



Chapter 5

Backtracking

단계적으로 선택을 해나가다가 조건이 만족되지 않으면 이전 상태로 복귀하여 남은 것 중에 선택을 해나간다.

Worst case time complexity는 나쁘지만
average case time complexity는 효율적이다.

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Backtracking

- ✓ A typical example
 - ✓ The maze of hedges by Hampton Court Palace
 - ✓ The maze of Micro-mouse
- ✓ Applicable problems
 - ✓ The solution is a sequence of objects satisfying some criterion.
- ✓ General approach
 - ✓ Basically generate all possible candidates
 - ✓ *Prune* the state space tree due to a decision function
 - ✓ Still exponential time in the worst case, but efficient for many large instances.

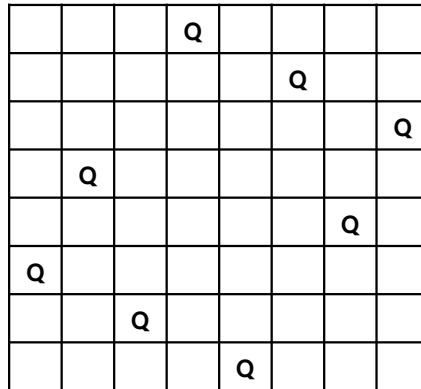
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The 8-Queens Problem

- ✓ **Horse:** King, Queen, 2 Rooks, 2 Bishops, 2 Knights
- ✓ Every horse threatens others on the same row, on the same column, or on the same diagonals.



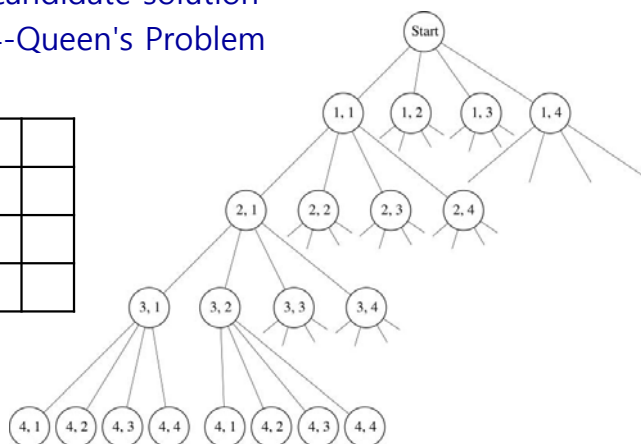
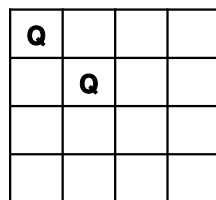
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State Space Tree

- ✓ The tree such that each path from the root to a leaf node is a candidate solution
- ✓ Example) 4-Queen's Problem



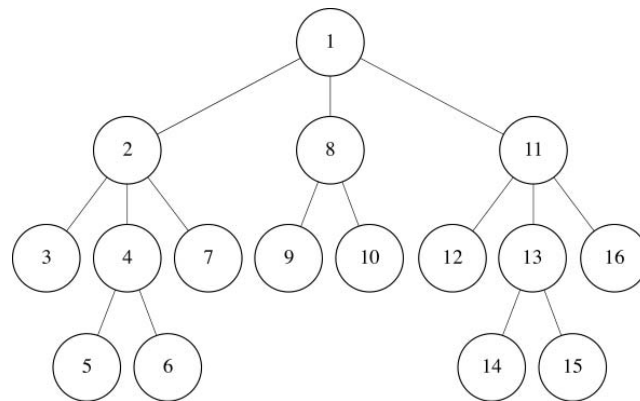
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Tree Traversal

- ✓ Search sequence of possible candidates
- ✓ Depth-First Search (DFS)



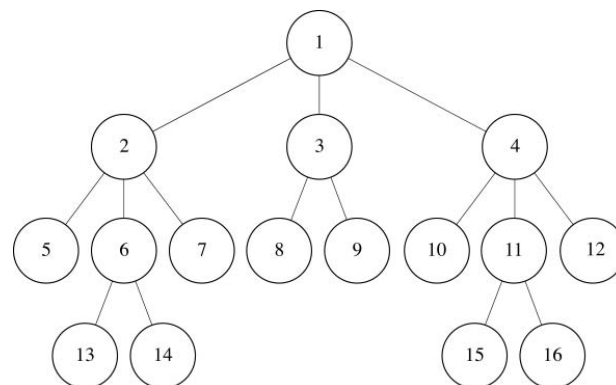
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Tree Traversal

- ✓ Breadth-First Search (BFS)



- ✓ Best-First Search (Branch-and-Bound Algorithm)

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Backtracking Algorithm

- ✓ **Non-promising** node (in a state space tree)
 - ✓ the node cannot lead to a solution
- ✓ **Promising** node
 - ✓ all nodes except non-promising nodes
- ✓ **Pruning of a state space tree**
 - ✓ If the visited node is non-promising, backtrack to the parent node.

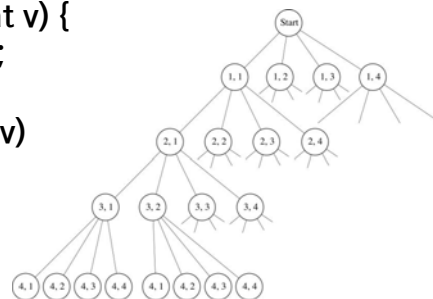
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Outline of the algorithm

```
void checknode(node v)
{
    node u;
    if (promising(v)) {
        if (there is a solution at v) {
            output the solution;
        } else {
            for (each child u of v)
                checknode(u);
        }
    }
}
```



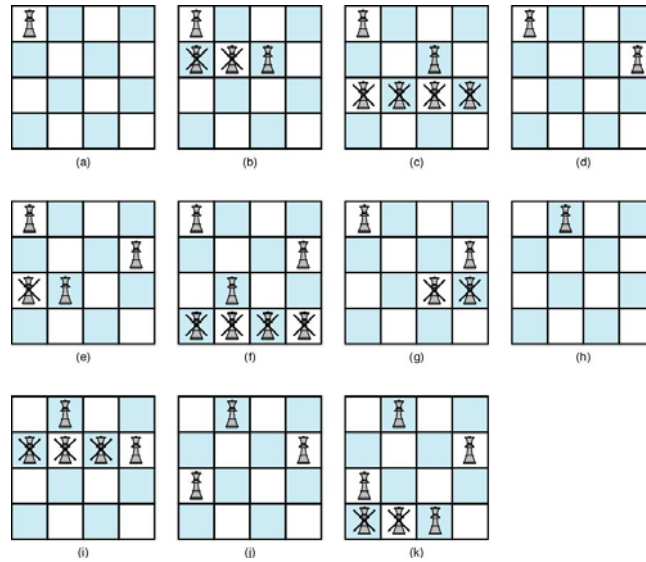
✓ (Note) The state space tree exists implicitly.

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4 Queen's Problem

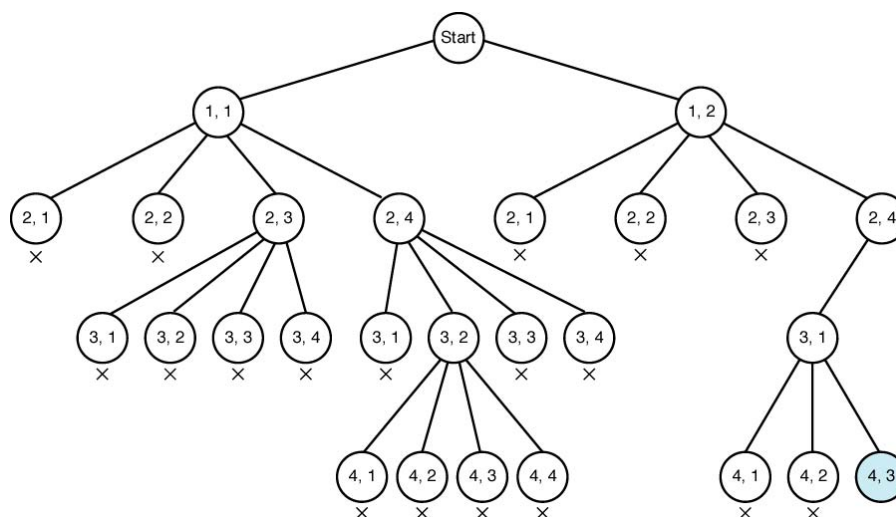


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State Space Tree of 4 Queen's Problem



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The n-Queens Problem

- ✓ Promising Function (or *bounding function*)
 - ✓ the same row : implicitly impossible
 - ✓ the same column : $\text{col}(i) = \text{col}(k)$
 - ✓ the same right diagonal : $\text{col}(i) - \text{col}(k) = i - k$
 - ✓ the same left diagonal : $\text{col}(i) + \text{col}(k) = i + k$
- ✓ Algorithm 5.1

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● The algorithm (print all solutions)

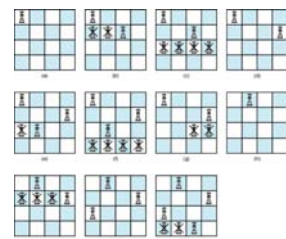
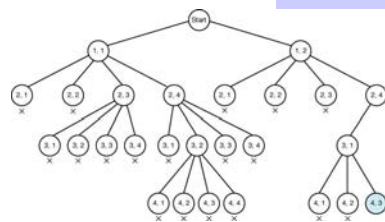
- Algorithm 5.1 *queens*
- Top level call : *queens(0)*

void *queens*(index i)

```

{
    index j;
    if (promising(i) {
        if (i == n) cout << col[1] through col[n];
        else
            for (j=1; j <= n; j++) {
                col[i+1] = j;
                queens(i+1);
            }
    }
}

```





Analysis of the Algorithm

- ✓ Comparison from some instances (Table. 5.1)
 - ✓ (# of checked nodes of the state space tree)
 - ✓ Algorithm 1: DFS without backtracking ($\sim n^n$)
 - ✓ Algorithm 2: avoid same column ($n!$)
 - ✓ Algorithm 3: apply checknode algorithm
 - ✓ Algorithm 4: apply expand algorithm
- ✓ Theoretical analysis
 - ✓ Difficult
- ✓ Measure real execution time
 - ✓ Not-reasonable
- ✓ Estimate the efficiency by probabilistic analysis
 - ✓ may use Monte Carlo Algorithm

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(참고) Monte Carlo Algorithm

- ✓ Characteristics
 - ✓ a probabilistic algorithm (c.f. deterministic algorithm)
 - ✓ the next instruction executed is determined at random
 - ✓ no guarantee that the estimate is close to the true expected value, but the probability is high
- ✓ Necessary condition
 - ✓ 1. the same promising function for all nodes at the same level
 - ✓ 2. nodes at the same level have the same number of children
- ✓ Outline of the Monte Carlo estimate algorithm
 - ✓ Algorithm 5.2 *Estimate*

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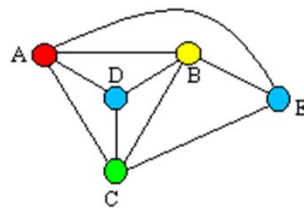
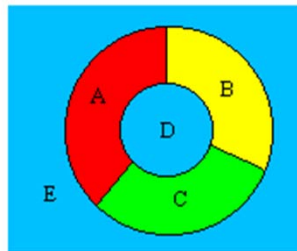
Graph Coloring

✓ Graph coloring problem (m -coloring)

- ✓ Color vertices of an undirected graph such that
- ✓ 1. no two adjacent vertices are the same color
- ✓ 2. and, use at most m colors

✓ Map coloring

- ✓ Map and its *planar graph* representation



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Graph Coloring

✓ The problem

- ✓ Find all different m -colorings for a given graph

✓ Promising function

- ✓ A node of the state space tree is non-promising if two adjacent vertices are the same color

✓ State space tree

- ✓ 3-Coloring of Fig. 5.10

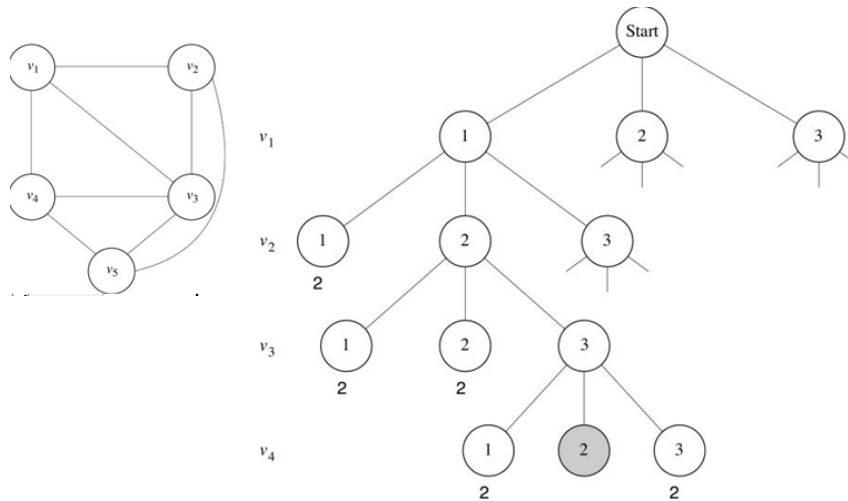
✓ Algorithm 5.5 m -coloring

- ✓ adjacency matrix $W[i][j]$: 1/0 represents that v_i and v_j are adjacent or not
- ✓ output $vcolor[1..n]$: color number (1.. m)
- ✓ top-level call : $m_coloring(0)$

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3-Coloring Example




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Algorithm 5.5

```
void m_coloring (index i)
{
    int color;


    if (promising(i))
        if (i == n)
            cout << vcolor[1] through vcolor[n];
        else
            for (color = 1; color <= m; color++){
                vcolor[i + 1] = color;
                m_coloring(i + 1);
            }
}
```



```
bool promising (index i)
{
    index j;
    bool switch;

    switch = true;
    j = 1;
    while (j < i && switch){
        if (W[i][j] && vcolor[i] == vcolor[j])
            switch = false;
        j++;
    }
    return switch;
}
```

Promising of Algorithm 5.5



(참고) More Considerations

- ✓ 2-Coloring Problem : exist efficient algorithms
- ✓ m-Coloring Problem for $m \geq 3$: NP-Hard
- ✓ 4-colorability conjecture for planar graph
 - ✓ first noted by August Ferdinand Mobius, 1840
 - ✓ proven to be true by Appel and Haken, 1976, with the help of computers
 - ✓ 2005, proven by Georges Gonthier with theorem proving software

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0-1 Knapsack Problem

✓ Assumption

- ✓ objects are ordered in p_i/w_i order

✓ Outline of the algorithm

```
void checknode(node v)
{
    node u;
    if (value(v) is better than best)
        best = value(v);
    if (promising(v))
        for (each child u of v)
            checknode(u);
}
```

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✓ Promising function (bounding function)

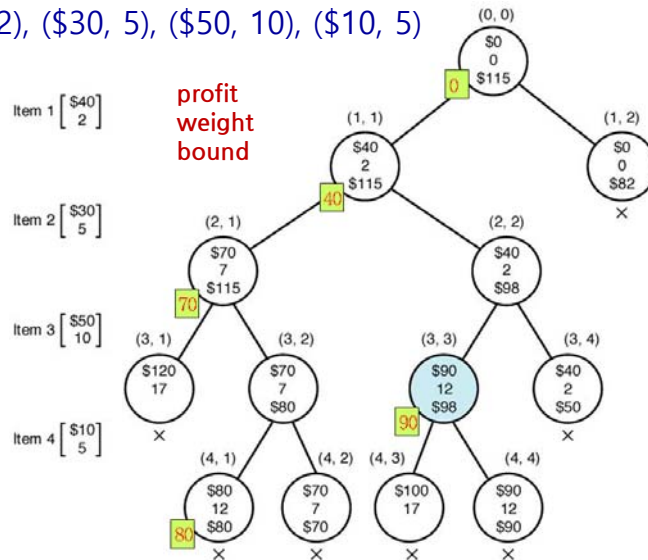
- (1) *weight* $\leq W$
 - (2) *bound* $>$ the known best solution, where *bound* is the profit bound of solutions by expanding the node.
- Note*) the profit bound might be the output of the Fractional Knapsack Problem

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Example 5.6, Fig. 5.14

(p,w) : (\$40, 2), (\$30, 5), (\$50, 10), (\$10, 5)
W = 16



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Algorithm 5.7 knapsack

The top level call

```

numbest = 0;           // # of items considered
maxprofit = 0;         // the known max profit
knapsack(0, 0, 0);
printResult();         // maxprofit, bestset[];
    
```

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Algorithm 5.7

```

void knapsack (index i,
              int profit, int weight)
{
    if (weight <= W && profit > maxprofit){
        maxprofit = profit;
        numbest = i;
        bestset = include;
    }

    if (promising(i)){
        include[i + 1] = "yes";
        knapsack(i + 1, profit + p[i + 1], weight + w[i + 1]);
        include[i + 1] = "no";
        knapsack(i + 1, profit, weight);
    }
}

```

Handwritten notes: "profit, weight" with an arrow pointing to the recursive call parameters; "r + weight" at the bottom.

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Promising of Algorithm 5.7

```

bool promising (index i)
{
    index j, k;
    int totweight;
    float bound;

    if (weight >= W)
        return false;
    else{
        j = i + 1;
        bound = profit;
        totweight = weight;
        while (j <= n && totweight + w[j] <= W){
            totweight = totweight + w[j];
            bound = bound + p[j];
            j++;
        }
        k = j;
        if (k <= n)
            bound = bound + (W - totweight) * p[k] / w[k];
        return bound > maxprofit;
    }
}

```

Handwritten notes: "profit, weight" with an arrow pointing to the parameter 'i'.

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Worst-case time complexity

- # of visited nodes in the state space tree

$$\sum_{i=0}^n 2^i = 2^{n+1} - 1 \in \Theta(2^n)$$

- time complexity of *promising*

$$n - i \in O(n)$$

- worst-case time complexity

$$W(n) = (2^{n+1} - 1)(n - i) \leq 2n \cdot 2^n$$

$$\text{Therefore, } W(n) \in O(n2^n)$$

- Simple derivation

$$W(n) \in \Theta(2^n) \cdot O(n) = O(n2^n)$$

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정리

- ✓ Backtracking Algorithm
- ✓ M-Coloring Problem
- ✓ 0-1 Knapsack Problem
- ✓ Chapter 6: Branch and Bound Algorithm
 - ✓ 0-1 Knapsack Problem
 - ✓ Traveling Salesperson Problem

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