODEL_PATH` is present and loaded into memory before use.

#### 7.4.4 Access Routine Semantics

`processFrame(frame):`

- transition: Executes the full CV pipeline on *frame*; updates `lastFrame := frame`.
- output: Returns detected game state as `GameStateData`.
- exception: raises `ProcessingError` if any stage of the pipeline fails.

`detectBoardElements(frame):`

- transition: Runs object detection model on *frame*; updates `lastFrame := frame` and updates `lastConfidence`.
- output: Returns *seq* of detected Elements.
- exception: raises `DetectionError` if detection fails.

`getConfidenceMetrics():`

- transition: -
- output: Returns the `lastConfidence` mapping (a dict from  $\Sigma^*$  to  $\mathbb{R}$ ).
- exception: -

#### 7.4.5 Local Functions

- `calibrateCamera()`: Corrects lens distortion in input frames.
- `filterNoise()`: Removes low-confidence or spurious detections.
- `parseElementsToState()`: Converts detected Elements into `GameStateData`.

## 8 MIS of User Interface Module

### 8.1 Module

User Interface (M3)

## 8.2 Uses

- **GameStateData**: Abstract representation of the current game state.
- **AIMove**: Encoded AI-generated move.
- **seq of Corrections**: A sequence of user-provided corrections to the game state.
- **RenderError**: Exception raised when visualization or rendering fails.

## 8.3 Syntax

### 8.3.1 Exported Constants

- **REFRESH\_RATE**:  $\mathbb{R}$  - frequency of UI updates (Hz)

### 8.3.2 Exported Access Programs

Name	In
renderBoard	state:GameStateData
displayAIMove	move:AIMove
getUserCorrections	-

## 8.4 Semantics

### 8.4.1 State Variables

- **uiState**: Abstract UI representation (type unspecified, internal)
- **correctionQueue**: seq of Corrections    A sequence of user-provided corrections where each correction may include:
  - element identifier:  $\Sigma^*$
  - correction value: arbitrary derived type

### 8.4.2 Environment Variables

- **window**: graphical display device managed by the environment

### 8.4.3 Assumptions

- The **window** device is functional and compatible with the UI rendering framework.
- User interactions are delivered to the system via environment-level event handling.

#### 8.4.4 Access Routine Semantics

renderBoard(state):

- transition: Updates `uiState` := graphical representation of `state`; renders `uiState` onto `window`.
- output: -
- exception: raises `RenderError` if rendering fails.

displayAIMove(move):

- transition: Updates `uiState` to include the visualization of `move`; refreshes `window`.
- output: -
- exception: -

getUserCorrections():

- transition: `tmp` := `correctionQueue`; `correctionQueue` := empty sequence.
- output: Returns `tmp`: seq of Corrections.
- exception: -

#### 8.4.5 Local Functions

- `updateDOM()`: Updates internal UI representation elements.
- `highlightElements()`: Highlights tiles, pieces, or game move indicators.
- `onUserInput()`: Adds user-generated corrections to `correctionQueue`.

## 9 MIS of Game State Manager Module

### 9.1 Module

Game State Manager (M4)

### 9.2 Uses

- **MoveData**: Represents the details of a player's move, including action type and parameters.
- **GameStateData**: Abstract representation of the complete game state.
- **InvalidMoveError**: Raised when an illegal move is applied.
- **M7.writeState()**: Persists updated game state to storage.

## 9.3 Syntax

### 9.3.1 Exported Constants

- MAX\_PLAYERS:  $\mathbb{Z} = 4$

### 9.3.2 Exported Access Programs

Name	In
updateState	move:MoveData
getState	-
validateMove	move:MoveData

## 9.4 Semantics

### 9.4.1 State Variables

- `currentGameState`: GameStateData  
The full internal representation of the game board.
- `playerAssets`: dict  
Mapping from player identifiers ( $\Sigma^*$ ) to their resource, structure, and score information.  
Each value may include:
  - resources: dict from resource type ( $\Sigma^*$ ) to quantity ( $\mathbb{Z}$ )
  - structures: seq of structure types
  - score:  $\mathbb{Z}$

### 9.4.2 Environment Variables

None.

### 9.4.3 Assumptions

- All instances of `MoveData` conform to the expected internal format.
- Calling modules will evaluate `validateMove(move)` before invoking `updateState(move)`.

### 9.4.4 Access Routine Semantics

`updateState(move)`:

- transition:

$$(\text{validateMove}(move) = \top \Rightarrow \text{currentGameState} := \text{applyMove}(move) | \text{validateMove}(move) = \perp \Rightarrow \text{currentGameState} := \text{currentGameState})$$

- output: -
- exception: raises `InvalidMoveError` if `validateMove(move) = ⊥`.

`getState()`:

- transition: -
- output: Returns a copy of `currentGameState`: `GameStateData`.
- exception: -

`validateMove(move)`:

- transition: -
- output:  $\mathbb{B} - \top$  iff *move* is valid according to Catan rules and the current values of `currentGameState` and `playerAssets`.
- exception: -

#### 9.4.5 Local Functions

- `calculateResources()`: Computes resource changes resulting from a move.
- `updateScores()`: Updates player score values based on new state.
- `checkVictory()`: Determines whether any player meets winning conditions.

## 10 MIS of Reinforcement Learning Environment Module

### 10.1 Module

Reinforcement Learning Environment (M5)

### 10.2 Uses

- **M4**: Uses the access programs `updateState`, `getState`, and `validateMove`.
- **AIMove**: Encoded AI-selected action.
- **GameStateData**: Abstract representation of a full game state.
- **Reward**: A real-valued score,  $\mathbb{R}$ .
- **StepError, RenderError**: Exceptions raised on invalid steps or rendering failures.

## 10.3 Syntax

### 10.3.1 Exported Constants

- MAX\_TURNS:  $\mathbb{Z}$  - maximum number of turns in an episode
- REWARD\_SCALE:  $\mathbb{R}$  - scaling factor applied to reward calculation

### 10.3.2 Exported Access Programs

Name	In	
step	action:AIMove	(Ga)
reset	-	-
render	-	-

## 10.4 Semantics

### 10.4.1 State Variables

- simulatedState: internal instance of M4  
Maintains the environment's evolving game state.
- turnCount:  $\mathbb{Z}$   
Number of turns elapsed in the current episode.

### 10.4.2 Environment Variables

- display: Rendering surface or graphical context used to visualize simulatedState.

### 10.4.3 Assumptions

- All inputs of type AIMove are syntactically valid.
- The environment is responsible for handling opponent moves internally.

### 10.4.4 Access Routine Semantics

step(action):

- transition: The state change is governed by the rule:

$$(\text{validateMove}(\text{action}) = \top \Rightarrow \text{apply actions} | \text{validateMove}(\text{action}) = \perp \Rightarrow -)$$

The "apply actions" transition includes the following sequential operations:

1. Apply action to simulatedState via updateState(action).

- 2. Apply `applyOpponentLogic()` to simulate adversarial moves.
- 3. `turnCount := turnCount + 1.`
- output: Returns the tuple (`simulatedState.getState()`, `calculateReward()`) of type (`GameStateData`,  $\mathbb{R}$ ).
- exception: raises `StepError` if `validateMove(action) = \perp`.

`reset():`

- transition: `simulatedState :=` new initial game state (via M4). `turnCount := 0.`
- output: Returns initial game state: `GameStateData`.
- exception: -

`render():`

- transition: Updates the `display` device to visualize the current `simulatedState`.
- output: -
- exception: raises `RenderError` if display rendering fails.

#### 10.4.5 Local Functions

- `applyOpponentLogic()`: Generates and applies opponent actions based on heuristics or baseline policies.
- `calculateReward()`: Returns a reward value in  $\mathbb{R}$  based on changes in `simulatedState`, scaled by `REWARD_SCALE`.

## 11 MIS of AI Model Module

### 11.1 Module

AI Model (M6)

### 11.2 Uses

- **GameStateData**: Abstract representation of the game state.
- **AIMove**: Encoded move predicted by the model.
- **PredictionError**: Exception raised when the model cannot generate a valid move.

## 11.3 Syntax

### 11.3.1 Exported Constants

- MODEL\_PATH:  $\Sigma^*$  - file path to stored model weights.

### 11.3.2 Exported Access Programs

Name	In
decide	state:GameStateData
getMoveConfidence	move:AIMove
explainMove	move:AIMove

## 11.4 Semantics

### 11.4.1 State Variables

- modelWeights: internal representation of learned parameters (vector or tensor values in  $\mathbb{R}$  or  $\mathbb{R}^n$ ).
- policyNetwork: An abstract data structure representing the architecture and layers of the DRL model, initialized using MODEL\_PATH.
- lastPredictionCache: dict mapping AIMove  $\rightarrow \mathbb{R}$  storing confidence values for the most recent decision.

### 11.4.2 Environment Variables

None.

### 11.4.3 Assumptions

- The input GameStateData conforms to the expected internal structure.
- MODEL\_PATH correctly references initialized modelWeights.

### 11.4.4 Access Routine Semantics

decide(state):

- transition:
  - Converts *state* using preprocessState().
  - Evaluates result by calling evaluatePolicy().
  - Updates lastPredictionCache with move-confidence pairs.

- **output:** Returns the optimal AIMove predicted by the model.
- **exception:** raises `PredictionError` if the model evaluation fails or produces an empty distribution.

`getMoveConfidence(move):`

- **transition:** -
- **output:** Returns  $\mathbb{R}$  - the confidence score associated with *move* retrieved from `lastPredictionCache`.
- **exception:** -

`explainMove(move):`

- **transition:** -
- **output:** Returns  $\Sigma^*$  - a human-readable textual explanation of the rationale behind selecting *move* (e.g., feature contributions or decision breakdown).
- **exception:** -

#### 11.4.5 Local Functions

- `preprocessState()`: Converts GameStateData into an abstract processed representation suitable for model inference.
- `postprocessOutput()`: Converts model policy output into a structured AIMove.
- `evaluatePolicy()`: ProcessedState → dist(AIMove)
  - **Output:** Returns a probability distribution over possible moves by applying the `policyNetwork` data structure and `modelWeights` to the input state.

## 12 MIS of Game State Database Module

### 12.1 Module

Game State Database (M7)

### 12.2 Uses

- **GameStateData:** Abstract representation of a game state.
- **DBWriteError:** Exception raised on failed write operations.
- **DBReadError:** Exception raised on failed read or query operations.
- **seq(GameStateData):** Ordered collection of game states.

## 12.3 Syntax

### 12.3.1 Exported Constants

- DB\_PATH:  $\Sigma^*$  - file system path or database URI.
- MAX\_ENTRIES:  $\mathbb{Z}$  - maximum number of stored states.

### 12.3.2 Exported Access Programs

Name	In
writeState	state:GameStateData
readState	gameID: $\Sigma^*$
queryHistory	playerID: $\Sigma^*$

## 12.4 Semantics

### 12.4.1 State Variables

- dbConnection: Active connection handle to the database (abstract type).
- gameRecords: dict mapping  $\Sigma^* \rightarrow$  GameStateData (cache of recently accessed or frequently used game states).

### 12.4.2 Environment Variables

- database: External file system or DB server located at DB\_PATH.

### 12.4.3 Assumptions

- The database at DB\_PATH is reachable and adheres to the expected schema.
- Identifiers such as gameID and playerID are valid  $\Sigma^*$  strings.

### 12.4.4 Access Routine Semantics

writeState(state):

- transition:
  - Converts *state* to a serializable format via `serializeState()`.
  - Writes serialized data to `database`.
  - Updates `gameRecords` cache if applicable.
- output: -

- exception: raises `DBWriteError` if the write operation fails.

`readState(gameID):`

- transition:
  - If *gameID* is cached, return entry from `gameRecords`.
  - Else, load corresponding data from `database`.
  - Deserialize via `deserializeState()`.
  - Update `gameRecords`.
- output: `GameStateData` corresponding to the given *gameID*.
- exception: raises `DBReadError` if no entry exists for *gameID* or if read fails.

`queryHistory(playerID):`

- transition:
  - Queries `database` for all entries linked to *playerID*.
  - Converts results to `seq(GameStateData)` via `deserializeState()`.
- output: `seq(GameStateData)` containing all states associated with *playerID*.
- exception: raises `DBReadError` if the query fails.

#### 12.4.5 Local Functions

- `serializeState()`: Converts `GameStateData` into a serializable representation.
- `deserializeState()`: Converts stored representation back to `GameStateData`.
- `openConnection()`: Initializes `dbConnection`.
- `closeConnection()`: Terminates `dbConnection`.

## 13 MIS of Image Queue Module

### 13.1 Module

Image Queue (M8)

## 13.2 Uses

- **FrameData**: Abstract representation of an image frame from the camera or simulation.
- **QueueFullError**: Exception raised when attempting to enqueue a frame into a full queue.
- **QueueEmptyError**: Exception raised when attempting to dequeue or peek from an empty queue.

## 13.3 Syntax

### 13.3.1 Exported Constants

- `QUEUE_SIZE`  $\in \mathbb{Z}^+$  - maximum number of frames in the buffer.

### 13.3.2 Exported Access Programs

Name	In	Out
enqueue	frame:FrameData	
dequeue	-	FrameData
peek	-	FrameData
isFull	-	
isEmpty	-	

## 13.4 Semantics

### 13.4.1 State Variables

- `queueBuffer` :  $[0..QUEUE\_SIZE - 1] \rightarrow \text{FrameData} \cup \{\perp\}$  - circular buffer storing frames.
- `head` :  $\mathbb{Z}$  - index of the front of the queue.
- `tail` :  $\mathbb{Z}$  - index of the end of the queue.
- `size` :  $\mathbb{Z}$  - current number of frames in the queue.

### 13.4.2 Environment Variables

None.

### 13.4.3 Assumptions

- Calling modules will check `isFull()` before `enqueue()`.
- Calling modules will check `isEmpty()` before `dequeue()` or `peek()`.

### 13.4.4 Access Routine Semantics

`enqueue(frame: FrameData):`

- transition:

`queueBuffer[tail] := frame, tail := (tail + 1) mod QUEUE_SIZE, size := size + 1`

- output: -
- exception: raises `QueueFullError` if `isFull() = T`.

`dequeue():`

- transition: `frame := queueBuffer[head]; queueBuffer[head] := ⊥; head := (head+1) mod QUEUE_SIZE; size := size-1`
- output: `frame`
- exception: `QueueEmptyError` if `isEmpty() = T`

`peek():`

- transition: -
- output: `queueBuffer[head]`
- exception: raises `QueueEmptyError` if `isEmpty() = T`.

`isFull():`

- transition: -
- output: `T` if `size = QUEUE_SIZE`, `⊥` otherwise
- exception: -

`isEmpty():`

- transition: -
- output: `T` if `size = 0`, `⊥` otherwise
- exception: -

### 13.4.5 Local Functions

- **resetQueue()**:

$\text{head} := 0, \quad \text{tail} := 0, \quad \text{size} := 0$

Resets the queue to an empty state.

### 13.4.6 Formalization

Let the state of this module be the tuple

$$S = (\text{queueBuffer}, \text{head}, \text{tail}, \text{size}).$$

**State Invariants** (must hold in all reachable states):

- $0 \leq \text{size} \leq \text{QUEUE\_SIZE}$
- $\text{head} \in [0..\text{QUEUE\_SIZE} - 1] \wedge \text{tail} \in [0..\text{QUEUE\_SIZE} - 1]$
- $\text{isEmpty}() = \top \iff \text{size} = 0$
- $\text{isFull}() = \top \iff \text{size} = \text{QUEUE\_SIZE}$

**enqueue(frame: FrameData)**   *Defined when isFull() = ⊥*

$$\text{head}' = \text{head}$$

$$\begin{aligned} \text{queueBuffer}'[\text{tail}] &= \text{frame} \wedge \text{tail}' = (\text{tail} + 1) \bmod \text{QUEUE\_SIZE} \wedge \text{size}' = \text{size} + 1 \\ \forall i \in [0..\text{QUEUE\_SIZE} - 1], i \neq \text{tail} &\Rightarrow \text{queueBuffer}'[i] = \text{queueBuffer}[i] \end{aligned}$$

**dequeue()**   *Defined when isEmpty() = ⊥, output is frame*

$$\text{frame} = \text{queueBuffer}[\text{head}]$$

$$\text{tail}' = \text{tail}$$

$$\begin{aligned} \text{queueBuffer}'[\text{head}] &= \perp \wedge \text{head}' = (\text{head} + 1) \bmod \text{QUEUE\_SIZE} \wedge \text{size}' = \text{size} - 1 \\ \forall i \in [0..\text{QUEUE\_SIZE} - 1], i \neq \text{head} &\Rightarrow \text{queueBuffer}'[i] = \text{queueBuffer}[i] \end{aligned}$$

**peek()**   *Defined when isEmpty() = ⊥, output is frame*

$$\text{frame} = \text{queueBuffer}[\text{head}]$$

$$\text{queueBuffer}' = \text{queueBuffer} \wedge \text{head}' = \text{head} \wedge \text{tail}' = \text{tail} \wedge \text{size}' = \text{size}$$

**resetQueue()**

$$\text{head}' = 0 \wedge \text{tail}' = 0 \wedge \text{size}' = 0 \wedge \text{queueBuffer}' = \text{queueBuffer}$$

## 14 Appendix

## Appendix - Reflection

1. What went well while writing this deliverable?

[Group] Our team collaborated effectively, dividing sections based on what each member was most familiar with. Rebecca and Matthew focused on the MIS and MG since they had the most experience with these documents from before. While Sunny and Jake focused on the Software during this time.

2. What pain points did you experience during this deliverable, and how did you resolve them?

[Group] One challenge we faced was ensuring consistency across the documents and ensuring our modules were decoupled enough. We resolved this by having multiple review sessions where we cross-checked each other's sections and provided feedback. This iterative process helped us create modules that were well defined and cohesive.

3. Which of your design decisions stemmed from speaking to your client(s) or a proxy (e.g. your peers, stakeholders, potential users)? For those that were not, why, and where did they come from?

[Group] A lot of our design decisions were influenced by discussions with our supervisor who provided insights into the software architecture of RL environments. We also consulted with peers who had experience in computer vision to refine our CV module design. Some decisions, like the choice of data structures, were based on our own research and understanding of best practices in software design.

4. While creating the design doc, what parts of your other documents (e.g. requirements, hazard analysis, etc), if any, needed to be changed, and why? unlimited resources, what could you do to make the project better? (LO\_ProbSolutions)

[Group] While developing the design document, several updates were required in our earlier project artifacts, particularly the hazard analysis and system requirements.

The most significant change came from refining our system architecture. During hazard analysis we originally treated the digital twin as a simple board state representation. However, while writing the design document we clarified that the digital twin must represent not only the board layout, but also the full game state, player actions, and system input and output interactions. Because of this expanded definition, multiple hazards had to be revised. Risks that were previously limited to incorrect board modeling were broadened to include incorrect state synchronization, input misinterpretation, and output decision errors. This led to updated mitigation strategies, such as stronger state validation checks and clearer interface boundaries between the AI agent and the game environment.

Our requirements document also changed. Some functional requirements were rewritten to reflect that the system must track and process full game context. Interface

requirements became more detailed to define how the model, simulation environment, and data storage components communicate.

These revisions improved consistency across documents and ensured the design accurately reflected the true scope and risks of the system.

With additional resources, we would rent more GPUs to run parallel training jobs, allowing faster experimentation and more extensive model tuning. We would also pay for access to online Catan game history databases to expand our training data and improve model performance and generalization.

5. Give a brief overview of other design solutions you considered. What are the benefits and tradeoffs of those other designs compared with the chosen design? From all the potential options, why did you select the documented design? (LO\_Explores)

[Group] We explored several alternative design approaches before selecting our final solution. One option was a simpler rule based system that relied on handcrafted heuristics rather than a learning model. The main benefit of this approach was predictability and lower computational cost, as it would not require long training times or large datasets. However, the tradeoff was limited adaptability and weaker performance in complex or unexpected game situations, since the system could only act within predefined rules.

6. (After you have implemented another team’s module, which means this isn’t filled in until after the original deadline). What did you learn by implementing another team’s module? Were all the details you needed in the documentation, or did you need to make assumptions, or ask the other team questions? If your team also had another team implement one of your modules, what was this experience like? Are there things in your documentation you could have changed to make the process go more smoothly for when an “outsider” completes some of the implementation?

[Group] Implementing the assigned team’s module was a significant learning experience in API design. While their `src/reporting_poc README.md` outlined the general API surface, it lacked concrete request/response payloads, formal error codes, and a runnable test. This documentation gap forced us to move forward based on assumptions and manual follow-up questions rather than clear technical specifications. We forked their repository and opened a pull request to merge our code, intentionally seeking their review comments to validate our integration. We noted that because a PR-driven workflow wasn’t used by the team, we missed out on automated CI/CD feedback, which made validating our integration assumptions more difficult. Moving forward, we’ve realized that truly exceptional modules must include explicit authorization contracts, a short integration checklist, and a tiny runnable test or CI workflow. This ensures that any implementer has a clear source of truth to reproduce expected behavior without needing to ask targeted questions.